

NAME: MOSUDI ISIAKA

REG. NUMBER: PG823362:

COURSE CODE: CME710

COURSE: ADVANCED ENGINEERING MATHEMATICS

DEPT: TELECOMMUNICATION ENGINEERING

APPLICATION: MATLAB R2017a(LIVE SCRIPT)

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Compare numerical solutions for the differential equation,

$y' = x + y$; given $y(0) = 0$, $h = 0.1$ and $h = 0.2$

Using Euler, Improved modified Euler and Runge-Kutta methods

```
clear

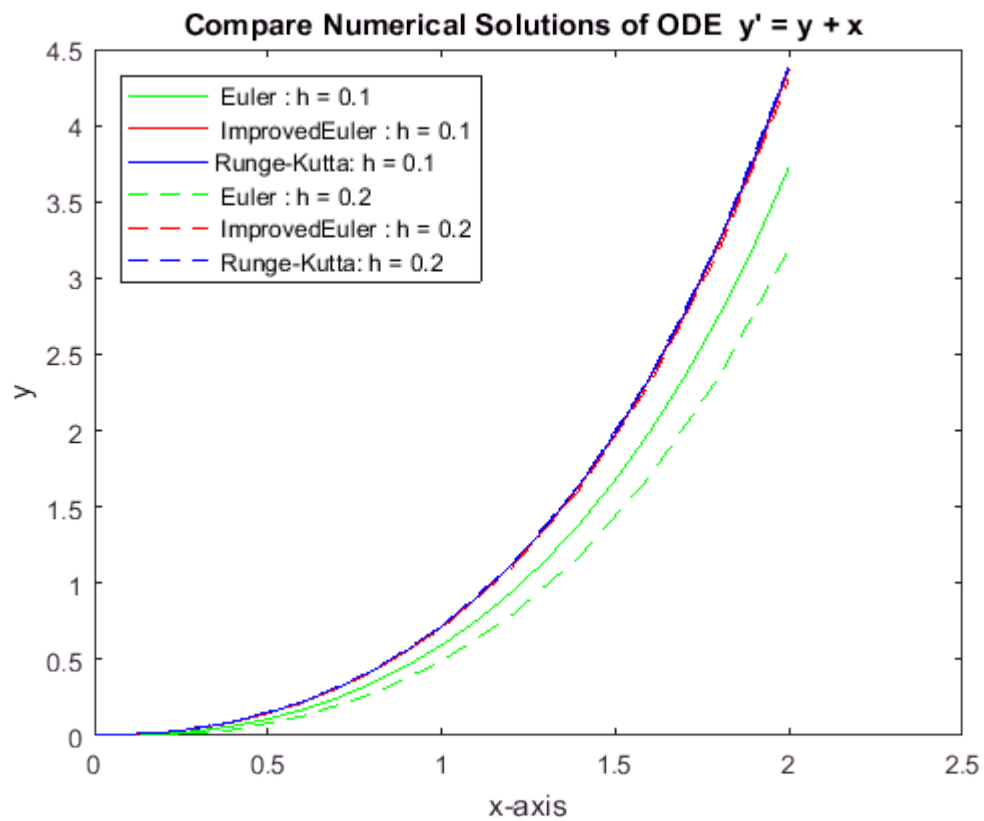
x=0;y=0;           %% Declare Initial Conditions
x_final=2;         %% Assuming I am expected to stop iteration at x=2

h=0.1;             %% Plot for step size, h=0.1
[t1,data1] = eulerm(x,y,h,x_final);           %% Euler method
[t2,data2] = eulermimproved(x,y,h,x_final);    %% Improved Euler method
[t3,data3] = rungek(x,y,h,x_final);            %% Runge-Kutta method
plot(t1,data1,'color','g'); hold on;
plot(t2,data2,'color','r')
plot(t3,data3,'color','b')

h=0.2;             %% Plot for step size, h=0.2
[t4,data4] = eulerm(x,y,h,x_final);           %% Euler method
[t5,data5] = eulermimproved(x,y,h,x_final);    %% Improved Euler method
[t6,data6] = rungek(x,y,h,x_final);            %% Runge-Kutta method
plot(t4,data4,'g--');
plot(t5,data5,'r--')
plot(t6,data6,'b--')

title("Compare Numerical Solutions of ODE   $y' = y + x$  ");
xlabel('x-axis'); ylabel("y")

legend(' Euler : h = 0.1', ' ImprovedEuler : h = 0.1', ...
      'Runge-Kutta: h = 0.1 ', ' Euler : h = 0.2', ...
      ' ImprovedEuler : h = 0.2', ' Runge-Kutta: h = 0.2 ', 'Location','northwest')
```



Runge-Kutta 4th Order

```
function [t, data] = rungek(x,y,h,x_final)
    Nsteps = round(x_final/h);
    t = zeros(Nsteps,1);    data = zeros(Nsteps,1);

    t(1) = x; data(1,:) = y; %% store intial condition
    for i =1:Nsteps
        dy = derivs(x,y); k1 = h*dy;
        dy = derivs(x + h/2,y+k1/2); k2 = h*dy;
        dy = derivs(x + h/2,y+k2/2); k3 = h*dy;
        dy = derivs(x + h,y+k3); k4 = h*dy;
        k = (k1 + 2 * k2 + 2 * k3 + k4)/6;
        y = y + k; x = x + h;
        t(i+1) = x; data(i+1,:) = y ;
    end
end
```

Improved Euler Method

```
function [t, data] = eulermimproved(x,y,h,x_final)
    Nsteps = round(x_final/h);
    t = zeros(Nsteps,1);    data = zeros(Nsteps,1);

    t(1) = x; data(1,:) = y; %% store intial condition
    for i =1:Nsteps
        dy = derivs(x,y); k1 = h*dy;
        x = x + h;
        dy = derivs(x, y+k1); k2 = h*dy;
        y = y + (k1 + k2)./2;
        t(i+1) = x; data(i+1,:) = y ;
    end
end
```

Euler Method

```
function [t, data] = eulerm(x,y,h,x_final)
    Nsteps = round(x_final/h);
    t = zeros(Nsteps,1);    data = zeros(Nsteps,1);

    t(1) = x;data(1,:) = y; %% store intial condition
    for i =1:Nsteps
        dy = derivs(x,y); y = y + h*dy;
        x = x + h;
        t(i+1) = x; data(i+1,:) = y ;
    end
end
```

The differential equation

```
function dy = derivs(x,y)
    dy = y + x ;
end
```