COSC 407

Intro to Parallel Computing

Topic 6 - Barriers and Mutexes (Critical Sections, Atomics and Locks)

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Outline

Previously (LiveStream):

- Student lead questions
- OpenMP
- Basics, HelloWorld
- Distributing the work
- Example: Summing it all up (as array)

Today:

- Synchronization (barriers, nowait)
- Mutual Exclusion (critical, atomic, locks)

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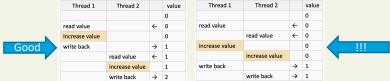
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Race Condition

 Unpredictable results when two (or more) threads attempt to read or write the same data simultaneously (previous unprotected example)

Consider two threads each increases the value of a shared integer variable by one



- Data Race happens when two or more threads work on a shared data item, where at least one thread is trying to update (write to) this item.
- Mutual Exclusion: only one thread at a time can have access to a shared resource (there can only be one!)

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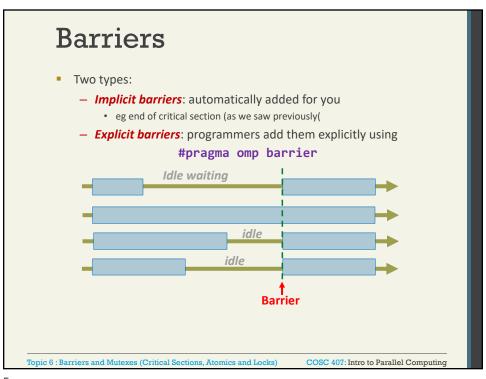
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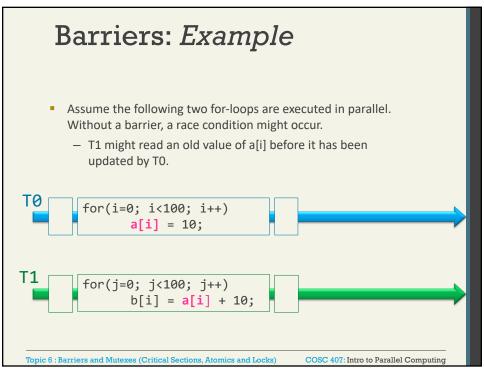


Barriers

- Barriers are used for threads synchronization
- All threads must reach the barrier before any of them can proceed
 - We may use barriers between parts of the code that read and write to the same memory locations
- Important
 - Each barrier needs to be encountered by all the threads in a team or none of them
 - The sequence of work-sharing regions and barrier regions encountered must be the same for every thread in the team (more on this soon....)

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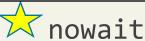


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different paths (Thread Divergence)

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- The use of barriers is expensive (as threads in a team will be idle for a while)
- To reduce synchronization, you can add the nowait clause.
- The **implicit barrier** at the end pragma construct can be cancelled with a nowait
 - i.e. If nowait is used in an OpenMP construct, threads will not synchronize (wait) at the end of these constructs.

```
Example: #pragma omp single nowait
                          Threads don't have to synchronize here
```

You can use nowait if there is no data dependency between two parts of your code

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Mutual Exclusion in OpenMP

- Sometimes, only one thread at a line can access a critical section of code or update a variable
 - Same concept as with POSIX threads
- OpenMP provides several mechanisms for insuring mutual exclusion in critical sections:
 - critical directive
 - Unnamed and named critical directives
 - atomic directive
 - simple locks

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critical Directive

- Race condition may be controlled by defining a critical region
 - # pragma omp critical *global_result_p += my_result;
- Critical regions force threads to work one at a time
 - All threads run the code, but <u>only one thread at a time can run</u> the code in the critical region
 - When a thread encounters a critical construct, it waits until no other thread is executing a critical region with the same name

#pragma omp critical [(name)] code block

All structured blocks modified by an unnamed critical directive form a single critical section

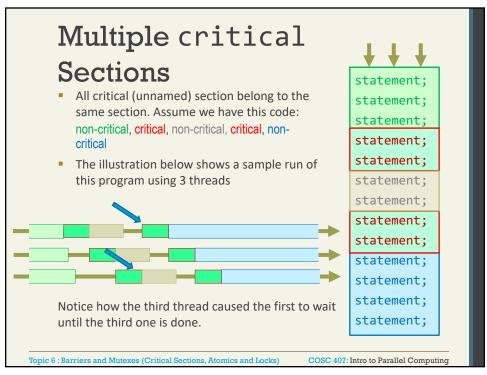
https://www.openmp.org/spec-html/5.0/openmpsu89.html

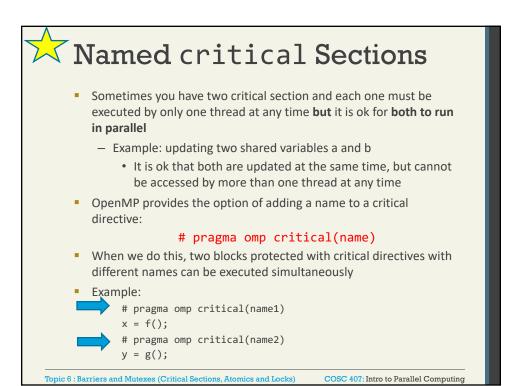
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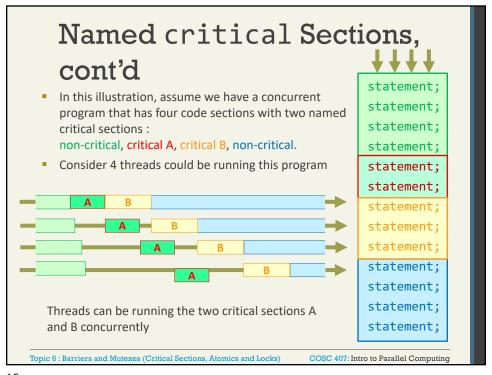
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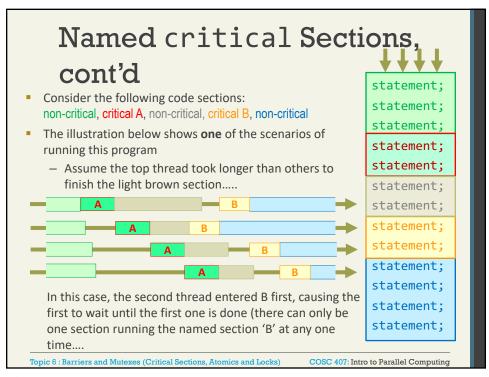
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critical Directive cont'd statement; • On the right, assume we have a concurrent statement; program that has three code sections: statement; non-critical, critical, non-critical. statement: The illustration below shows how 4 threads statement; could be running this program statement; statement; A thread has to wait if it reaches a critical statement; section that is being executed by another statement; thread Critical sections have no sync barriers at their entry or exit points within a thread Threads wait for each other at a barrier. **Critical region Non-critical region Non-critical region** Topic 6: Barriers and Mutexes (Critical Sections, Atomics and Locks) COSC 407: Intro to Parallel Computing











atomic Directive

- Allows threads to safely update a shared variable and avoids data race conditions
- Similar to critical directive (protects shared data) and can be faster on many processors (if implemented correctly -> but can cause problems if done incorrectly)
 - A critical section that only does a load-modify-store can be protected much more efficiently using this special instruction
 - Only the memory update is atomic

Example:

```
#pragma omp atomic
*global_result_p += my_result;
```

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atomic Directive

- It can only be applied to load-modify-store operation in one of following forms:
 - a) A single statement in the form:

```
x++, ++x, x--, --x
x <op>= <expression>
x = x \langle op \rangle \langle expression \rangle
x = \langle expression \rangle \langle op \rangle x
   where <op> is one of +, -, *, /, &, ^, |, <<, >>
    and <expression> does not reference x
```

b) A structured block in the form:

```
{ value = x; //any of the expressions in (b) above; }
{ //any of the expressions in (b) above; value = x; }
e.g. {value = x; x += 1;}
```

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Danger!

Case 1

- All elements are added sequentially, and there is performance penalty for using atomic, because the system coordinates all threads
- Slower than a serial code!
 - Each thread must wait!

```
sum = 0;

for (i=0; i<n; i++)

{

    #pragma omp atomic

    sum += a[i];

} /*-- End of parallel for --*/
```

Case 2

- Each thread adds up its local sum.
- The atomic is only applied for adding up local sums to obtain the total sum

```
sumLocal = 0;

#pragma omp for

for (i=0; i<n; i++) sumLocal += a[i];

#pragma omp atomic

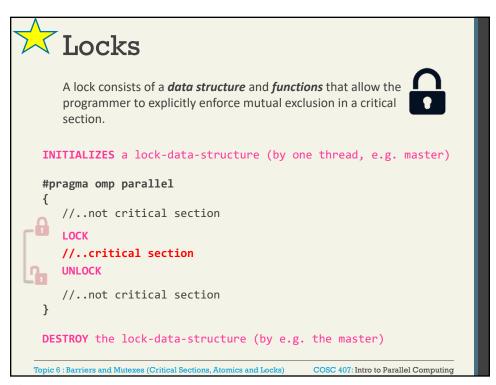
sum += sumLocal;

} /*-- End of parallel region --*/
```

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Locks

A lock consists of a *data structure* and *functions* that allow the programmer to explicitly enforce mutual exclusion in a critical section



```
static omp_lock_t mylock; lock data structure is shared among the
                                        threads
 omp_init_lock(&mylock);
                                        One of the threads (e.g., master)
 #pragma omp parallel
                                        initializes it
     //not critical code
                                        Only one thread can own (set) mylock,
                                        and only this thread can unset it.
 omp_set_lock(&mylock);
                                       While a thread owns mylock, no other
     //critical region
                                        thread can enter this critical section. If
     omp_unset_lock(&mylock);
                                        another thread attempts to enter the
                                        critical section, it will block when it
     //not critical region
                                        calls the lock function.
 }
 omp_destroy_lock(&mylock); ← One of the threads destroys the lock.
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When to Use Which?

- First, think of atomic (usually highest performance)
 - Use atomic for single load-modify-store statement (be careful!)
- Second, think of critical
 - No large difference between the performance between critical directive and locks.
- Finally, if neither atomic nor critical is possible then use locks
 - e.g., if you want to leave a locked region with jumps (e.g. break or return).
 - You cannot leave a region protected by 'critical' with a jump
 - · Don't forget to unset the lock!!!!
 - e.g., if you want to protect a single data structure, not the complete block of code.

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Some Caveats

- Different types of mutual exclusion don't belong to the same critical region
 - Don't mix the different types for a **single** critical section
- 2. There is **no guarantee of fairness** in mutual exclusion constructs
- 3. It can be dangerous to "nest" mutual exclusion constructs
 - Use named critical sections if you have to nest mutual exclusion constructs, but even then there is no guarantee to avoid deadlocks

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Conclusion/Up Next

- What we covered today (review key concepts):
 - Synchronization (barriers, nowait)
 - Mutual Exclusion (critical, atomic, locks)
- Next:
 - Variable scope (shared, private, firstprivate)
 - Reduction
 - Work Sharing

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Homework

- Please review
 - OpenMP Resources (See week three module)
 - Additional resources on Canvas
 - Run the sample code and try the challenge
 - You need to be able to run and understand how to approach a problem
 - Be familiar with the OpenMP directives introduced so far

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