Insertion Sort Algorithm

```
#include <stdio.h>
void insertionSort(int arr[], int n)
{
   int i, key, j;
   for (i = 1; i < n; i++)
   {
      key = arr[i];
      j = i - 1;
      while (j >= 0 && arr[j] > key)
      {
         arr[j + 1] = arr[j];
         j = j - 1;
      }
      arr[j + 1] = key;
   }
}
void printArray(int arr[], int n)
{
   int i;
   for (i = 0; i < n; i++)
      printf("%d ", arr[i]);
   printf("\n");
}
int main()
{
   int arr[] = {12, 11, 13, 5, 6};
   int n = sizeof(arr) / sizeof(arr[0]);
   printArray(arr, n);
   insertionSort(arr, n);
   printArray(arr, n);
   return 0;
}
```

Merge Sort Algorithm

```
#include <stdio.h>

void merge(int arr[], int l, int m, int r)
{
  int n1 = m - l + 1;
  int n2 = r - m;

  int L[n1], R[n2];

  for (int i = 0; i < n1; i++)
    L[i] = arr[l + i];
  for (int j = 0; j < n2; j++)
    R[j] = arr[m + 1 + j];

  int i = 0, j = 0, k = l;

  while (i < n1 && j < n2)
  {
    if (L[i] <= R[j])
    {
      arr[k] = L[i];
      i++;
    }
    else
    {
      arr[k] = R[j];
      j++;
    }
    k++;
  }

  while (i < n1)
  {
    arr[k] = L[i];
    i++;
    k++;
  }

  while (j < n2)
  {
    arr[k] = R[j];
    j++;
    k++;
  }
}

void mergeSort(int arr[], int l, int r)
{
  if (l < r)
  {
    int m = l + (r - l) / 2;

    mergeSort(arr, l, m);
    mergeSort(arr, m + 1, r);

    merge(arr, l, m, r);
  }
}
```

```
void printArray(int arr[], int size)
{
   for (int i = 0; i < size; i++)
      printf("%d ", arr[i]);
   printf("\n");
}

int main()
{
   int arr[] = {12, 11, 13, 5, 6, 7};
   int arr_size = sizeof(arr) / sizeof(arr[0]);

   printf("Original array:\n");
   printArray(arr, arr_size);

   mergeSort(arr, 0, arr_size - 1);

   printf("Sorted array:\n");
   printArray(arr, arr_size);

   return 0;
}
```

Quick Sort Algorithm

```
#include <stdio.h>

#define N 5

int arr[N];

int partition(int low, int high) {
   int pivot = arr[high], i = low - 1, temp;
   int j; // Declared outside the loop
   for (j = low; j < high; j++) {
      if (arr[j] < pivot) {
         i++;
         temp = arr[i];
         arr[i] = arr[j];
         arr[j] = temp;
      }
   }
   temp = arr[i + 1];
   arr[i + 1] = arr[high];
   arr[high] = temp;
   return i + 1;
}

void quickSort(int low, int high) {
   int pi;
   if (low < high) {
      pi = partition(low, high);
      quickSort(low, pi - 1);
      quickSort(pi + 1, high);
   }
}

int main() {
   int i; // Declared outside the loop
   printf("Enter 5 numbers: ");
   for (i = 0; i < N; i++) scanf("%d", &arr[i]);

   quickSort(0, N - 1);

   printf("Sorted array: ");
   for (i = 0; i < N; i++) printf("%d ", arr[i]);
   return 0;
}
```

Dijkstra Algorithm

```
#include <stdio.h>
void swap(int *a, int *b)
{
  int t = *a;
  *a = *b;
  *b = t;
}

int partition(int arr[], int low, int high)
{
  int pivot = arr[high];
  int i = (low - 1);

  for (int j = low; j < high; j++)
          {
    if (arr[j] < pivot)
                    {
      i++;
      swap(&arr[i], &arr[j]);
    }
  }

  swap(&arr[i + 1], &arr[high]);
  return (i + 1);
}

void quickSort(int arr[], int low, int high)
{
  if (low < high)
          {
    int pi = partition(arr, low, high);

    quickSort(arr, low, pi - 1);
    quickSort(arr, pi + 1, high);
  }
}

void printArray(int arr[], int size)
{
  for (int i = 0; i < size; i++)
    printf("%d ", arr[i]);
  printf("\n");
}

int main()
{
  int arr[] = {10, 7, 8, 9, 1, 5};
  int n = sizeof(arr) / sizeof(arr[0]);
  printf("Original array:\n");
  printArray(arr, n);
  quickSort(arr, 0, n - 1);
  printf("Sorted array:\n");
  printArray(arr, n);

  return 0;
}
```

Prims Algorithm

```
#include <stdio.h>
#include <limits.h>
#define V 5
int minKey(int key[], int mstSet[])
{
   int min = INT_MAX, minIndex, v;
   for (v = 0; v < V; v++) {
      if (mstSet[v] == 0 && key[v] < min)
     {
         min = key[v];
         minIndex = v;
      }
   }
   return minIndex;
}

void printMST(int parent[], int graph[V][V])
{
   int i;
   for (i = 1; i < V; i++)
  {
      printf("%d - %d   %d\n", parent[i], i, graph[i][parent[i]]);
   }
}

void primMST(int graph[V][V])
{
   int parent[V], key[V], mstSet[V];
   int count, u, v,i;
   for (i = 0; i < V; i++)
  {
      key[i] = INT_MAX;
      mstSet[i] = 0;
   }
   key[0] = 0;
   parent[0] = -1;
   for (count = 0; count < V - 1; count++)
  {
      u = minKey(key, mstSet);
      mstSet[u] = 1;
      for (v = 0; v < V; v++) {
         if (graph[u][v] && mstSet[v] == 0 && graph[u][v] < key[v])
        {
            key[v] = graph[u][v];
            parent[v] = u;
         }
      }
   }
   printMST(parent, graph);
}

int main() {
   int graph[V][V] = {
      {0, 2, 0, 6, 0},
      {2, 0, 3, 8, 5},
      {0, 3, 0, 0, 7},
      {6, 8, 0, 0, 9},
      {0, 5, 7, 9, 0}
   };
   primMST(graph);
   return 0;
}
```

Fractional Knapsack problem

```
#include <stdio.h>

#define N 5

struct Item {
   int weight;
   int value;
};

int compare(const void *a, const void *b) {
   double r1 = ((struct Item *)a)->value / (double)((struct Item *)a)->weight;
   double r2 = ((struct Item *)b)->value / (double)((struct Item *)b)->weight;
   return (r1 < r2) - (r1 > r2);
}

double fractionalKnapsack(struct Item arr[], int W) {
   int i;
   double totalValue = 0.0;
   for (i = 0; i < N; i++) {
      if (arr[i].weight <= W) {
         totalValue += arr[i].value;
         W -= arr[i].weight;
      } else {
         totalValue += arr[i].value * ((double) W / arr[i].weight);
         break;
      }
   }
   return totalValue;
}

int main() {
   struct Item arr[N] = {{60, 10}, {100, 20}, {120, 30}, {90, 10}, {70, 15}};
   int W = 50;  // Knapsack capacity
   qsort(arr, N, sizeof(arr[0]), compare);
   printf("Maximum value in Knapsack = %.2f\n", fractionalKnapsack(arr, W));
   return 0;
}
```

Bellman Ford Algorithm

```
#include <stdio.h>
#include <limits.h>

#define V 5
#define E 8

struct Edge {
  int u, v, weight;
};

void bellmanFord(struct Edge edges[], int src) {
  int dist[V], i, j;

  for (i = 0; i < V; i++)
    dist[i] = INT_MAX;
  dist[src] = 0;

  for (i = 1; i < V; i++) {
    for (j = 0; j < E; j++) {
      int u = edges[j].u;
      int v = edges[j].v;
      int weight = edges[j].weight;
      if (dist[u] != INT_MAX && dist[u] + weight < dist[v])
        dist[v] = dist[u] + weight;
    }
  }

  for (i = 0; i < E; i++) {
    int u = edges[i].u;
    int v = edges[i].v;
    int weight = edges[i].weight;
    if (dist[u] != INT_MAX && dist[u] + weight < dist[v])
      printf("Graph contains negative weight cycle\n");
  }

  printf("Vertex Distance from Source %d\n", src);
  for (i = 0; i < V; i++)
    printf("%d \t\t %d\n", i, dist[i]);
}

int main() {
  struct Edge edges[E] = {
    {0, 1, -1}, {0, 2, 4}, {1, 2, 3}, {1, 3, 2}, {1, 4, 2}, {3, 2, 5}, {3, 1, 1}, {4, 3, -3}
  };
  bellmanFord(edges, 0);
  return 0;
}
```

Travelling salesperson problem

```
#include <stdio.h>
#include <limits.h>

#define N 4

int dist[N][N] = {
  {0, 10, 15, 20},
  {10, 0, 35, 25},
  {15, 35, 0, 30},
  {20, 25, 30, 0}
};

int dp[1 << N][N];

int tsp(int mask, int pos) {
  int city, newAns, ans;
  if (mask == (1 << N) - 1) {
    return dist[pos][0]; // Return to the starting point
  }
  if (dp[mask][pos] != -1) return dp[mask][pos];

  ans = INT_MAX;
  for (city = 0; city < N; city++) {
    if ((mask & (1 << city)) == 0) {
      newAns = dist[pos][city] + tsp(mask | (1 << city), city);
      ans = (ans < newAns) ? ans : newAns;
    }
  }
  return dp[mask][pos] = ans;
}

int main() {
  int i, j;
  for (i = 0; i < (1 << N); i++)
    for (j = 0; j < N; j++)
      dp[i][j] = -1;

  printf("Minimum cost: %d\n", tsp(1, 0));
  return 0;
}
```

N-queen problem

```
#include <stdio.h>
#define N 4

int board[N][N];
int isSafe(int r, int c)
{
   int i, j;
   for (i = 0; i < r; i++)
   {
      if (board[i][c]) return 0;
   }
   for (i = r - 1, j = c - 1; i >= 0 && j >= 0; i--, j--)
   {
      if (board[i][j]) return 0;
   }
   for (i = r - 1, j = c + 1; i >= 0 && j < N; i--, j++)
   {
      if (board[i][j]) return 0;
   }
   return 1;
}

int solve(int r)
{
   int c, i, j;
   if (r == N) {
      for (i = 0; i < N; i++)
      {
         for (j = 0; j < N; j++)
         {
            printf("%d ", board[i][j]);
         }
         printf("\n");
      }
      return 1;
   }
   for (c = 0; c < N; c++)
   {
      if (isSafe(r, c))
      {
         board[r][c] = 1;
         if (solve(r + 1)) return 1;
         board[r][c] = 0;
      }
   }
   return 0;
}

int main()
{
   solve(0);
   return 0;
}
```

Rabin Karp Algorithm

```
#include <stdio.h>
#include <string.h>

#define d 256
#define q 101
int hash(char s[], int l, int m)
{
   int h = 0;
   int i;
   for (i = 0; i < l; i++)
      h = (h * d + s[i]) % m;
   return h;
}
void rk(char t[], char p[]) {
   int m = strlen(p);
   int n = strlen(t);
   int ph = hash(p, m, q);
   int th = hash(t, m, q);
   int h = 1;
   int i, j;
   for (i = 0; i < m - 1; i++)
      h = (h * d) % q;

   for (i = 0; i <= n - m; i++) {
      if (ph == th) {
         j = 0;
         while (j < m && t[i + j] == p[j])
            j++;
         if (j == m)
            printf("Pattern found at index %d\n", i);
      }
      if (i < n - m) {
         th = (d * (th - t[i] * h) + t[i + m]) % q;
         if (th < 0)
            th += q;
      }
   }
}

int main() {
   char t[100], p[100];
   printf("Enter text: ");
   scanf("%s", t);  // Takes input for text
   printf("Enter pattern: ");
   scanf("%s", p);  // Takes input for pattern
   rk(t, p);
   return 0;
}
```