

Algebraic Topology - MATH0023

Based on lectures by Prof FEA Johnson

Notes taken by Imran Radzi

Notes based on the Autumn 2021 Algebraic Topology lectures by Prof FEA Johnson.

Contents

1	Simplicial complexes	1
2	Homology	4
2.1	Quotient spaces	4
2.2	Chain complex	9
2.3	Simplicial mapping	9
2.4	Chain mapping	10

1 Simplicial complexes

Definition (Simplicial complex). A *simplicial complex* X is a pair (V_X, \mathcal{S}_X) where V_X denotes the vertex set of X and \mathcal{S}_X is the set of *finite, non-empty* subsets of V_X satisfying

1. $\forall v \in V_X$, then $\{v\} \in \mathcal{S}_X$
2. If $\sigma \in \mathcal{S}_X$, $\tau \subset \sigma$, $\tau \neq \emptyset$, then $\tau \in \mathcal{S}_X$.

\mathcal{S}_X is called the set of *simplices* of X .

Example. A *standard 1-simplex*, denoted by Δ^1 is simply the line segment (or usually denoted by I).

$$V_{\Delta^1} = \{0, 1\}$$

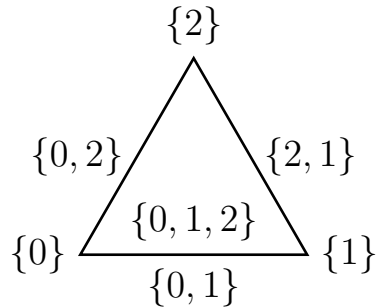
$$\mathcal{S}_{\Delta^1} = \{\{0\}, \{1\}, \{0, 1\}\}$$

$$\{0\} \xrightarrow{\{0, 1\}} \{1\}$$

A *standard 2-simplex*, denoted by Δ^2 is the equilateral triangle.

$$V_{\Delta^2} = \{0, 1, 2\}$$

$$\mathcal{S}_{\Delta^2} = \{\{0\}, \{1\}, \{2\}, \{0, 1\}, \{0, 2\}, \{1, 2\}, \{0, 1, 2\}\}$$



In general, the *standard n -simplex* Δ^n , is $\Delta^n = (V_{\Delta^n}, \mathcal{S}_{\Delta^n})$ where

$$V_{\Delta^n} = \{0, 1, \dots, n\}$$

$$\mathcal{S}_{\Delta^n} = \{\alpha : \alpha \subset \{0, \dots, n\}, \alpha \neq \emptyset\}$$

If $X = (V_x, \mathcal{S}_X)$ is a simplicial complex, we now want to pick a field \mathbb{F} , usually \mathbb{Q} or \mathbb{F}_2 (in this course) and want to produce a sequence of vector spaces (over \mathbb{F})

$$C_n(X)_{0 \leq n}$$

$C_0(X)$ is the vector space whose basis elements are simply the vertices of the simplicial complex, and this has dimension 0.

Definition (k -simplex of a simplicial complex). If X is a simplicial complex then a k -simplex of X is a simplex $\sigma \in \mathcal{S}_X$ such that $|\sigma| = k + 1$.

$C_k(X)$ is the vector space whose basis elements are the *oriented k -simplices* of X which are the following symbols,

$$[v_0, v_1, \dots, v_n]$$

(where $\{v_0, \dots, v_n\}$ is an n -simplex of X) subject to the rules

$$[v_{\rho(0)}, v_{\rho(1)}, \dots, v_{\rho(n)}] = \text{sign}(\rho)[v_0, \dots, v_n]$$

Definition.

$$\partial_n : C_n(X) \rightarrow C_{n-1}(X)$$

is a linear map defined on basis elements as follows;

$$\partial_n[v_0, \dots, v_n] = \sum_{r=0}^n (-1)^r [v_0, \dots, \hat{v}_r, \dots, v_n]$$

where \hat{v}_r indicates omission of v_r .

Example.

$$\begin{aligned}\partial_2[0, 1, 2] &= [1, 2] - [0, 2] + [0, 1] \\ \partial_1[v_0, v_2] &= [v_1] - [v_0]\end{aligned}$$

$$\begin{aligned}\partial_1\partial_2[0, 1, 2] &= \partial_1([1, 2] - [0, 2] + [0, 1]) \\ &= ([2] - [1]) - ([2] - [0]) + ([1] - [0]) \\ &= 0\end{aligned}$$

Proposition (Poincaré lemma). Let X be a simplicial complex. Consider

$$\partial_r : C_r(X) \rightarrow C_{r-1}(X)$$

for $r \geq 1$, then

$$\partial_{n-1}\partial_n \equiv 0$$

Proof.

$$\partial_n[v_0, \dots, v_n] = \sum_{r=0}^n (-1)^r [v_0, \dots, \hat{v}_r, \dots, v_n]$$

$$\begin{aligned}\partial_{n-1}[v_0, \dots, \hat{v}_r, \dots, v_n] &= \sum_{s < r} (-1)^s [v_0, \dots, \hat{v}_s, \dots, \hat{v}_r, \dots, v_n] \\ &\quad + \sum_{s > r} (-1)^{s-1} [v_0, \dots, \hat{v}_r, \dots, \hat{v}_s, \dots, v_n]\end{aligned}$$

$$\begin{aligned}\partial_{n-1}\partial_n[v_0, \dots, v_n] &= \sum_{s < r} (-1)^{r+s} [v_0, \dots, \hat{v}_s, \dots, \hat{v}_r, \dots, v_n] \\ &\quad + \sum_{s > r} (-1)^{r+s-1} [v_0, \dots, \hat{v}_r, \dots, \hat{v}_s, \dots, v_n] \\ &= 0\end{aligned}$$

□

Proposition. If

$$C_{n+1} \xrightarrow{\partial_{n+1}} C_n \xrightarrow{\partial_n} C_{n-1}$$

then

$$\text{im}(\partial_{n+1}) \subset \ker(\partial_n)$$

Proof. By previous lemma. □

2 Homology

2.1 Quotient spaces

Let V be a vector space over a field \mathbb{F} , and $U \subset V$ a vector subspace.

Definition. The following set

$$x + U = \{x + u : u \in U\}$$

is called the (left) coset of U in V . Note that

$$x + U = x' + U \iff x - x' \in U$$

Definition (Quotient space). The quotient space V/U is the set

$$V/U = \{x + U : x \in V\}$$

where addition and scalar multiplication is defined by

$$(x + U) + (y + U) = x + y + U$$

$$\lambda \cdot (x + U) = \lambda x + U$$

and 0 is represented by

$$0 + U$$

Note that V/U is a vector space.

Proposition.

$$\dim(V/U) = \dim(V) - \dim(U)$$

Proof. There exists a natural linear map

$$\eta : V \rightarrow V/U$$

given by

$$\eta(x) = x + U$$

Clearly this map is surjective so

$$\dim(V/U) = \dim(\text{im}(\eta))$$

Now,

$$\begin{aligned} \ker(\eta) &= \{x \in V : \eta(x) = U\} \\ &= \{x \in V : x + U = U\} \end{aligned}$$

and

$$x + U = U \iff x - 0 \in U \iff x \in U$$

so $\ker(\eta) = U$. Then,

$$\dim(V) = \dim \ker(\eta) + \dim \text{im}(\eta)$$

so

$$\dim(V/U) = \dim \text{im}(\eta) = \dim(V) - \dim(U)$$

□

Definition.

$$H_n(X; \mathbb{F}) = \ker(\partial_n) / \text{im}(\partial_{n+1})$$

We call $H_n(X; \mathbb{F})$ the n^{th} *homology group* of X with coefficients in \mathbb{F} . If $\mathbb{F} = \mathbb{Q}$, then $\dim H_n(X; \mathbb{Q})$ is called the n^{th} *Betti* number of X .

Consider Δ^3 . The set $\{0, 1, 2, 3\}$ represents the 'middle' of the tetrahedron (inside, interior). If we exclude the middle and simply take its boundary, we have

$$\partial \Delta^3 = S^2$$

It happens that S^2 (middle excluded) is the simplest simplicial model of the 2-sphere.

Example. Consider

$$H_k(S^2; \mathbb{F})$$

Note that

$$C_n(S^2) = 0 \text{ for } n \geq 3$$

as there are no 3-simplices, so we only have to worry about

$$H_2(S^2; \mathbb{F}), H_1(S^2; \mathbb{F}), H_0(S^2; \mathbb{F})$$

We proceed to calculate these from first principles. First note that $C_3(S^2) = 0$. Now, (noting the order of these bases) $C_2(S^2)$ has basis

$$[0, 1, 2], [0, 1, 3], [0, 2, 3], [1, 2, 3]$$

$C_1(S^2)$ has basis

$$[0, 1], [0, 2], [0, 3], [1, 2], [1, 3], [2, 3]$$

and lastly $C_0(S^2)$ has basis

$$[0], [1], [2], [3]$$

The linear maps

$$\partial_2 : C_2(S^2) \rightarrow C_1(S^2)$$

$$\partial_1 : C_1(S^2) \rightarrow C_0(S^2)$$

can both be represented by a 6×4 matrix and a 4×6 matrix respectively.

We apply ∂_2 and ∂_1 to the bases to obtain the entries to the matrices, so for example

$$\partial_2([0, 1, 2]) = [1, 2] - [0, 2] + [0, 1]$$

so the first column of the matrix representing ∂_2 is $\begin{pmatrix} 1 \\ -1 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ Proceeding,

we will obtain that

$$\partial_2 = \begin{pmatrix} 1 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & -1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$

$$\partial_1 = \begin{pmatrix} -1 & -1 & -1 & 0 & 0 & 0 \\ 1 & 0 & 0 & -1 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 1 \end{pmatrix}$$

Notice that $\partial_1 \partial_2 = 0$, which further confirms the lemma from before. Now reducing both the matrices to row reduced echelon form, we obtain

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

thus $\dim \ker \partial_2 = 1$, $\dim \operatorname{im} \partial_2 = 3$

$$\begin{pmatrix} 1 & 0 & 0 & -1 & -1 & 0 \\ 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

thus $\dim \ker \partial_1 = 3$, $\dim \operatorname{im} \partial_1 = 3$

$$0 \xrightarrow[\partial_3]{} C_2 \xrightarrow{\partial_2} C_1 \xrightarrow{\partial_1} C_0 \rightarrow 0$$

so now

$$H_2(S^3) = \ker(\partial_2)/\operatorname{im}(\partial_3) = \ker(\partial_2) \cong \mathbb{F}$$

as $\text{im}(\partial_3) = 0$, so in total,

$$H_2(S^2; \mathbb{F}) \cong \mathbb{F}$$

Next,

$$H_1(S^2) = \ker(\partial_1)/\text{im}(\partial_2)$$

Now note that

$$\dim H_1(S^2) = \dim \ker(\partial_1) - \dim \text{im}(\partial_2) = 3 - 3 = 0$$

thus

$$H_1(S^2; \mathbb{F}) = 0$$

Next,

$$H_0(S^2) = \ker(\partial_0)/\text{im}(\partial_1) = C_0/\text{im}(\partial_1)$$

and

$$\dim H_0(S^2) = \dim C_0 - \dim \text{im}(\partial_1) = 4 - 3 = 1$$

thus

$$H_0(S^2; \mathbb{F}) \cong \mathbb{F}$$

We've shown

$$H_k(S^2; \mathbb{F}) = \begin{cases} \mathbb{F} & k = 0 \\ 0 & k = 1 \\ \mathbb{F} & k = 2 \\ 0 & k \geq 3 \end{cases}$$

We will soon see that this theorem generalises if

$$S^n = \Delta^{n+1}$$

then

$$H_k(S^n) = \begin{cases} \mathbb{F} & k = 0, n \\ 0 & \text{otherwise} \end{cases}$$

2.2 Chain complex

Definition (Chain complex). Let \mathbb{F} be a field. A *chain complex* over \mathbb{F} is

$$C_* = (C_r, \partial_r)_{r \in \mathbb{N}}$$

where

1. Each C_r is a vector space over \mathbb{F}
2. $\partial_r : C_r \rightarrow C_{r-1}$ is a linear map such that $\partial_r \partial_{r+1} = 0$ for all r .

If $X = (V_X, \mathcal{S}_X)$, we have defined a chain complex

$$C_*(X) = (C_r(X), \partial_r)$$

Given a chain complex

$$C_* = (C_r, \partial_r)_{r \geq 0}$$

we define its *homology* $H_*(C_*)$ by

$$H_k(C_*) = \ker(\partial_k) / \text{im}(\partial_{k+1})$$

If $X = (V_X, \mathcal{S}_X)$ is a simplicial complex, we define

$$H_k(X, \mathbb{F}) = H_k(C_*(X; \mathbb{F}))$$

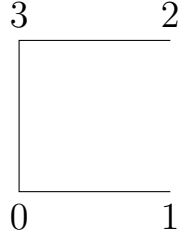
2.3 Simplicial mapping

Definition (Simplicial mapping). Let X, Y be simplicial complexes, i.e., $X = (V_X, \mathcal{S}_X)$ and $Y = (V_Y, \mathcal{S}_Y)$. A *simplicial mapping* $f : X \rightarrow Y$ is a mapping of vertex sets $f : V_X \rightarrow V_Y$ such that

$$\sigma \in \mathcal{S}_X \implies f(\sigma) \in \mathcal{S}_Y$$

Example. Let $X = Y = \Delta^2$. Then defining f by $f(0) = 1, f(1) = 2, f(2) = 0$, it is obvious that this mapping is simplicial.

Consider the following simplicial complex



and consider

$$f(0) = 1, f(1) = 2, f(2) = 3, f(3) = 0$$

This mapping is *not* simplicial as $f(\{0, 1\})$ is *not* a simplex.

Given a simplicial mapping $f : X \rightarrow Y$, we are going to produce linear maps

$$H_k(f) : H_k(X) \rightarrow H_k(Y)$$

such that if

$$g : Y \rightarrow Z$$

then

$$g \circ f : X \rightarrow Z$$

and

1. $H_k(g \circ f) = H_k(g) \circ H_k(f)$
2. $H_k(\text{id}_X) = \text{id}_{H_k(X)}$

2.4 Chain mapping

Definition. Let

$$\begin{aligned} C_* &= (C_r, \partial_r^C) \\ D_* &= (D_r, \partial_r^D) \end{aligned}$$

be chain complexes. A *chain mapping* $f_* : C_* \rightarrow D_*$ is a collection of linear maps

$$f_* = (f_r)_{r \geq 0}$$

where $f_r : C_r \rightarrow D_r$ and the following commutes

$$\begin{array}{ccc} C_r & \xrightarrow{\partial_r^C} & C_{r-1} \\ f_r \downarrow & & \downarrow f_{r-1} \\ D_r & \xrightarrow{\partial_r^D} & D_{r-1} \end{array}$$