# Topology and Groups - MATH0074

#### Based on lectures by Dr. Lars Louder

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## 1 Point-set Topology

#### 1.1 Preliminaries

**Definition** (Topological space). A topological space is a pair  $(X, \mathcal{T})$  such that

- 1. X is a set
- 2.  $\mathcal{T} \subset \mathcal{P}(X)$  is a collection of subsets of X
- 3.  $\emptyset \in \mathcal{T}, X \in \mathcal{T}$
- 4.  $\mathcal{T}$  is closed under finite intersections and arbitrary unions

**Definition** (Open neighbourhood). If  $x \in X$ , U open in X, and  $x \in U$ , then U is an *open neighbourhood* of x.

**Definition** (Hausdorff spaces). A topological space  $(X, \mathcal{T})$  is *Hausdorff* if  $\forall x, y \in X$ , there exists U, V open neighbourhoods of x, y respectively such that  $U \cap V = \emptyset$ .

**Definition** (Homeomorphisms). A map  $f: X \to Y$  is a homeomorphism if

- 1. f is bijective
- 2. f is continuous
- 3.  $f^{-1}$  is continuous

**Definition** (Continuous maps). A map  $f: X \to Y$  is continuous if  $\forall U \text{ (open)} \subset Y, f^{-1}(U)$  is open in X.

**Definition.** If  $\mathcal{T}$  and  $\mathcal{T}'$  are topologies on X such that  $\mathcal{T} \subsetneq \mathcal{T}'$  then  $\mathcal{T}'$  is *finer* than  $\mathcal{T}$ , and  $\mathcal{T}$  is *coarser* than  $\mathcal{T}'$ .

**Proposition.** id:  $(X, \mathcal{T}) \to (X, \mathcal{T}')$  is continuous if and only if  $\mathcal{T}$  is finer than  $\mathcal{T}'$ .

**Definition** (Subspace topology). If X is a topological space,  $Y \subset X$ , the subspace topology on Y is defined by

$$U$$
 open in  $Y \iff \exists V$  open in  $X$  such that  $U = Y \cap V$ 

**Definition.** If a map  $f: X \to Y$  is continuous, the *image* of f is the set

$$f(X) = \{ f(x) \mid x \in X \} \subset Y$$

with the subspace topology.

**Definition** (Product topology). Let X, Y be spaces. The *product* topology on  $X \times Y$  is the smallest (coarsest) topology making the projections

$$p_X: X \times Y \to X, \ p_Y: X \times Y \to Y$$

continuous.

**Proposition.** Product of Hausdorff spaces is Hausdorff.

#### 1.2 Connectedness

**Definition** (Connectedness). A space X is disconnected if there exists a surjective continuous map  $f: X \to \{p_1, p_2\}$ . A space is connected if every continuous function  $f: X \to \{p_1, p_2\}$  is constant.

**Definition.** A pair of sets  $U, V \subset X$  is said to disconnect X if they are non-empty, disjoint,  $U \cup V = X$  and both are open.

**Definition.** X is disconnected if there exists U, V which disconnect X.

**Definition** (Path). A path in X is a continuous map  $\gamma : [0,1] \to X$ .  $\gamma$  is a path from  $\gamma(0)$  to  $\gamma(1)$ .  $a,b \in X$  are said to be connected by a path if there is a path from a to b.

**Definition** (Path-connectedness). A space X is path-connected if for all x, y, there exists

$$\gamma: [0,1] \to X$$
 such that  $\gamma(0) = x, \, \gamma(1) = y$ 

or equivalently,

**Definition.** We say X is path-connected if there exists a unique equivalence class, where the equivalence relation  $\sim$  is defined  $a \sim b$  if and only if there exists a path from a to b.

**Proposition.** Suppose X is connected. Then, if  $f: X \to Y$ , then  $f(X) \subset Y$  is connected.

**Proposition.** [0,1] is connected.

Corollary. If X is path-connected, then X is connected.

**Definition.**  $X \subset \mathbb{R}$  is an *interval* if  $a \leq b \leq c$ ,  $a, c \in X \implies b \in X$ .

**Proposition.** A subset of  $\mathbb{R}$  is connected if and only if it is an interval.

**Definition** (Locally (path) connected). A space X is locally (path) connected at a point p if for every open neighbourhood U of p, there exists a (path) connected open neighbourhood V of p such that  $p \in V \subset U$ .

**Proposition.** If X is locally path-connected then the path components of X are open.

**Proposition.** If X is connected and locally path-connected, then X is path connected.

#### 1.3 Compactness

**Definition** (Open cover). An *open cover* of a space X is a collection of open sets  $\mathcal{U}$  such that

$$X = \bigcup_{U \in \mathcal{U}} U$$

**Definition.** A space X is *compact* if every open cover has a finite subcover.

**Lemma.** Closed subsets of compact spaces are compact.

**Theorem.** If X, Y are compact, then  $X \times Y$  is compact.

**Theorem** (Heine-Borel theorem).  $X \subset \mathbb{R}^n$  is compact if and only if X is closed and bounded.

**Theorem.** [0,1] is compact.

**Theorem.** If  $f: X \to Y$  is continuous, X compact, then  $f(X) \subset Y$  is compact with respect to the subspace topology.

**Proposition.** If  $C \subset Y$  is compact, Y Hausdorff, then C is closed.

**Proposition.** If  $f: X \to Y$  is a continuous bijection, X compact, Y Hausdorff, then f is a homeomorphism

#### 1.4 Quotient spaces

**Definition** (Quotient map). Let  $q: X \to Y$  be a continuous surjection. Then q is a quotient map if  $q^{-1}(Y)$  is open if and only if U is open. (A bijective quotient map is a homeomorphism)

**Definition** (Quotient space). Let X be a space, and  $\sim$  an equivalence relation on X, and  $q: X \to X/\sim = Y$  the quotient map. The quotient topology on Y is defined by U open in Y if and only if  $q^{-1}(U)$  is open in X.

Lemma.

Let f be continuous, and suppose f factors through  $q:X\to Y$ , a quotient map, i.e.,  $\exists h:Y\to Z$  such that  $h\circ q=f$ . Then h is continuous.

**Proposition.** Let  $f:X\to Y$  be a continuous surjection with X compact, Y Hausdorff. Then f is a quotient map.

**Definition** (Disjoint union). Let  $X_1, X_2$  be topological spaces. The disjoint union of  $X_1$  and  $X_2, X_1 \sqcup X_2$ , is the space with the underlying set  $X_1 \sqcup X_2$ , with U open in  $X_1 \sqcup X_2$  if and only if  $U \cap X_1$  is open in  $X_1$ , and  $U \cap X_2$  is open in  $X_2$ .

**Definition** (Cell complex). A *cell complex* is a space built up inductively, as follows

- 1. (n=0) We start with a discrete set  $X^{(0)}$  consisting of points, which we call 0-cells  $\{e_i^0 \mid i \in I_0\}, e_i^0 \cong pt.$   $X^{(0)} = \coprod_i e_i^0$  is called the 0-skeleton.
- 2. (n > 0) We add a (possibly empty) subset of *n*-cells  $\{e_i^n \mid i \in I_n\}$   $e_i^n \cong D^n$ , the *n*-dimensional disk, and a continuous map

$$\phi_i^n : \partial e_i^n \cong S^{n-1} \to X^{(n-1)}$$

and here the n-skeleton is

$$X^{(n)} = X^{(n-1)} \sqcup \bigsqcup e_i^n / \sim$$

A space X is a cell complex if there exists  $X^{(0)} \subset X^{(1)} \subset \dots$  as above, with the condition that U is open in X if and only if  $X^{(n)} \cap U$  is open for all n.

 $X^{(0)} \subseteq X^{(1)} \subseteq \dots$  is called the *cell decomposition* of X.

**Definition.** The suspension SX of a space X is the space

$$SX = X \times I/\sim$$

where  $(x,t) \sim (x',t')$  if and only if (x,t) = (x',t') or t=t'=1 or t=t'=0.

**Proposition.**  $SS^n$  is homeomorphic to  $S^{n+1}$ .  $SD^n$  is homeomorphic to  $D^{n+1}$ .

**Definition** (Presentation complex). Given a group G and its presentation, the presentation complex of G with respect to the given presentation is the 2-dimension cell complex with 1 vertex, obtained by attaching a loop (1-cell) at the vertex for each generator of G, and attaching a 2-cell along every relation in the presentation, where the boundary of the 2-cell is attached according to the appropriate word.

**Definition** (Cayley graph). Given a group G and its presentation, and S a (possibly generating) set of G, then the Cayley graph  $C(G, S) = (G \sqcup G \times I \times S)/\sim$  where the equivalence relation  $\sim$  is given by  $g \sim (g, 0, s), gs \sim (g, 1, s)$ .

## 2 Homotopy

#### 2.1 Homotopy

**Definition.** Let (X, A) be a pair of spaces, where  $A \subseteq X$ ,  $f_0, f_1 : X \to Y$ . We say  $f_0$  and  $f_1$  are homotopic relative to A if there exists a continuous function F where  $F : X \times I \to Y$  such that  $F(-,0) = f_0, F(-,1) = f_1$  and  $F(a,t) = f_0(a) = f_1(a)$  for all t. In this case we write  $f_0 \simeq_A f_1$ .

If  $A = \emptyset$  then we say  $f_0$  and  $f_1$  are homotopic and write  $f_0 \simeq f_1$ .

**Lemma** (\*). A function defined on the union of two closed sets is continuous if it is continuous when restricted to each of the closed sets separately.

**Proposition.** Any two continuous maps  $f_0, f_1 : X \to \mathbb{R}^n$  are homotopic via the homotopy

$$F(x,t) = tf_1(x) + (1-t)f_0(x)$$

**Definition** (Homotopy equivalence). Two spaces X and Y are homotopy equivalent if there exists  $f: X \to Y$ ,  $g: Y \to X$  such that  $f \circ g \simeq \mathrm{id}_Y$ ,  $g \circ f \simeq \mathrm{id}_X$ . In this case, we write  $X \simeq Y$ .

**Proposition.** Homotopy equivalence is an equivalence relation on (topological) spaces.

**Proposition.**  $\mathbb{R}^n \simeq pt$ 

**Definition.** A space X is *contractible* if  $X \simeq pt$ , or in other words, id:  $X \to X$  is homotopic to a constant map. In this case the map id<sub>X</sub> is said to be *null-homotopic*.

**Proposition.**  $\mathbb{R}^n \setminus pt \simeq S^{n-1}$ 

**Proposition.** If  $f: X \to S^2$  is a non-surjective map then f is homotopic to a constant map.

**Definition.** The cone CX on a space X is the space

$$CX = X \times I/\sim$$

where  $(x,t) \sim (x',t')$  if and only if (x,t) = (x',t') or t=t'=1.

**Proposition.** CX is always contractible.

**Proposition.** If X is contractible then X is path-connected.

**Definition** (Retract). Let  $A \subseteq X$  be a subspace. A is a retract of X if there exists a continuous map  $r: X \to A$  (retraction) such that  $r|_A = \mathrm{id}_A$ . A is a deformation retract of X if there exists such a function r such that r is homotopic to  $\mathrm{id}_X$  relative to A.

**Proposition.** If A is a deformation retract of X then  $X \simeq A$ .

#### 2.2 Paths and path-homotopy

**Definition** (Path-homotopy). Two paths  $\gamma_0$  and  $\gamma_1$  are path-homotopic if they are homotopic relative to  $\{0,1\} \subseteq I$ . In particular  $\gamma_0(0) = \gamma_1(0)$ ,  $\gamma_0(1) = \gamma_1(1)$ . If F is a homotopy from  $\gamma_0$  to  $\gamma_1$ ,

$$F(-,0) = \gamma_0(0), F(-,1) = \gamma_1(1)$$

F is a family of paths connecting  $\gamma_0(0)$  and  $\gamma_0(1)$ 

**Proposition.** Path-homotopy is an equivalence relation on the set of paths in (a topological space) X.

**Definition** (Based loop). A based loop at  $x_0 \in X$  is a path  $\gamma : I \to X$  such that  $\gamma(0) = \gamma(1) = x_0$ .

**Definition** (Fundamental group of a space). The fundamental group of X at  $x_0$  is the set (group)

$$\{ [\gamma] \mid \gamma \text{ is a loop based at } x_0 \}$$

which is denoted by  $\pi_1(X, x_0)$ .

**Definition** ( $n^{\text{th}}$  homotopy group). The  $n^{\text{th}}$  homotopy group of a space X at  $x_0$  is the set (group)

$$\pi_n(X, x_0) = \{ [f : I^n \to X \mid f(\partial I^n) \to x_0] \}$$

**Definition.** A loop based at  $x_0$  is null-homotopic if it is path-homotopic to a constant path.

**Definition** (Free homotopy). If  $\gamma_0$  and  $\gamma_1$  are based loops (not necessarily at the same point), then  $\gamma_0$  and  $\gamma_1$  are freely homotopic if they are homotopic through based loops, so if F is a free homotopy between  $\gamma_0$  and  $\gamma_1$ , then,

$$F(x_0) = \gamma_0, F(x, 1) = \gamma_1$$
  
 $F(0, t) = F(1, t)$  for all  $t$ 

**Proposition.** Free homotopy is an equivalence relation on the set of based loops in (a topological space) X.

**Definition.** A based loop bounds a disk if the induced map

$$\bar{\gamma}: [0,1]/_{0=1} \cong S^1 \subseteq D^2$$

extends to a continuous function  $D^2 \to X$ .

Lemma. The following are equivalent

- 1.  $\gamma$  bounds a disk.
- 2.  $\gamma$  is null-homotopic.
- 3.  $\gamma$  is freely homotopic to a constant path.

## 3 Covering spaces

**Definition** (Covering map). A map  $p: X' \to X$  is a covering map if  $\forall x \in X$ , there exists U, an open neighbourhood of x, and a discrete set  $\Delta$  and a homeomorphism  $h_U: U \times \Delta \to p^{-1}(U)$  such that

$$p \circ h_u = \pi_U : U \times \Delta \to U$$

and such a neighbourhood U is called a covering neighbourhood.

**Definition** (Lift). Let  $f: Y \to X$  and  $g: Z \to X$  be two maps,

$$\begin{array}{c}
Z \\
\downarrow g \\
Y \xrightarrow{\tilde{f}} X
\end{array}$$

a lift of f is a map  $\tilde{f}: Y \to Z$  such that

$$g \circ \tilde{f} = f$$

#### 3.1 Path/Homotopy lifting lemma

**Lemma** (Path/Homotopy lifting lemma). Let  $p: X' \to X$  be a covering map and  $f: I^n \to X$  a continuous map. Then for any  $x' \in p^{-1}(f(U))$ , there exists a unique lift  $\tilde{f}$  of f to X', where  $\tilde{f}(0) = x'$ .

**Definition.** A covering space  $p: X' \to X$  is *trivial* if X is a covering neighbourhood.

**Lemma.** Suppose  $p: X' \to X$  is a trivial covering map, and  $f: Y \to X$  is continuous, Y connected, the for any  $y_0 \in Y$  and  $x' \in p^{-1}(f(y_0))$ , there exists a unique lift  $\tilde{f}: Y \to X'$  such that  $\tilde{f}(y_0) = x'$ .

**Lemma.** Let X be a compact metric space. Then a continuous function  $f: X \to \mathbb{R}$  attains a maximum and minimum value on X.

**Lemma** (Lebesgue's number lemma). Let X be a compact metric space,  $\mathcal{U}$  an open cover of X, then there exists  $\epsilon > 0$  such that for all  $x \in X$ , there exists  $U \in \mathcal{U}$  such that  $B_{\epsilon}(x) \subseteq U$ . Such an  $\epsilon$  is called the Lebesgue number for  $\mathcal{U}$ .

**Lemma** ((+)). Let  $p: X' \to X$  be a covering space, and  $f: Y \to X$  a continuous map, Y connected. Then two lifts  $\tilde{f}_1, \tilde{f}_2: Y \to X'$  are equal for all  $y \in Y$  if and only if they are equal for some  $y \in Y$ .

**Corollary.** If  $[\gamma] \in \pi_1(X, x_0)$  and there exists a covering space X' of X so that  $\gamma$  lifts to a non-closed path then  $[\gamma] \neq 1 \in \pi_1(X, x_0)$ .

Corollary.

$$\pi_1(S^1) \neq 1$$

**Corollary.**  $\mathrm{id}_{S^1}:S^1\to S^1$  is *not* null-homotopic. In particular  $S^1$  is not contractible.

#### 3.2 Winding numbers

**Definition.** Let  $\gamma$  be a closed path in  $S^1$ . The winding number of  $\gamma$ ,  $\omega(\gamma)$  is the integer  $\gamma(1) - \gamma(0)$  where  $\tilde{\gamma}$  is any lift of  $\gamma$  to  $\mathbb{R}$ .

**Proposition.**  $\omega(\gamma)$  is well-defined, and only depends on the free homotopy classes of  $\gamma$ .

**Proposition.** If  $\gamma \simeq \gamma'$  (freely homotopic) then  $\omega(\gamma) = \omega(\gamma')$ .

#### 3.3 Covering transformations

**Definition** (Covering transformation). Let  $p: X' \to X$  be a covering map. A covering transformation is a homeomorphism  $h: X' \to X'$  such that  $p \circ h = p$ 

**Theorem.** If X' is the universal cover of space X, then

$$\pi_1(X, x_0) = \{h : X' \to X' \mid p \circ h = p\}$$

## 4 More on fundamental groups and covering spaces

**Definition.** Let  $\alpha, \beta$  be paths in a space X. We say  $\alpha, \beta$  are *composable* if

$$\alpha(1) = \beta(0)$$
 (note that the order matters)

If  $\alpha, \beta$  are composable, their product  $\alpha \cdot \beta$  is the path

$$\alpha \cdot \beta = \begin{cases} \alpha(2t) & 0 \le t \le \frac{1}{2} \\ \beta(2t-1) & \frac{1}{2} \le 1 \end{cases}$$

i.e., we traverse through  $\alpha, \beta$  with twice the speed. Note that in some sources they may write  $\beta \cdot \alpha$  instead of  $\alpha \cdot \beta$  to mean the same thing.

**Definition.** If  $\alpha$  is a path (not necessarily closed), then  $\bar{\alpha}$  is the path defined by  $\bar{\alpha} = \alpha(1-t)$ , i.e., traversing through  $\alpha$  in the backwards direction.

**Theorem.** Let X be a path-connected space,  $x_0$  a basepoint. The set

$$\pi(X, x_0) = \{\text{loops based at } x_0\}/\text{path homotopy}$$

with multiplication given by  $[\alpha] \cdot [\beta] = [\alpha \cdot \beta]$ , for any  $[\alpha], [\beta] \in \pi(X, x_0)$ , and inverses given by  $[\alpha]^{-1} = [\bar{\alpha}]$ , and the identity given by  $1 = [x_0]$ , defines a group, called the *fundamental group* (of X).

We note that it makes sense to talk about *the* fundamental group, if we restrict the spaces in question to path-connected spaces, so we shall restrict our attention to path-connected spaces from now on.

**Theorem.** Let  $\alpha$  be a path from  $x_0$  to  $x_1$ . The map

$$[\alpha]_* : \pi_1(X, x_0) \to \pi_1(X, x_1)$$

defined by

$$[\gamma] \mapsto [\bar{\alpha} \cdot \gamma \cdot \alpha]$$

is an isomorphism.

**Theorem.** Let  $(X, x_0)$ ,  $(Y, y_0)$  be two (pointed) path-connected spaces, and  $f: (X, x_0) \to (Y, y_0)$  be continuous and such that  $f(x_0) = y_0$ . Then this map induces the map

$$f_*: \pi_1(X, x_0) \to \pi_1(Y, y_0)$$

defined by  $f_*([\gamma]) = [f \circ \gamma].$ 

**Theorem.** With conditions as the previous theorem, along with another path-connected space  $(Z, z_0)$  and another continuous  $g: (Y, y_0) \to (Z, z_0)$ , we have

$$(g \circ f)_* = g_* \circ f_*$$

In other words, the previous two theorems show that  $\pi$  is a functor taking the category of topological spaces to the category of groups.

**Theorem.** Let  $f_t: X \times I \to Y$  be a homotopy of  $f_0$  and  $f_1$ , and let  $\alpha$  be the path  $f_t(x_0)$  from  $f_0(x_0) = y_0$  to  $f_1(x_0) = y_1$ . Then,

$$[\alpha]_* \circ (f_0)_* = (f_1)_*$$

Corollary. Let X, Y be path-connected and homotopy equivalent. Then,

$$\pi_1(X) \cong \pi_1(Y)$$

**Theorem** (Brouwer's no retraction theorem). There does not exist  $r: D^2 \to S^1$  such that  $r|_{S^1} = \mathrm{id}_{S^1}$ .

**Theorem** (Brouwer's fixed point theorem). Let  $f: D^2 \to D^2$  be continuous. Then f has a fixed point, i.e.,

$$\exists x \in D^2 \text{ such that } f(x) = x$$

#### 4.1 Classification of covering spaces

**Definition.** Let  $Y_0, Y_1$  be two covers of a space X. We say that  $Y_0$  and  $Y_1$  are equivalent if there exists a homeomorphism  $h: Y_0 \to Y_1$  such that

$$p_1 \circ h = p_0$$

(and  $h(y_0) = y_1$  if  $Y_0, Y_1$  have base points).

If  $Y_0 = Y_1$ , an equivalence  $h: Y_0 \to Y_0$  is a covering transformation. It also follows that

$$Aut(Y) = \{h : Y \to Y \mid p \circ h = p\}$$

**Lemma.** Let  $p:(Y,y_0)\to (X,x_0)$  be a cover. Then

$$p_*: \pi_1(Y, y_0) \to \pi_1(X, x_0)$$

is injective.

This way we get a map from the pointed covering spaces of  $(X, x_0)$  (quotient according to equivalences) to the subgroups of  $\pi_1(X, x_0)$ , where X is path-connected and locally contractible.

**Proposition.** 
$$p_*(\pi_1(Y, y_0)) < \pi_1(X, x_0)$$

**Theorem** (Classification of covering spaces). Let X be path-connected and locally contractible.

1. The map from the set of connected covering spaces under the quotient of equivalence,

$$\{(Y, y_0)\}/\text{equiv} \to \{\text{subgroups of } \pi_1(X, x_0)\}\}$$

defined by

$$(Y, y_0) \mapsto p_*(\pi(Y, y_0))$$

is bijective.

- 2. Given (1),  $H < \pi_1(X, x_0)$  let  $(X_H, x_H)$  be the cover of  $\pi_1(X, x_0)$  corresponding to H.  $H < K \iff \exists (X_H, x_H) \xrightarrow{h} (X_K, x_K)$ 
  - i. h is a cover

ii. 
$$[H:K] = \#h^{-1}(X_K)$$

3.

$$Aut(X_H) = \{h : X_H \to X_H | h \text{ a covering transformation}\}\$$

Then

$$X_H \cong N(H)/H$$

In particular if  $H = 1 < \pi_1(X, x_0)$ , then

$$Aut(X_H) \cong \pi_1(X, x_0)$$

in which case  $X_H$  is the universal cover.