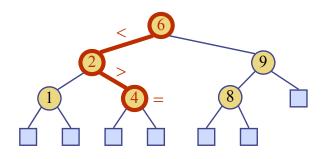
Lecture 8-1: Binary Search Trees





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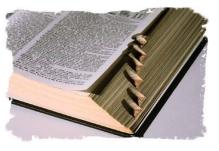
Keywords



Queue



Priority Queue



MAP and Dictionary

Think about the purpose of each data structure!

Ordered Maps

- Keys are assumed to come from a total order.
- New operations:
 - firstEntry(): entry with smallest key value null
 - lastEntry(): entry with largest key value
 - floorEntry(k):entry with largest key \leq k
 - ceilingEntry(k): entry with smallest key \geq k
 - These operations return null if the map is empty



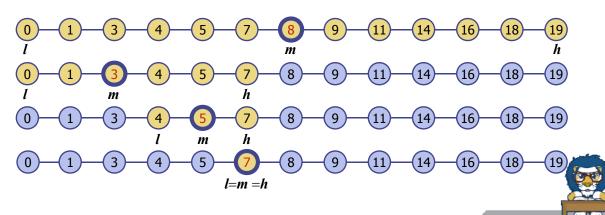


3

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Binary Search

- Binary search can perform operations get, floorEntry and ceilingEntry on an ordered map implemented by means of an array-based sequence, sorted by key
 - similar to the high-low game
 - at each step, the number of candidate items is halved
 - terminates after O(log n) steps
- Example: find(7)



Search Tables (skip)

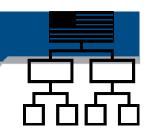
- A search table is an ordered map implemented by means of a sorted sequence
 - We store the items in an array-based sequence, sorted by key
 - We use an external comparator for the keys
- Performance:
 - get, floorEntry and ceilingEntry take $O(\log n)$ time, using binary search
 - put takes O(n) time since in the worst case we have to shift n/2 items to make room for the new item
 - remove take O(n) time since in the worst case we have to shift n/2 items to compact the items after the removal
- The lookup (search) table is effective only for dictionaries of small size or for dictionaries on which searches are the most common operations, while insertions and removals are rarely performed (e.g., credit card authorizations)



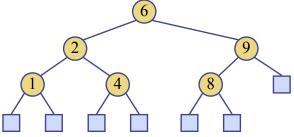
5

Binary Search Trees (ADT)

- A binary search tree is a binary tree storing keys (or key-value entries) at its internal nodes and satisfying the following property:
 - Let u, v, and w be three nodes such that u is in the left subtree of v and w is in the right subtree of v. We have key(u) ≤ key(v) ≤ key(w)
- External nodes do not store items



An inorder traversal of a binary search trees visits the keys in increasing order



프로그램 구현상의 편의를 위해서 의미없는 외부노드를 추가(혹은 범위를 위해서)



Binary Search Trees (ADT)

- Fundamental Methods
 - get (k)
 - \triangleright return the value ν for the entry, (k, ν) , with key equal to k, if it exists
 - put (k, ν)
 - \triangleright enter the entry (k, ν) as the mapping of k to ν
 - remove (*k*)
 - \triangleright remove the entry with key equal to k, and return it's value



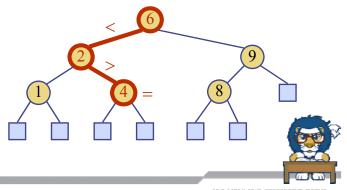
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7

Search

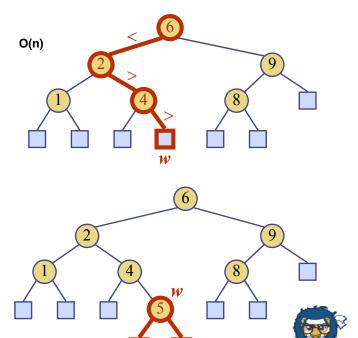
- To search for a key k, we trace a downward path starting at the root
- The next node visited depends on the comparison of k with the key of the current node
- If we reach a leaf, the key is not found
- Example: get(4):
 - Call TreeSearch(4,root)
- The algorithms for floorEntry and ceilingEntry are similar

```
Algorithm TreeSearch(k, v)
if T.isExternal(v)
return v
if k < key(v)
return TreeSearch(k, T.left(v))
else if k = key(v)
return v
else \{k > key(v)\}
return TreeSearch(k, T.right(v))
```



Insertion

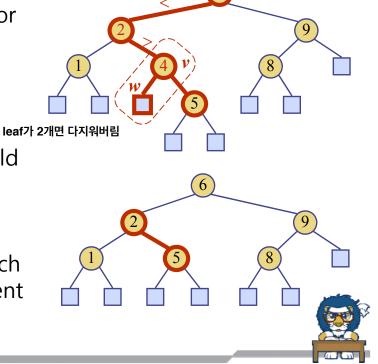
- To perform operation put(k, o), we search for key k (using TreeSearch)
- Assume k is not already in the tree, and let w be the leaf reached by the search
- We insert k at node w and expand w into an internal node
- Example: insert 5



9

Deletion

- To perform operation remove(k), we search for key k
- Assume key k is in the tree, and let v be the node storing k
- If node v has a leaf child w, we remove v and w from the tree with operation removeExternal(w), which removes w and its parent
- Example: remove 4



10

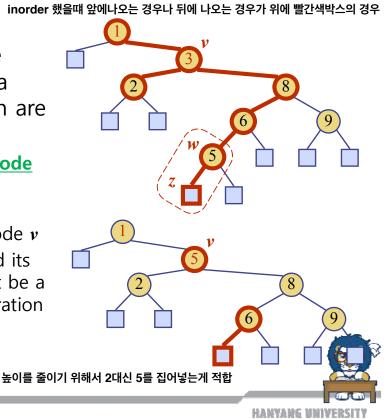
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Deletion (cont.)

- swap with the rightmost node of its left subtree or
- swap with the leftmost node of its right subtree

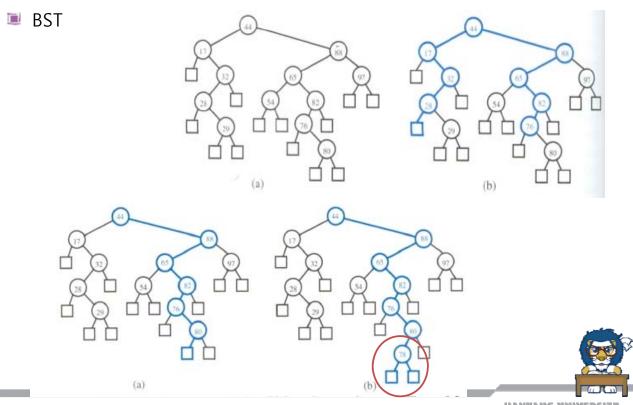
We consider the case where the key k to be removed is stored at a node v whose children are both internal

- we <u>find the internal node</u>
 <u>w that follows v in an</u>
 inorder traversal
- we copy key(w) into node v
- we remove node w and its left child z (which must be a leaf) by means of operation removeExternal(z)
- Example: remove 3



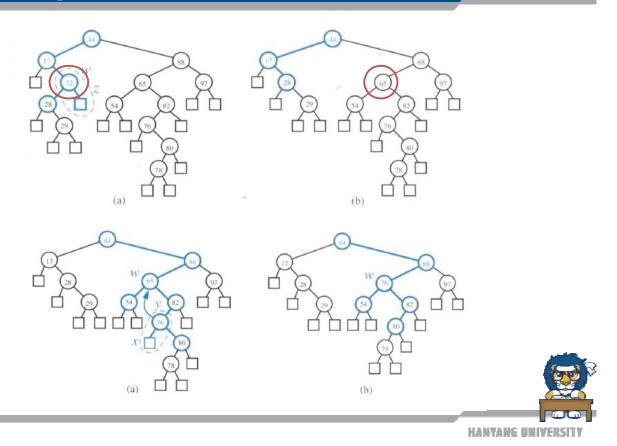
11

Example (insertion)



12

Example (deletion)



Performance

13

- Consider an ordered map with n items implemented by means of a binary search tree of height h
 - the space used is O(n)
 - methods get, floorEntry,
 ceilingEntry, put and remove
 take O(h) time
- The height h is O(n) in the worst case and $O(\log n)$ in the best case

