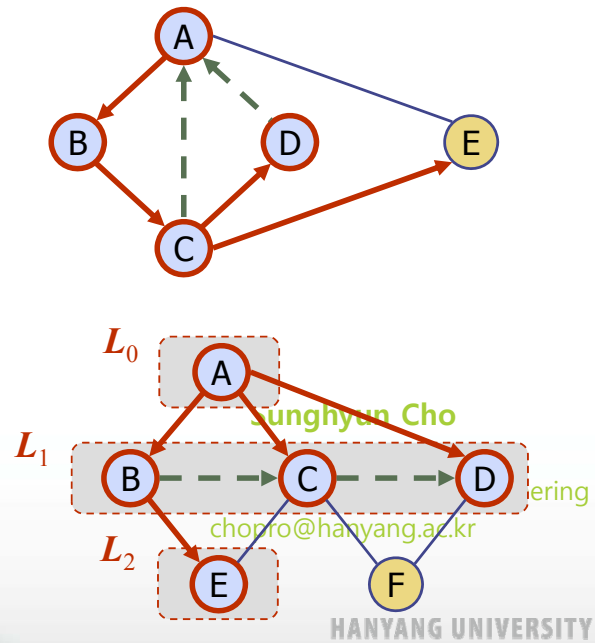


Lecture 10-2: Graph Traversals



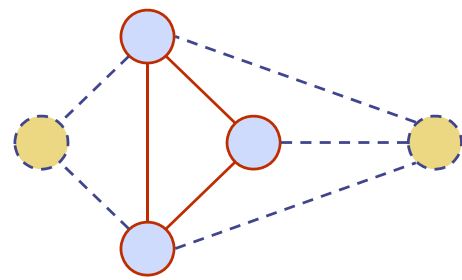
Keywords

- Depth-First Search
- Breadth-First Search

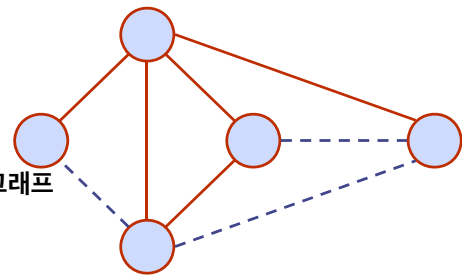
Subgraphs

- A subgraph S of a graph G is a graph such that
 - The vertices of S are a subset of the vertices of G
 - The edges of S are a subset of the edges of G
- A spanning subgraph of G is a subgraph that contains all the vertices of G

그래프가 가지고 있는 모든 vertex를 가지고 있는 그래프
엣지(edge)는 빠져도 됨



Subgraph



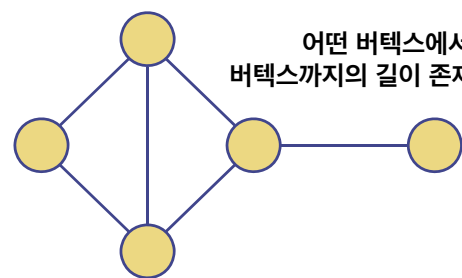
Spanning subgraph



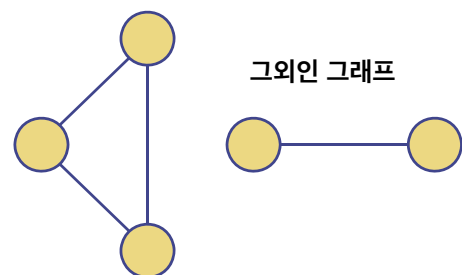
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Connectivity

- A graph is connected if there is a path between every pair of vertices
- A connected component of a graph G is a maximal connected subgraph of G



Connected graph



Non connected graph with two connected components
cc: 가장 연결관계가 많은 것들을 모은 것



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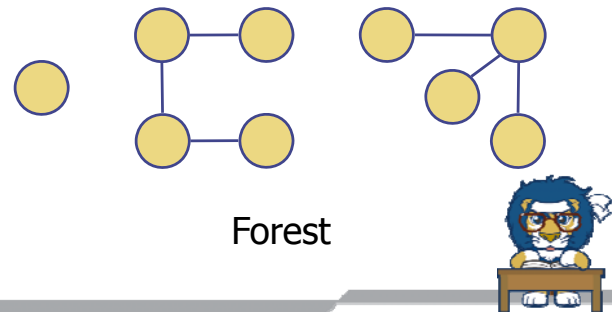
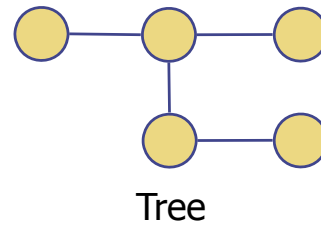
Trees and Forests

- **A (free) tree** is an undirected graph T such that

- T is connected
- T has no cycles

This definition of tree is different from the one of a rooted tree

- A forest is an undirected graph without cycles
- The connected components of a forest are trees



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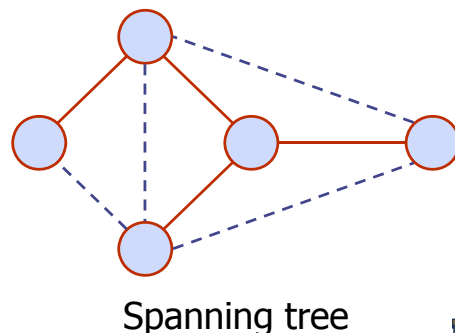
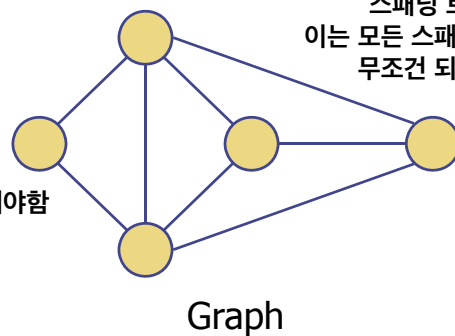
Spanning Trees and Forests

- **A spanning tree of a connected graph is a spanning subgraph that is a tree**

- A spanning tree is not unique unless the graph is a tree
- Spanning trees have applications to the design of communication networks
- A spanning forest of a graph is a spanning subgraph that is a forest

스패닝이면서 트리속성을 만족해야함

이것은 사이클이 존재하므로 스패닝 트리가 아니고 이는 모든 스패닝이 스패닝 트리가 무조건 되는것이 아니다



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Depth-First Search

- Depth-first search (DFS) is a general technique for traversing a graph
- A DFS traversal of a graph G
 - Visits all the vertices and edges of G
 - Determines whether G is connected
 - Computes the connected components of G
 - Computes a spanning forest of G
- DFS on a graph with n vertices and m edges takes $O(n + m)$ time
- DFS can be further extended to solve other graph problems
 - Find and report a path between two given vertices
 - Find a cycle in the graph
- Depth-first search is to graphs what Euler tour is to binary trees



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DFS Algorithm

- The algorithm uses a mechanism for setting and getting "labels" of vertices and edges

Algorithm **DFS**(G)

Input graph G

Output labeling of the edges of G as discovery edges and back edges

```
for all  $u \in G.vertices()$ 
     $setLabel(u, UNEXPLORED)$ 
for all  $e \in G.edges()$ 
     $setLabel(e, UNEXPLORED)$ 
for all  $v \in G.vertices()$ 
    if  $getLabel(v) = UNEXPLORED$ 
         $DFS(G, v)$ 
```

둘다 공부하기

Algorithm **DFS**(G, v)

Input graph G and a start vertex v of G

Output labeling of the edges of G in the connected component of v as discovery edges and back edges

$setLabel(v, VISITED)$

for all $e \in G.incidentEdges(v)$

if $getLabel(e) = UNEXPLORED$

$w \leftarrow opposite(v, e)$

if $getLabel(w) = UNEXPLORED$

$setLabel(e, DISCOVERY)$

$DFS(G, w)$

else

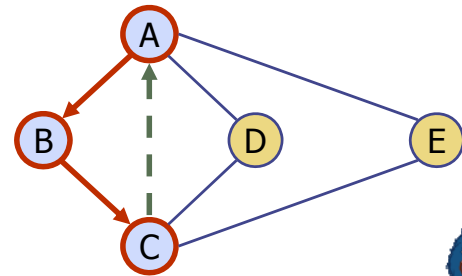
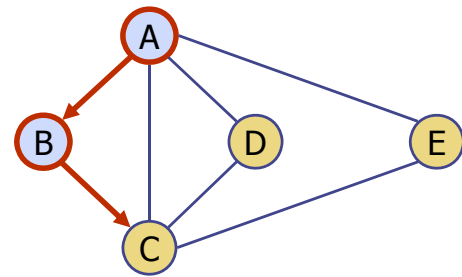
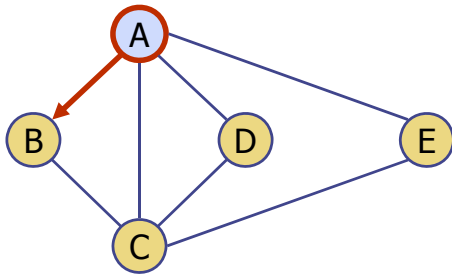
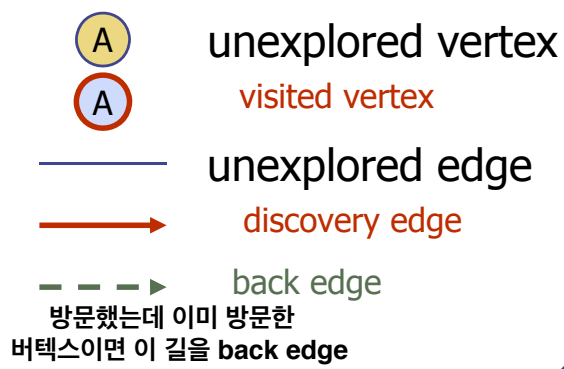
$setLabel(e, BACK)$



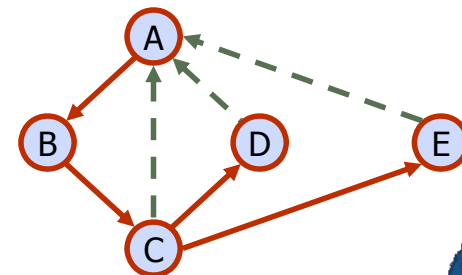
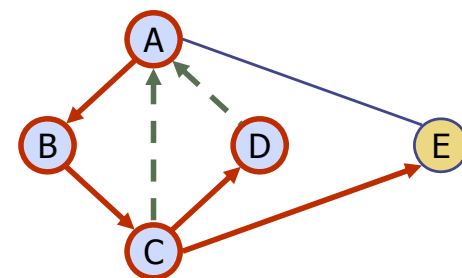
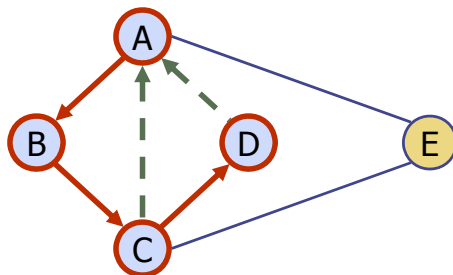
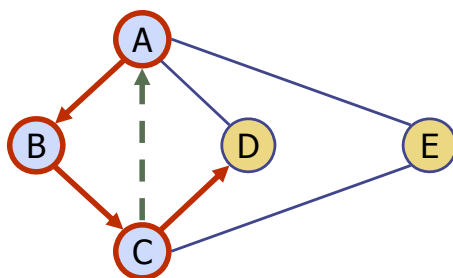
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Example

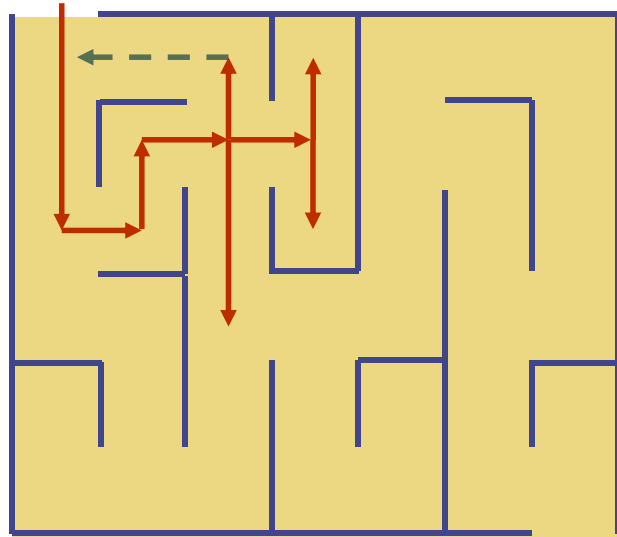


Example (cont.)



DFS and Maze Traversal

- The DFS algorithm is similar to a classic strategy for exploring a maze
 - We mark each intersection, corner and dead end (vertex) visited
 - We mark each corridor (edge) traversed
 - We keep track of the path back to the entrance (start vertex) by means of a rope (recursion stack)



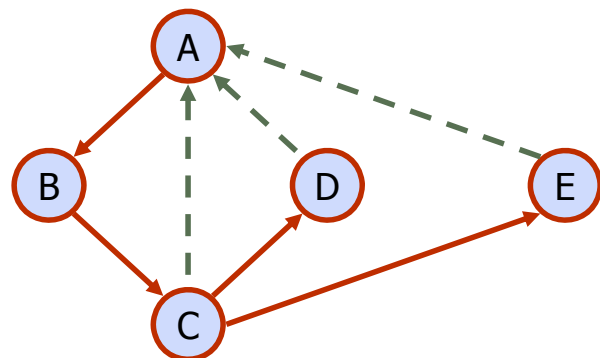
Properties of DFS

Property 1

$DFS(G, v)$ visits all the vertices and edges in the connected component of v

Property 2

The discovery edges labeled by $DFS(G, v)$ form a **spanning tree of the connected component of v**



Analysis of DFS

- Setting/getting a vertex/edge label takes $O(1)$ time
- Each vertex is labeled twice
 - once as UNEXPLORED
 - once as VISITED
- Each edge is labeled twice
 - once as UNEXPLORED
 - once as DISCOVERY or BACK
- Method incidentEdges is called once for each vertex
- DFS runs in $O(n + m)$ time provided the graph is represented by the adjacency list structure
 - Recall that $\sum_v \deg(v) = 2m$



Path Finding



둘중에 하나 기말고사에 나옴

- We can specialize the DFS algorithm to find a path between two given vertices u and z using the template method pattern
- We call $DFS(G, u)$ with u as the start vertex
- We use a stack S to keep track of the path between the start vertex and the current vertex
- As soon as destination vertex z is encountered, we return the path as the contents of the stack

```
Algorithm pathDFS( $G, v, z$ )
  setLabel( $v, VISITED$ )
  S.push( $v$ )
  if  $v = z$ 
    return S.elements()
  for all  $e \in G.incidentEdges(v)$ 
    if getLabel( $e$ ) = UNEXPLORED
       $w \leftarrow opposite(v, e)$ 
      if getLabel( $w$ ) = UNEXPLORED
        setLabel( $e, DISCOVERY$ )
        S.push( $e$ )
        pathDFS( $G, w, z$ )
        S.pop( $e$ )
      else
        setLabel( $e, BACK$ )
  S.pop( $v$ )
```





둘중에 하나 기말고사에 나옴

- We can specialize the DFS algorithm to find a simple cycle using the template method pattern
- We use a stack S to keep track of the path between the start vertex and the current vertex
- As soon as a back edge (v, w) is encountered, we return the cycle as the portion of the stack from the top to vertex w

```
Algorithm cycleDFS( $G, v, z$ )
  setLabel( $v, VISITED$ )
   $S.push(v)$ 
  for all  $e \in G.incidentEdges(v)$ 
    if getLabel( $e$ ) = UNEXPLORED
       $w \leftarrow opposite(v, e)$ 
       $S.push(e)$ 
      if getLabel( $w$ ) = UNEXPLORED
        setLabel( $e, DISCOVERY$ )
        pathDFS( $G, w, z$ )
         $S.pop(e)$ 
      else
         $T \leftarrow$  new empty stack
        repeat
           $o \leftarrow S.pop()$ 
           $T.push(o)$ 
        until  $o = w$ 
        return  $T.elements()$ 
   $S.pop(v)$ 
```



Keywords

- Breadth-First Search

Breadth-First Search

- Breadth-first search (BFS) is a general technique for traversing a graph
- A BFS traversal of a graph G
 - Visits all the vertices and edges of G
 - Determines whether G is connected
 - Computes the connected components of G
 - Computes a spanning forest of G
- BFS on a graph with n vertices and m edges takes $O(n + m)$ time
- BFS can be further extended to solve other graph problems
 - Find and report a path with the minimum number of edges between two given vertices
 - Find a simple cycle, if there is one



BFS Algorithm

- The algorithm uses a mechanism for setting and getting "labels" of vertices and edges

Algorithm **BFS**(G)

Input graph G

Output labeling of the edges and partition of the vertices of G

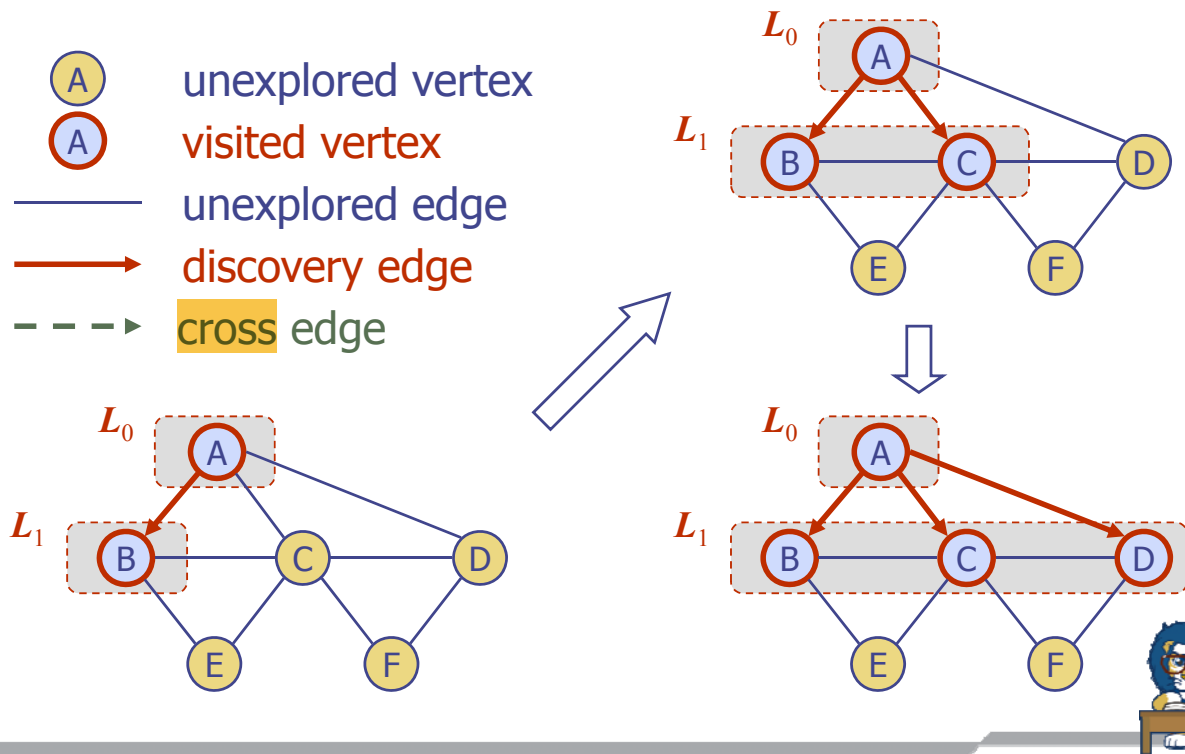
```
for all  $u \in G.vertices()$ 
     $setLabel(u, UNEXPLORED)$ 
for all  $e \in G.edges()$ 
     $setLabel(e, UNEXPLORED)$ 
for all  $v \in G.vertices()$ 
    if  $getLabel(v) = UNEXPLORED$ 
         $BFS(G, v)$ 
```

Algorithm **BFS**(G, s)

```
 $L_0 \leftarrow$  new empty sequence
 $L_0.addLast(s)$ 
 $setLabel(s, VISITED)$ 
 $i \leftarrow 0$ 
while  $\neg L_i.isEmpty()$ 
     $L_{i+1} \leftarrow$  new empty sequence
    for all  $v \in L_i.elements()$ 
        for all  $e \in G.incidentEdges(v)$ 
            if  $getLabel(e) = UNEXPLORED$ 
                 $w \leftarrow opposite(v, e)$ 
                if  $getLabel(w) = UNEXPLORED$ 
                     $setLabel(e, DISCOVERY)$ 
                     $setLabel(w, VISITED)$ 
                     $L_{i+1}.addLast(w)$ 
            else
                 $setLabel(e, CROSS)$ 
     $i \leftarrow i + 1$ 
```



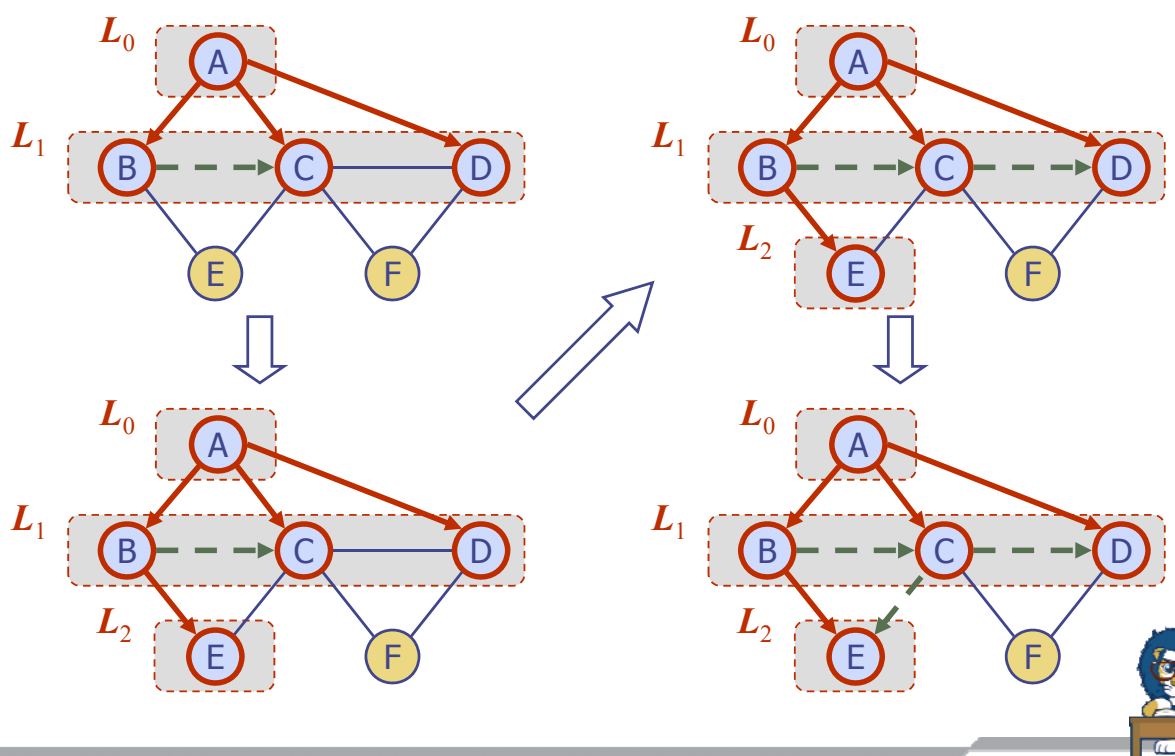
Example



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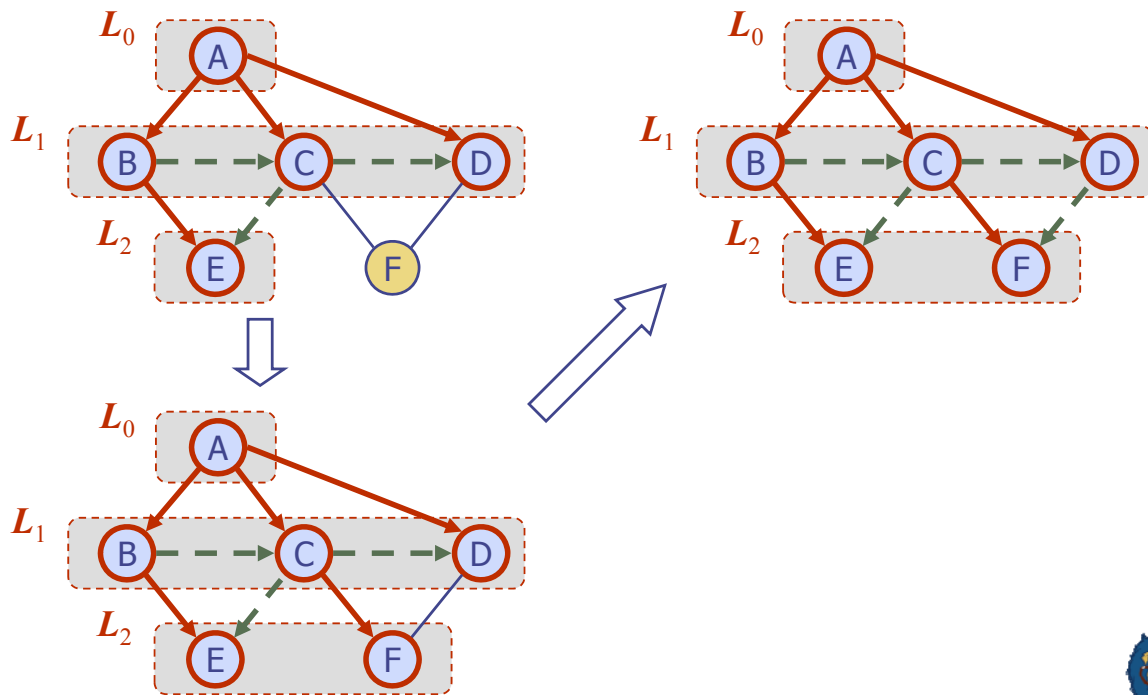
Example (cont.)



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Example (cont.)



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Properties

Notation

G_s : connected component of s

Property 1

$BFS(G, s)$ visits all the vertices and edges of G_s

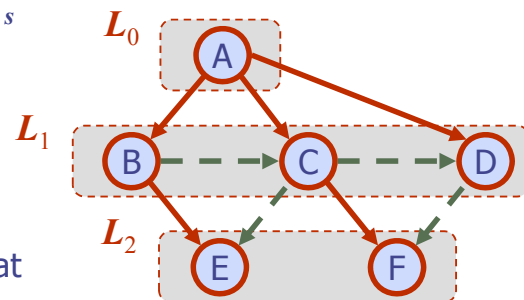
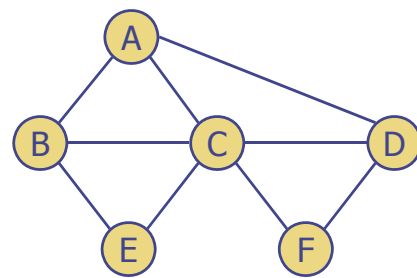
Property 2

The discovery edges labeled by $BFS(G, s)$ form a spanning tree T_s of G_s

Property 3

For each vertex v in L_i

- The path of T_s from s to v has i edges
- Every path from s to v in G_s has at least i edges



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Analysis

- Setting/getting a vertex/edge label takes $O(1)$ time
- Each vertex is labeled twice
 - once as UNEXPLORED
 - once as VISITED
- Each edge is labeled twice
 - once as UNEXPLORED
 - once as DISCOVERY or CROSS
- Each vertex is inserted once into a sequence L_i
- Method incidentEdges is called once for each vertex
- BFS runs in $O(n + m)$ time provided the graph is represented by the adjacency list structure
 - Recall that $\sum_v \deg(v) = 2m$



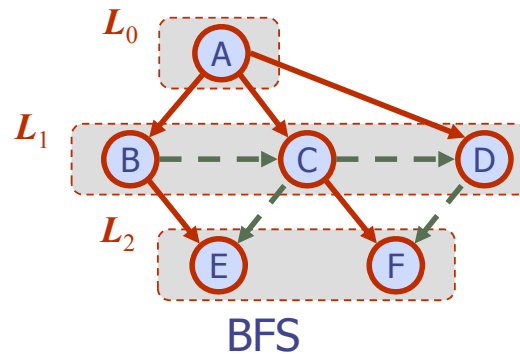
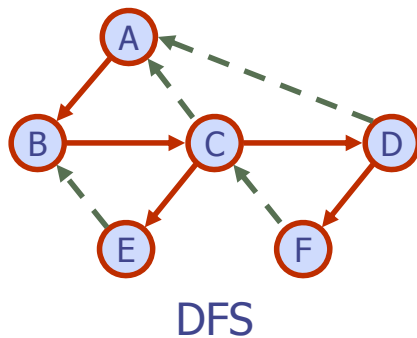
Applications

- Using the template method pattern, we can specialize the BFS traversal of a graph G to solve the following problems in $O(n + m)$ time
 - Compute the connected components of G
 - Compute a spanning forest of G
 - Find a simple cycle in G , or report that G is a forest
 - Given two vertices of G , find a path in G between them with the minimum number of edges, or report that no such path exists



DFS vs. BFS

Applications	DFS	BFS
Spanning forest, connected components, paths, cycles	✓	✓
Shortest paths		✓
Biconnected components	✓	



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Biconnected Graph

- **Articulation point:** An Articulation point in a connected graph is a vertex that, if delete, would break the graph into two or more pieces (connected component).
- **Biconnected graph:** A graph with no articulation point called biconnected. In other words, a graph is biconnected if and only if any vertex is deleted, the graph remains connected.
- **Biconnected component:** A biconnected component of a graph is a maximal biconnected subgraph- a biconnected subgraph that is not properly contained in a larger biconnected subgraph.
- A graph that is not biconnected can divide into biconnected components, sets of nodes mutually accessible via two distinct paths.

The graphs we discuss below are all about loop-free undirected ones.

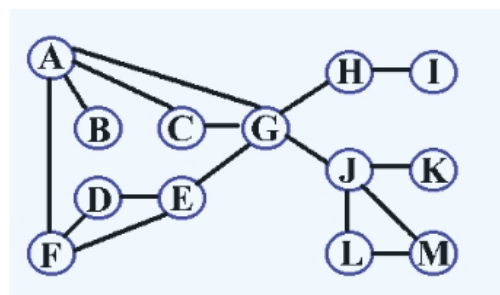


Figure 1. The graph G that is not biconnected

[Example] Graph G in Figure 1:

- Articulation points: A, H, G, J
- Biconnected components: {A, C, G, D, E, F} ∪ {G, J, L, B} ∪ B ∪ H ∪ I ∪ K



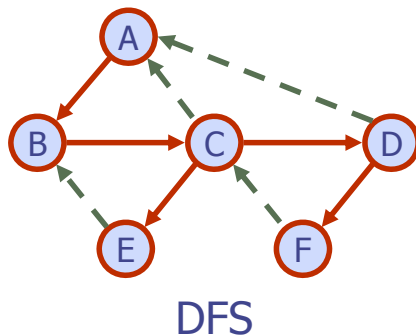
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DFS vs. BFS (cont.)

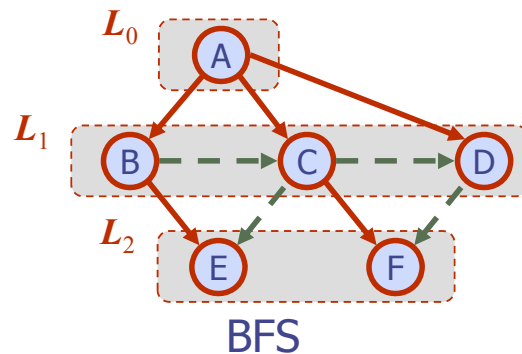
Back edge (v, w)

- w is an ancestor of v in the tree of discovery edges



Cross edge (v, w)

- w is in the same level as v or in the next level



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Biconnected Graph

How to find all articulation points in a given graph?

A simple approach is to one by one remove all vertices and see if removal of a vertex causes disconnected graph. Following are steps of simple approach for connected graph.

- 1) For every vertex v , do following
 -a) Remove v from graph
 -b) See if the graph remains connected (We can either use BFS or DFS)
 -c) Add v back to the graph

Time complexity of above method is $O(V*(V+E))$ for a graph represented using adjacency list. Can we do better?

connectivity 깨지는 지 확인은 dfs

A $O(V+E)$ algorithm to find all Articulation Points (APs)

The idea is to use DFS (Depth First Search). In DFS, we follow vertices in tree form called DFS tree. In DFS tree, a vertex u is parent of another vertex v , if v is discovered by u (obviously v is an adjacent of u in graph). In DFS tree, a vertex u is articulation point if one of the following two conditions is true.

- 1) u is root of DFS tree and it has at least two children.
- 2) u is not root of DFS tree and it has a child v such that no vertex in subtree rooted with v has a back edge to one of the ancestors (in DFS tree) of u .

이 두 조건을 만족하면
articulation point(절단 점)이다



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Q & A



한양대학교 ERICA 캠퍼스