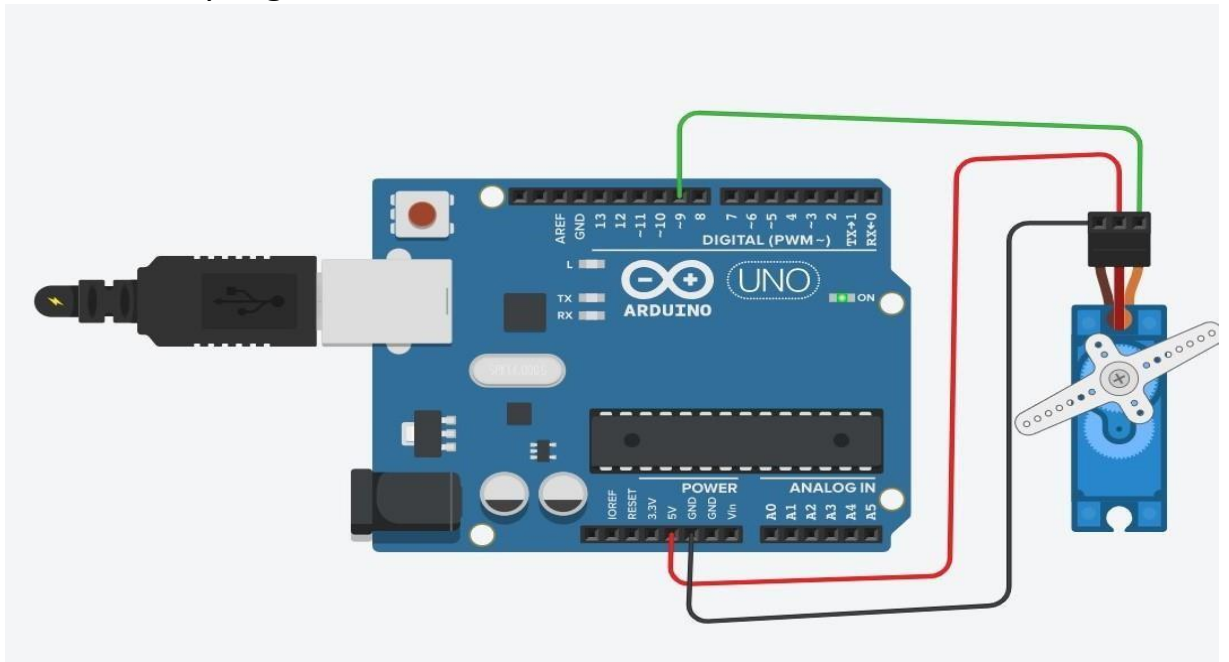IOT practical 2

TITLE:- Draw and interfacing diagram of Servo motor with Arduino and write a program to Rotate it.

• Code

```
#include<Servo.h> int
pos = 0;
Servo servo_9;

void setup()
{
  servo_9.attach(9);

}
void loop()
{
for(pos = 0; pos<=180; pos+=1)
{
 servo_9.write(pos);  delay(15);
}
  for(pos=180;pos>=0; pos -= 1)
  {
   servo_9.write(pos);
delay(15);
```

IOT practical 2

TITLE:- Draw and interfacing diagram of Servo motor with Arduino and write a program to Rotate it.

 }

}