Tlemcen University Department of Computer Science 1st Year Engineering

" Introduction to operating systems 1"

Sessions 10: Process management

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Outline

- Process concepts
- Process visualization
- ☐ Types of process
- Process management
- Process priority
- Operating modes
- Process management commands

Process concepts

Process

- When a program is executed, the system creates a process by placing the program data and code in memory and creating an execution stack.
- A process is therefore an instance of a program with an associated processor environment (ordinal counter, registers, etc.) and memory environment.
- Each process has:
 - > a PID: Process IDentifier, a unique process identifier;
 - ➤ a **PPID**: **P**arent **P**rocess **ID**entifier, a unique identifier for the parent process.

- By successive filiations, the **init** process is the parent of all processes.
 - ➤ A process is always created by a parent process;
 - ➤ A parent process can have several child processes.
- There is a parent/child relationship between processes,
- A child process is the result of a system call to the fork() primitive by the parent process, which duplicates its own code to create a child.
- The child's PID is sent back to the parent process so that it can talk to it.
- Each child has its parent's identifier, the PPID.

- The PID represents the process at the time of execution.
- At the end of the process, the number is available again for another process.
- Executing the same command or program several times will produce a different PID each time.

Each process is represented in the OS by a PCB (process control

block).

PCB					
Pointer	Process state				
Process ID					
Program counter					
Registers					
Memory limits					
List of open files					

- □ PCB: contains information about a specific process, for example:
 - *The state of the process.*
 - Instruction counter: indicates the address of the next instruction to be executed by this process.
 - Pointer: It is a stack pointer that is required to be saved when the process is switched from one state to another to retain the current position of the process.
 - CPU scheduling information: information about the priority of the process.
 - Memory management information: values of the base and limit registers, page tables or segment tables.
 - I/O status information: list of I/O devices allocated to this process, a list of open files, etc.

Process visualization

- ☐ The command *ps* displays the status of current processes.
 - ps command syntax:

Example:

- Main options for the ps command:
 - **>**-e : Displays all processes.
 - ➤-f: Displays additional information.
 - ➤-u login: Displays the user's processes.

Other options :

- -g: Displays processes in the group.
- > -t tty: Displays processes running from the terminal.
- ➤ -p PID: Displays process information.
- ➤ -H: Displays information in the form of a tree structure.
- > -I: Displays additional information.
- > --sort COL: Sort the result according to a column.
- If no option is specified, the **ps** command will only display processes running from the current terminal.

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mohamed@mohamed-VirtualBox:~/TP4\$ ps -ef							
UID	PID	PPID	C	STIME	TTY	TIME CMD	
root	1	0	0	18:15	?	00:00:01 /sbin/init splash	
root	2	0	0	18:15	?	00:00:00 [kthreadd]	
root	3	2	0	18:15	?	00:00:00 [rcu_gp]	
root	4	2	0	18:15	?	00:00:00 [rcu_par_gp]	
root	5	2	0	18:15	?	00:00:00 [slub_flushwq]	
root	6	2	0	18:15	?	00:00:00 [netns]	
root	8	2	0	18:15	?	00:00:00 [kworker/0:0H-events_highpri]	
root	10	2	0	18:15	?	00:00:00 [mm_percpu_wq]	
root	11	2	0	18:15	?	00:00:00 [rcu_tasks_kthread]	
root	12	2	0	18:15	?	00:00:00 [rcu_tasks_rude_kthread]	
root	13	2	0	18:15	?	00:00:00 [rcu_tasks_trace_kthread]	
root	14	2	0	18:15	?	00:00:00 [ksoftirqd/0]	
root	15	2	0	18:15	?	00:00:05 [rcu_preempt]	
root	16	2	0	18:15	?	00:00:00 [migration/0]	
root	17	2	0	18:15	?	00:00:00 [idle_inject/0]	
root	19	2	0	18:15	?	00:00:00 [cpuhp/0]	
root	20	2	0	18:15	?	00:00:00 [cpuhp/1]	
root	21	2	0	18:15	?	00:00:00 [idle_inject/1]	
root	22	2	0	18:15	?	00:00:00 [migration/1]	
root	23	2	0	18:15	?	00:00:00 [ksoftirqd/1]	

- *UID*: *User owner.*
- PID: Process IDentifier.
- PPID: Parent Process IDentifier.
- C: Process priority.
- **STIME**: Execution date and time.
- *TTY*: *Terminal of execution*.
- TIME: Processing time.
- **CMD:** Command executed.

- The **ps** command display can be customized.
- Example

ps -e --format "%P%p%c%n" --sort ppid --headers

```
mohamed@mohamed-VirtualBox:~/TP4$ ps -e --format "%P%p%c%n" --sort ppid --headers
   PPID
            PID COMMAND
              1 systemd
              2 kthreadd
            195 systemd-journal
            253 systemd-udevd
            395 systemd-oomd
            404 systemd-resolve
                                  0
            407 systemd-timesyn
            598 accounts-daemon
            599 acpid
            602 avahi-daemon
           603 cron
           605 dbus-daemon
            607 NetworkManager
                                  0
```

Types of process

- ☐ The user process :
 - is started from a terminal associated with an user,
 - accesses resources via requests or daemons.
- ☐ The system process (daemon):
 - is started by the system,
 - is not associated with any terminal and its owner is a system user (often root),
 - is loaded at start-up, resides in memory and is waiting for a call,
 - is generally identified by the letter d associated with the process name.

Process management

- □ A process cannot be run indefinitely, as this would be to the detriment of other running processes and would prevent multitasking.
- □ The total processing time available is therefore divided into time slots and each process with a priority accesses the processor in sequence.
- □ The process will take on several states during its lifetime:
 - **ready**: waiting for the processor to be available,
 - **running**: accesses the processor,
 - **suspended**: waiting for an I/O (input/output),
 - **stopped**: waiting for a signal from another process,
 - **zombie**: If a terminated process cannot be unloaded from memory, for example if one of its children is not terminated, it goes into a state called zombie.
 - **dead**: the parent of the process kills its child.

R	Running
I	Sleepy (> 20 s)
S	Sleepy (< 20 s)
D	Waiting for a disk operation
Т	Interrupted
Z	Zombie

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- ☐ The end-of-process sequence is as follows:
 - Open files are closed,
 - Release of used memory,
 - Sending a signal to the parent and child processes.
- □When a parent process dies, its children are orphaned.
 - These are then adopted by the **init** process, which is responsible for destroying them.

Process priority

- ☐ The processor works on a time-sharing basis, with each process occupying a quantum of processor time.
- □ Processes are classified by priority, the value of which varies from:
 - ■-20 (the highest priority) to +20 (the lowest priority).
 - *The default priority of a process is 0.*

Operating modes

- ☐ Processes can operate in two ways:
 - Synchronous:
 - The user cannot access the shell while the command is being executed.
 - The command prompt reappears at the end of the process.
 - *Asynchronous:
 - > The process is run in the background,
 - > The command prompt is re-displayed immediately

Process management commands

- ☐ The command *kill*
 - The command kill sends a stop signal to a process.
 - Syntax of the command kill:

Example:

Codes for the main process stop signals

Code	Signal	Description
2	SIGINT	Process interruption (CTRL+D)
9	SIGKILL	Immediate end of process
15	SIGTERM	End of process
18	SIGCONT	Restarting the process
19	SIGSTOP	Suspending the process

- □ Signals are the means of communication between processes.
- ☐ The kill command is used to send a signal to a process.
- ☐ The full list of kill signals is available by typing the command:

man 7 signal

- \Box [CTRL] + [Z]
 - By typing [CTRL+Z], the synchronous process is temporarily suspended.
 - •Access to the prompt is restored after displaying the number of the process that has just been suspended.
- □ Command &
 - The & instruction executes the command in asynchronous mode (the command is then called a job) and displays the job number.
 - •Access to the prompt is then restored.

Example:

```
time ls -lR / > list.ls 2> /dev/null &
```

The job number is obtained during background processing and is displayed in square brackets, followed by the PID number.

Character string conversion: tr ((TRanslate)

- ☐ The commands fg and bg
 - The command fg brings the process to the foreground:
 - **Example**:

```
$time ls -lR / > list.ls 2>/dev/null & $fg 1 $time ls -lR / > list.ls 2/dev/null
```

- The command bg places it in the background:[CTRL]+[Z]
- A process can be placed in the background when it is created using the & argument or later using the [CTRL+Z] keys,
- It can be brought back to the foreground using the fg command and its job number.

```
mohamed@mohamed-VirtualBox:~/TP4$ time ls -lR / > list.ls 2>/dev/null &
[1] 10025
mohamed@mohamed-VirtualBox:~/TP4$ fg 1
time ls --color=auto -lR / > list.ls 2> /dev/null

real    0m7,145s
user    0m2,407s
sys    0m4,555s
mohamed@mohamed-VirtualBox:~/TP4$
```

☐ The command *jobs*

- The command jobs displays the list of processes running in the background and specifies their job number.
- **E**xample:

```
mohamed@mohamed-VirtualBox:~/TP4$ time ls -lR / > list.ls 2>/dev/null
^Z
[1]+ Arrêté
                           ls --color=auto -lR / > list.ls 2> /dev/null
real
       0m1,025s
       0m0,000s
user
        0m0,000s
SVS
mohamed@mohamed-VirtualBox:~/TP4$ time ls -lR / > list.ls 2>/dev/null &
[2] 11298
mohamed@mohamed-VirtualBox:~/TP4S jobs
[1]+ Arrêté
                           ls --color=auto -lR / > list.ls 2> /dev/null
      En cours d'exécution time ls --color=auto -lR / > list.ls 2> /dev/null &
mohamed@mohamed-VirtualBox:~/TP4$
real
       0m7,734s
       0m2.794s
user
        0m4,635s
sys
```

- *The columns represent :*
 - >the job number;
 - >process order
 - + : the next process to run by default with fg or bg,
 - -: the next process to take the +,
 - > Running or Stopped (process suspended),
 - > the command

☐ The commands *nice* and *renice*

- The command **nice** is used to execute a command, specifying its priority.
- Syntax of the nice command

 \$nice command priority
- **E**xample:

\$ nice -n +10 find / -name "file

- Unlike root, a standard user can only reduce the priority of a process.
 - \triangleright Only values between +0 and +19 will be accepted.
 - ➤ This constraint can be lifted by user or by group by modifying the file "/etc/security/limits.conf".

- The command renice is used to change the priority of a running process.
- Syntax of the renice command

\$renice priority [-g GID] [-p PID] [-u UID]

- Main options for the command renice
 - \triangleright -g: GID of the process owner group.
 - \rightarrow -p: PID of the process.
 - **>**-*u* :*UID of the process owner.*
- **E**xample:

\$ renice +15 -p 1652

- The renice command acts on processes already running.
- It is therefore possible to change the priority of a specific process or several processes belonging to a user or group.

☐ The command *top*

- The command top displays the processes and their resource consumption.
- The command top is used to control processes in real time and in interactive mode.

top - 23:20:16 up 11:52, 1 user, load average: 0,10, 0,24, 0,13 Tâches: 199 total, 1 en cours, 198 en veille, 0 arrêté, 0 zombie %Cpu(s): **2,7** ut, **0,3** sy, **0,0** ni, **97,0** id, **0,0** wa, **0,0** hi, **0,0** si, **0,0** st MiB Mem : 3907,6 total, 278,5 libr, 1690,9 util, 1938,2 tamp/cache MiB Éch: 2680,0 total, 2680,0 libr, 0,0 util. 1857,1 dispo Mem

PID	UTIL.	PR	NI	VIRT	RES	SHR	S	%CPU	%MEM	TEMPS+	COM.
1489	mohamed	20	0	4644808	470084	153888	S	5,0	11,7	10:33.39	gnome-shell
380	systemd+	20	0	14828	6912	6144	S	0,3	0,2	1:14.86	systemd-oomd
1671	mohamed	20	0	317976	12248	7296	S	0,3	0,3	0:27.05	ibus-daemon
1735	mohamed	20	0	351140	30380	19204	S	0,3	0,8	0:04.79	ibus-extension-
2049	mohamed	20	0	636368	58612	45476	S	0,3	1,5	0:45.80	gnome-terminal-
4450	mohamed	20	0	15916	4352	3456	R	0,3	0,1	0:00.50	top
4586	mohamed	20	0	11,0g	422692	200036	S	0,3	10,6	0:23.53	firefox
1	root	20	0	166864	11936	8224	S	0,0	0,3	0:03.40	systemd
2	root	20	0	0	0	0	S	0,0	0,0	0:00.01	kthreadd
3	root	0	-20	0	0	0	Ι	0,0	0,0	0:00.00	rcu_gp
4	root	0	-20	0	0	0	Ι	0,0	0,0	0:00.00	rcu_par_gp
5	root	0	-20	0	0	0	Ι	0,0	0,0	0:00.00	slub_flushwq
6	root	0	-20	0	0	0	Ι	0,0	0,0	0:00.00	netns
8	root	0	-20	0	0	0	Ι	0,0	0,0	0:00.00	kworker/0:0H-events_highpri
10	root	0	-20	0	0	0	Ι	0,0	0,0	0:00.00	mm_percpu_wq
11	root	20	0	0	0	0	Ι	0,0	0,0	0:00.00	rcu_tasks_kthread
12	root	20	0	0	0	0	Ι	0,0	0,0		rcu_tasks_rude_kthread
13	root	20	0	0	0	0	Ι	0,0	0,0		rcu_tasks_trace_kthread
14	root	20	0	0	0	0	S	0,0	0,0	0:00.28	ksoftirqd/0
4.5	coot	20	0	0	0	0	т	0 0	0 0	0.12 01	ceu pecamat

☐ Information returned by the command top

Column	Description
PID	Process identifier
USER	User owner
PR	Process priority
NI	Value of nice
%CPU	CPU load
%MEM	Memory load
TIME+	CPU usage time
COMMAND	The command executed

☐ The commands pgrep and pkill

- The command pgrep searches the running processes for a process name and displays the PIDs corresponding to the selection criteria on the standard output.
- The command pkill sends the indicated signal (by default SIGTERM) to each process.
- Syntax of the commands pgrep and pkill

```
pgrep process
pkill [-signal] process
```

- Examples:
 - To retrieve the sshd process number

```
pgrep -u root sshd
```

➤ To kill all tomcat processes:

pkill tomcat