the IMDB class

```
In []: #import os
        #os.environ['CUDA_VISIBLE_DEVICES'] = '-1'
        # Import packages
        import numpy as np
        from tensorflow import keras
        from tensorflow.keras import layers
        from tensorflow.keras.datasets import imdb
        #from sklearn.model_selection import train_test_split
        import matplotlib.pyplot as plt
        # default values
        NUM WORDS = 10000
        BATCH_SIZE = 512
        class Imdb:
            def __init__(self, num_words = NUM_WORDS):
                self.x_train, self.y_train, \
                self.x_test, self.y_test = self._load(num_words)
                self.model = self._model()
            def _load(self, num_words):
                (x_train_raw, y_train_raw), (x_test_raw, y_test_raw) \
                    = imdb.load data(num words=num words)
                # vectorize reviews
                x_train = self._vectorize_sequences(x_train_raw, num_words)
                y_train = np.asarray(y_train_raw).astype('float32')
                x_test = self._vectorize_sequences(x_test_raw, num_words)
                y_test = np.asarray(y_test_raw).astype('float32')
                #x_train, x_val, y_train, y_val \
                # = train_test_split(x_train_vec, y_train, test_size=0.2)
                return x_train, y_train, x_test, y_test
            def _model(self):
                model = keras.Sequential([
                    layers.Dense(32, activation="relu"),
                    layers.Dense(16, activation="relu"),
                    layers.Dense(1, activation="sigmoid")
                1)
                # model compilation
                model.compile(optimizer="rmsprop",
                                loss="binary_crossentropy",
                                metrics=["accuracy"])
                return model
```

```
def plot_loss(self, history):
    # Plotting the training and validation loss
    history dict = history.history
    loss_values = history_dict["loss"]
    val_loss_values = history_dict["val_loss"]
    epochs = range(1, len(loss values) + 1)
    plt.figure(1)
    plt.plot(epochs, loss_values, "r", label="Training loss")
    plt.plot(epochs, val_loss_values, "r--", label="Validation loss")
    plt.title("Training and validation loss")
    plt.xlabel("Epochs")
    plt.ylabel("Loss")
    plt.legend()
    plt.show()
def plot accuracy(self, history):
    history_dict = history.history
    acc = history_dict["accuracy"]
    val_acc = history_dict["val_accuracy"]
    epochs = range(1, len(acc) + 1)
    plt.figure(2)
    plt.plot(epochs, acc, "b", label="Training acc")
    plt.plot(epochs, val_acc, "b--", label="Validation acc")
    plt.title("Training and validation accuracy")
    plt.xlabel("Epochs")
    plt.ylabel("Accuracy")
    plt.legend()
    plt.show()
def train(self, epochs=20):
    if self.model is None:
        print('[INFO] model is not defined.')
        return
    history = self.model.fit(self.x_train, self.y_train, \
                             epochs = epochs, validation_split = 0.2,
                             batch size = BATCH SIZE)
    self.plot_loss(history)
    self.plot_accuracy(history)
    return history
def evaluate(self):
    score = self.model.evaluate(self.x_test, self.y_test)
    print(f'[INFO] Test loss: {score[0]}')
    print(f'[INFO] Test accuracy: {score[1]}')
def vectorize sequences(self, sequences, dimension):
    results = np.zeros((len(sequences), dimension))
    for i, sequence in enumerate(sequences):
        for j in sequence:
            results[i, j] = 1.
    return results
```

Calling the Imdb class and loading the dataset

```
In []: imdb = Imdb()
      Metal device set to: Apple M1 Pro
      systemMemory: 16.00 GB
      maxCacheSize: 5.33 GB
      2022-11-14 22:51:41.939096: I tensorflow/core/common_runtime/pluggable_d
      evice/pluggable_device_factory.cc:306] Could not identify NUMA node of p
      latform GPU ID 0, defaulting to 0. Your kernel may not have been built w
      ith NUMA support.
      2022-11-14 22:51:41.939210: I tensorflow/core/common_runtime/pluggable_d
      evice/pluggable_device_factory.cc:272] Created TensorFlow device (/job:l
      ocalhost/replica:0/task:0/device:GPU:0 with 0 MB memory) -> physical Plu
      ggableDevice (device: 0, name: METAL, pci bus id: <undefined>)
      Traing the model
In [ ]: history = imdb.train(epochs=100)
      Epoch 1/100
      2022-11-14 22:52:02.372578: W tensorflow/core/platform/profile_utils/cpu
      _utils.cc:128] Failed to get CPU frequency: 0 Hz
      2022-11-14 22:52:02.667980: I tensorflow/core/grappler/optimizers/custom
      _graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
      s enabled.
      ccuracy: 0.8031 - val_loss: 0.3330 - val_accuracy: 0.8842
      Epoch 2/100
       1/40 [.....] - ETA: 0s - loss: 0.2740 - accura
      cy: 0.9199
      2022-11-14 22:52:03.909305: I tensorflow/core/grappler/optimizers/custom
      _graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
      s enabled.
      ccuracy: 0.9100 - val_loss: 0.4011 - val_accuracy: 0.8324
      Epoch 3/100
      40/40 [============= ] - 1s 13ms/step - loss: 0.1992 - a
      ccuracy: 0.9288 - val_loss: 0.2736 - val_accuracy: 0.8906
      Epoch 4/100
      ccuracy: 0.9419 - val_loss: 0.2803 - val_accuracy: 0.8920
      Epoch 5/100
      ccuracy: 0.9556 - val_loss: 0.3165 - val_accuracy: 0.8808
      Epoch 6/100
      40/40 [============= ] - 1s 14ms/step - loss: 0.1096 - a
      ccuracy: 0.9631 - val_loss: 0.3237 - val_accuracy: 0.8852
      ccuracy: 0.9725 - val_loss: 0.3560 - val_accuracy: 0.8788
      Epoch 8/100
```

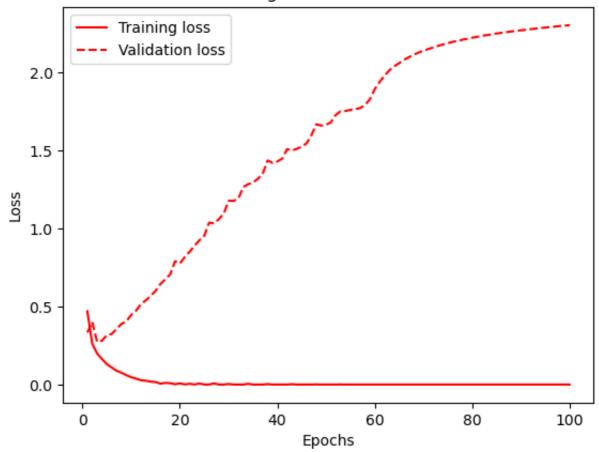
```
ccuracy: 0.9768 - val_loss: 0.3880 - val_accuracy: 0.8748
Epoch 9/100
ccuracy: 0.9818 - val_loss: 0.4049 - val_accuracy: 0.8812
Epoch 10/100
ccuracy: 0.9865 - val_loss: 0.4456 - val_accuracy: 0.8802
Epoch 11/100
ccuracy: 0.9896 - val_loss: 0.4731 - val_accuracy: 0.8724
Epoch 12/100
ccuracy: 0.9929 - val_loss: 0.5147 - val_accuracy: 0.8712
Epoch 13/100
ccuracy: 0.9934 - val_loss: 0.5391 - val_accuracy: 0.8738
Epoch 14/100
40/40 [============= ] - 0s 13ms/step - loss: 0.0186 - a
ccuracy: 0.9951 - val loss: 0.5678 - val accuracy: 0.8726
Epoch 15/100
ccuracy: 0.9963 - val_loss: 0.5996 - val_accuracy: 0.8714
Epoch 16/100
ccuracy: 0.9996 - val_loss: 0.6435 - val_accuracy: 0.8698
Epoch 17/100
ccuracy: 0.9973 - val_loss: 0.6740 - val_accuracy: 0.8694
Epoch 18/100
ccuracy: 0.9975 - val_loss: 0.7047 - val_accuracy: 0.8692
Epoch 19/100
40/40 [============= ] - 0s 13ms/step - loss: 0.0020 - a
ccuracy: 1.0000 - val_loss: 0.7902 - val_accuracy: 0.8656
Epoch 20/100
ccuracy: 0.9981 - val_loss: 0.7754 - val_accuracy: 0.8716
Epoch 21/100
ccuracy: 1.0000 - val_loss: 0.8159 - val_accuracy: 0.8702
Epoch 22/100
40/40 [============== ] - 1s 15ms/step - loss: 0.0047 - a
ccuracy: 0.9987 - val loss: 0.8504 - val accuracy: 0.8690
Epoch 23/100
40/40 [============== ] - 1s 14ms/step - loss: 5.5643e-04
- accuracy: 1.0000 - val_loss: 0.8883 - val_accuracy: 0.8668
Epoch 24/100
ccuracy: 0.9985 - val_loss: 0.9237 - val_accuracy: 0.8666
Epoch 25/100
- accuracy: 1.0000 - val_loss: 0.9521 - val_accuracy: 0.8674
Epoch 26/100
- accuracy: 1.0000 - val loss: 1.0373 - val accuracy: 0.8656
Epoch 27/100
40/40 [============= ] - 0s 12ms/step - loss: 0.0070 - a
```

```
ccuracy: 0.9980 - val_loss: 1.0314 - val_accuracy: 0.8682
Epoch 28/100
- accuracy: 1.0000 - val_loss: 1.0594 - val_accuracy: 0.8682
Epoch 29/100
- accuracy: 1.0000 - val_loss: 1.0946 - val_accuracy: 0.8672
Epoch 30/100
ccuracy: 0.9989 - val_loss: 1.1769 - val_accuracy: 0.8666
Epoch 31/100
- accuracy: 1.0000 - val_loss: 1.1762 - val_accuracy: 0.8664
Epoch 32/100
- accuracy: 1.0000 - val_loss: 1.1910 - val_accuracy: 0.8646
Epoch 33/100
- accuracy: 1.0000 - val_loss: 1.2639 - val_accuracy: 0.8682
Epoch 34/100
ccuracy: 0.9988 - val_loss: 1.2828 - val_accuracy: 0.8642
Epoch 35/100
- accuracy: 1.0000 - val_loss: 1.2940 - val_accuracy: 0.8652
Epoch 36/100
- accuracy: 1.0000 - val_loss: 1.3171 - val_accuracy: 0.8644
Epoch 37/100
40/40 [============== ] - 0s 12ms/step - loss: 7.8016e-06
- accuracy: 1.0000 - val_loss: 1.3502 - val_accuracy: 0.8652
Epoch 38/100
40/40 [============= ] - 1s 13ms/step - loss: 0.0030 - a
ccuracy: 0.9993 - val_loss: 1.4351 - val_accuracy: 0.8670
Epoch 39/100
- accuracy: 1.0000 - val_loss: 1.4198 - val_accuracy: 0.8646
Epoch 40/100
- accuracy: 1.0000 - val_loss: 1.4284 - val_accuracy: 0.8640
Epoch 41/100
- accuracy: 1.0000 - val loss: 1.4469 - val accuracy: 0.8656
Epoch 42/100
- accuracy: 1.0000 - val_loss: 1.5073 - val_accuracy: 0.8654
Epoch 43/100
ccuracy: 0.9994 - val_loss: 1.4987 - val_accuracy: 0.8670
Epoch 44/100
- accuracy: 1.0000 - val_loss: 1.5094 - val_accuracy: 0.8670
Epoch 45/100
- accuracy: 1.0000 - val loss: 1.5232 - val accuracy: 0.8664
Epoch 46/100
40/40 [============== ] - 0s 12ms/step - loss: 1.1113e-06
```

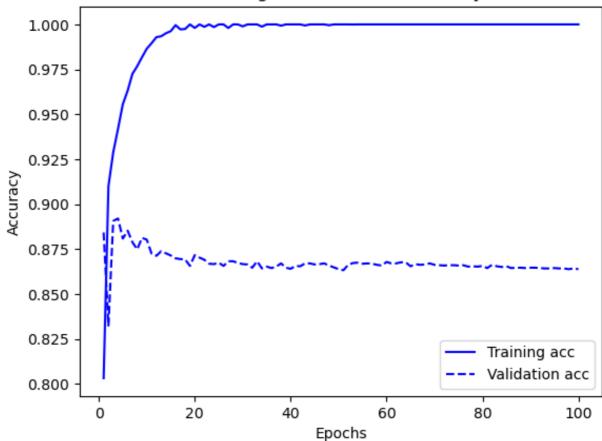
```
- accuracy: 1.0000 - val_loss: 1.5443 - val_accuracy: 0.8666
Epoch 47/100
- accuracy: 1.0000 - val_loss: 1.5963 - val_accuracy: 0.8670
Epoch 48/100
ccuracy: 0.9996 - val_loss: 1.6673 - val_accuracy: 0.8658
Epoch 49/100
- accuracy: 1.0000 - val_loss: 1.6582 - val_accuracy: 0.8648
Epoch 50/100
- accuracy: 1.0000 - val_loss: 1.6634 - val_accuracy: 0.8638
Epoch 51/100
- accuracy: 1.0000 - val_loss: 1.6794 - val_accuracy: 0.8632
Epoch 52/100
40/40 [============= ] - 1s 13ms/step - loss: 3.8262e-07
- accuracy: 1.0000 - val_loss: 1.7265 - val_accuracy: 0.8662
Epoch 53/100
40/40 [============== ] - 1s 13ms/step - loss: 7.2209e-04
- accuracy: 1.0000 - val_loss: 1.7506 - val_accuracy: 0.8672
Epoch 54/100
- accuracy: 1.0000 - val_loss: 1.7520 - val_accuracy: 0.8674
Epoch 55/100
- accuracy: 1.0000 - val_loss: 1.7591 - val_accuracy: 0.8668
Epoch 56/100
40/40 [============== ] - 1s 13ms/step - loss: 1.8506e-07
- accuracy: 1.0000 - val_loss: 1.7643 - val_accuracy: 0.8670
Epoch 57/100
40/40 [============== ] - 0s 13ms/step - loss: 1.5928e-07
- accuracy: 1.0000 - val_loss: 1.7701 - val_accuracy: 0.8668
Epoch 58/100
- accuracy: 1.0000 - val_loss: 1.7893 - val_accuracy: 0.8662
Epoch 59/100
- accuracy: 1.0000 - val_loss: 1.8266 - val_accuracy: 0.8658
Epoch 60/100
- accuracy: 1.0000 - val loss: 1.8912 - val accuracy: 0.8678
Epoch 61/100
- accuracy: 1.0000 - val_loss: 1.9381 - val_accuracy: 0.8670
Epoch 62/100
- accuracy: 1.0000 - val_loss: 1.9778 - val_accuracy: 0.8670
Epoch 63/100
- accuracy: 1.0000 - val_loss: 2.0121 - val_accuracy: 0.8676
Epoch 64/100
- accuracy: 1.0000 - val loss: 2.0383 - val accuracy: 0.8676
Epoch 65/100
40/40 [============== ] - 0s 12ms/step - loss: 1.3014e-08
```

```
- accuracy: 1.0000 - val_loss: 2.0578 - val_accuracy: 0.8654
Epoch 66/100
- accuracy: 1.0000 - val_loss: 2.0796 - val_accuracy: 0.8666
Epoch 67/100
- accuracy: 1.0000 - val_loss: 2.0962 - val_accuracy: 0.8662
Epoch 68/100
- accuracy: 1.0000 - val_loss: 2.1124 - val_accuracy: 0.8664
Epoch 69/100
- accuracy: 1.0000 - val_loss: 2.1259 - val_accuracy: 0.8670
Epoch 70/100
- accuracy: 1.0000 - val_loss: 2.1377 - val_accuracy: 0.8662
Epoch 71/100
40/40 [============== ] - 0s 13ms/step - loss: 4.9784e-09
- accuracy: 1.0000 - val_loss: 2.1488 - val_accuracy: 0.8660
Epoch 72/100
40/40 [============== ] - 1s 13ms/step - loss: 4.3422e-09
- accuracy: 1.0000 - val_loss: 2.1585 - val_accuracy: 0.8658
Epoch 73/100
- accuracy: 1.0000 - val_loss: 2.1686 - val_accuracy: 0.8660
Epoch 74/100
- accuracy: 1.0000 - val_loss: 2.1776 - val_accuracy: 0.8660
Epoch 75/100
40/40 [============= ] - 0s 12ms/step - loss: 3.1606e-09
- accuracy: 1.0000 - val_loss: 2.1863 - val_accuracy: 0.8658
Epoch 76/100
40/40 [============= ] - 0s 12ms/step - loss: 2.8920e-09
- accuracy: 1.0000 - val_loss: 2.1943 - val_accuracy: 0.8660
Epoch 77/100
- accuracy: 1.0000 - val_loss: 2.2005 - val_accuracy: 0.8652
Epoch 78/100
- accuracy: 1.0000 - val_loss: 2.2082 - val_accuracy: 0.8654
Epoch 79/100
- accuracy: 1.0000 - val loss: 2.2143 - val accuracy: 0.8652
Epoch 80/100
40/40 [============== ] - 0s 12ms/step - loss: 2.0203e-09
- accuracy: 1.0000 - val_loss: 2.2210 - val_accuracy: 0.8656
Epoch 81/100
- accuracy: 1.0000 - val_loss: 2.2266 - val_accuracy: 0.8644
Epoch 82/100
40/40 [============== ] - 0s 12ms/step - loss: 1.7104e-09
- accuracy: 1.0000 - val_loss: 2.2335 - val_accuracy: 0.8662
Epoch 83/100
40/40 [============== ] - 1s 13ms/step - loss: 1.5948e-09
- accuracy: 1.0000 - val loss: 2.2376 - val accuracy: 0.8654
Epoch 84/100
```

```
- accuracy: 1.0000 - val_loss: 2.2425 - val_accuracy: 0.8650
Epoch 85/100
- accuracy: 1.0000 - val_loss: 2.2482 - val_accuracy: 0.8654
Epoch 86/100
40/40 [============= ] - 1s 13ms/step - loss: 1.3634e-09
- accuracy: 1.0000 - val_loss: 2.2522 - val_accuracy: 0.8644
Epoch 87/100
- accuracy: 1.0000 - val_loss: 2.2565 - val_accuracy: 0.8646
Epoch 88/100
- accuracy: 1.0000 - val_loss: 2.2610 - val_accuracy: 0.8646
Epoch 89/100
- accuracy: 1.0000 - val_loss: 2.2646 - val_accuracy: 0.8644
Epoch 90/100
40/40 [============== ] - 1s 13ms/step - loss: 1.0783e-09
- accuracy: 1.0000 - val_loss: 2.2686 - val_accuracy: 0.8646
Epoch 91/100
40/40 [============== ] - 1s 13ms/step - loss: 1.0577e-09
- accuracy: 1.0000 - val_loss: 2.2722 - val_accuracy: 0.8646
Epoch 92/100
- accuracy: 1.0000 - val_loss: 2.2759 - val_accuracy: 0.8644
Epoch 93/100
- accuracy: 1.0000 - val_loss: 2.2796 - val_accuracy: 0.8642
Epoch 94/100
- accuracy: 1.0000 - val_loss: 2.2830 - val_accuracy: 0.8642
Epoch 95/100
40/40 [============== ] - 1s 13ms/step - loss: 9.0893e-10
- accuracy: 1.0000 - val_loss: 2.2862 - val_accuracy: 0.8644
Epoch 96/100
- accuracy: 1.0000 - val_loss: 2.2895 - val_accuracy: 0.8642
Epoch 97/100
- accuracy: 1.0000 - val_loss: 2.2922 - val_accuracy: 0.8642
Epoch 98/100
- accuracy: 1.0000 - val loss: 2.2957 - val accuracy: 0.8638
Epoch 99/100
- accuracy: 1.0000 - val_loss: 2.2987 - val_accuracy: 0.8642
Epoch 100/100
- accuracy: 1.0000 - val_loss: 2.3014 - val_accuracy: 0.8638
```





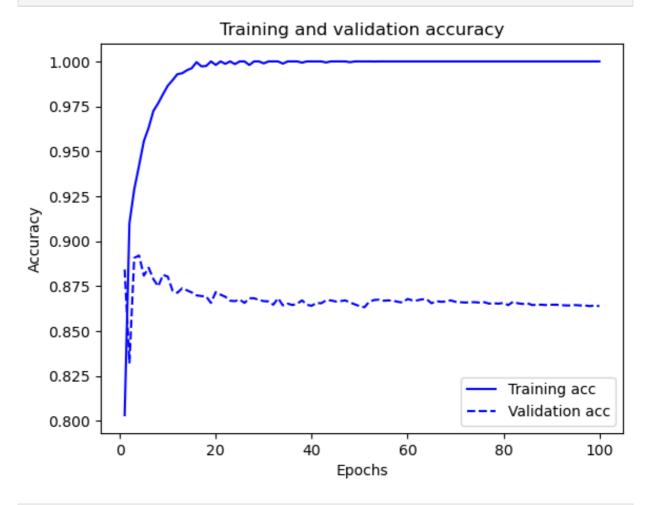


In []: # Evalluting the model
imdb.evaluate()

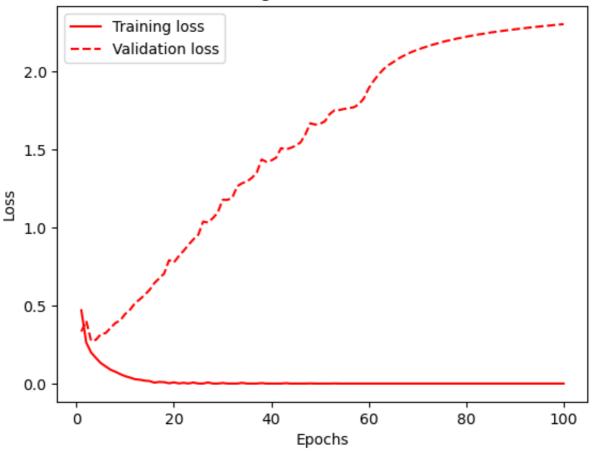
accuracy: 0.8496

[INF0] Test loss: 2.4978740215301514
[INF0] Test accuracy: 0.8495600819587708

In []: # Plotting IMDB model accuracy history
imdb.plot_accuracy(history)



In []: # Plotiing model loss history
imdb.plot_loss(history)



Reuters Class

```
In []: #import os
        #os.environ['CUDA_VISIBLE_DEVICES'] = '-1'
        # Import packages
        import numpy as np
        from tensorflow import keras
        from tensorflow.keras import layers
        #from tensorflow.keras.datasets import reuters
        #from sklearn.model_selection import train_test_split
        import matplotlib.pyplot as plt
        from keras.utils.np_utils import to_categorical
        # default values
        NUM_WORDS = 10000
        BATCH_SIZE = 512
        class Reuters:
            def __init__(self, num_words = NUM_WORDS):
                self.x_train, self.y_train, \
                self.x_test, self.y_test = self._load(num_words)
                self.model = self._model()
            def _load(self, num_words):
                (x_train_raw, y_train_raw), (x_test_raw, y_test_raw) = keras.data
```

```
# vectorize reviews
    x_train = self._vectorize_sequences(x_train_raw, num_words)
    y_train = np.asarray(y_train_raw).astype('float32')
    x_test = self._vectorize_sequences(x_test_raw, num_words)
    y_test = np.asarray(y_test_raw).astype('float32')
    y_train=to_categorical(y_train)
    y_test=to_categorical(y_test)
    #x_train, x_val, y_train, y_val \
    # = train_test_split(x_train_vec, y_train, test_size=0.2)
    return x_train, y_train, x_test, y_test
def _model(self):
    model = keras.Sequential([
        layers.Dense(64, activation="relu"),
        layers.Dense(64, activation="relu"),
        layers.Dense(46, activation="softmax")
    1)
    # model compilation
    model.compile(optimizer="rmsprop",
                    loss="categorical crossentropy",
                    metrics=["accuracy"])
    return model
def plot_loss(self, history):
    # Plotting the training and validation loss
    history dict = history.history
    loss_values = history_dict["loss"]
    val_loss_values = history_dict["val_loss"]
    epochs = range(1, len(loss_values) + 1)
    plt.figure(1)
    plt.plot(epochs, loss_values, "r", label="Training loss")
    plt.plot(epochs, val_loss_values, "r--", label="Validation loss")
    plt.title("Training and validation loss")
    plt.xlabel("Epochs")
    plt.ylabel("Loss")
    plt.legend()
    plt.show()
def plot_accuracy(self, history):
    history_dict = history.history
    acc = history_dict["accuracy"]
    val_acc = history_dict["val_accuracy"]
    epochs = range(1, len(acc) + 1)
    plt.figure(2)
    plt.plot(epochs, acc, "b", label="Training acc")
    plt.plot(epochs, val_acc, "b--", label="Validation acc")
    plt.title("Training and validation accuracy")
    plt.xlabel("Epochs")
    plt.ylabel("Accuracy")
    plt.legend()
    plt.show()
```

```
def train(self, epochs=20):
              if self.model is None:
                  print('[INFO] model is not defined.')
                  return
              history = self.model.fit(self.x_train, self.y_train, \
                                     epochs = epochs, validation_split = 0.2,
                                     batch_size = BATCH_SIZE)
              self.plot loss(history)
              self.plot_accuracy(history)
              return history
           def evaluate(self):
              score = self.model.evaluate(self.x test, self.y test)
              print(f'[INFO] Test loss: {score[0]}')
              print(f'[INFO] Test accuracy: {score[1]}')
           def _vectorize_sequences(self, sequences, dimension=10000):
              results = np.zeros((len(sequences), dimension))
              for i, sequence in enumerate(sequences):
                  for j in sequence:
                      results[i, j] = 1.
              return results
           def to_one_hot(labels, dimension=46):
              results = np.zeros((len(labels), dimension))
              for i,label in enumerate(labels):
                  results[i,label] = 1
              return results
In [ ]: # Calling Reuters class
       reuters = Reuters()
In [ ]: # training Reuters model
       reuters.train(epochs = 100)
       Epoch 1/100
       2022-11-14 22:54:49.838113: I tensorflow/core/grappler/optimizers/custom
       _graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
       s enabled.
       15/15 [============= ] - 1s 33ms/step - loss: 2.6243 - a
       ccuracy: 0.5113 - val loss: 1.8076 - val accuracy: 0.6316
       Epoch 2/100
        1/15 [=>.....] - ETA: 0s - loss: 1.6648 - accura
       cy: 0.6660
       2022-11-14 22:54:50.381809: I tensorflow/core/grappler/optimizers/custom
       _graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
       s enabled.
       ccuracy: 0.6928 - val_loss: 1.3861 - val_accuracy: 0.7084
       Epoch 3/100
       ccuracy: 0.7692 - val_loss: 1.2254 - val_accuracy: 0.7407
```

```
Epoch 4/100
ccuracy: 0.8173 - val_loss: 1.1613 - val_accuracy: 0.7234
Epoch 5/100
ccuracy: 0.8498 - val loss: 1.1089 - val accuracy: 0.7401
Epoch 6/100
ccuracy: 0.8777 - val_loss: 1.0099 - val_accuracy: 0.7807
Epoch 7/100
ccuracy: 0.9040 - val_loss: 0.9789 - val_accuracy: 0.7974
Epoch 8/100
15/15 [============== ] - 0s 18ms/step - loss: 0.3789 - a
ccuracy: 0.9236 - val_loss: 1.0399 - val_accuracy: 0.7846
Epoch 9/100
ccuracy: 0.9350 - val_loss: 0.9930 - val_accuracy: 0.7813
Epoch 10/100
ccuracy: 0.9442 - val_loss: 1.0420 - val_accuracy: 0.7757
Epoch 11/100
ccuracy: 0.9534 - val loss: 1.0512 - val accuracy: 0.7735
Epoch 12/100
15/15 [============= ] - 0s 17ms/step - loss: 0.1962 - a
ccuracy: 0.9549 - val_loss: 0.9683 - val_accuracy: 0.7991
Epoch 13/100
ccuracy: 0.9591 - val_loss: 1.0314 - val_accuracy: 0.7885
Epoch 14/100
ccuracy: 0.9594 - val_loss: 1.0356 - val_accuracy: 0.8036
Epoch 15/100
ccuracy: 0.9606 - val_loss: 1.0655 - val_accuracy: 0.7846
Epoch 16/100
ccuracy: 0.9633 - val_loss: 1.0840 - val_accuracy: 0.7935
Epoch 17/100
ccuracy: 0.9624 - val_loss: 1.1875 - val_accuracy: 0.7819
ccuracy: 0.9628 - val_loss: 1.1112 - val_accuracy: 0.8013
Epoch 19/100
15/15 [============= ] - 0s 17ms/step - loss: 0.1099 - a
ccuracy: 0.9623 - val_loss: 1.1089 - val_accuracy: 0.7986
Epoch 20/100
ccuracy: 0.9640 - val loss: 1.1800 - val accuracy: 0.7830
Epoch 21/100
15/15 [============= ] - 0s 17ms/step - loss: 0.1005 - a
ccuracy: 0.9637 - val_loss: 1.2333 - val_accuracy: 0.7802
Epoch 22/100
ccuracy: 0.9635 - val_loss: 1.2402 - val_accuracy: 0.7807
```

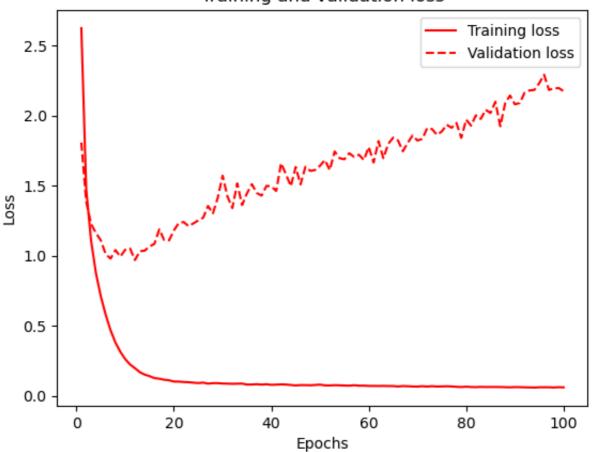
```
Epoch 23/100
ccuracy: 0.9630 - val_loss: 1.2104 - val_accuracy: 0.7869
Epoch 24/100
ccuracy: 0.9619 - val loss: 1.2301 - val accuracy: 0.7941
Epoch 25/100
ccuracy: 0.9630 - val_loss: 1.2515 - val_accuracy: 0.7813
Epoch 26/100
ccuracy: 0.9621 - val_loss: 1.2706 - val_accuracy: 0.7935
Epoch 27/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0859 - a
ccuracy: 0.9655 - val_loss: 1.3550 - val_accuracy: 0.7885
Epoch 28/100
ccuracy: 0.9623 - val_loss: 1.3014 - val_accuracy: 0.7858
Epoch 29/100
ccuracy: 0.9641 - val_loss: 1.4132 - val_accuracy: 0.7819
Epoch 30/100
ccuracy: 0.9635 - val loss: 1.5711 - val accuracy: 0.7518
Epoch 31/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0860 - a
ccuracy: 0.9626 - val_loss: 1.4222 - val_accuracy: 0.7769
Epoch 32/100
ccuracy: 0.9617 - val_loss: 1.3394 - val_accuracy: 0.7813
Epoch 33/100
ccuracy: 0.9637 - val_loss: 1.5161 - val_accuracy: 0.7685
Epoch 34/100
ccuracy: 0.9613 - val_loss: 1.3610 - val_accuracy: 0.7830
Epoch 35/100
ccuracy: 0.9637 - val_loss: 1.4450 - val_accuracy: 0.7841
Epoch 36/100
ccuracy: 0.9635 - val_loss: 1.5104 - val_accuracy: 0.7702
ccuracy: 0.9641 - val_loss: 1.4478 - val_accuracy: 0.7824
Epoch 38/100
15/15 [============== ] - 0s 17ms/step - loss: 0.0791 - a
ccuracy: 0.9651 - val_loss: 1.4280 - val_accuracy: 0.7869
Epoch 39/100
ccuracy: 0.9623 - val loss: 1.4982 - val accuracy: 0.7691
Epoch 40/100
15/15 [============== ] - 0s 16ms/step - loss: 0.0775 - a
ccuracy: 0.9623 - val_loss: 1.4946 - val_accuracy: 0.7780
Epoch 41/100
ccuracy: 0.9635 - val_loss: 1.4620 - val_accuracy: 0.7841
```

```
Epoch 42/100
ccuracy: 0.9617 - val_loss: 1.6595 - val_accuracy: 0.7629
Epoch 43/100
ccuracy: 0.9637 - val loss: 1.5817 - val accuracy: 0.7735
Epoch 44/100
ccuracy: 0.9635 - val_loss: 1.4956 - val_accuracy: 0.7785
Epoch 45/100
ccuracy: 0.9649 - val_loss: 1.6329 - val_accuracy: 0.7624
Epoch 46/100
15/15 [============== ] - 0s 16ms/step - loss: 0.0756 - a
ccuracy: 0.9659 - val_loss: 1.5085 - val_accuracy: 0.7824
Epoch 47/100
ccuracy: 0.9645 - val_loss: 1.6346 - val_accuracy: 0.7718
Epoch 48/100
ccuracy: 0.9665 - val_loss: 1.6052 - val_accuracy: 0.7752
Epoch 49/100
ccuracy: 0.9646 - val loss: 1.6118 - val accuracy: 0.7763
Epoch 50/100
15/15 [============= ] - 0s 16ms/step - loss: 0.0789 - a
ccuracy: 0.9640 - val_loss: 1.6418 - val_accuracy: 0.7735
Epoch 51/100
ccuracy: 0.9644 - val_loss: 1.6833 - val_accuracy: 0.7730
Epoch 52/100
ccuracy: 0.9642 - val_loss: 1.6105 - val_accuracy: 0.7713
Epoch 53/100
ccuracy: 0.9631 - val_loss: 1.7441 - val_accuracy: 0.7691
Epoch 54/100
ccuracy: 0.9637 - val_loss: 1.6961 - val_accuracy: 0.7691
Epoch 55/100
ccuracy: 0.9644 - val_loss: 1.6884 - val_accuracy: 0.7724
Epoch 56/100
ccuracy: 0.9634 - val_loss: 1.7313 - val_accuracy: 0.7702
Epoch 57/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0746 - a
ccuracy: 0.9619 - val_loss: 1.7050 - val_accuracy: 0.7746
Epoch 58/100
ccuracy: 0.9633 - val_loss: 1.7204 - val_accuracy: 0.7624
Epoch 59/100
15/15 [============= ] - 0s 16ms/step - loss: 0.0716 - a
ccuracy: 0.9617 - val_loss: 1.6829 - val_accuracy: 0.7752
Epoch 60/100
ccuracy: 0.9635 - val_loss: 1.7759 - val_accuracy: 0.7696
```

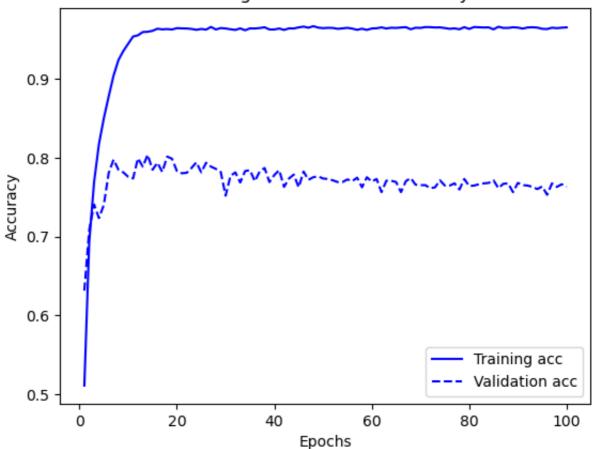
```
Epoch 61/100
ccuracy: 0.9638 - val_loss: 1.6649 - val_accuracy: 0.7730
Epoch 62/100
ccuracy: 0.9649 - val loss: 1.8181 - val accuracy: 0.7563
Epoch 63/100
ccuracy: 0.9635 - val_loss: 1.6959 - val_accuracy: 0.7707
Epoch 64/100
ccuracy: 0.9645 - val_loss: 1.7979 - val_accuracy: 0.7707
Epoch 65/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0689 - a
ccuracy: 0.9642 - val_loss: 1.8425 - val_accuracy: 0.7691
Epoch 66/100
ccuracy: 0.9648 - val_loss: 1.8229 - val_accuracy: 0.7563
Epoch 67/100
ccuracy: 0.9652 - val_loss: 1.7454 - val_accuracy: 0.7702
Epoch 68/100
ccuracy: 0.9626 - val loss: 1.8052 - val accuracy: 0.7741
Epoch 69/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0656 - a
ccuracy: 0.9645 - val_loss: 1.8582 - val_accuracy: 0.7657
Epoch 70/100
ccuracy: 0.9642 - val_loss: 1.8221 - val_accuracy: 0.7652
Epoch 71/100
ccuracy: 0.9653 - val_loss: 1.8333 - val_accuracy: 0.7652
Epoch 72/100
ccuracy: 0.9652 - val_loss: 1.9107 - val_accuracy: 0.7613
Epoch 73/100
ccuracy: 0.9648 - val_loss: 1.9037 - val_accuracy: 0.7624
Epoch 74/100
ccuracy: 0.9649 - val_loss: 1.8622 - val_accuracy: 0.7713
ccuracy: 0.9641 - val_loss: 1.8870 - val_accuracy: 0.7646
Epoch 76/100
15/15 [============== ] - 0s 16ms/step - loss: 0.0672 - a
ccuracy: 0.9631 - val_loss: 1.9351 - val_accuracy: 0.7646
Epoch 77/100
ccuracy: 0.9637 - val_loss: 1.9130 - val_accuracy: 0.7674
Epoch 78/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0635 - a
ccuracy: 0.9626 - val_loss: 1.9478 - val_accuracy: 0.7596
Epoch 79/100
ccuracy: 0.9652 - val_loss: 1.8416 - val_accuracy: 0.7730
```

```
Epoch 80/100
15/15 [============= ] - 0s 16ms/step - loss: 0.0643 - a
ccuracy: 0.9630 - val_loss: 1.9713 - val_accuracy: 0.7641
Epoch 81/100
ccuracy: 0.9653 - val loss: 1.9284 - val accuracy: 0.7646
Epoch 82/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0613 - a
ccuracy: 0.9651 - val_loss: 2.0020 - val_accuracy: 0.7663
Epoch 83/100
ccuracy: 0.9648 - val_loss: 1.9761 - val_accuracy: 0.7674
Epoch 84/100
15/15 [============== ] - 0s 17ms/step - loss: 0.0620 - a
ccuracy: 0.9649 - val_loss: 2.0416 - val_accuracy: 0.7679
Epoch 85/100
ccuracy: 0.9624 - val_loss: 2.0183 - val_accuracy: 0.7713
Epoch 86/100
ccuracy: 0.9658 - val_loss: 2.0991 - val_accuracy: 0.7613
Epoch 87/100
ccuracy: 0.9642 - val loss: 1.9240 - val accuracy: 0.7668
Epoch 88/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0608 - a
ccuracy: 0.9642 - val_loss: 2.0874 - val_accuracy: 0.7674
Epoch 89/100
ccuracy: 0.9651 - val_loss: 2.1437 - val_accuracy: 0.7563
Epoch 90/100
ccuracy: 0.9646 - val_loss: 2.0809 - val_accuracy: 0.7679
Epoch 91/100
ccuracy: 0.9634 - val_loss: 2.0892 - val_accuracy: 0.7652
Epoch 92/100
ccuracy: 0.9648 - val_loss: 2.1635 - val_accuracy: 0.7646
Epoch 93/100
ccuracy: 0.9651 - val_loss: 2.1794 - val_accuracy: 0.7629
Epoch 94/100
ccuracy: 0.9646 - val_loss: 2.1834 - val_accuracy: 0.7602
Epoch 95/100
15/15 [============= ] - 0s 20ms/step - loss: 0.0601 - a
ccuracy: 0.9631 - val_loss: 2.2312 - val_accuracy: 0.7635
Epoch 96/100
ccuracy: 0.9628 - val_loss: 2.2918 - val_accuracy: 0.7529
Epoch 97/100
15/15 [============= ] - 0s 17ms/step - loss: 0.0601 - a
ccuracy: 0.9645 - val_loss: 2.1830 - val_accuracy: 0.7674
Epoch 98/100
ccuracy: 0.9640 - val_loss: 2.1945 - val_accuracy: 0.7629
```





Training and validation accuracy



Out[]: <keras.callbacks.History at 0x2cb18bfd0>

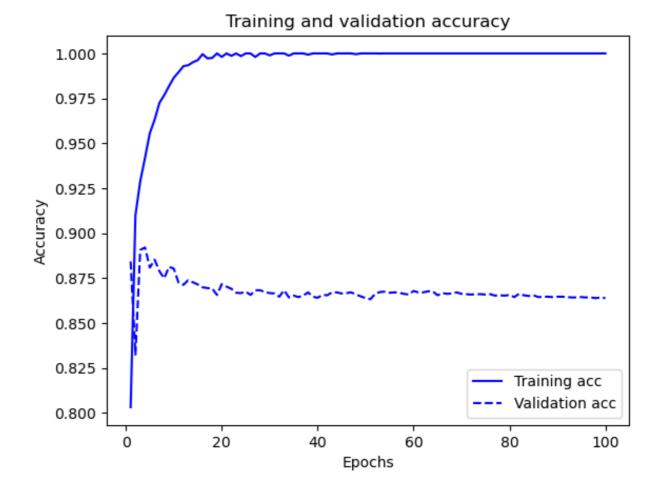
In []: # evaluting the Reuters model
 reuters.evaluate()

ccuracy: 0.7542

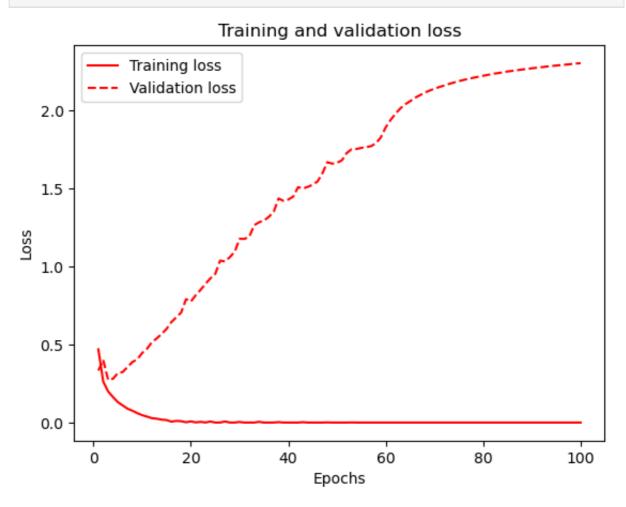
[INFO] Test loss: 2.214082956314087

[INFO] Test accuracy: 0.7542297840118408

In []: # plotting Reuters accuracy
reuters.plot_accuracy(history)



In []: # plotting Reuters loss history
reuters.plot_loss(history)



the Boston_Housing class

```
In [ ]: #import os
        #os.environ['CUDA_VISIBLE_DEVICES'] = '-1'
        # Import packages
        import numpy as np
        from tensorflow import keras
        from tensorflow.keras import layers
        #from tensorflow.keras.datasets import boston_housing
        #from sklearn.model_selection import train_test_split
        import matplotlib.pyplot as plt
        # default values
        NUM WORDS = 10000
        BATCH_SIZE = 512
        class Boston_Housing:
            def __init__(self):
                self.x_train, self.y_train, \
                self.x_test, self.y_test = self._load()
                self.model = self._model()
            def _load(self):
                 (x_train, y_train), (x_test, y_test) = keras.datasets.boston_hous
                # vectorize reviews
                mean=x_train.mean(axis=0)
                x_train-=mean
                std=x_train.std(axis=0)
                x_train/=std
                x_test==mean
                x_test/=std
                return x_train, y_train, x_test, y_test
            def model(self):
                model = keras.Sequential([
                     layers.Dense(64, activation="relu",input_shape=(self.x_train.
                     layers.Dense(64, activation="relu"),
                     layers.Dense(1)
                1)
                # model compilation
                model.compile(optimizer="rmsprop",
                                 loss="mse",
                                 metrics=["mae"])
                 return model
            def plot_loss(self, history):
                # Plotting the training and validation loss
                history_dict = history.history
```

```
loss_values = history_dict["loss"]
    val_loss_values = history_dict["val_loss"]
    epochs = range(1, len(loss_values) + 1)
    plt.figure(1)
    plt.plot(epochs, loss_values, "r", label="Training loss")
    plt.plot(epochs, val_loss_values, "r--", label="Validation loss")
    plt.title("Training and validation loss")
    plt.xlabel("Epochs")
    plt.ylabel("Loss")
    plt.legend()
    plt.show()
def plot_accuracy(self, history):
    history_dict = history.history
    acc = history_dict["mae"]
    val_acc = history_dict["val_mae"]
    epochs = range(1, len(acc) + 1)
    plt.figure(2)
    plt.plot(epochs, acc, "b", label="Training acc")
    plt.plot(epochs, val_acc, "b--", label="Validation acc")
    plt.title("Training and validation accuracy")
    plt.xlabel("Epochs")
    plt.ylabel("Accuracy")
    plt.legend()
    plt.show()
def train(self, epochs=20):
    if self.model is None:
        print('[INFO] model is not defined.')
        return
    history = self.model.fit(self.x_train, self.y_train, \
                             epochs = epochs, validation_split = 0.2,
                             batch size = BATCH SIZE)
    self.plot_loss(history)
    self.plot_accuracy(history)
    return history
def evaluate(self):
    score = self.model.evaluate(self.x test, self.y test)
    print(f'[INFO] Test loss: {score[0]}')
    print(f'[INFO] Test accuracy: {score[1]}')
def _vectorize_sequences(self, sequences, dimension=10000):
    results = np.zeros((len(sequences), dimension))
    for i, sequence in enumerate(sequences):
        for j in sequence:
            results[i, j] = 1.
    return results
def k_fold(self):
      num_val_samples = len(self.x_train) // k
      num epochs = 40
```

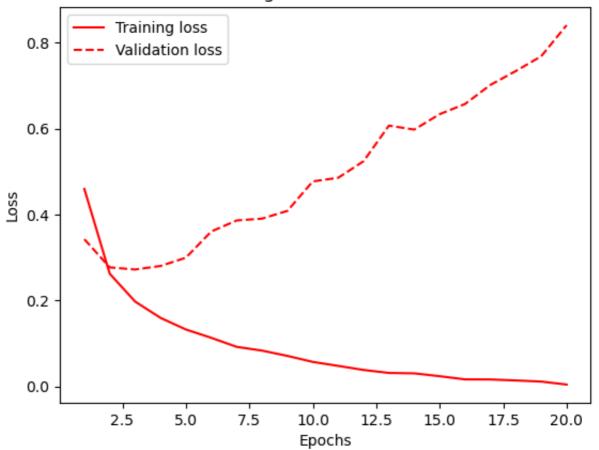
```
all_scores = []
                   for i in range(self, k):
                     print(f'Processing fold # {i}')
                     val_data = self.x_train[i * num_val_samples: (i+1) * num_val
                     val_targets = self.y_train[i * num_val_samples: (i+1) * num_
                     partial_train_data = np.concatenate(
                                              [self.x_train[:i * num_val_samples],
                                              self.x_train[(i+1) * num_val_samples
                                              axis=0)
                     partial_train_targets = np.concatenate(
                                              [self.y train[:i * num val samples],
                                              self.y_train[(i+1)*num_val_samples:]
                                              axis=0)
                     model = self.train()
                     model.fit(partial_train_data,
                                partial_train_targets,
                                epochs=num_epochs,
                                batch_size=16,
                                verbose=0)
                     val_mse, val_mae = model.evaluate(val_data, val_targets, ver
                     all_scores.append(val_mae)
In [ ]: # calling Boston_Housing class
        boston_housing = Boston_Housing()
In [ ]: from imdb import Imdb
        imdb=Imdb()
        imdb. load(num words=10000)
        imdb.train(epochs=20)
        imdb.evaluate()
            #%%
        #from reuters import Reuters
        reuters=Reuters()
        reuters._load(num_words=10000)
        reuters.train(epochs=30)
        reuters.evaluate()
        # Boston Housing price analysis
        # from boston_housing import Boston_Housing
        boston_housing= Boston_Housing()
        boston_housing._load()
        boston_housing.train(epochs=30)
        boston_housing.evaluate()
```

Epoch 1/20

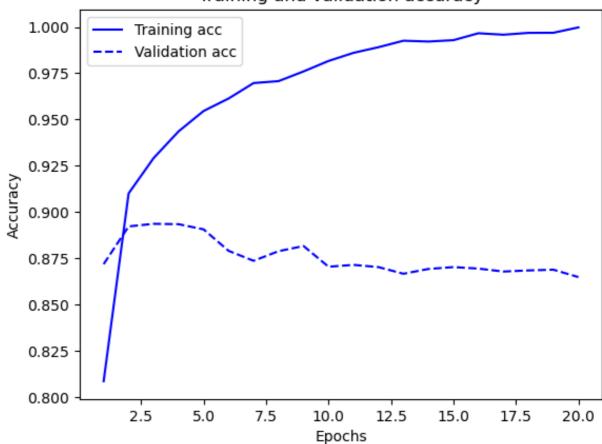
2022-11-14 22:36:28.753666: I tensorflow/core/grappler/optimizers/custom _graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i s enabled.

2022-11-14 22:36:29.736919: I tensorflow/core/grappler/optimizers/custom _graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i s enabled.

```
ccuracy: 0.9101 - val_loss: 0.2768 - val_accuracy: 0.8922
Epoch 3/20
40/40 [============== ] - 1s 15ms/step - loss: 0.1973 - a
ccuracy: 0.9292 - val_loss: 0.2718 - val_accuracy: 0.8936
Epoch 4/20
ccuracy: 0.9436 - val_loss: 0.2801 - val_accuracy: 0.8934
Epoch 5/20
40/40 [============= ] - 1s 13ms/step - loss: 0.1323 - a
ccuracy: 0.9546 - val loss: 0.2993 - val accuracy: 0.8906
40/40 [============= ] - 1s 13ms/step - loss: 0.1129 - a
ccuracy: 0.9614 - val_loss: 0.3603 - val_accuracy: 0.8790
40/40 [============= ] - 1s 13ms/step - loss: 0.0918 - a
ccuracy: 0.9697 - val_loss: 0.3860 - val_accuracy: 0.8736
Epoch 8/20
ccuracy: 0.9708 - val_loss: 0.3903 - val_accuracy: 0.8788
Epoch 9/20
ccuracy: 0.9760 - val_loss: 0.4083 - val_accuracy: 0.8816
Epoch 10/20
ccuracy: 0.9817 - val_loss: 0.4769 - val_accuracy: 0.8704
Epoch 11/20
40/40 [============= ] - 1s 14ms/step - loss: 0.0475 - a
ccuracy: 0.9861 - val_loss: 0.4852 - val_accuracy: 0.8714
Epoch 12/20
ccuracy: 0.9891 - val_loss: 0.5238 - val_accuracy: 0.8702
Epoch 13/20
ccuracy: 0.9926 - val_loss: 0.6067 - val_accuracy: 0.8666
Epoch 14/20
ccuracy: 0.9922 - val_loss: 0.5974 - val_accuracy: 0.8692
Epoch 15/20
40/40 [============= ] - 1s 13ms/step - loss: 0.0235 - a
ccuracy: 0.9929 - val_loss: 0.6334 - val_accuracy: 0.8702
Epoch 16/20
ccuracy: 0.9967 - val_loss: 0.6571 - val_accuracy: 0.8694
Epoch 17/20
ccuracy: 0.9959 - val_loss: 0.7014 - val_accuracy: 0.8678
ccuracy: 0.9969 - val_loss: 0.7337 - val_accuracy: 0.8684
Epoch 19/20
40/40 [============= ] - 1s 13ms/step - loss: 0.0111 - a
ccuracy: 0.9969 - val_loss: 0.7681 - val_accuracy: 0.8688
Epoch 20/20
ccuracy: 0.9998 - val_loss: 0.8404 - val_accuracy: 0.8648
```

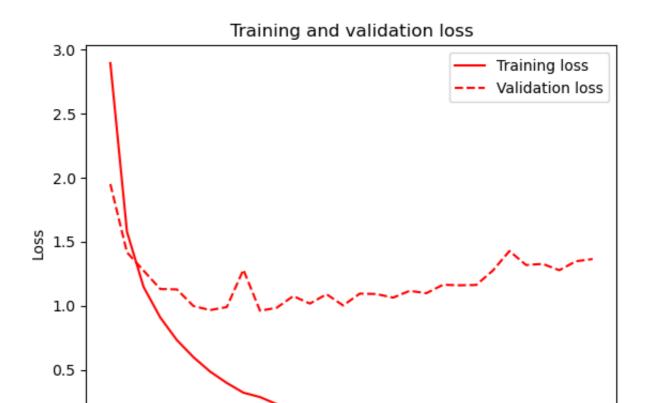


Training and validation accuracy



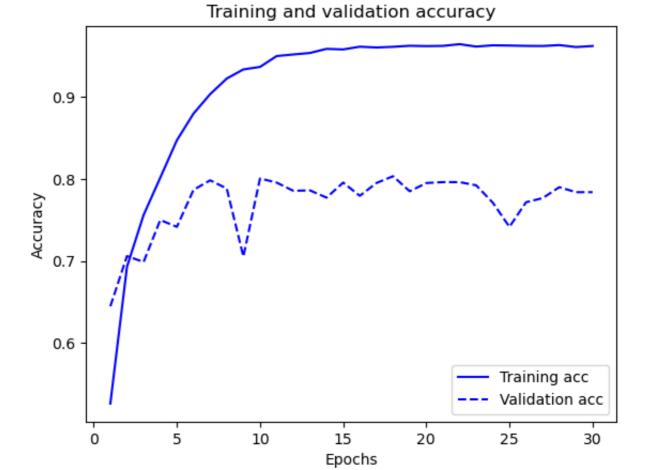
```
accuracy: 0.8432
[INFO] Test loss: 0.9275516271591187
[INFO] Test accuracy: 0.8432000279426575
Epoch 1/30
2022-11-14 22:36:46.892253: I tensorflow/core/grappler/optimizers/custom
_graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
s enabled.
ccuracy: 0.5264 - val_loss: 1.9488 - val_accuracy: 0.6450
Epoch 2/30
5/15 [=======>....] - ETA: 0s - loss: 1.7266 - accura
cv: 0.6762
2022-11-14 22:36:47.566312: I tensorflow/core/grappler/optimizers/custom
_graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
s enabled.
15/15 [============= ] - 0s 19ms/step - loss: 1.5767 - a
ccuracy: 0.6931 - val_loss: 1.4160 - val_accuracy: 0.7062
Epoch 3/30
15/15 [============= ] - 0s 18ms/step - loss: 1.1454 - a
ccuracy: 0.7563 - val_loss: 1.2732 - val_accuracy: 0.6989
Epoch 4/30
15/15 [============= ] - 0s 17ms/step - loss: 0.9079 - a
ccuracy: 0.8017 - val_loss: 1.1303 - val_accuracy: 0.7501
Epoch 5/30
ccuracy: 0.8473 - val_loss: 1.1269 - val_accuracy: 0.7418
Epoch 6/30
ccuracy: 0.8799 - val_loss: 0.9965 - val_accuracy: 0.7869
Epoch 7/30
ccuracy: 0.9035 - val_loss: 0.9655 - val_accuracy: 0.7986
Epoch 8/30
ccuracy: 0.9226 - val_loss: 0.9888 - val_accuracy: 0.7885
Epoch 9/30
ccuracy: 0.9338 - val_loss: 1.2804 - val_accuracy: 0.7056
Epoch 10/30
ccuracy: 0.9368 - val_loss: 0.9601 - val_accuracy: 0.8008
Epoch 11/30
ccuracy: 0.9500 - val_loss: 0.9833 - val_accuracy: 0.7958
Epoch 12/30
ccuracy: 0.9520 - val_loss: 1.0748 - val_accuracy: 0.7858
15/15 [============== ] - 0s 18ms/step - loss: 0.1856 - a
ccuracy: 0.9538 - val_loss: 1.0161 - val_accuracy: 0.7863
Epoch 14/30
15/15 [============= ] - 0s 18ms/step - loss: 0.1593 - a
ccuracy: 0.9588 - val_loss: 1.0894 - val_accuracy: 0.7774
Epoch 15/30
```

```
ccuracy: 0.9581 - val_loss: 1.0015 - val_accuracy: 0.7958
Epoch 16/30
ccuracy: 0.9614 - val_loss: 1.0939 - val_accuracy: 0.7796
Epoch 17/30
ccuracy: 0.9605 - val_loss: 1.0909 - val_accuracy: 0.7952
Epoch 18/30
15/15 [============= ] - 0s 18ms/step - loss: 0.1189 - a
ccuracy: 0.9613 - val_loss: 1.0626 - val_accuracy: 0.8036
Epoch 19/30
ccuracy: 0.9626 - val_loss: 1.1155 - val_accuracy: 0.7852
Epoch 20/30
ccuracy: 0.9621 - val_loss: 1.0971 - val_accuracy: 0.7952
Epoch 21/30
15/15 [============= ] - 0s 18ms/step - loss: 0.1048 - a
ccuracy: 0.9624 - val_loss: 1.1629 - val_accuracy: 0.7963
Epoch 22/30
15/15 [============= ] - 0s 18ms/step - loss: 0.1014 - a
ccuracy: 0.9645 - val_loss: 1.1591 - val_accuracy: 0.7963
Epoch 23/30
ccuracy: 0.9616 - val_loss: 1.1614 - val_accuracy: 0.7924
Epoch 24/30
15/15 [============ ] - 0s 18ms/step - loss: 0.0955 - a
ccuracy: 0.9631 - val_loss: 1.2738 - val_accuracy: 0.7713
Epoch 25/30
ccuracy: 0.9628 - val_loss: 1.4268 - val_accuracy: 0.7418
Epoch 26/30
15/15 [============== ] - 0s 17ms/step - loss: 0.0966 - a
ccuracy: 0.9624 - val_loss: 1.3171 - val_accuracy: 0.7718
Epoch 27/30
ccuracy: 0.9623 - val_loss: 1.3261 - val_accuracy: 0.7769
Epoch 28/30
ccuracy: 0.9634 - val_loss: 1.2766 - val_accuracy: 0.7902
Epoch 29/30
15/15 [============= ] - 0s 18ms/step - loss: 0.0906 - a
ccuracy: 0.9610 - val loss: 1.3465 - val accuracy: 0.7841
Epoch 30/30
15/15 [============= ] - 0s 17ms/step - loss: 0.0891 - a
ccuracy: 0.9623 - val_loss: 1.3637 - val_accuracy: 0.7841
```



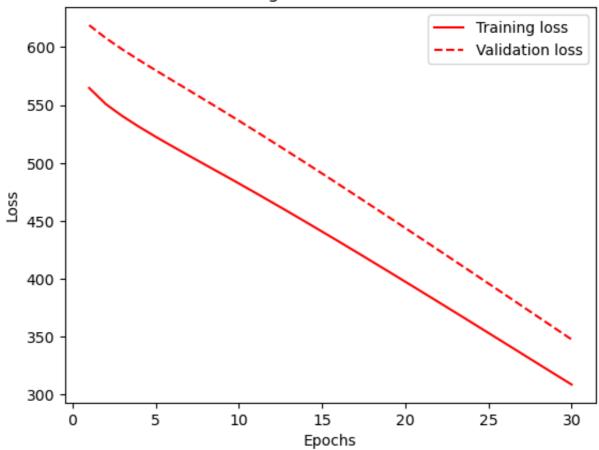
Epochs

0.0

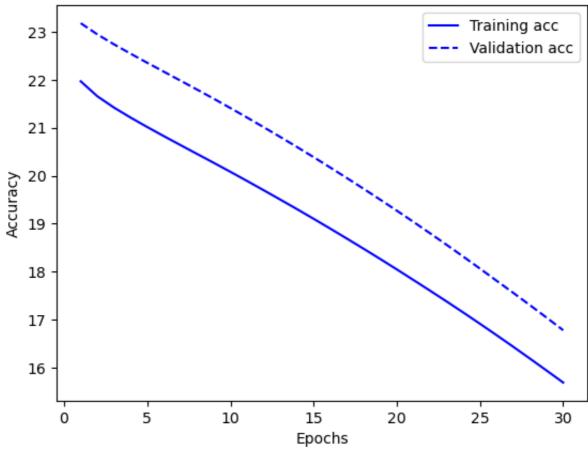


```
ccuracy: 0.7729
[INFO] Test loss: 1.4664809703826904
[INFO] Test accuracy: 0.7729296684265137
Epoch 1/30
1/1 [============= ] - ETA: 0s - loss: 564.7747 - mae: 2
1.9693
2022-11-14 22:36:56.467337: I tensorflow/core/grappler/optimizers/custom
_graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
mae: 21.9693 - val_loss: 618.9827 - val_mae: 23.1810
1/1 [============ ] - 0s 50ms/step - loss: 550.8596 - m
ae: 21.6566 - val_loss: 607.8082 - val_mae: 22.9473
Epoch 3/30
1/1 [============= ] - 0s 30ms/step - loss: 540.4371 - m
ae: 21.4212 - val_loss: 597.9879 - val_mae: 22.7399
Epoch 4/30
ae: 21.2123 - val_loss: 588.8207 - val_mae: 22.5445
Epoch 5/30
1.0154
2022-11-14 22:36:56.694447: I tensorflow/core/grappler/optimizers/custom
_graph_optimizer_registry.cc:114] Plugin optimizer for device_type GPU i
s enabled.
ae: 21.0154 - val_loss: 579.9846 - val_mae: 22.3551
Epoch 6/30
1/1 [============ ] - 0s 29ms/step - loss: 514.4047 - m
ae: 20.8254 - val_loss: 571.3124 - val_mae: 22.1685
Epoch 7/30
1/1 [=========== ] - 0s 28ms/step - loss: 506.3159 - m
ae: 20.6384 - val_loss: 562.7026 - val_mae: 21.9825
1/1 [=========== ] - 0s 28ms/step - loss: 498.3360 - m
ae: 20.4535 - val_loss: 554.0555 - val_mae: 21.7953
Epoch 9/30
ae: 20.2687 - val_loss: 545.3280 - val_mae: 21.6052
Epoch 10/30
ae: 20.0815 - val_loss: 536.4844 - val_mae: 21.4111
Epoch 11/30
1/1 [=========== ] - 0s 29ms/step - loss: 474.2122 - m
ae: 19.8909 - val_loss: 527.5212 - val_mae: 21.2130
Epoch 12/30
ae: 19.6973 - val_loss: 518.4819 - val_mae: 21.0118
Epoch 13/30
1/1 [============= ] - 0s 29ms/step - loss: 457.6729 - m
ae: 19.5018 - val_loss: 509.3884 - val_mae: 20.8075
Epoch 14/30
1/1 [=========== ] - 0s 44ms/step - loss: 449.2865 - m
ae: 19.3037 - val_loss: 500.2132 - val_mae: 20.5994
```

```
Epoch 15/30
1/1 [=========== ] - 0s 31ms/step - loss: 440.8206 - m
ae: 19.1022 - val_loss: 490.9606 - val_mae: 20.3874
Epoch 16/30
1/1 [=========== ] - 0s 28ms/step - loss: 432.2888 - m
ae: 18.8975 - val loss: 481.6207 - val mae: 20.1713
Epoch 17/30
ae: 18.6892 - val_loss: 472.2291 - val_mae: 19.9516
Epoch 18/30
1/1 [============= ] - 0s 29ms/step - loss: 415.0319 - m
ae: 18.4788 - val_loss: 462.8207 - val_mae: 19.7287
Epoch 19/30
1/1 [============ ] - 0s 31ms/step - loss: 406.3150 - m
ae: 18.2647 - val_loss: 453.3689 - val_mae: 19.5021
Epoch 20/30
ae: 18.0472 - val_loss: 443.8889 - val_mae: 19.2720
Epoch 21/30
ae: 17.8259 - val_loss: 434.3673 - val_mae: 19.0378
Epoch 22/30
1/1 [=========== ] - 0s 26ms/step - loss: 379.9724 - m
ae: 17.6031 - val loss: 424.8190 - val mae: 18.7998
Epoch 23/30
1/1 [============ ] - 0s 27ms/step - loss: 371.1253 - m
ae: 17.3770 - val_loss: 415.2525 - val_mae: 18.5583
Epoch 24/30
ae: 17.1471 - val_loss: 405.6491 - val_mae: 18.3128
Epoch 25/30
1/1 [============ ] - 0s 26ms/step - loss: 353.3479 - m
ae: 16.9131 - val_loss: 396.0240 - val_mae: 18.0634
Epoch 26/30
1/1 [=========== ] - 0s 26ms/step - loss: 344.4354 - m
ae: 16.6754 - val_loss: 386.3694 - val_mae: 17.8097
Epoch 27/30
1/1 [============ ] - 0s 26ms/step - loss: 335.5133 - m
ae: 16.4337 - val_loss: 376.6990 - val_mae: 17.5580
Epoch 28/30
ae: 16.1879 - val_loss: 367.0369 - val_mae: 17.3025
1/1 [============= ] - 0s 28ms/step - loss: 317.6822 - m
ae: 15.9391 - val_loss: 357.3693 - val_mae: 17.0426
Epoch 30/30
1/1 [============ ] - 0s 27ms/step - loss: 308.7940 - m
ae: 15.6878 - val_loss: 347.7158 - val_mae: 16.7785
```



Training and validation accuracy



```
ae: 16.1766
        [INFO] Test loss: 326.21868896484375
        [INFO] Test accuracy: 16.176576614379883
In [ ]: import cv2
        import mediapipe as mp
        mp_drawing = mp.solutions.drawing_utils
        mp_drawing_styles = mp.solutions.drawing_styles
        mp_pose = mp.solutions.pose
        # For webcam input:
        cap = cv2.VideoCapture(0)
        with mp_pose.Pose(
            min detection confidence=0.5.
            min_tracking_confidence=0.5) as pose:
          while cap.isOpened():
            success, image = cap.read()
            if not success:
              print("Ignoring empty camera frame.")
              # If loading a video, use 'break' instead of 'continue'.
              continue
            # To improve performance, optionally mark the image as not writeable
            # pass by reference.
            image.flags.writeable = False
            image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
            results = pose.process(image)
            # Draw the pose annotation on the image.
            image.flags.writeable = True
            image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)
            mp_drawing.draw_landmarks(
                image,
                results.pose_landmarks,
                mp_pose.POSE_CONNECTIONS,
                landmark_drawing_spec=mp_drawing_styles.get_default_pose_landmark
            # Flip the image horizontally for a selfie-view display.
            cv2.imshow('MediaPipe Pose', cv2.flip(image, 1))
            if cv2.waitKey(5) & 0xFF == 27:
              break
        cap.release()
        OpenCV: not authorized to capture video (status 0), requesting...
        OpenCV: camera failed to properly initialize!
```

```
In []: import cv2
        import mediapipe as mp
        mp_drawing = mp.solutions.drawing_utils
        mp_drawing_styles = mp.solutions.drawing_styles
        mp_hands = mp.solutions.hands
        # For webcam input:
        cap = cv2.VideoCapture(0)
        with mp_hands.Hands(
            model_complexity=0,
            min_detection_confidence=0.5,
            min_tracking_confidence=0.5) as hands:
          while cap.isOpened():
            success, image = cap.read()
            if not success:
              print("Ignoring empty camera frame.")
              # If loading a video, use 'break' instead of 'continue'.
              continue
            # To improve performance, optionally mark the image as not writeable
            # pass by reference.
            image.flags.writeable = False
            image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
            results = hands.process(image)
            # Draw the hand annotations on the image.
            image.flags.writeable = True
            image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)
            if results.multi_hand_landmarks:
              for hand_landmarks in results.multi_hand_landmarks:
                mp_drawing.draw_landmarks(
                    image,
                    hand_landmarks,
                    mp_hands.HAND_CONNECTIONS,
                    mp_drawing_styles.get_default_hand_landmarks_style(),
                    mp_drawing_styles.get_default_hand_connections_style())
            # Flip the image horizontally for a selfie-view display.
            cv2.imshow('MediaPipe Hands', cv2.flip(image, 1))
            if cv2.waitKey(5) & 0xFF == 27:
              break
        cap.release()
```

In []: