

Computer Vision Assignment-1

Theory

Ans. 1:- Given: No. of Classes = K

True Class Label as One-hot encoded vector $y \in \{0, 1\}^K$, $\|y\|_1 = 1$

Prob. Distribution over class

$$q = [q_1, q_2, q_3, \dots, q_K], \quad \sum_{i=1}^K q_i = 1, \quad q_i \geq 0$$

Label Smoothing \rightarrow

Add ϵ/K to each incorrect class

& Add $1 - \epsilon + \epsilon/K$ to each correct class

$$(a) H(p, q) = E_p[-\log q(x)]$$

, where p & q are two arbitrary distributions;
 x is a Random Variable;

$H(p, q)$ is the cross-entropy b/w p & q .

It is given that, for Label Smoothing, regularisation is done by adding a small probability in order to reward the model for correct predictions & penalise it for the incorrect ones.

Mathematically,

$$p_i = \begin{cases} \epsilon/K & , i \neq y \\ 1 - \epsilon + \epsilon/K & , i = y \end{cases}$$

\therefore , Cross Entropy Loss with Label Smoothing
 $H(y, q) \rightarrow$

$$H(y, q) = - \sum_{i=1}^K p_i \log q_i$$

$$= - \left(\left(1 - \epsilon + \frac{\epsilon}{K} \right) \log q_y \right) - \sum_{i \neq y} \frac{\epsilon}{K} \log q_i$$

$$= - \frac{\epsilon}{K} \sum_{i=1}^K \log q_i + (\epsilon - 1) \log q_y$$

$$= - \left(\frac{\epsilon}{K} \sum_{i=1}^K \log q_i - (1 - \epsilon) \log q_y \right)$$

(b) Effect of Label Smoothing \rightarrow

- * Prevents Overfitting by adding a regularisation term to the loss function to penalise it for incorrect predictions.
- * Since Label Smoothing is aimed at reducing overfitting, it acts as a regularisation technique where it ensure the model logits are constrained within a finite range, thus avoiding the chance of extreme probabilities, thereby making the model more generalised (less biased) which eventually results in efficient/stable training.

Ans 2: - (a) Given \rightarrow Two Univariate Gaussian Distributions

$$p(x) = \mathcal{N}(\mu_p, \sigma_p^2)$$

$$q(x) = \mathcal{N}(\mu_q, \sigma_q^2)$$

(a) Cross Entropy b/w $p(x)$ & $q(x)$ as an expectation \rightarrow

$$H(p, q) = - E_{p(x)} [\log q(x)]$$

(b) We know that,

$$q(x) = \frac{1}{\sqrt{2\pi\sigma_q^2}} e^{-\frac{(x-\mu_q)^2}{2\sigma_q^2}} \quad \text{--- (1)}$$

, acc. to the formula of Gaussian Distribution

$$\therefore, H(p, q) = -E_{p(x)} [\log q(x)]$$

$$= -E_{p(x)} \left[\log \left(\frac{1}{\sqrt{2\pi\sigma_q^2}} e^{-\frac{(x-\mu_q)^2}{2\sigma_q^2}} \right) \right] \quad (\text{from (1)})$$

$$= -E_{p(x)} \left[\frac{-1}{2} \log(2\pi\sigma_q^2) - \frac{(x-\mu_q)^2}{2\sigma_q^2} \right]$$

$$= \frac{1}{2} \log(2\pi\sigma_q^2) + \frac{1}{2\sigma_q^2} E_{p(x)} [(x-\mu_q)^2]$$

$$= \frac{1}{2} \left[\log(2\pi\sigma_q^2) + \frac{1}{\sigma_q^2} E_{p(x)} [(x-\mu_q)^2] \right]$$

$$\therefore, p(x) = \mathcal{N}(\mu_p, \sigma_p^2)$$

$$\therefore, H(p, q) = \frac{1}{2} \left[\log(2\pi\sigma_q^2) + \frac{\sigma_p^2 + (\mu_p - \mu_q)^2}{\sigma_q^2} \right]$$

(c) For $\sigma_p = \sigma_q = \sigma$

$$H(p, q) = \frac{1}{2} \left[\log(2\pi\sigma^2) + \frac{\sigma^2 + (\mu_p - \mu_q)^2}{\sigma^2} \right]$$

$$= \frac{1}{2} \left[\log(2\pi\sigma^2) + 1 + \frac{(\mu_p - \mu_q)^2}{\sigma^2} \right]$$

If $p = q$,

$$H(p) = \frac{1}{2} [\log(2\pi\sigma^2) + 1] \quad \text{--- ①}$$

Using ①, we can infer

$$H(p, q) = H(p) + \frac{(\mu_p - \mu_q)^2}{2\sigma^2}$$

Thus, $H(p, q)$ is a sum of $H(p)$ & a regularisation term when variances are equal.

The extent of regularisation increases as the size of the penalty increases when the mean difference b/w the two distribution increase.