

BSc (Hons) in Information Technology Year 1

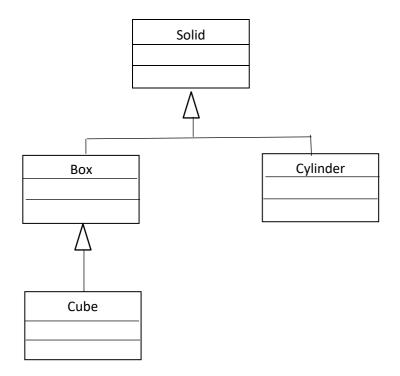
Lab Exercise 12

IT1050 – Object Oriented Concepts

Semester 1, 2023

Objectives:

• Implementing Inheritance relationship.



a) Implement the Solid class

```
class Solid {
  public:
      Solid(); // default constructor
      virtual float volume();
      virtual float surfaceArea();
};
```

Note: The content of the functions and constructor is blank



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b) Implement the Box derived class.

class Box : public Solid

Hint: Use protected instead of private for the properties for all classes.

You should have the following properties.

length, width, height

Implement the *volume()* and *surfaceArea()* methods

volume = length x width x height

surfaceArea = 2x(length x width + length x height + width x height)

c) Implement the Cylinder derived class.

class Cylinder : public Solid

Hint: Use protected instead of private for the properties for all classes.

You should have the following properties.

radius, height

Implement the volume() and surfaceArea() methods



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```
volume = height x pi x radius<sup>2</sup>
surfaceArea = height x 2 x pi x radius + 2 x pi x radius<sup>2</sup>
```

e) Implement the Cube class to derive from the Box class

```
class Cube : public Box
```

Note: You can assign to length, width and height the value mlength that you get from the constructor. You don't need to redefine volume () or surfaceArea() methods again.

Note: The #ifndef function is used to check if there is a definition of _CUBE. This is to prevent the Cube.h code being executed more than one time (which results in an error). Do this for the other header files as well (use unique identifiers for each header file). You do not need to redefine volume() and surfaceArea() functions in Cube since it is defined in the Box class.



}

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- g) Implement a main program where you have objects of all the classes, calculate and print their areas and perimeters.
- h) Implement an array of Solid objects and calculate the total area and total perimeter of the shapes.

```
// Modify this code that prints the area and perimeter of the 3 shapes
```

```
Solid *solids[5];
solids[0] = new Box(10,5,4);
solids[1] = new Cylinder(5, 10);
solids[2] = new Cube(20);

for (int r=0; r<3; r++) {
    cout << "Solids : " << r << endl;
    cout << solids[r]->volume() << endl;</pre>
```

cout << solids[r]->surfaceArea() << endl;</pre>