Lens Design Lecture #1

College of Optical Sciences University of Arizona



What is imaging?

Photo credit: Gary Mackender







Imaging with rays: theories

Maxwell's Ideal:

- 1) Each point is imaged stigmatically
- 2) The images of all points in an object plane lie on an image plane
- 3) The ratio of image to heights to object heights is the same for all points.

Collinear transformation

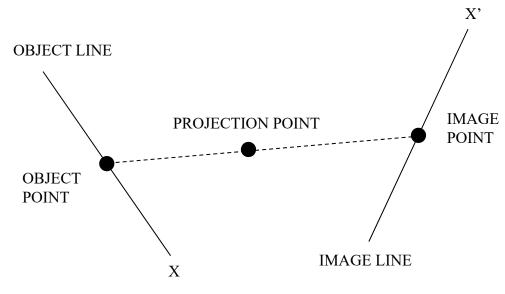
$$X' = \frac{a_1 X + b_1 Y + c_1 Z + d_1}{a_0 X + b_0 Y + c_0 Z + d_0} \qquad Y' = \frac{a_2 X + b_2 Y + c_2 Z + d_2}{a_0 X + b_0 Y + c_0 Z + d_0} \qquad Z' = \frac{a_3 X + b_3 Y + c_3 Z + d_3}{a_0 X + b_0 Y + c_0 Z + d_0}$$

$$Y = \frac{a_2X + b_2Y + c_2Z + d_2}{a_0X + b_0Y + c_0Z + d_0}$$

$$Z' = \frac{a_3 X + b_3 Y + c_3 Z + d_3}{a_0 X + b_0 Y + c_0 Z + d_0}$$



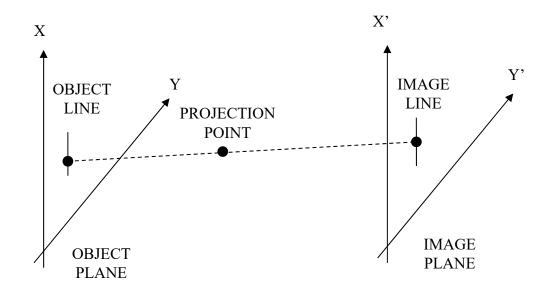
Central Projection 1D



$$X' = \frac{a_1 X}{a_0 X + b_0}$$



Central Projection 2D



$$X' = \frac{a_1 X}{a_0 X + b_0 Y + c_0} \qquad Y' = \frac{a_2 Y}{a_0 X + b_0 Y + c_0}$$



Central Projection 3D

$$X' = \frac{a_1 X + b_1 Y + c_1 Z + d_1}{a_0 X + b_0 Y + c_0 Z + d_0}$$

$$Y = \frac{a_2X + b_2Y + c_2Z + d_2}{a_0X + b_0Y + c_0Z + d_0}$$

$$Z' = \frac{a_3 X + b_3 Y + c_3 Z + d_3}{a_0 X + b_0 Y + c_0 Z + d_0}$$

Point into points, lines into lines, and planes into planes.

Axial symmetry I

$$\rho = \sqrt{x^2 + y^2}$$
 $\rho' = \sqrt{x'^2 + y'^2}$

 ρ^{ι} and Z' must be only a function of ρ and Z, leads to:

$$X' = \frac{a_1 X}{c_0 Z + d_0} \qquad Y' = \frac{a_1 Y}{c_0 Z + d_0} \qquad Z' = \frac{c_3 Z + d_3}{c_0 Z + d_0}$$

- •Origins transform into the origins: d3=0
- Origins located at the planes of unit magnification implies: a1 equal to d0



Axial Symmetry II

$$X' = \frac{X}{c_0 Z + 1}$$
 $Y' = \frac{Y}{c_0 Z + 1}$ $Z' = \frac{c_3 Z}{c_0 Z + 1}$

$$Y' = \frac{Y}{c_0 Z + 1}$$

$$Z' = \frac{c_3 Z}{c_0 Z + 1}$$

$$m = \frac{1}{c_0 Z + 1}$$

$$Z' = f' = \frac{c_3}{c_0}$$

$$m = \frac{1}{c_0 Z + 1}$$
 $Z' = f' = \frac{c_3}{c_0}$ $Z = f = \frac{-1}{c_0}$



Gaussian equations

$$\frac{Z}{f} = 1 - \frac{1}{m}$$

$$m = \frac{1}{1 - Z \setminus f}$$

$$\frac{Z'}{f'} = 1 - m$$

$$\frac{f'}{Z'} + \frac{f}{Z} = 1$$



Newtonian Equations

$$\frac{Z}{f} = -\frac{1}{m}$$

$$ZZ' = ff'$$

$$\frac{Z'}{f'} = - m$$

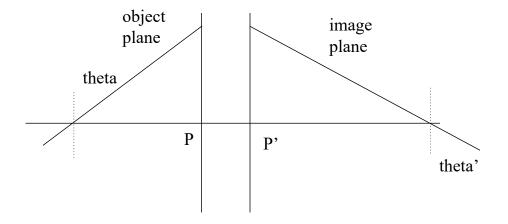


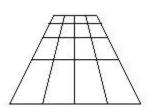
Scheimpflug condition

(Plane symmetry)

$$tan(\theta') - (Z' \backslash Z) tan(\theta) = 0$$







Scheimpflug construction

$$X' = m \frac{X}{1 + KY}$$

$$Y' = m \frac{Y}{1 + KY}$$

$$X' = m \frac{X}{1 + KY} \qquad Y' = m \frac{Y}{1 + KY} \qquad K = -m \frac{\tan(\theta)}{f} = \frac{\tan(\theta')}{f'}$$



Civil War 1859



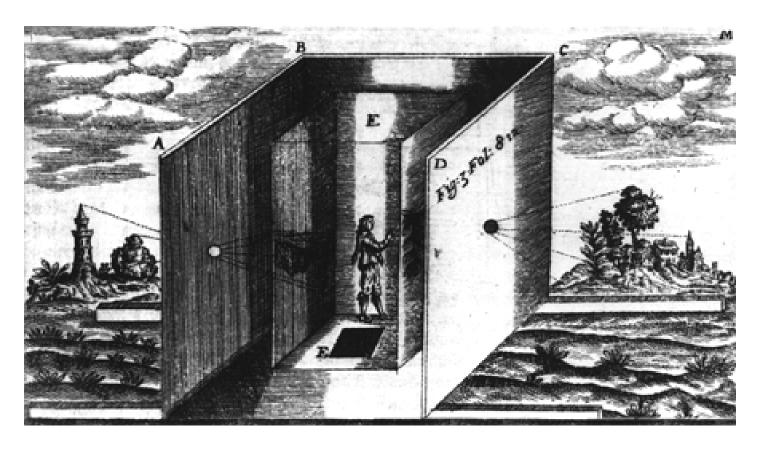


And much more...

- Gaussian equations
- Newtonian equations
- Anamorphic systems
- Focal and afocal systems
- Scheimpflug condition
- Cardinal points
- Keystone distortion
- •...and much more!



Collinear transformation, camera obscura and lenses



Camera Obscura, Athanasius Kircher, 1646



The secret in Vermeer's paintings



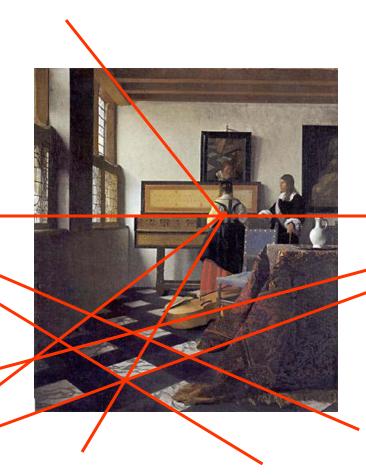




Johannes Vermeer, XVII century



Perspective of the painting



$$f = 68 \ cm$$

$$D = f \times \tan(\theta) = f \tan(45^\circ)$$

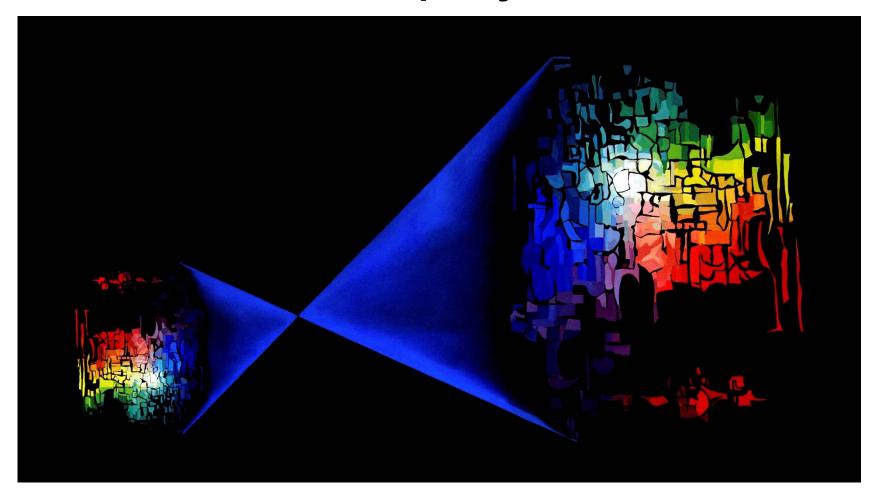


However...

- Image parity issues
- Needed a flat mirror or
- To copy again the image



Central projection





Other "perspectives"





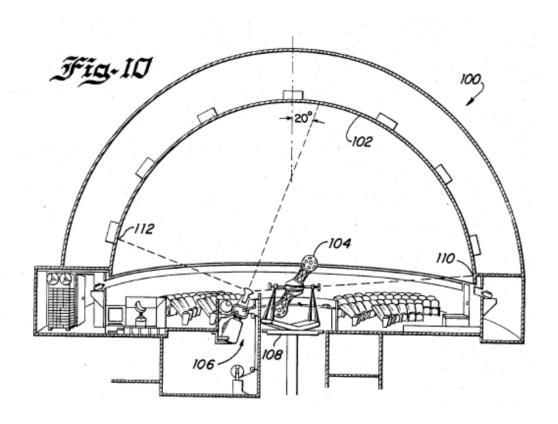


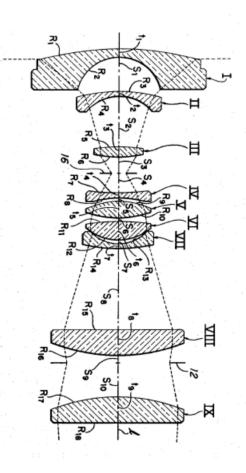
Classical Impressionism Cubism

A plurality of new and exciting new concepts in imaging



Imaging on the sphere







IPAD Imaging



Prof. Jose Sasian

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Class summary

- Syllabus
- Imaging
- Collinear transformation
- Art application
- Codev, OSLO, Zemax
- Review of first-order optics

