An analysis of the ability reinforcement learning methods to cooperate in infinitely repeated games

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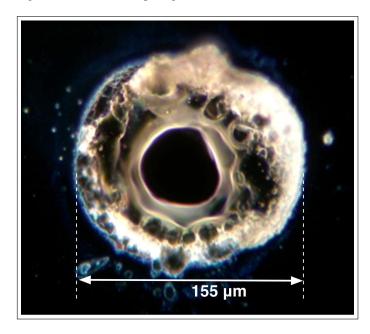


Fig. 1. Dark-field image of a point absorber.

B. Sample Table

Table 1 shows an example table.

Table 1. Shape Functions for Quadratic Line Elements

local node	$\{N\}_m$	$\{\Phi_i\}_m \ (i=x,y,z)$
m = 1	$L_1(2L_1-1)$	Φ_{i1}
m = 2	$L_2(2L_2-1)$	Φ_{i2}
m = 3	$L_3 = 4L_1L_2$	Φ_{i3}

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4. SAMPLE EQUATION

Let X_1, X_2, \dots, X_n be a sequence of independent and identically distributed random variables with $E[X_i] = \mu$ and $Var[X_i] =$ $\sigma^2 < \infty$, and let

$$S_n = \frac{X_1 + X_2 + \dots + X_n}{n} = \frac{1}{n} \sum_{i=1}^{n} X_i$$
 (1)

denote their mean. Then as n approaches infinity, the random variables $\sqrt{n}(S_n - \mu)$ converge in distribution to a normal 34 35

5. SAMPLE ALGORITHM

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Algorithms can be included using the commands as shown in algorithm 1.

Algorithm 1. Euclid's algorithm

1: procedure EUCLID(<i>a</i> , <i>b</i>)		⊳ The g.c.d. of a and b
2:	$r \leftarrow a \bmod b$	
3:	while $r \neq 0$ do	\triangleright We have the answer if r is 0
4:	$a \leftarrow b$	
5:	$b \leftarrow r$	
6:	$r \leftarrow a \bmod b$	
7:	return b	⊳ The gcd is b

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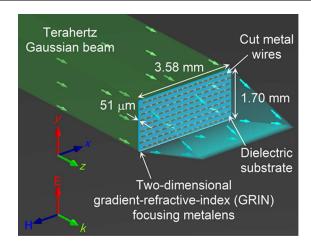


Fig. 2. Terahertz focusing metalens.

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