

# Markov chains – first steps

## A not very exciting game

Consider a game with a playing board consisting of squares numbered 1-10 arranged in a circle. A player starts at square 1. At each turn, the player rolls a die and moves around the board by the number of spaces shown on the face of the die.

Let  $X_k$  be the position of the player after  $k$  moves (with  $X_0 = 1$ ). For example, assume that the player successively rolls 2, 1, and 4. The first four positions are:

- $X_0 = 1$
- $X_1 = 3$
- $X_2 = 4$
- $X_3 = 8$ .

Given this information, what can be said about the player's next location?

## A not very exciting game - cont'd

Even though we know the player's full past history of moves, the only information relevant for predicting a future position is the most recent location  $X_3$ . Since  $X_3 = 8$ , then necessarily

$$X_4 \in \{9, 10, 1, 2, 3, 4\},$$

with equal probabilities, so

$$\mathbb{P}(X_4 = j | X_0 = 1, X_1 = 3, X_2 = 4, X_3 = 8) = \mathbb{P}(X_4 = j | X_3 = 8) = \frac{1}{6}$$

for  $j = 9, 10, 1, 2, 3, 4$ . Given the player's most recent location  $X_3$ , her/his future position  $X_4$  is independent of past history  $X_0, X_1, X_2$ .

# Markov chains

## Definition 1

Let  $S$  be a discrete set. A **(discrete-time) Markov chain** with the state space  $S$  is a sequence of random variables  $X_0, X_1, \dots$ , denoted as  $(X_n)_{n \in \mathbb{N}_0}$ , taking values in  $S$  such that for all  $n = 0, 1, 2, \dots$ , and for all  $x_0, x_1, \dots, x_n, x_{n+1} \in S$

$$\begin{aligned}\mathbb{P}(X_{n+1} = x_{n+1} | X_0 = x_0, \dots, X_n = x_n) \\ = \mathbb{P}(X_{n+1} = x_{n+1} | X_n = x_n) .\end{aligned}$$

This is the so called **Markov property** - for a Markov chain the future, given the present, is independent of the past.

# Time-homogeneity

## Definition 2

A Markov chain  $(X_n)_n$  is *time-homogeneous* if

$$\mathbb{P}(X_{n+1} = j | X_n = i) = \mathbb{P}(X_1 = j | X_0 = i)$$

for all  $i, j \in S$  and  $n = 0, 1, 2, \dots$

### Example 3

As an example of a **time-homogeneous Markov chain**, we can consider the following random process with two states  $S = \{1, 2\}$ .

We assume that for  $n = 0, 1, 2, \dots$

- $\mathbb{P}(X_{n+1} = 1 | X_n = 1) = 0.2,$
- $\mathbb{P}(X_{n+1} = 2 | X_n = 1) = 0.8,$
- $\mathbb{P}(X_{n+1} = 1 | X_n = 2) = 0.5,$
- $\mathbb{P}(X_{n+1} = 2 | X_n = 2) = 0.5.$

## Example 4

As an example of a **non-homogeneous Markov chain**, consider a random process on states  $S = \{1, 2\}$ , generated according the following rules: if  $n = 0, 2, 4, 6, \dots$ , then

- $\mathbb{P}(X_{n+1} = 1 | X_n = 1) = 0.2,$
- $\mathbb{P}(X_{n+1} = 2 | X_n = 1) = 0.8,$
- $\mathbb{P}(X_{n+1} = 1 | X_n = 2) = 0.5,$
- $\mathbb{P}(X_{n+1} = 2 | X_n = 2) = 0.5,$

whereas if  $n = 1, 3, 5, 7, \dots$ , then

- $\mathbb{P}(X_{n+1} = 1 | X_n = 1) = 0.1,$
- $\mathbb{P}(X_{n+1} = 2 | X_n = 1) = 0.9,$
- $\mathbb{P}(X_{n+1} = 1 | X_n = 2) = 0.9,$
- $\mathbb{P}(X_{n+1} = 2 | X_n = 2) = 0.1.$

Unless stated otherwise,

the Markov chains in this course will be time-homogeneous.

It makes sense to define:

$$p_{ij} := \mathbb{P}(X_{n+1} = j | X_n = i) = \mathbb{P}(X_1 = j | X_0 = i)$$

- **one-step transition probability** of moving from state  $i$  to state  $j$ .

The one-step transition probabilities can be arranged into a matrix  $\mathbf{P}$ , whose  $(i, j)$ -th entry is  $p_{ij}$ :

$$\mathbf{P} = (p_{ij})_{i, j \in S}.$$

This is the **transition matrix**, which contains the one-step transition probabilities of moving from state to state.

If the state space  $S$  has  $n$  elements, then  $\mathbf{P}$  is a square  $n \times n$  matrix. If  $S$  is countably infinite,  $\mathbf{P}$  is an infinite matrix.



## Definition 5

A **stochastic matrix** is a square matrix  $\mathbf{P}$ , which satisfies

- $\mathbf{P}_{ij} \geq 0$  for all  $i, j$ ,
- For each row  $i$ ,

$$\sum_j \mathbf{P}_{ij} = 1.$$

## Fact 6

*If  $\mathbf{P}$  is a one-step transition matrix of a Markov chain, then  $\mathbf{P}$  is a stochastic matrix.*

# Markov chains – basic computations

A powerful feature of Markov chains is the ability to use matrix algebra for computing probabilities. To use matrix methods, we consider probability distributions as vectors.

If  $X$  is a discrete random variable with  $\mathbb{P}(X = j) = \alpha_j$ , then  $\alpha := (\alpha_1, \alpha_2, \dots)$  is a **probability vector**. We say then that **the distribution of  $X$  is  $\alpha$** . For matrix computations we will identify discrete probability distributions with *row vectors*.

For a Markov chain  $(X_n)_{n \in \mathbb{N}_0}$ , the distribution of  $X_0$  is called **the initial distribution** of the Markov chain  $(X_n)_n$ . Thus, if  $\alpha$  is the initial distribution of  $(X_n)_n$ , then

$$\mathbb{P}(X_0 = j) = \alpha_j$$

for all  $j \in S$ .

## $n$ -step transition probabilities

For states  $i$  and  $j$ , and for  $n \geq 1$ ,

$$\mathbb{P}(X_n = j | X_0 = i)$$

is the probability that the chain started in  $i$  hits  $j$  in  $n$  steps.

The  $n$ -step transition probabilities can be arranged into a matrix, whose  $(i, j)$ -th entry is  $\mathbb{P}(X_n = j | X_0 = i)$  (this is the  **$n$ -step transition matrix** of the Markov chain). Clearly, for  $n = 1$ , this is just the usual (one-step) transition matrix  $\mathbf{P}$ .

### Theorem 7

*The  $n$ -step transition matrix is  $\mathbf{P}^n$  (the  $n$ -th matrix power of  $\mathbf{P}$ ).*

### Example 8

Let  $(X_n)_n$  be a Markov chain with the state space  $S = \{1, 2\}$  and transition matrix

$$\mathbf{P} = \begin{bmatrix} \frac{1}{4} & \frac{3}{4} \\ \frac{3}{4} & \frac{1}{4} \end{bmatrix}.$$

Compute  $\mathbb{P}(X_2 = j | X_0 = i)$  for  $i, j \in \{1, 2\}$ .

# Chapman-Kolmogorov

## Theorem 9

*The Chapman-Kolmogorov equations:*

$$\mathbb{P}(X_{n+m} = j | X_0 = i) = \sum_{k \in S} \mathbb{P}(X_m = k | X_0 = i) \mathbb{P}(X_{m+n} = j | X_m = k)$$

Interpretation: transitioning from  $i$  to  $j$  in  $m + n$  steps is equivalent to transitioning from  $i$  to some state  $k$  in  $m$  steps and then from that state to  $j$  in the remaining  $n$  steps.

# Law of Total Probability

## Theorem 10

*Let  $B_1, \dots, B_k$  be a sequence of events that partition the sample space. That is, the  $B_i$  are mutually exclusive (disjoint) and their union is equal to  $\Omega$ . Then, for any event  $A$ ,*

$$\mathbb{P}(A) = \sum_{i=1}^k \mathbb{P}(A|B_i) \mathbb{P}(B_i).$$

## Example 11

There are nine fair coins and one two-headed coin. We pick one coin and random and make five tosses. What is the probability of obtaining three heads in this way?

# Distribution of $X_n$

## Example 12

Let  $(X_n)_n$  be a Markov chain with the state space  $S = \{1, 2\}$ , initial distribution  $\alpha$  and transition matrix

$$\mathbf{P} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ 0 & 1 \end{bmatrix}.$$

- Find the distribution of  $X_1$  if  $\alpha = (1/2, 1/2)$ .
- Find the distribution of  $X_1$  if  $\alpha = (1, 0)$ .
- Find the distribution of  $X_1$  if  $\alpha = (0, 1)$ .
- Find the distribution of  $X_2$  if  $\alpha = (0, 1)$ .



# Distribution of $X_n$ - cont'd

## Theorem 13

Let  $(X_n)_n$  be a Markov chain with transition matrix  $\mathbf{P}$  and initial distribution  $\alpha$ . For all  $n \geq 0$  the distribution of  $X_n$  is  $\alpha\mathbf{P}^n$ . That is

$$\mathbb{P}(X_n = j) = (\alpha\mathbf{P}^n)_j \quad \forall j.$$

## Example 14

Let

$$\mathbf{P} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ 0 & 1 \end{bmatrix}.$$

- If  $\alpha = (1/2, 1/2)$  then  $\alpha\mathbf{P} = (1/4, 3/4)$ .
- If  $\alpha = (1, 0)$  then  $\alpha\mathbf{P} = (1/2, 1/2)$ .
- If  $\alpha = (0, 1)$  then  $\alpha\mathbf{P} = (0, 1)$ .
- If  $\alpha = (0, 1)$  then  $\alpha\mathbf{P}^2 = (0, 1)$ .

# Present, future, and most recent past

The Markov property says that past and future are independent given the present. It is also true that past and future are independent, given *the most recent* past.

## Example 15

If  $(X_n)_n$  is a Markov chain then

$$\begin{aligned}\mathbb{P}(X_9 = x_9 | X_6 = x_6, X_4 = x_4, X_3 = x_3, X_1 = x_1) \\ = \mathbb{P}(X_9 = x_9 | X_6 = x_6) .\end{aligned}$$

# Joint distribution

The marginal distributions of a Markov chain are determined by the initial distribution  $\alpha$  and the one-step transition matrix  $\mathbf{P}$ .

However, a much stronger result is true. In fact,  $\alpha$  and  $\mathbf{P}$  determine all the joint distributions of a Markov chain, that is, the joint distribution of any finite subset of  $X_0, X_1, X_2, \dots$ . In that sense, the initial distribution and transition matrix give a complete probabilistic description of a Markov chain.

## Example 16

Express

$$\mathbb{P}(X_5 = i, X_3 = j)$$

in terms of  $\alpha$  and  $\mathbf{P}$ .