

# Solutions Manual to Mechanics

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# 1 The Equations of Motion

## 1.1

Let the field be a uniform gravitational one with the acceleration  $g$ . Let the system be a coplanar double pendulum of the strings with the lengths  $l_1$  and  $l_2$  and the particles with masses  $m_1$  and  $m_2$  with the angles  $\phi_1$  and  $\phi_2$  from the  $y$  axis. Then,

$$\mathbf{r}_1 = \begin{bmatrix} l_1 \sin \phi_1 \\ l_1 \cos \phi_1 \end{bmatrix}, \mathbf{r}_2 = \begin{bmatrix} l_1 \sin \phi_1 + l_2 \sin \phi_2 \\ l_1 \cos \phi_1 + l_2 \cos \phi_2 \end{bmatrix}, \quad (1.1)$$

so that

$$\mathbf{v}_1 = \begin{bmatrix} l_1 \dot{\phi}_1 \cos \phi_1 \\ -l_1 \dot{\phi}_1 \sin \phi_1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} l_1 \dot{\phi}_1 \cos \phi_1 + l_2 \dot{\phi}_2 \cos \phi_2 \\ -l_1 \dot{\phi}_1 \sin \phi_1 - l_2 \dot{\phi}_2 \sin \phi_2 \end{bmatrix}. \quad (1.2)$$

Then, the Lagrangian is given by

$$L = \frac{1}{2}m_1\|\mathbf{v}_1\|^2 + mgr_{1y} + \frac{1}{2}m_2\|\mathbf{v}_2\|^2 + mgr_{2y}. \quad (1.3)$$

The right hand side can be written as

$$\begin{aligned} & \frac{1}{2}m_1 l_1^2 \dot{\phi}_1^2 + m_1 g l_1 \cos \phi_1 + \frac{1}{2}m_2 \left( l_1^2 \dot{\phi}_1^2 + l_2^2 \dot{\phi}_2^2 + 2l_1 l_2 \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2) \right) \\ & + m_2 g (l_1 \cos \phi_1 + l_2 \cos \phi_2). \end{aligned} \quad (1.4)$$

Therefore,

$$\begin{aligned} L = & \frac{1}{2}(m_1 + m_2)l_1^2 \dot{\phi}_1^2 + \frac{1}{2}m_2 l_2^2 \dot{\phi}_2^2 + m_2 l_1 l_2 \dot{\phi}_1 \dot{\phi}_2 \cos(\phi_1 - \phi_2) \\ & + (m_1 + m_2)g l_1 \cos \phi_1 + m_2 g l_2 \cos \phi_2. \end{aligned} \quad (1.5)$$

## 1.2

Let the field be a uniform gravitational one with the acceleration  $g$ . Let the system be a pendulum of the string with the length  $l$  and the particles with the mass  $m_1$  at the point of support which can move on the  $x$  axis and the mass  $m_2$  at the end of the string with the angle  $\phi$  from the  $y$  axis. Then,

$$\mathbf{r}_1 = \begin{bmatrix} x \\ 0 \end{bmatrix}, \mathbf{r}_2 = \begin{bmatrix} x + l \sin \phi \\ l \cos \phi \end{bmatrix}, \quad (1.6)$$

so that

$$\mathbf{v}_1 = \begin{bmatrix} \dot{x} \\ 0 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} \dot{x} + l\dot{\phi} \cos \phi \\ -l\dot{\phi} \sin \phi \end{bmatrix}. \quad (1.7)$$

Then, the Lagrangian is given by

$$L = \frac{1}{2}m_1\|\mathbf{v}_1\|^2 + mgr_{1y} + \frac{1}{2}m_2\|\mathbf{v}_2\|^2 + mgr_{2y}. \quad (1.8)$$

The right hand side can be written as

$$\frac{1}{2}m_1\dot{x}^2 + \frac{1}{2}m_2 \left( \dot{x}^2 + l^2\dot{\phi}^2 + 2\dot{x}l\dot{\phi} \cos \phi \right) + m_2gl \cos \phi. \quad (1.9)$$

Therefore,

$$L = \frac{1}{2}(m_1 + m_2)\dot{x}^2 + \frac{1}{2}m_2l^2\dot{\phi}^2 + m_2\dot{x}l\dot{\phi} \cos \phi + m_2gl \cos \phi. \quad (1.10)$$