

Monotonic Abstraction for Programs with Multiply-Linked Structures

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Introduction

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- Verification of programs

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- Programs written in a subset of C

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- Operating on multiply linked data structures

Outline

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struct B {  
    T1 t1;  
    T2 t2;  
    T3 t3;  
    T4 t4;  
}
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- Labels on nodes for variables

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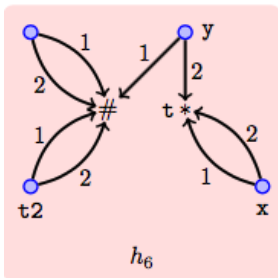
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Example of a heap:

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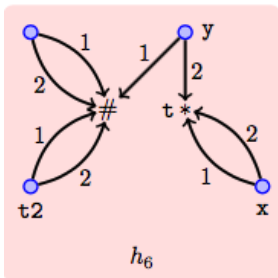
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Example Heap [ACV13]

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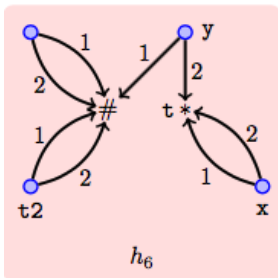


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- Given states s, s' , $s \rightarrow s'$ exists if an operation is defined which transforms h into h'

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A signature is a heap with some parts 'missing'. It represents the set of all heaps that have at least the property or structural information described by this signature.

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- We say that a heap h satisfies sig_1 , written as $h \in \llbracket sig_1 \rrbracket$, if $sig_1 \sqsubseteq h$

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A transition system T is monotonic if the following holds. For any states sig_1, sig_2 and sig_3 such that $sig_1 \sqsubseteq sig_2$ and $sig_1 \longrightarrow sig_3$, we can always find a state sig_4 such that $sig_2 \longrightarrow sig_4$ and $sig_3 \sqsubseteq sig_4$.

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We say $s \rightarrow_A s'$ for two signatures s and s' iff there is an s'' such that $s'' \sqsubseteq s$ and $s \rightarrow s'$.

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- If the set of signatures is disjoint from the initial set of states
 \Rightarrow program execution is safe

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Table 1. Experimental results

Program	Struct	Time	#Sig.
Traverse	DLL	11.4 s	294
Insert	DLL	3.5 s	121
Ordered Insert	DLL	19.4 s	793
Merge	DLL	6 min 40 s	8171
Reverse	DLL	10.8 s	395
Search	Tree	1.2 s	51
Insert	Tree	6.8 s	241

Prototype Results [ACV13]

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- Very generic approach
- Successfully implemented

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Any questions?



Parosh Aziz Abdulla, Jonathan Cederberg, and Tomáš Vojnar, *Monotonic abstraction for programs with multiply-linked structures*, International Journal of Foundations of Computer Science **24** (2013), no. 02, 187–210.