week4

March 20, 2021

1 Principal Component Analysis (PCA)

We will implement the PCA algorithm. We will first implement PCA, then apply it (once again) to the MNIST digit dataset.

1.1 Learning objective

- 1. Write code that implements PCA.
- 2. Write code that implements PCA for high-dimensional datasets

Let's first import the packages we need for this week.

```
[2]: # PACKAGE: DO NOT EDIT
import numpy as np
import scipy
import scipy.stats
```

```
[3]: import matplotlib.pyplot as plt from ipywidgets import interact

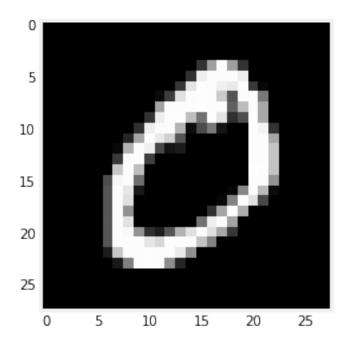
plt.style.use('fivethirtyeight')
%matplotlib inline
```

```
[4]: from load_data import load_mnist

MNIST = load_mnist('./')
images, labels = MNIST['data'], MNIST['target']
```

Now, let's plot a digit from the dataset:

```
[5]: plt.figure(figsize=(4,4))
  plt.imshow(images[0].reshape(28,28), cmap='gray');
  plt.grid(False)
```



1.2 PCA

Now we will implement PCA. Before we do that, let's pause for a moment and think about the steps for performing PCA. Assume that we are performing PCA on some dataset X for M principal components. We then need to perform the following steps, which we break into parts:

- 1. Data normalization (normalize).
- 2. Find eigenvalues and corresponding eigenvectors for the covariance matrix S. Sort by the largest eigenvalues and the corresponding eigenvectors (eig).
- 3. Compute the orthogonal projection matrix and use that to project the data onto the subspace spanned by the eigenvectors.

1.2.1 Data normalization normalize

We will first implement the data normalization mentioned above.

Before we implement the main steps of PCA, we will need to do some data preprocessing.

To preprocess the dataset for PCA, we will make sure that the dataset has zero mean. Given a dataset X, we will subtract the mean vector from each row of the dataset to obtain a zero-mean dataset \overline{X} . In the first part of this notebook, you will implement normalize to do that.

To work with images, it's also a common practice to convert the pixels from unsigned interger 8 (uint8) encoding to a floating point number representation between 0-1. We will do this conversion for you for the MNIST dataset so that you don't have to worry about it.

Data normalization is a common practice. More details can be found in Data Normalization or Feature Scaling.

```
[6]: # GRADED FUNCTION: DO NOT EDIT THIS LINE
     def normalize(X):
         """Normalize the given dataset X to have zero mean.
             X: ndarray, dataset of shape (N,D)
         Returns:
             (Xbar, mean): tuple of ndarray, Xbar is the normalized dataset
             with mean 0; mean is the sample mean of the dataset.
         mu = X.mean(0)
         Xbar = X - mu
         return Xbar, mu
     # def normalize(X):
     #
           """Normalize the given dataset X to have zero mean.
     #
               X: ndarray, dataset of shape (N,D)
           Returns:
     #
                (Xbar, mean): tuple of ndarray, Xbar is the normalized dataset
     #
               with mean 0; mean is the sample mean of the dataset.
           11 11 11
     #
     #
           # YOUR CODE HERE
     #
           ### Uncomment and modify the code below
     #
           mu = np.mean(X, axis=0)
     #
           std = np.std(X, axis=0)
           std filled = std.copy()
           std_filled[std == 0] = 1 # <-- EDIT THIS, compute the mean of X
           Xbar = (X - mu) / std_filled # <-- EDIT THIS, compute the normalized_1
      \rightarrow data Xbar
           return Xbar, mu
```

1.2.2 Compute eigenvalues and eigenvectors eig

```
[8]: # GRADED FUNCTION: DO NOT EDIT THIS LINE
     def eig(S):
         """Compute the eigenvalues and corresponding eigenvectors
             for the covariance matrix S.
         Args:
             S: ndarray, covariance matrix
         Returns:
             (eigvals, eigvecs): ndarray, the eigenvalues and eigenvectors
         Note:
             the eigenvals and eigenvecs should be sorted in descending
             order of the eigen values
         # YOUR CODE HERE
         # Uncomment and modify the code below
         # Compute the eigenvalues and eigenvectors
         # You can use library routines in `np.linalg.*`
         # https://numpy.org/doc/stable/reference/routines.linalg.html
         # for this
         eigvals, eigvecs = np.linalg.eig(S)
         # The eigenvalues and eigenvectors need to be
         # sorted in descending order according to the eigenvalues
         # We will use `np.argsort` (https://docs.scipy.org/doc/numpy/reference/
      \rightarrow generated/numpy.argsort.html)
         # to find a permutation of the indices
         # of eigvals that will sort eigvals in ascending order and
         # then find the descending order via [::-1], which reverse
```

```
# the indices
    sort_indices = np.argsort(eigvals)[::-1]
    # Notice that we are sorting the columns (not rows) of
    # eigvecs since the columns represent the eigenvectors.
   return eigvals[sort_indices], eigvecs[:, sort_indices]
# def eig(S):
      """Compute the eigenvalues and corresponding eigenvectors
#
          for the covariance matrix S.
      Args:
#
          S: ndarray, covariance matrix
      Returns:
          (eigvals, eigvecs): ndarray, the eigenvalues and eigenvectors
      Note:
          the eigenvals and eigenvecs should be sorted in descending
          order of the eigen values
#
      11 11 11
#
#
      # YOUR CODE HERE
      # Uncomment and modify the code below
      # Compute the eigenvalues and eigenvectors
#
#
      # You can use library routines in `np.linalg.*`
      # https://numpy.org/doc/stable/reference/routines.linalq.html
      # for this
#
      eigvals, eigvecs = np.linalg.eig(S)
#
#
      # The eigenvalues and eigenvectors need to be
      # sorted in descending order according to the eigenvalues
      # We will use `np.arqsort` (https://docs.scipy.org/doc/numpy/reference/
→ generated/numpy.argsort.html)
      # to find a permutation of the indices
      # of eigvals that will sort eigvals in ascending order and
#
      # then find the descending order via [::-1], which reverse
      # the indices
#
      sort_indices = np.argsort(eigvals)[::-1]
      # Notice that we are sorting the columns (not rows) of
#
      # eigvecs since the columns represent the eigenvectors.
      return eigvals[sort_indices], eigvecs[:, sort_indices]
```

Some test cases for implementing eig.

```
[9]: def _flip_eigenvectors(B):
    """Flip the eigenvectors.
    """
    signs = np.sign(B[np.argmax(np.abs(B), axis=0), range(B.shape[1])])
```

```
return B * signs
def _normalize_eigenvectors(B):
    # Normalize eigenvectors to have unit length
    # Also flip the direction of the eigenvector based on
    # the first element
    B_normalized = B / np.linalg.norm(B, axis=0)
    for i in range(B.shape[1]):
        if (B normalized[0, i] < 0):</pre>
            B_normalized[:, i] = -B_normalized[:, i]
    return B normalized
A = np.array([[3, 2], [2, 3]])
expected_eigenvalues = np.array([5., 1.])
expected_eigenvectors = np.array(
    [[0.70710678, -0.70710678],
     [ 0.70710678, 0.70710678]]
)
actual_eigenvalues, actual_eigenvectors = eig(A)
# Check that the eigenvalues match
assert_allclose(actual_eigenvalues, expected_eigenvalues)
# Check that the eigenvectors match
assert allclose(
    _normalize_eigenvectors(actual_eigenvectors),
    normalize eigenvectors(expected eigenvectors),
```

1.2.3 Compute projection matrix

Next given a orthonormal basis spanned by the eigenvectors, we will compute the projection matrix. This should be the same as what you have done last week.

```
[10]: # GRADED FUNCTION: DO NOT EDIT THIS LINE
def projection_matrix(B):
    """Compute the projection matrix onto the space spanned by `B`
    Args:
        B: ndarray of dimension (D, M), the basis for the subspace

Returns:
        P: the projection matrix
        """
        P = B @ np.linalg.inv(B.T @ B) @ B.T
        return P

# def projection_matrix(B):
```

```
#
      """Compute the projection matrix onto the space spanned by `B`
#
      Args:
#
          B: ndarray of dimension (D, M), the basis for the subspace
#
      Returns:
#
          P: the projection matrix
#
      # YOUR CODE HERE
#
#
      # Uncomment and modify the code below
      P = B @ np.linalg.inv(B.T @ B) @ B.T
#
      return P # <-- EDIT THIS to compute the projection matrix
```

1.2.4 Compute principal component analysis

```
[12]: # GRADED FUNCTION: DO NOT EDIT THIS LINE
      def PCA(X, num_components):
          HHHH
          Arqs:
              X: ndarray of size (N, D), where D is the dimension of the data,
                 and N is the number of datapoints
              num_components: the number of principal components to use.
          Returns:
              the reconstructed data, the sample mean of the X, principal values
              and principal components
          11 11 11
          N, D = X.shape
          # first perform normalization on the digits so that they have zero mean and
       \rightarrowunit variance
          X_normalized, mean = normalize(X)
          \# Then compute the data covariance matrix S
```

```
S = np.cov(X_normalized/ N, rowvar=False, bias=True)
    # Next find eigenvalues and corresponding eigenvectors for S
    eig_vals, eig_vecs = eig(S)
    # Take the top `num_components` of eig_vals and eig_vecs,
    # This will be the corresponding principal values and components
    principal_vals = eig_vals[:num_components]
    principal_components = eig_vecs[:, :num_components]
    # reconstruct the data from the using the basis spanned by the principal,
\rightarrow components
    # Notice that we have subtracted the mean from X so make sure that you add \square
\rightarrow it back
    # to the reconstructed data
    P = projection_matrix(principal_components) # projection matrix
    reconst = (P @ X_normalized.T).T + mean
    return reconst, mean, principal_vals, principal_components
      # YOUR CODE HERE
      # your solution should take advantage of the functions you have
\rightarrow implemented above.
      ### Uncomment and modify the code below
      # first perform normalization on the digits so that they have zero mean,
\rightarrow and unit variance
      X normalized, mean = None, None # EDIT THIS
      \# Then compute the data covariance matrix S
      S = np.cov(X, rowvar=False, bias=True) # EDIT THIS
      # Next find eigenvalues and corresponding eigenvectors for S
      eig\_vals, eig\_vecs = eig(S)
      # Take the top `num_components` of eig_vals and eig_vecs,
#
      # This will be the corresponding principal values and components
      principal vals, principal components = None, None
      # reconstruct the data from the using the basis spanned by the principal \Box
\hookrightarrow components
      # Notice that we have subtracted the mean from X so make sure that you\square
\rightarrow add it back
      # to the reconstructed data
      reconst = np.zeros_like(X_normalized)
      return reconst, mean, principal_vals, principal_components
```

```
[13]: def draw_vector(v0, v1, ax=None, label=None):
"""Draw a vector from v0 to v1."""
```

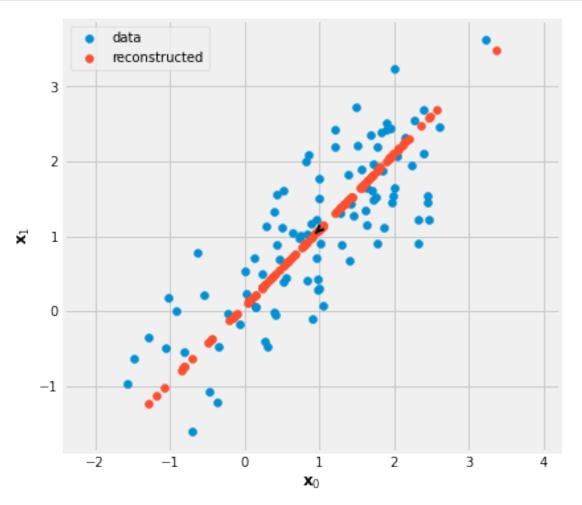
Some test cases that check the implementation of PCA

```
[14]: D = 2
      N = 10
      # Generate a dataset X from a 2D Gaussian distribution
      mvn = scipy.stats.multivariate_normal(
          mean=np.ones(D, dtype=np.float64),
          cov=np.array([[1, 0.8], [0.8, 1]], dtype=np.float64)
      )
      X = mvn.rvs((N,), random_state=np.random.RandomState(0))
      reconst, m, pv, pc = PCA(X, 1)
      # Check the shape returned by the PCA implementation matches the specification.
      assert reconst.shape == X.shape
      assert m.shape == (D, )
      assert pv.shape == (1, )
      assert pc.shape == (D, 1)
      # Check that PCA with num_components == D gives identical reconstruction
      reconst, m, pv, pc = PCA(X, D)
      assert reconst.shape == X.shape
      assert m.shape == (D, )
      assert pv.shape == (2, )
      assert pc.shape == (D, 2)
      assert_allclose(reconst, X)
```

[]:

1.3 Visualize PCA

We will first visualize what PCA does on a 2D toy dataset. You can use the visualization below to get better intuition about what PCA does and use it to debug your code above.



We can also compare our PCA implementation with the implementation in scikit-learn (a popular machine learning library in Python that includes implementation of PCA) to see if we get identical results.

```
difference in reconstruction for num_components = 1: 3.4416233291103798e-28 difference in reconstruction for num_components = 2: 1.3798459901658458e-28 difference in reconstruction for num_components = 3: 7.89881648091537e-29
```

1.4 PCA for MNIST digits

Once you have implemented PCA correctly, it's time to apply to the MNIST dataset. First, we will do some preprocessing of the data to get it into a good shape.

```
[17]: ## Some preprocessing of the data
# NUM_DATAPOINTS = 1000
# X = (images.reshape(-1, 28 * 28)[:NUM_DATAPOINTS]) / 255.

## Some preprocessing of the data
NUM_DATAPOINTS = 1000
X = (images.reshape(-1, 28 * 28)[:NUM_DATAPOINTS]) / 255.
Xbar, mu, std = normalize(X)
```

```
ValueError Traceback (most recent call_u → last)
```

```
<ipython-input-17-e50ce10f3ee0> in <module>
               6 NUM_DATAPOINTS = 1000
               7 X = (images.reshape(-1, 28 * 28)[:NUM_DATAPOINTS]) / 255.
         ----> 8 Xbar, mu, std = normalize(X)
             ValueError: not enough values to unpack (expected 3, got 2)
[18]: for num_component in range(1, 20):
          from sklearn.decomposition import PCA as SKPCA
          # We can compute a standard solution given by scikit-learn's implementation
       \hookrightarrow of PCA
          pca = SKPCA(n_components=num_component, svd_solver='full')
          sklearn_reconst = pca.inverse_transform(pca.fit_transform(Xbar))
          reconst = PCA(Xbar, num_component)
          np.testing.assert_almost_equal(reconst, sklearn_reconst)
          print(np.square(reconst - sklearn_reconst).sum())
             NameError
                                                        Traceback (most recent call_
      →last)
             <ipython-input-18-a5b269259de6> in <module>
                     # We can compute a standard solution given by scikit-learn's
      →implementation of PCA
                     pca = SKPCA(n_components=num_component, svd_solver='full')
         ----> 5
                     sklearn_reconst = pca.inverse_transform(pca.fit_transform(Xbar))
                    reconst = PCA(Xbar, num_component)
                     np.testing.assert_almost_equal(reconst, sklearn_reconst)
             NameError: name 'Xbar' is not defined
[27]: reconst, _, _, = PCA(X, num_components=10)
      num_images_to_show = 10
      reconst_images = np.reshape(reconst[:num_images_to_show], (-1, 28, 28))
      fig, ax = plt.subplots(2, 1, figsize=(num_images_to_show * 3, 3))
      ax[0].imshow(np.concatenate(np.reshape(X[:num_images_to_show], (-1, 28, 28)),__
      \hookrightarrow-1), cmap="gray")
      ax[1].imshow(np.concatenate(reconst_images, -1), cmap="gray");
```

The greater number of of principal components we use, the smaller will our reconstruction error be. Now, let's answer the following question:

How many principal components do we need in order to reach a Mean Squared Error (MSE) of less than 10.0 for our dataset?

We have provided a function in the next cell which computes the mean squared error (MSE), which will be useful for answering the question above.

```
[11]: def mse(predict, actual):

"""Helper function for computing the mean squared error (MSE)"""

return np.square(predict - actual).sum(axis=1).mean()
```

```
[12]: loss = []
    reconstructions = []
# iterate over different number of principal components, and compute the MSE
for num_component in range(1, 50):
    reconst = PCA(Xbar, num_component)
    error = mse(reconst, Xbar)
    reconstructions.append(reconst)
    # print('n = {:d}, reconstruction_error = {:f}'.format(num_component, userror))
    loss.append((num_component, error))

reconstructions = np.asarray(reconstructions)
reconstructions = reconstructions * std + mu # "unnormalize" the reconstructed usering image
loss = np.asarray(loss)
```

```
# loss = []
# reconstructions = []
# iterate over different number of principal components, and compute the MSE
# for num_component in range(1, 100, 5):
# reconst, _, _, _ = PCA(X, num_component)
# error = mse(reconst, X)
# reconstructions.append(reconst)
# # print('n = {:d}, reconstruction_error = {:f}'.format(num_component, undersor))
# loss.append((num_component, error))
# reconstructions = np.asarray(reconstructions)
# reconstructions = reconstructions
# loss = np.asarray(loss)
```

[13]: import pandas as pd
create a table showing the number of principal components and MSE
pd.DataFrame(loss, columns=['no. of components', 'mse']).head()

```
[13]: no. of components mse

0 1.000000+0.000000j 445.176488+0.000000j

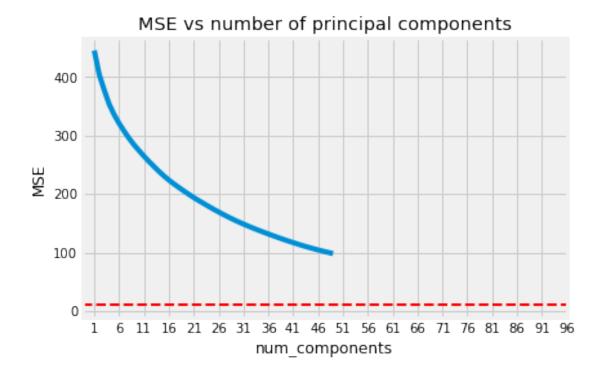
1 2.000000+0.000000j 403.941979+0.000000j

2 3.000000+0.000000j 377.592431+0.000000j

3 4.000000+0.000000j 353.300124+0.000000j

4 5.000000+0.000000j 335.442895+0.000000j
```

We can also put these numbers into perspective by plotting them.



But numbers dont't tell us everything! Just what does it mean qualitatively for the loss to decrease from around 45.0 to less than 10.0?

Let's find out! In the next cell, we draw the the leftmost image is the original dight. Then we show the reconstruction of the image on the right, in descending number of principal components used.

interactive(children=(IntSlider(value=500, description='image_idx', max=1000), Output()), _dom

We can also browse through the reconstructions for other digits. Once again, interact becomes handy for visualing the reconstruction.

```
[17]: @interact(i=(0, 10))
  def show_pca_digits(i=1):
    """Show the i th digit and its reconstruction"""
    plt.figure(figsize=(4,4))
    actual_sample = X[i].reshape(28,28)
    reconst_sample = (reconst[i, :] * std + mu).reshape(28, 28)
    actual_sample = np.real(actual_sample)
    reconst_sample = np.real(reconst_sample)
    plt.imshow(np.hstack([actual_sample, reconst_sample]), cmap='gray')
    plt.show()
```

interactive(children=(IntSlider(value=1, description='i', max=10), Output()), _dom_classes=('was a second of the control of the control

1.5 PCA for high-dimensional datasets

Sometimes, the dimensionality of our dataset may be larger than the number of samples we have. Then it might be inefficient to perform PCA with your implementation above. Instead, as mentioned in the lectures, you can implement PCA in a more efficient manner, which we call "PCA for high dimensional data" (PCA_high_dim).

Below are the steps for performing PCA for high dimensional dataset 1. Normalize the dataset matrix X to obtain \overline{X} that has zero mean. 2. Compute the matrix \overline{XX}^T (a N by N matrix with N << D) 3. Compute eigenvalues λ s and eigenvectors V for \overline{XX}^T with shape (N, N). Compare this with computing the eigenspectrum of $\overline{X}^T\overline{X}$ which has shape (D, D), when N << D, computation of the eigenspectrum of \overline{XX}^T will be computationally less expensive. 4. Compute the eigenvectors for the original covariance matrix as \overline{X}^TV . Choose the eigenvectors associated with the \mathbf{n} largest eigenvalues to be the basis of the principal subspace U. 1. Notice that \overline{X}^TV would give a matrix of shape (D, N) but the eigenvectors beyond the Dth column will have eigenvalues of 0, so it is safe to drop any columns beyond the D'th dimension. 2. Also note that the columns of U will not be unit-length if we pre-multiply V with \overline{X}^T , so we will have to normalize the columns of U so that they have unit-length to be consistent with the PCA implementation above. 5. Compute the orthogonal projection of the data onto the subspace spanned by columns of U.

Functions you wrote for earlier assignments will be useful.

```
[19]: # GRADED FUNCTION: DO NOT EDIT THIS LINE
### PCA for high dimensional datasets

def PCA_high_dim(X, num_components):
    """Compute PCA for small sample size but high-dimensional features.
    Args:
        X: ndarray of size (N, D), where D is the dimension of the sample,
        and N is the number of samples
        num_components: the number of principal components to use.
    Returns:
        X_reconstruct: (N, D) ndarray. the reconstruction
```

```
of X from the first `num_components` pricipal components.
#
     N, D = X.shape
      # Normalize the dataset
     X normalized, mean = normalize(X)
      # Find the covariance matrix
     M = np.dot(X_normalized, X_normalized.T) / N
      # Next find eigenvalues and corresponding eigenvectors for S
      # Make sure that you only take the first D eigenvalues/vectors
      # You can also take a look at the eigenvalues beyond column (D-1) and \Box
→ they should be
      # zero (or a very small number due to finite floating point precision)
      eig\_vals\_M, eig\_vecs\_M = eig(M)
      # Compute the eigenvalues and eigenvectors for the original system
#
      S = np.cov(X\_normalized.T @ eig\_vecs\_M[:, :D], rowvar=False, bias=True)
      \#S = np.cov(X normalized, rowvar=False, bias=True)
      eig\_vals, eig\_vecs = eig(S)
#
#
      # Normalize the eigenvectors to have unit-length
      # Take the top `num_components` of the eigenvalues / eigenvectors
      # as the principal values and principal components
      principal_values = eig_vals[:num_components]
#
#
     principal_components = eig_vecs[:, :num_components]
      # reconstruct the images from the lower dimensional representation
#
      # Remember to add back the sample mean
      P = projection matrix(principal components)
      reconst = (P @ X_normalized.T).T + mean
      return reconst, mean, principal_values, principal_components
   N, D = X.shape
    # Normalize the dataset
   X_normalized, mean = normalize(X)
    # Find the covariance matrix
   M = np.dot(X_normalized, X_normalized.T) / N
    # Next find eigenvalues and corresponding eigenvectors for S
    # Make sure that you only take the first D eigenvalues/vectors
    # You can also take a look at the eigenvalues beyond column (D-1) and they\Box
⇒should be
    # zero (or a very small number due to finite floating point precision)
    # Compute the eigenvalues and eigenvectors for the original system
    eig_vals, eig_vecs = eig(M)
```

```
# Normalize the eigenvectors to have unit-length
    # Take the top `num components` of the eigenvalues / eigenvectors
    # as the principal values and principal components
   principal_values = eig_vals[:num_components]
   principal_components = eig_vecs[:, :num_components]
    # reconstruct the images from the lower dimensional representation
    # Remember to add back the sample mean
   P = projection_matrix(principal_components)
   reconst = (P @ X normalized) + mean
   return reconst, mean, principal_values, principal_components
# def PCA_high_dim(X, num_components):
      """Compute PCA for small sample size but high-dimensional features.
#
      Arqs:
#
          X: ndarray of size (N, D), where D is the dimension of the sample,
             and N is the number of samples
#
          num_components: the number of principal components to use.
#
     Returns:
#
          X reconstruct: (N, D) ndarray. the reconstruction
#
          of X from the first `num_components` pricipal components.
#
    # YOUR CODE HERE
    # Uncomment and modify the code below
     N, D = X.shape
     # Normalize the dataset
#
     X_normalized, mean = None, None
      # Find the covariance matrix
     M = np.dot(X_normalized, X_normalized.T) / N
      # Next find eigenvalues and corresponding eigenvectors for S
      # Make sure that you only take the first D eigenvalues/vectors
      # You can also take a look at the eigenvalues beyond column (D-1) and \Box
→ they should be
      # zero (or a very small number due to finite floating point precision)
      eig vals, eig vecs = None, None
      # Compute the eigenvalues and eigenvectors for the original system
      # Normalize the eigenvectors to have unit-length
#
      # Take the top `num components` of the eigenvalues / eigenvectors
#
      # as the principal values and principal components
#
      principal_values = None
#
     principal_components = None
#
      # reconstruct the images from the lower dimensional representation
#
      # Remember to add back the sample mean
      reconst = None
```

```
# return reconst, mean, principal_values, principal_components
```

[]: # YOUR CODE HERE

```
[]: # Some hidden tests below ### ...
```

Given the same dataset, PCA_high_dim and PCA should give the same output. Assuming we have implemented PCA, correctly, we can then use PCA to test the correctness of PCA_high_dim. Given the same dataset, PCA and PCA_high_dim should give identical results.

We can use this **invariant** to test our implementation of PCA_high_dim, assuming that we have correctly implemented PCA.

```
[20]: np.testing.assert_almost_equal(PCA(Xbar, 2), PCA_high_dim(Xbar, 2))

# random = np.random.RandomState(0)

# # Generate some random data

# X = random.randn(5, 4)

# pca_rec, pca_mean, pca_pvs, pca_pcs = PCA(X, 2)

# pca_hd_rec, pca_hd_mean, pca_hd_pvs, pca_hd_pcs = PCA_high_dim(X, 2)

# # Check that the results returned by PCA and PCA_high_dim are identical

# np.testing.assert_allclose(pca_rec, pca_hd_rec)

# np.testing.assert_allclose(pca_mean, pca_hd_mean)

# np.testing.assert_allclose(pca_pvs, pca_pvs)

# np.testing.assert_allclose(pca_pcs, pca_pcs)
```

Congratulations! You have now learned how PCA works!