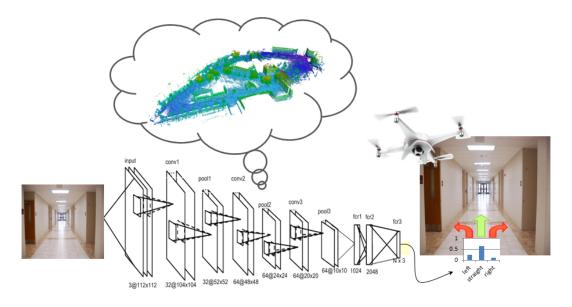




Autonomous Navigation and Perception via Deep Learning



In this project we will reproduce recent results in the field, in an Unreal Engine - based environment. Time permitting, we will investigate modifications to the agent, in varying environments.

https://www.unrealengine.com/en-US/what-is-unreal-engine-4

Project steps:

- 1. Set up infrastructure for reinforcement learning with Unreal Engine
- 2. Train agent to navigate the simulation environment
- 3. Investigate behavior in a set of navigation tasks, modifying the agent and the environment.

Prerequisites: strong programming skills, python (or willingness to learn). Background in machine (deep) learning, computer vision, robotics is an advantage.

Supervisor: Yuri Feldman, yurif@cs.technion.ac.il

Academic supervisor: Asst. Prof. Vadim Indelman, vadim.indelman@technion.ac.il

Duration: 1 or 2 semesters