**Collaborative Multi-Robot Aerial Autonomous Navigation and 3D Reconstruction**

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# Interested in **collaborative multi-robot perception**? Contact us!

# Numerous algorithms to implement and examine on real robots (quadortors), so much to learn - **are you up for the challenge**?

* Pose estimation and 3D reconstruction
* Collaborative RGBD sensing
* Autonomous navigation in unknown environments
* Online decision making under uncertainty

For more information contact us and visit [ANPL website](http://vindelman.net.technion.ac.il/) (Google it!)

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