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Github: <https://github.com/indhu0204/mlp-depth-width-breast-cancer>

Exploring Multilayer Perceptron Depth and Width on Breast Cancer Diagnosis

Introduction

What is a neural network?

A neural network is a computer model that learns from examples, a bit like how people learn from experience. It takes input information (for example, measurements of a tumour) and passes it through layers of simple processing units called “neurons” to make a prediction, such as whether a tumour is malignant or benign.

Multilayer Perceptrons (MLPs) are among the most fundamental neural network architectures and are widely used for tabular classification tasks, including medical diagnosis. A key question for practitioners is: how do design choices—specifically the **depth** (number of hidden layers) and **width** (number of neurons per layer)—affect model performance? This tutorial investigates this question using the Breast Cancer Wisconsin (Diagnostic) dataset, a well-known benchmark for machine learning in healthcare.

The motivation is practical: on small-to-medium tabular datasets, more complex models do not always generalise better. Understanding when to use shallow vs deep networks, and narrow vs wide networks, is essential for building efficient, interpretable models in real applications.

Dataset and preprocessing

The Breast Cancer Wisconsin (Diagnostic) dataset contains 569 samples of cell nuclei measurements extracted from histopathology images, with 30 numeric features (e.g. mean radius, texture, perimeter) and a binary target: malignant (0) or benign (1). The dataset is imbalanced: 212 malignant and 357 benign cases.

We split the data into training (60%), validation (20%), and test (20%) sets using stratified random sampling to preserve class ratios. All features are scaled to zero mean and unit variance using `StandardScaler`, fitted only on the training set to prevent data leakage. A fixed random seed ensures reproducibility.

Multilayer Perceptron architecture

An MLP consists of an input layer, one or more hidden layers with non-linear activation functions, and an output layer. For binary classification, we use:

- **Input layer:** 30 features (the dataset dimensionality).
- **Hidden layers:** variable number and size, with ReLU activation ($\max(0, x)$), which introduces non-linearity.
- **Output layer:** single neuron with sigmoid activation for probability output.

The network is trained using the Adam optimiser with binary cross-entropy loss and early stopping on the validation set to prevent overfitting.

Depth refers to the number of hidden layers; **width** refers to the number of neurons per hidden layer. Both parameters control the model's capacity: the ability to learn complex, non-linear decision boundaries. However, higher capacity does not always translate to better generalisation, especially on small datasets.

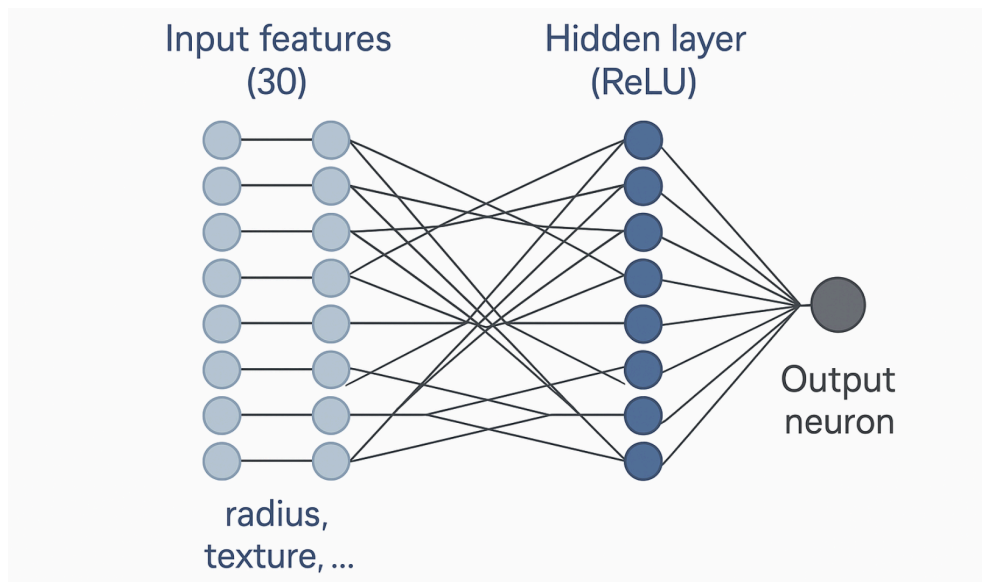


Figure 01

Multilayer Perceptron architecture used in this tutorial, with 30 input features, one hidden ReLU layer, and a single sigmoid output neuron for binary classification.

Overview of Multilayer Perceptrons

A Multilayer Perceptron (MLP) is a feed-forward neural network composed of an input layer, one or more hidden layers, and an output layer. Each layer contains a set of neurons, and every neuron computes a weighted sum of its inputs followed by a non-linear activation function such as ReLU. By stacking layers, MLPs can learn complex non-linear decision boundaries that simpler linear models cannot represent. In this tutorial, the MLP takes 30 numeric features describing cell nuclei as input and outputs the probability that a tumour is malignant. The input layer has 30 units (one per feature). The hidden layers are the part we experiment with: their depth (how many layers) and width (how many neurons in each) determine the model's capacity. A deeper or wider network can, in principle, represent more complex patterns, but it also becomes easier to overfit small datasets such as Breast Cancer Wisconsin (Diagnostic). The output layer contains a single neuron with a sigmoid activation, producing a value between 0 and 1 that can be interpreted as the probability of malignancy. During training, the model adjusts its weights to minimise binary cross-entropy loss using the Adam optimiser, while early stopping monitors validation performance to avoid overfitting.

Conceptually, the MLP used here can be visualised as a series of fully connected layers:

- A 30-node input layer receiving the scaled features.
- One or more hidden layers (e.g. 32 neurons each) with ReLU activations.
- A final sigmoid neuron producing the classification output.

This simple architecture is sufficient to explore how changing depth and width affects performance. The rest of the tutorial focuses on systematically varying these hidden layers to study underfitting, overfitting, and the trade-off between model capacity and generalisation on a real medical dataset.

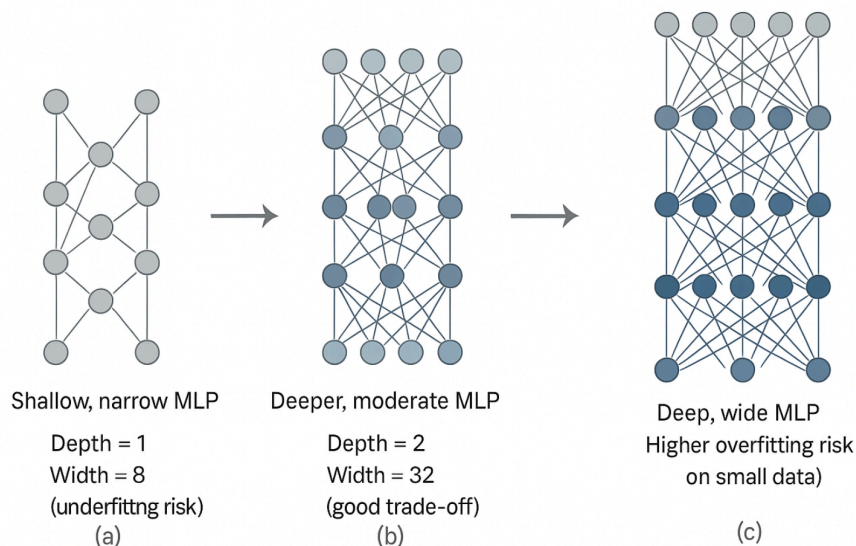


Figure 02

Illustrating depth (number of hidden layers) and width (neurons per layer) for shallow, moderate, and deep-wide MLPs. Increasing depth and width increases capacity but also overfitting risk on small datasets.

Experiment 1: effect of depth

To isolate the effect of depth, we fixed the width at 32 neurons per layer and trained three architectures:

- 1 hidden layer: (32,)
- 2 hidden layers: (32, 32)
- 3 hidden layers: (32, 32, 32)

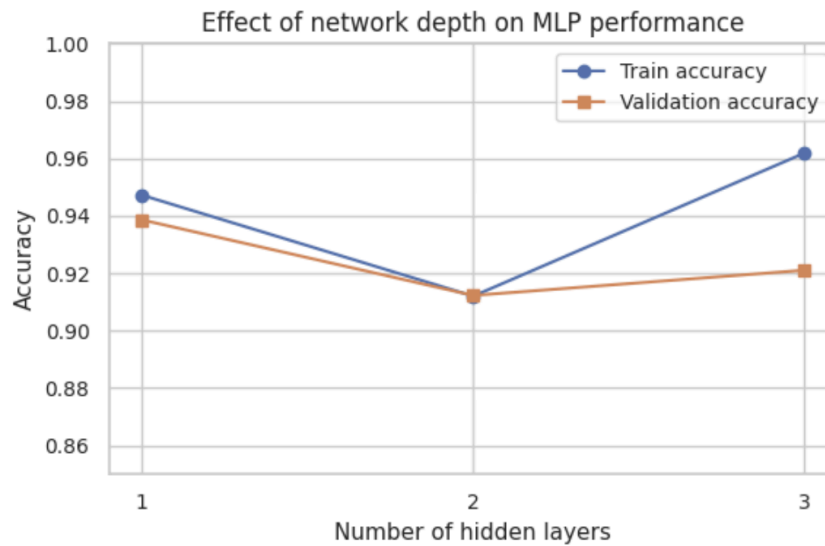


Figure 03 (depth plot)

Figure 03 shows train and validation accuracy for each depth. The single-layer model achieves the highest validation accuracy (~0.939), indicating it generalises best. The two-layer model drops in both train and validation accuracy (~0.912), suggesting that the additional depth makes optimisation harder without providing useful capacity. The three-layer model recovers high training accuracy (~0.962) but validation accuracy (~0.921) lags, a classic sign of **overfitting**: the model memorises the training set without learning robust features.

Key insight: Adding depth does not monotonically improve generalisation on this dataset. A single hidden layer is sufficient to capture the decision boundary.

Experiment 2: effect of width

To isolate the effect of width, we fixed the architecture at two hidden layers and varied the width:

- **Narrow:** (8, 8) (64 parameters total in hidden layers)
- **Medium:** (32, 32) (1024 parameters)
- **Wide:** (128, 128) (16384 parameters)

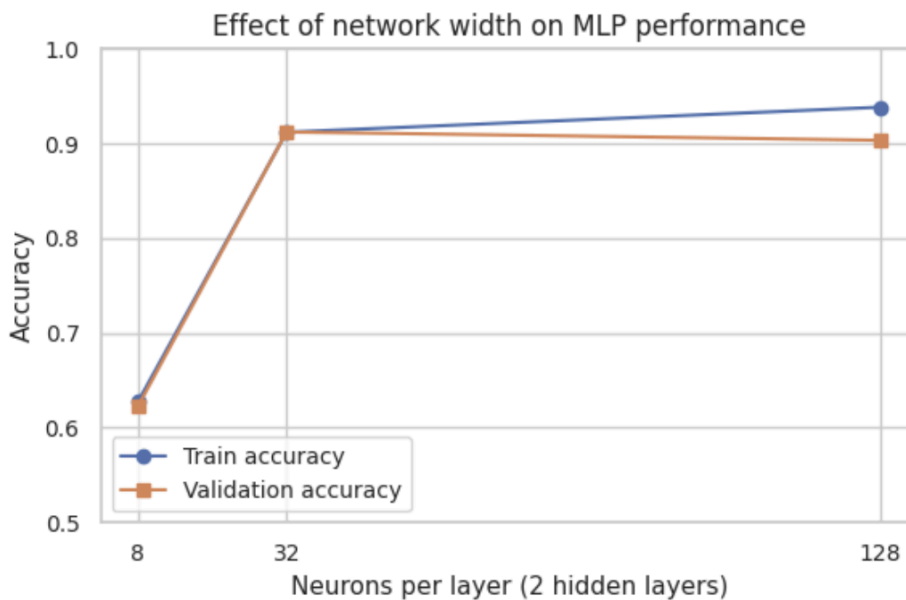


Figure 04 (width plot)

Figure 04 shows train and validation accuracy for each width. The narrow network severely **underfits**: both train and validation accuracy are only ~ 0.62 , meaning the model cannot learn the task. The medium-width network achieves good validation accuracy (~ 0.912), indicating a good bias–variance trade-off. The wide network further increases training accuracy (~ 0.938) but decreases validation accuracy (~ 0.904), again indicating **overfitting**.

Key insight: Increasing width helps up to a point but can hurt generalisation if the model is unnecessarily complex for the dataset size.

Final model and test evaluation

Based on validation accuracy, the final architecture chosen is a single-hidden-layer MLP with 32 neurons. Retraining this model on the combined training and validation data yields a test accuracy of about 0.95, with the confusion matrix showing almost all benign tumours correctly identified and a small number of malignant tumours misclassified as benign. This pattern highlights that even the best MLP configuration must be evaluated carefully in medical settings, where false negatives are critical.

For context, a simple logistic regression trained on the same scaled features attains slightly higher test accuracy on this dataset, indicating that a linear decision boundary already fits the data very well. This does not reduce the value of the MLP experiments; instead, it emphasises that depth and width primarily change the bias–variance trade-off, and that neural networks should be compared to simpler models rather than assumed to be superior.

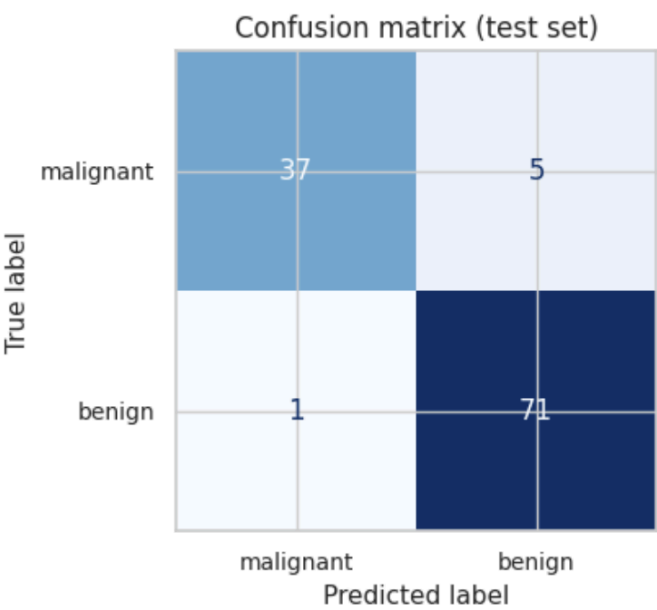


Figure 05 (feature importance table)

Feature importance and interpretability

To understand which features the MLP relies on most, we computed permutation feature importance on the test set. Figure 07 shows the top 10 most important features. The leading features are:

	feature	mean_importance	std_importance
0	mean concave points	0.012719	0.012855
1	worst radius	0.010965	0.008717
2	worst smoothness	0.010088	0.007980
3	fractal dimension error	0.008333	0.001912
4	perimeter error	0.007895	0.009158
5	mean perimeter	0.007895	0.008275
6	worst perimeter	0.007456	0.008448
7	worst compactness	0.007456	0.003132
8	texture error	0.007018	0.006564
9	worst fractal dimension	0.007018	0.003509

Figure 06 (feature importance table)

- **Mean concave points** (importance ~0.013)
- **Worst radius** (importance ~0.011)
- **Worst smoothness** (importance ~0.010)
- **Fractal dimension error, perimeter error, mean perimeter**

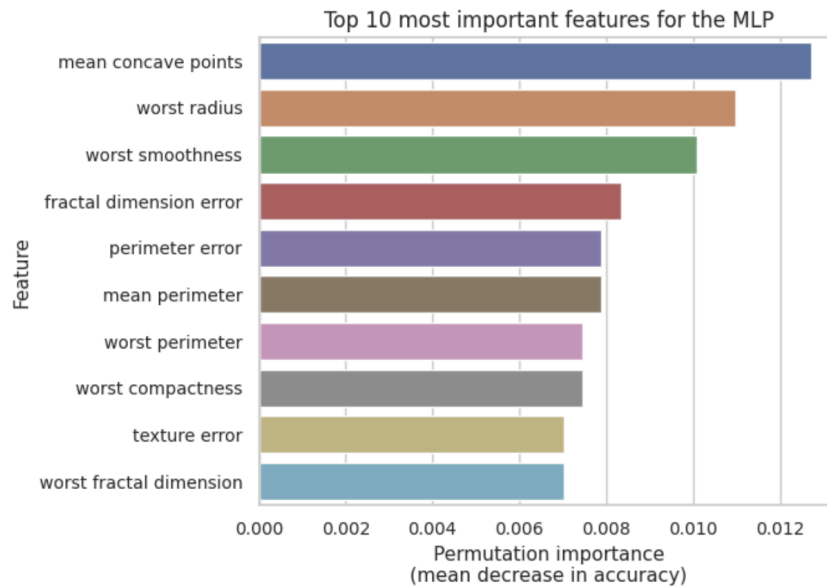


Figure 07 (feature importance plot)

These features describe the size, shape regularity, and boundary characteristics of the cell nuclei. Irregular, concave boundaries with large variance (high "worst" values) are strongly associated with malignancy, aligning with clinical knowledge. Notably, the MLP's decisions are driven by only a small subset of the 30 features, suggesting that deeper or wider networks mainly change how the model combines these key variables.

Practical guidelines and limitations

Based on these experiments, this tutorial recommends

1. **Start with simple baselines** (logistic regression, decision trees) before investing in deep MLPs.
2. **Use shallow, moderately wide networks** on small tabular datasets (<10,000 samples). A single or two hidden layers with 32–64 neurons is a good starting point.
3. **Monitor train vs validation accuracy curves** to detect overfitting and apply early stopping.
4. **Leverage feature importance** to build trust in model decisions and connect them to domain knowledge.
5. **Limitations:** This study uses a single, relatively small dataset. Findings may not generalise to other medical datasets or domains. Additionally, we did not systematically search over learning rate, regularisation (L2 / dropout), or batch size; such a search might reveal different optimal architectures.
6. **Extensions:** Future work could compare MLPs against tree-based models (random forests, gradient boosting), explore regularisation techniques to combat overfitting, or apply the same depth/width analysis to other tabular datasets.

Ethics and Accessibility

Even with good accuracy, the MLP in this tutorial is only an approximation and still makes clinically important errors, including false negatives where malignant tumours are predicted as benign. It should therefore be treated as a decision-support tool that complements, not replaces, clinical judgement.

Interpretability methods such as permutation feature importance help reveal which features drive predictions but do not prove causality; they can also be unstable when features are highly correlated, so results must be read as approximate explanations of model behaviour.

Ethically, any medical ML system must consider bias, privacy, and transparency, especially if the training data under-represent certain patient groups. In this project, a colour-blind-friendly style, clear labels, and descriptive figure text are used so that plots remain readable for colour-blind users and accessible to screen-reader users viewing the PDF.

Conclusion

This tutorial showed how the depth and width of a Multilayer Perceptron influence performance on the Breast Cancer Wisconsin (Diagnostic) dataset. A shallow network with a single hidden layer of 32 neurons achieved the best validation and strong test accuracy, while deeper or very wide architectures mainly increased training accuracy without improving generalisation, indicating overfitting on this small tabular dataset.

Comparing against a logistic regression baseline revealed that a simple linear model can outperform the MLP, reinforcing the importance of starting with low-capacity models before adding complexity. Permutation feature importance further showed that the network relies heavily on a small subset, indicating over geometrical features—such as mean concave points and worst radius—that align with established clinical indicators of malignancy.

Overall, the experiments highlight that careful control of model capacity, baseline comparisons, and interpretability tools are crucial when applying neural networks to real medical data.

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