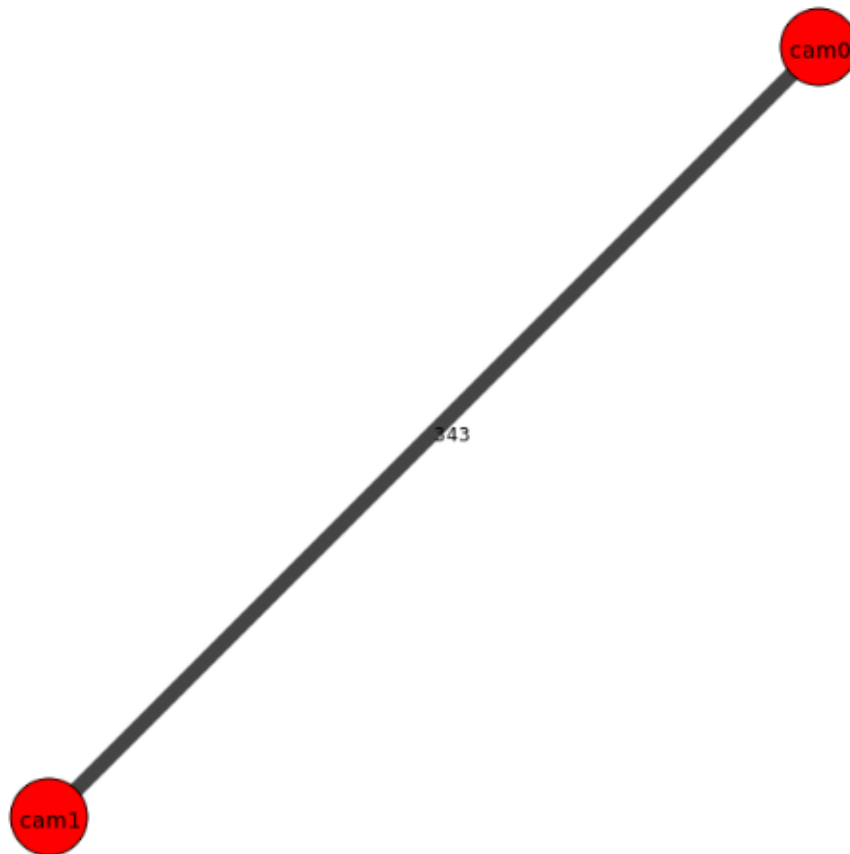
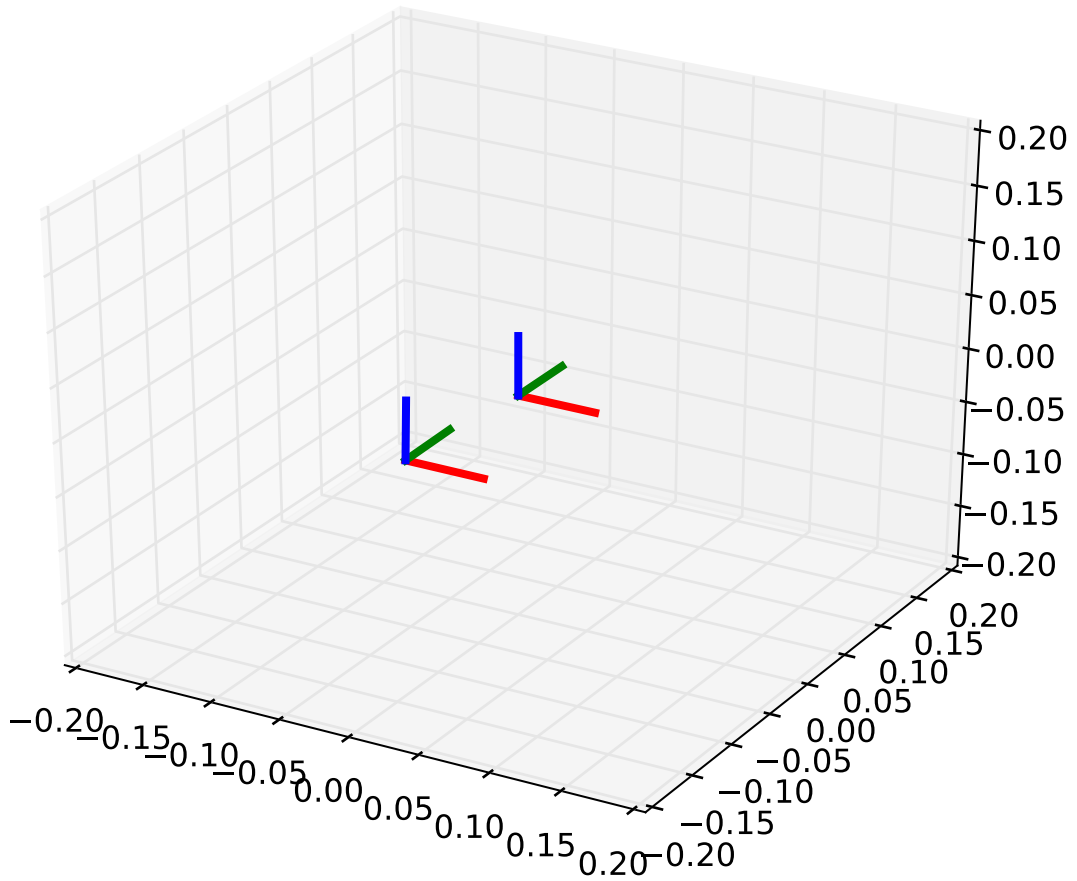


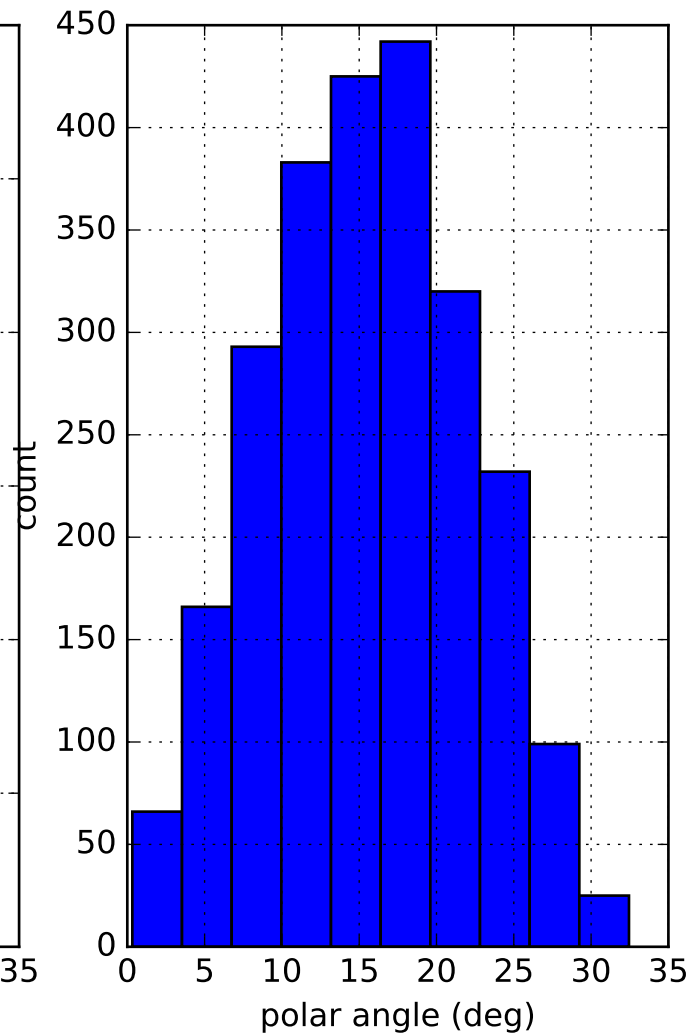
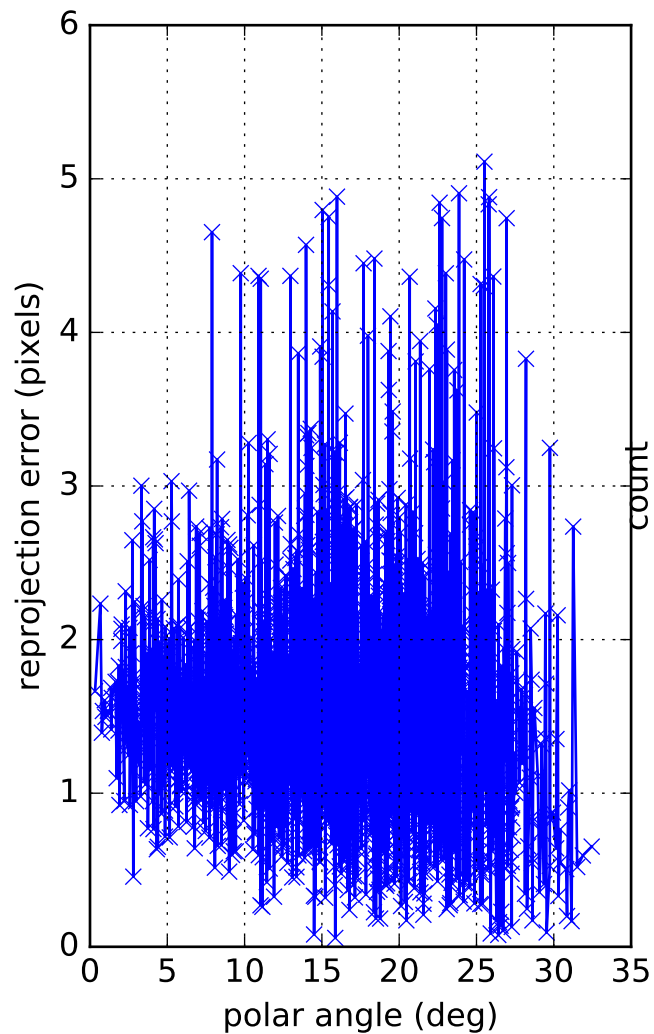
Inter-camera observations graph (edge weight=#mutual obs.)



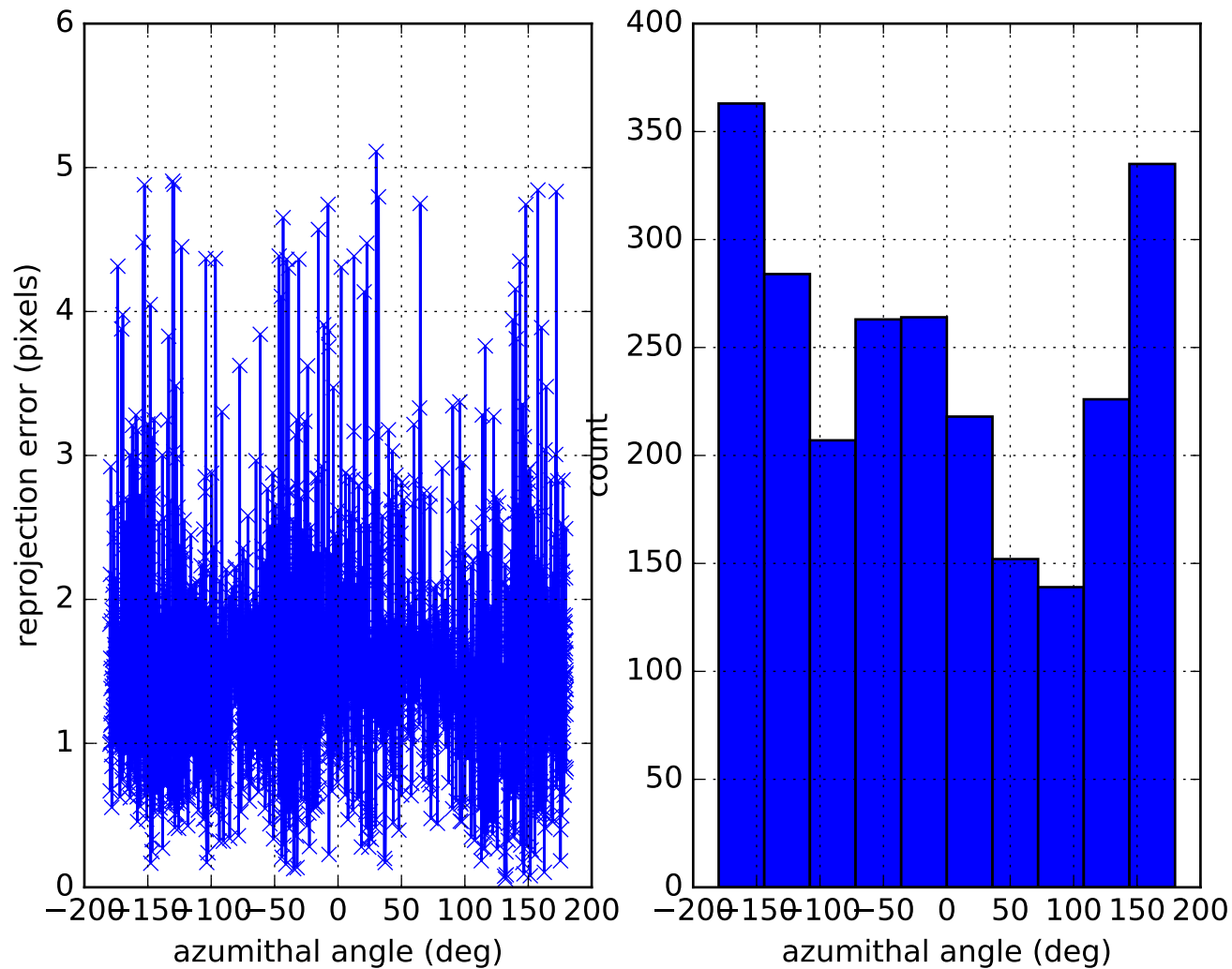
camera system



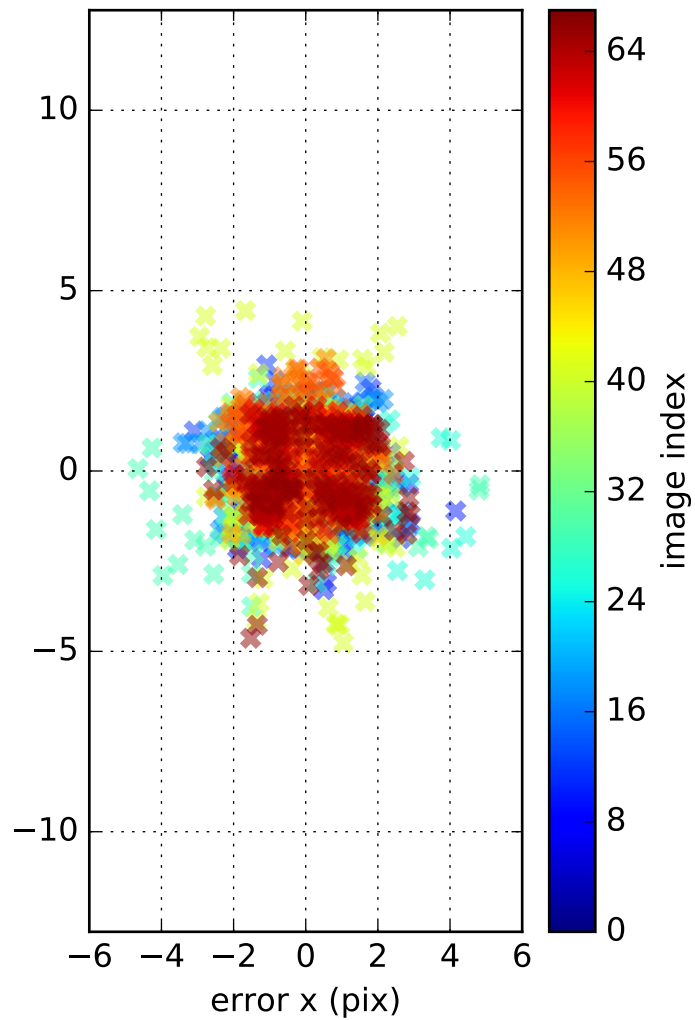
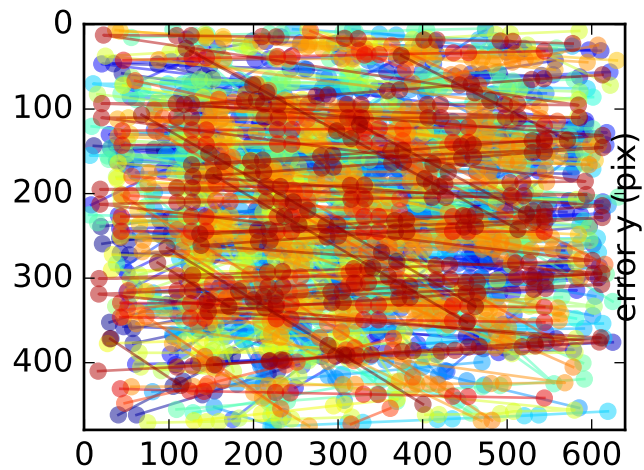
cam0: polar error



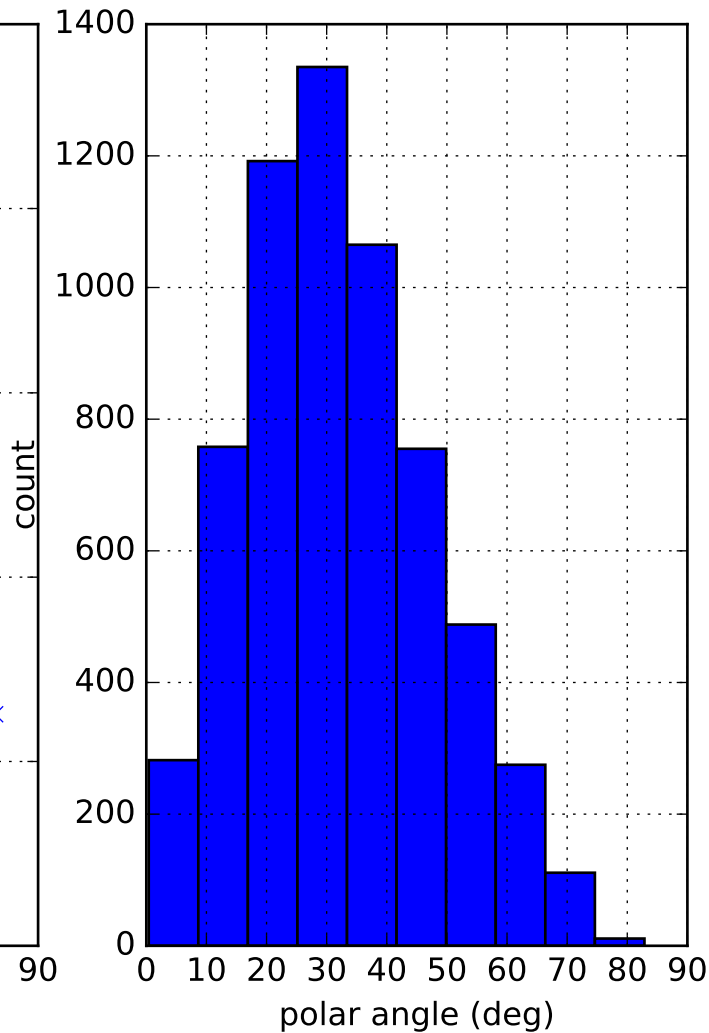
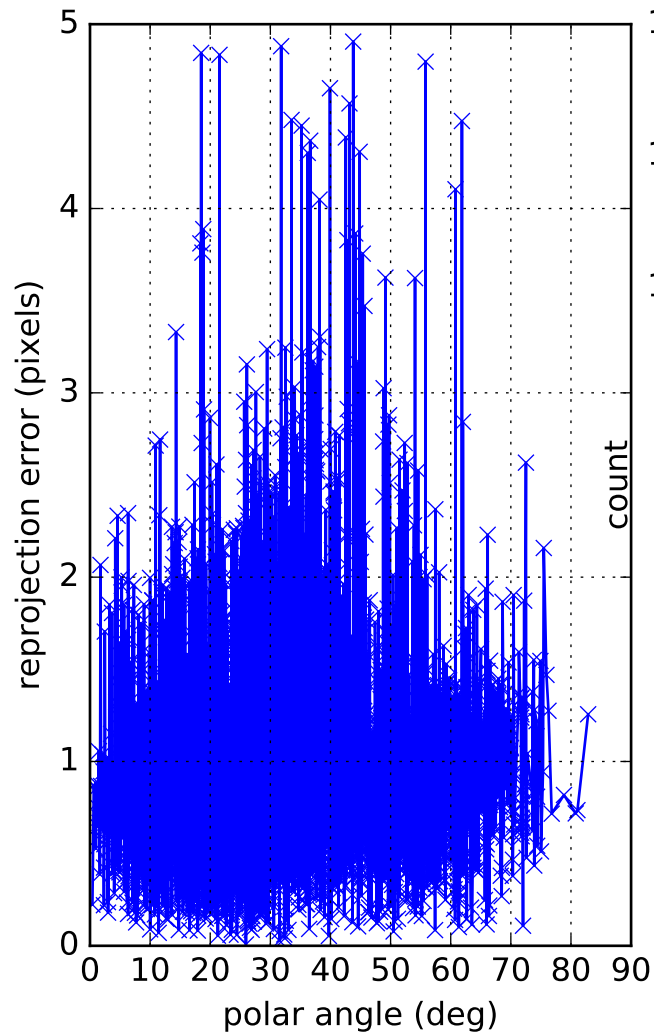
cam0: azimuthal error



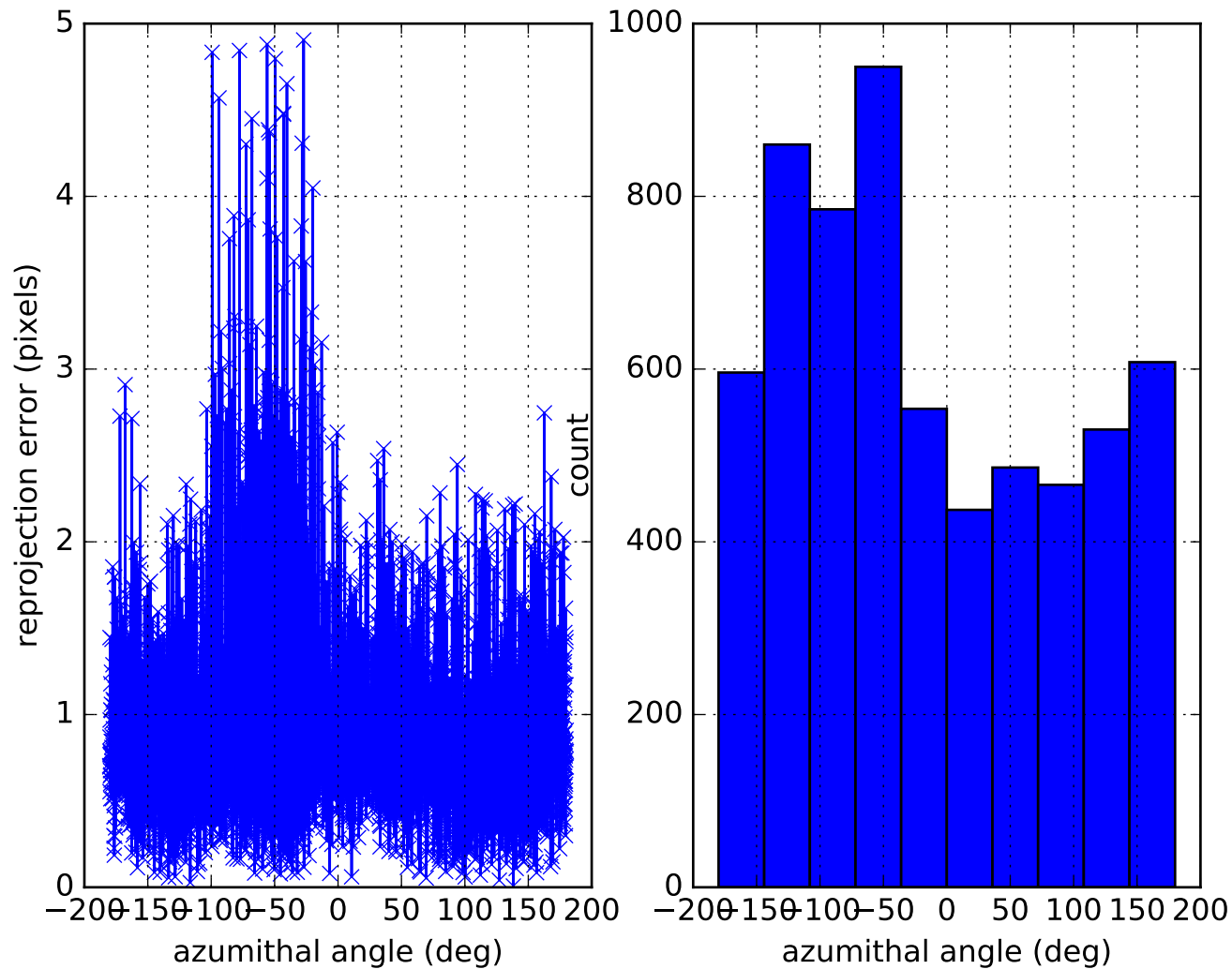
cam0: reprojection errors



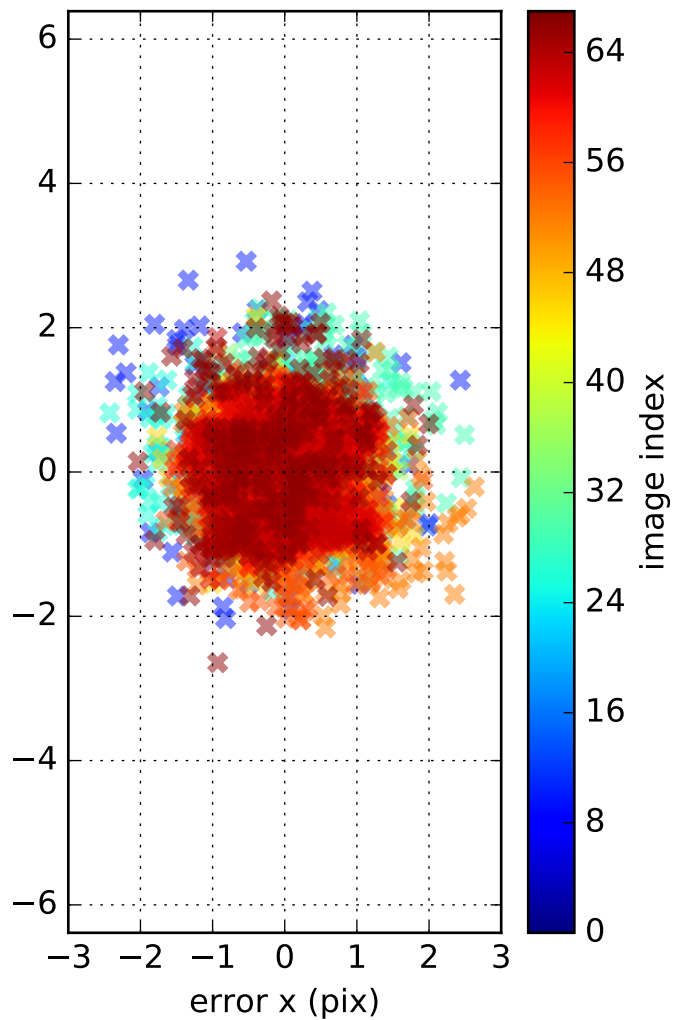
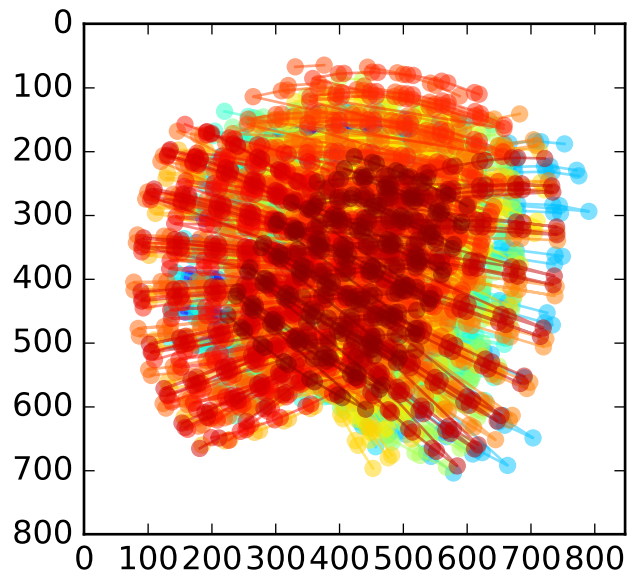
cam1: polar error



cam1: azimuthal error



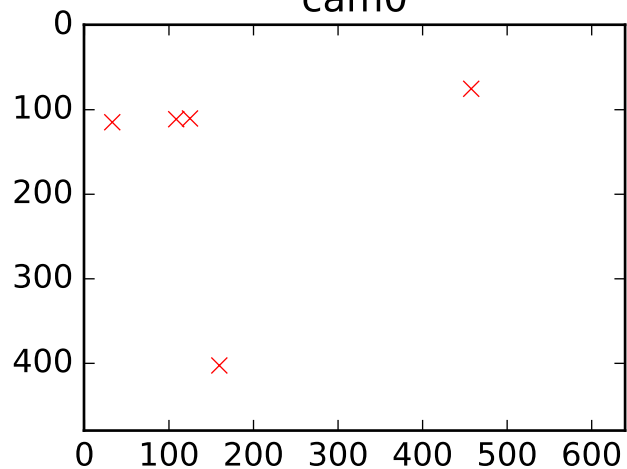
cam1: reprojection errors





# Location of removed outlier corners

cam0



cam1

