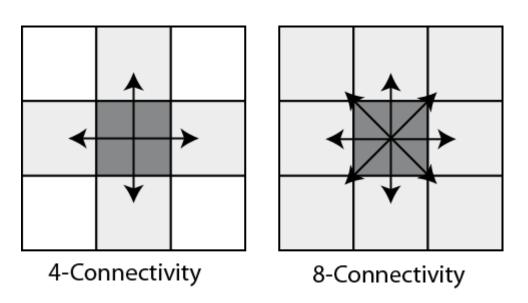
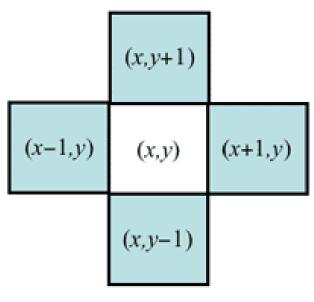
# CST382-3 Digital Image Processing

### Pixel Relationship

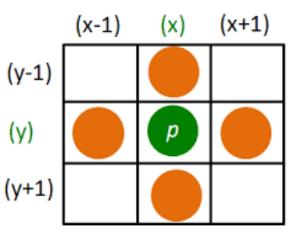
- Neighborhood
- Connectivity
- Adjacency



# Neighborhood N<sub>4</sub>(p)

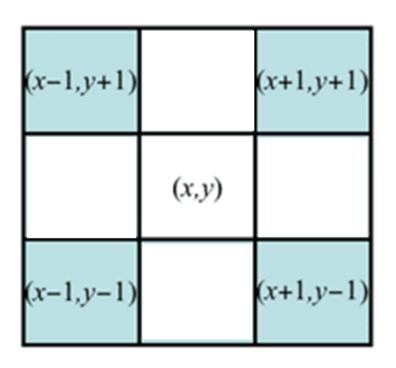


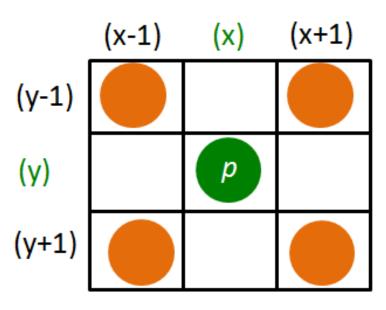
4-neighbourhood



4-neighbors N<sub>4</sub>(p)

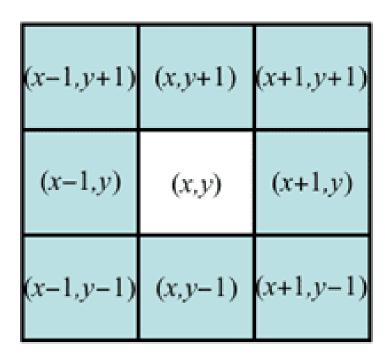
# Neighborhood N<sub>D</sub>(p)



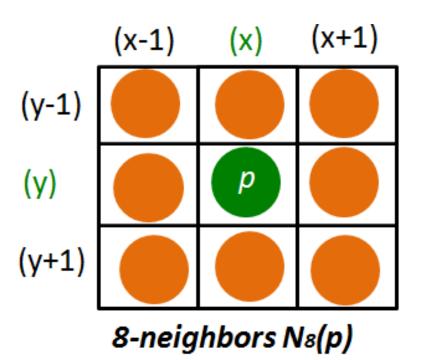


Diagonal neighbors N<sub>d</sub>(p)

## Neighborhood N<sub>8</sub>(p)



8-neighbourhood



### Object and Connection

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1	0
0	1	1	1	1	1	1	1	1	0	0	1	1	1	1	0	0
0	0	0	1	1	1	1	0	0	0	1	1	1	1	0	0	0
0	0	1	1	1	1	0	0	0	1	1	1	0	0	1	1	0
0	1	1	1	0	0	1	1	0	0	0	1	1	1	0	0	0
0	0	1	1	0	0	0	0	0	1	1	0	0	0	1	1	0
0	0	0	0	0	0	1	1	1	1	0	0	1	1	1	1	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

### Adjacency and Connectivity

- Let *V*: a set of intensity values used to define adjacency and connectivity.
- In a binary image,  $V = \{1\}$ , if we are referring to adjacency of pixels with value 1.
- In a gray-scale image, the idea is the same, but *V* typically contains more elements, for example, *V* = {180, 181, 182, ..., 200}
- If the possible intensity values 0 255, *V* set can be any subset of these 256 values.

### Type of Adjacency

- **1. 4-adjacency:** Two pixels p and q with values from V are 4-adjacent if q is in the set  $N_4(p)$ .
- **2. 8-adjacency:** Two pixels p and q with values from V are 8-adjacent if q is in the set  $N_8(p)$ .
- **3.** m-adjacency = (mixed) Two pixels *p* and *q* with the values from V are m-adjacent if
  - -q is in N4(p), or
  - -q is in  $N_D(p)$  and the set N4(p)  $\cap$  N4(q) has no pixels whose values are from V.

### Question

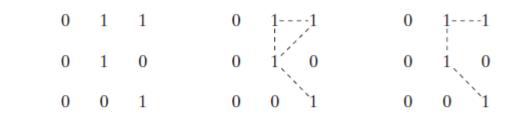
Consider the two image subsets, and shown in the following figure. For determine whether these two subsets are (a) 4-adjacent, (b) 8-adjacent, or (c) *m*-adjacent.

		5	1		$S_2$				
0	10	0	0	0	[0	0	1	1	0
1	0 0 0	0	1	0	0	1	0	0	1
1	0	0	1	0	1	1	0	0	0
0	<u>[0</u>	1_	1_	_1_	0	0_	0	0	0
0	0	1	1	1	0	0	1	1	1

### Digital Path

- A digital path (or curve) from pixel p with coordinate (x,y) to pixel q with coordinate (s,t) is a sequence of distinct pixels with
  - coordinates  $(x_0,y_0)$ ,  $(x_1,y_1)$ , ...,  $(x_n,y_n)$  where  $(x_0,y_0) = (x,y)$  and  $(x_n,y_n) = (s,t)$  and pixels  $(x_i,y_i)$  and  $(x_{i-1},y_{i-1})$  are adjacent for  $1 \le i \le n$
- n is the length of the path
- If  $(x_0,y_0) = (x_n,y_n)$ , the path is closed.
- We can specify 4-, 8- or m-paths depending on the type of adjacency specified.

### Digital Path



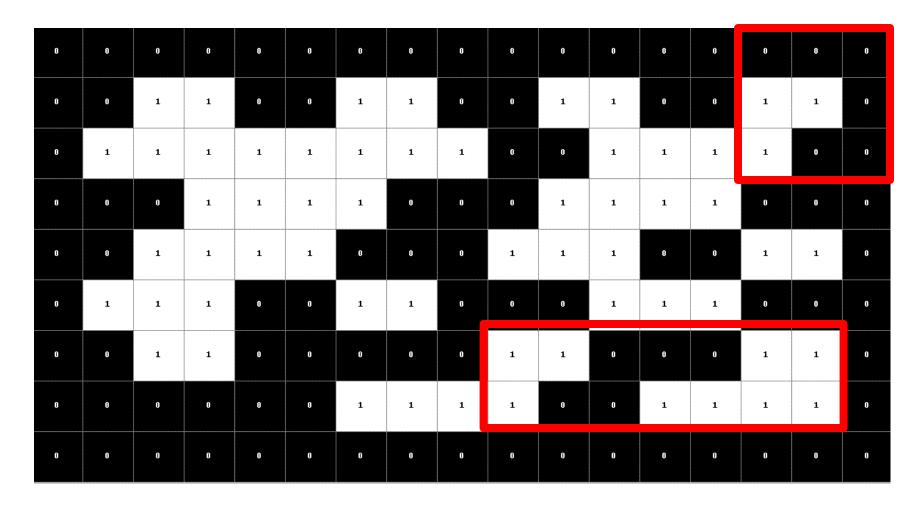
a b c

**FIGURE 2.26** (a) Arrangement of pixels; (b) pixels that are 8-adjacent (shown dashed) to the center pixel; (c) *m*-adjacency.

### Connectivity

- Let S represent a subset of pixels in an image.
- Two pixels *p* and *q* are said to be *connected* in *S* if there exists a path between them consisting entirely of pixels in *S*.
- For any pixel p in S, the set of pixels that are connected to it in S is called a connected component of S.
  - $-S = \{p,q,r,s\}$
- Only one connected component, then set S is called a *connected set*.

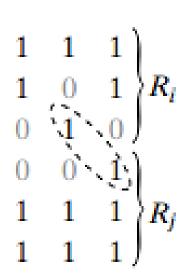
## Connectivity



### Region and Boundary

#### Region

- Let R be a subset of pixels in an image, we call R a **region** of the image if R is a connected set.
- Two regions, and are said to be adjacent if their union forms a connected set.
- Regions that are not adjacent are said to be *disjoint*.
- We consider 4- and 8-adjacency when referring to regions.



## Region and Boundary

#### Boundary

The *boundary* (also called the *border* or *contour*) of a region *R* is

 the set of points that are adjacent to points in the complement of *R*.

#### OR

 the set of pixels in the region that have at least one background neighbor.

1	1	1	1
1	1	1	1
1	1	1	1
1	1	1	1
1	1	1	1

0	0	0	0
1	1	1	0
1	1	1	0
1	1	1	0
0	0	0	0

- If *R* happens to be an entire image, then its boundary is defined as the set of pixels in the first and last rows and columns in the image.
- This extra definition is required because an image has no neighbors beyond its borders
- Normally, when we refer to a region, we are referring to subset of an image, and any pixels in the boundary of the region that happen to coincide with the border of the image are included implicitly as part of the region boundary.

 For pixels p, q and z, with coordinates (x,y), (s,t) and (v,w), respectively, D is a distance function if:

(a) 
$$D(p,q) \ge 0$$
 ( $D(p,q) = 0$  iff  $p = q$ ),

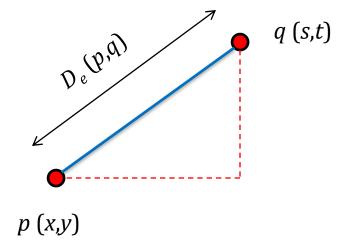
(b) 
$$D(p,q) = D(q,p)$$
, and

(c) 
$$D(p,z) \leq D(p,q) + D(q,z)$$
.

• The *Euclidean Distance* between *p* and *q* is defined as:

$$D_e(p,q) = [(x-s)^2 + (y-t)^2]^{1/2}$$

Pixels having a distance less than or equal to some value r from (x,y) are the points contained in a disk of radius r centered at (x,y)



• The  $D_4$  distance (also called city-block distance) between p and q is defined as:

$$D_4(p,q) = |x - s| + |y - t|$$

Pixels having a  $D_4$  distance from (x,y), less than or equal to some value r form a Diamond  $D_4$  centered at (x,y)

#### Example:

The pixels with distance  $D_4 \le 2$  from (x,y) form the following contours of constant distance.

The pixels with  $D_4 = 1$  are the 4-neighbors of (x,y)

• The  $D_8$  distance (also called chessboard distance) between p and q is defined as:

$$D_{8}\left(p,q\right) = \max(\mid x - s \mid, \mid y - t \mid)$$

Pixels having a  $D_8$  distance from (x,y), less than or equal to some value r form a square Centered at (x,y)  $D_8 = \max(D_{8(a)}, D_{8(b)})$ 

#### Example:

 $D_8$  distance  $\leq 2$  from (x,y) form the following contours of constant distance.

```
2
2
2
2

2
1
1
1
2

2
1
0
1
2

2
1
1
1
2

2
2
2
2
2
```

#### Dm distance:

is defined as the shortest m-path between the points.

In this case, the distance between two pixels will depend on the values of the pixels along the path, as well as the values of their neighbors.

#### • Example:

Consider the following arrangement of pixels and assume that p,  $p_2$ , and  $p_4$  have value 1 and that  $p_1$  and  $p_3$  can have a value of 0 or 1

Suppose that we consider the adjacency of pixels values 1 (i.e.  $V = \{1\}$ )

```
p_3 p_4 p_1 p_2 p
```

Cont. Example:

Now, to compute the  $D_m$  between points p and  $p_4$ 

Here we have 4 cases:

**Case1:** If  $p_1 = 0$  and  $p_3 = 0$ 

The length of the shortest m-path (the  $D_m$  distance) is 2  $(p, p_2, p_4)$ 

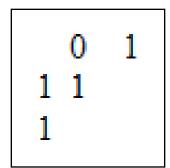
0 1 0 1 1

Cont. Example:

**Case2:** If  $p_1 = 1$  and  $p_3 = 0$ 

now,  $p_1$  and p will no longer be adjacent (see m-adjacency definition)

then, the length of the shortest path will be 3  $(p, p_1, p_2, p_4)$ 



Cont. Example:

**Case3:** If  $p_1 = 0$  and  $p_3 = 1$ 

The same applies here, and the shortest –m-path will be 3  $(p, p_2, p_3, p_4)$ 

1 1 0 1 1

Cont. Example:

**Case4:** If  $p_1 = 1$  and  $p_3 = 1$ 

The length of the shortest m-path will be 4  $(p, p_1, p_2, p_3, p_4)$ 

1 1 1 1 1