

Certificate

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(N.B: The candidate is expected to retain his/her journal till he/she passes in the subject.)

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(1) Write a program to conduct uninformed Search.

(2) Breadth First Search.

from collections import defaultdict

class Graph:

```
def __init__(self):
```

```
    self.graph = defaultdict(list)
```

```
def addEdge(self, u, v):
```

```
    self.graph[u].append(v)
```

```
def BFS(self, v):
```

```
    print("The BFS traversal of the given graph is as follows :")
```

```
visited = [False] * (max(self.graph) + 1)
```

```
queue = []
```

```
queue.append(v)
```

```
visited[v] = True
```

```
while queue:
```

```
v = queue.pop(0)
```

```
print(v, end = " ")
```

```
for neighbour in self.graph[v]:
```

```
if visited[neighbour] == False:
```

```
queue.append(neighbour)
```

```
visited[neighbour] = True
```

My graph = graph()

My graph.addEdge(0, 1)

My graph.addEdge(0, 2)

My graph.addEdge(1, 2)

My graph.addEdge(2, 0)

My graph.addEdge(2, 3)

My graph.addEdge(3, 3)

My graph.BFS(2)

Output

The BFS traversal of the given graph is as follows,

2 0 3 1

(b) Depth First Search.

from collections import defaultdict

class Graph:

```
def __init__(self):
    self.graph = defaultdict(list)
```

```
def addEdge(self, u, v):
```

```
    self.graph[u].append(v)
```

```
def DFSUtil(self, v, visited):
```

```
    visited.add(v)
```

```
    print(v, end=" ")
```

for neighbour in self.graph[v]:

if neighbour not in visited:

```
    self.DFSUtil(neighbour, visited)
```

```
def DFS(self, v):
```

```
    visited = set()
```

```
    print("The DFS traversal is as follows : ")
```

```
    self.DFSUtil(v, visited)
```

Mygraph = Graph()

Mygraph.addEdge(0, 1)

Mygraph.addEdge(0, 2)

Mygraph.addEdge(1, 2)

Mygraph.addEdge(2, 0)

Mygraph.addEdge(2, 3)

Mygraph.addEdge(3, 3)

Mygraph.DFS(2)

Output

The DFS traversal is as follows :

2 0 1 3

- (2) Write a program to conduct informed Search.
 (a) Best first Search

from queue import Priority Queue

$V = 14$

graph = [[] for i in range(V)]

gives o/p path having lowest search

def best-first-search (source, target, n):
 visited = [0] * n.

visited[0] = 1

pq = Priority Queue()

pq.put((0, source))

while pq.empty() == False:

u = pq.get()[1]

Displaying the path having lowest cost

print(u, end=' ')

if u == target:

break.

for v, c in graph[u]:

if visited[v] == 0:

visited[v] = 1

pq.put((c, v))

print()

adding edges to graph

def addedge(x, y, cost):

graph[x].append((y, cost))

graph[y].append((x, cost))

add edge (0, 1, 3)

add edge (0, 2, 6)

add edge (0, 3, 5)

add edge (1, 4, 9)

add edge (1, 5, 8)

add edge (2, 6, 12)

add edge (2, 7, 14)

add edge (3, 8, 7)

add edge (8, 9, 5)

add edge (8, 10, 6)

add edge (9, 11, 1)

add edge (9, 12, 10)

add edge (9, 13, 2)

source = 0

target = 9

best-first-search(source, target, V)

out put

0 1 3 2 8 9

(b) A* Algorithm

class Node():

```

    def __init__(self, parent=None, position=None):
        self.parent = parent
        self.position = position
        self.g = 0
        self.h = 0
        self.f = 0

    def __eq__(self, other):
        return self.position == other.position

```

def astar(maze, start, end):

start_node = Node(None, start)

start_node.g = start_node.h = start_node.f = 0

end_node = Node(None, end)

end_node.g = end_node.h = end_node.f = 0

open_list = []

closed_list = []

open_list.append(start_node)

while len(open_list) > 0:

current_node = open_list[0]

current_index = 0

for index, item in enumerate(open_list):

if item.f < current_node.f:

current_node = item

current_index = index

open_list.pop(current_index)

closed_list.append(current_node)

```

if current-node == end-node :
    path = []
    current = current-node.
while current is not None :
    path.append(current.position)
    current = current.parent -
return path[::-1]

children = []
for new-position in [(0,-1), (0,1), (-1,0), (1,0),
                     (-1,-1), (1,-1), (1,1), (-1,1)]:
    node-position = (current-node.position[0] +
                      new-position[0],
                      current-node.position[1] +
                      new-position[1])
    if node-position[0] > (len(maze) - 1) or
       node-position[0] < 0 or node-position[1] >
       (len(maze [len(maze) - 1]) - 1) or node-position[1] < 0:
        continue.
    if maze [node-position[0]][node-position[1]] != 0:
        continue.
    new-node = Node (current-node, node-position)
    children.append (new-node)

for child in children:
    for closed-child in closed-list:
        if child == closed-child:
            continue.
    child.g = current-node.g + 1

```

$\text{child.h} = (\text{child.position}[0] - \text{end-node.position}[0])^2 + (\text{child.position}[1] - \text{end-node.position}[1])^2$

$\text{child.f} = \text{child.g} + \text{child.h}$

for open-node in open-list :

if child == open-node and child.g > open-node.g :
continue.

open-list.append(child)

def main() :

```
maze = [[0, 0, 0, 0, 1, 0],
        [0, 0, 0, 0, 1, 0],
        [0, 0, 0, 0, 1, 0],
        [0, 0, 0, 0, 1, 0],
        [0, 0, 0, 0, 1, 0],
        [0, 0, 0, 0, 1, 0]]
```

```
graph = [[0, 1, 0, 0, 0, 0, 0],
          [1, 0, 1, 0, 1, 0],
          [0, 1, 0, 0, 0, 1],
          [0, 0, 0, 0, 1, 0],
          [0, 1, 0, 1, 0, 0],
          [0, 0, 1, 0, 0, 0]]
```

start = (0, 0)

end = (5, 5)

end1 = (5, 5)

path = aStar(maze, start, end)

print(path)

path1 = aStar(graph, start, end1)

if __name__ == "__main__":
 main()

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Output

[(0,0) , (1,1) , (2,2) , (3,3) , (4,4) , (5,5)]

[(0,0) , (1,1) , (2,2) , (3,3) , (4,4) , (5,5)]

(C) Hill climbing Algorithm

```
import random
```

```
def randomSolution(tsp):
    cities = list(range(len(tsp)))
    solution = []
```

```
for i in range(len(tsp)):
    randomCity = cities[random.randint(0, len(cities)-1)]
    solution.append(randomCity)
    cities.remove(randomCity)
```

```
return solution.
```

```
def routeLength(tsp, solution):
    routeLength = 0
    for i in range(len(solution)):
        routeLength += tsp[solution[i-1]][solution[i]]
    return routeLength.
```

```
def getNeighbours(solution):
    neighbours = []
    for i in range(len(solution)):
        for j in range(i+1, len(solution)):
            neighbour = solution.copy()
            neighbour[i] = solution[j]
            neighbour[j] = solution[i]
```

neighbours, append (neighbour)
return neighbours.

def getBestNeighbour(tsp, neighbours):

bestRouteLength = routeLength(tsp, neighbours[0])

bestNeighbour = neighbours[0]

for neighbour in neighbours:

currentRouteLength = routeLength(tsp, neighbour)

if currentRouteLength < bestRouteLength:

bestRouteLength = currentRouteLength

bestNeighbour = neighbour

return bestNeighbour, bestRouteLength.

def hillClimbing(tsp):

currentSolution = randomSolution(tsp)

currentRouteLength = routeLength(tsp, currentSolution)

neighbours = getNeighbours(currentSolution)

bestNeighbour, bestNeighbourRouteLength = getBestNeighbour(tsp,
neighbours)

while bestNeighbourRouteLength < currentRouteLength:

currentSolution = bestNeighbour

currentRouteLength = bestNeighbourRouteLength

neighbours = getNeighbours(currentSolution)

bestNeighbour, bestNeighbourRouteLength = getBestNeighbour(tsp,
neighbours)

return currentSolution, currentRouteLength.

```
def main():
    tsp = [
        [0, 400, 500, 300],
        [400, 0, 300, 500],
        [500, 300, 0, 400],
        [300, 500, 400, 0]
    ]
    print(hillClimbing(tsp))
```

```
if __name__ == "__main__":
    main()
```

Output

([1, 2, 3, 0] , 1400)

(3) Implementation of Game Search.

(a) Minimax Algorithm

```
import math
```

```
def minimax (curDepth, nodeIndex, maxTurn, scores,
             targetDepth):
    if (curDepth == targetDepth):
        return scores [nodeIndex]

    if (maxTurn):
        return max (minimax (curDepth + 1, nodeIndex * 2,
                             False, scores, targetDepth),
                  minimax (curDepth + 1, nodeIndex * 2 + 1,
                             False, scores, targetDepth))

    else:
        return min (minimax (curDepth + 1, nodeIndex * 2,
                             True, scores, targetDepth),
                  minimax (curDepth + 1, nodeIndex * 2 + 1,
                             True, scores, targetDepth))
```

```
scores = [3, 5, 2, 9, 12, 5, 23, 23]
```

```
treeDepth = math.log (len (scores), 2)
```

```
print ("The optimal value is : ", end = "")
```

```
print (minimax (0, 0, True, scores, treeDepth))
```

output

The optimal value is: 12.

(b) Alpha Beta Pruning

$\text{MAX}, \text{MIN} = 1000, -1000$

```
def minimax(depth, nodeIndex, maximizingPlayer, values,
           alpha, beta):
```

```
    if depth == 3:
```

```
        return values[nodeIndex]
```

```
    if maximizingPlayer:
```

```
        best = MIN
```

```
        for i in range(0, 2):
```

```
            val = minimax(depth+1, nodeIndex*2+i,
                           False, values, alpha, beta)
```

```
            best = max(best, val)
```

```
            alpha = max(alpha, best)
```

```
            if beta <= alpha:
```

```
                break.
```

```
        return best
```

```
    else:
```

```
        best = MAX
```

```
        for i in range(0, 2):
```

```
            val = minimax(depth+1, nodeIndex*2+i,
                           True, values, alpha, beta)
```

```
            best = min(best, val)
```

```
            beta = min(beta, best)
```

if beta <= alpha:
break.

return best.

```
if __name__ == "__main__":
    values = [3, 5, 6, 9, 1, 2, 0, -1]
    print("The optimal value is:", minimax(0, 0, True,
                                         values, MIN, MAX))
```

The optimal value is : 5

(a) Prolog(a) prime.pl

$\text{is-prime}(2).$ $\text{is-prime}(3).$ $\text{is-prime}(P) :- \text{integer}(P), P > 3,$

$P \bmod 2 = \backslash = 0,$
 $\backslash + \text{has-factor}(P, 3).$

$\% \text{ has-factor}(N, L) :- N \text{ has an odd factor } f \geq L.$
 $\% (\text{integer}, \text{integer}) (+, +)$

$\text{has-factor}(N, L) :- N \bmod L =:= 0,$

(b) factorial.pl

$\text{factorial}(0, 1).$

$\text{factorial}(N, F) :-$

$N > 0,$

$N_1 \text{ is } N - 1,$

$\text{factorial}(N_1, F_1), F \text{ is } N * F_1.$

(c) adjacent, pl.

adjacent (1,2). adjacent (2,1).
 adjacent (1,3). adjacent (3,1).
 adjacent (1,4). adjacent (4,1).
 adjacent (1,5). adjacent (5,1).
 adjacent (2,3). adjacent (3,2).
 adjacent (2,4). adjacent (4,2).
 adjacent (3,4). adjacent (4,3).
 adjacent (4,5). adjacent (5,4).

(d) family, pl.

%. This is the prolog version of the family example

child (john, sue). child (john, sam).
 child (jane, sue). child (jane, sam).
 child (sue, george). child (sue, gina).

male (john). male (sam). male (george).
 female (sue). female (jane). female (june).

parent (Y,X) :- child (X,Y).

father (Y,X) :- child (X,Y), male (Y).

oppsex (X,Y) :- male (X), female (Y).

opp-sex (Y,X) :- male (X), female (Y).

grand-father (X,Z) :- father (X,Y), parent (Y,Z).

(S) Bayesian Network.

→ from pgmpy.models import BayesianModel
 → from pgmpy.inference import VariableElimination

alarm_model = BayesianModel([('Burglary', 'Alarm'),
 ('Earthquake', 'Alarm'),
 ('Alarm', 'JohnCalls'),
 ('Alarm', 'MaryCalls')])

Defining the parameters using CPT
 → from pgmpy.factors.discrete import TabularCPD

Cpd_burglary = TabularCPD(variable = 'Burglary', variable_card=2,
 values = [[0.999], [0.001]])

Cpd_earthquake = TabularCPD(variable = 'Earthquake', variable_card=2,
 values = [[0.998], [0.002]])

Cpd_alarm = TabularCPD(variable = 'Alarm', variable_card=2,
 values = [[[0.999, 0.71, 0.06, 0.05],
 [0.001, 0.29, 0.94, 0.95]]],
 evidence = ['Burglary', 'Earthquake'],
 evidence_card = [2, 2])

Cpd_johncalls = TabularCPD(variable = 'JohnCalls', variable_card=2,
 values = [[0.95, 0.1], [0.05, 0.9]],
 evidence = ['Alarm'], evidence_card = [2])

```
cpd - Mary calls = tabularCPD(variable = 'Mary calls', variableCard = 2,  
values = [[0.1, 0.7], [0.9, 0.3]],  
evidence = ['Alarm'], evidenceCard = [2])
```

Associating the parameters with the model structure.

```
alarm-model.addCPDs(cpd - burglary, cpd - earthquake,  
cpd - alarm, cpd - john calls,  
cpd - mary calls)
```

→ alarm-model.checkModel()

(*) True.

→ alarm-model.nodes()

(*) NodeView(['Burglary', 'Alarm', 'Earthquake', 'John calls', 'Mary calls'])

→ alarm-model.edges()

(*) outEdgeView([('Burglary', 'Alarm'), ('Alarm', 'John calls'),
('Alarm', 'Mary calls'), ('Earthquake', 'Alarm')])

→ alarm-model.local-independencies('Burglary')

(Burglary ⊥ Earthquake).

(6) Bayesian Model

→ from pybbn.graph.dag import Bbn
 from pybbn.graph.edge import Edge, EdgeType
 from pybbn.graph.jointree import EvidenceBuilder
 from pybbn.graph.node import BbnNode
 from pybbn.graph.variable import variable
 from pybbn.graph.inferencecontroller import InferenceController.

→ Season = BbnNode(variable(0, 'season', ['winter', 'summer']),
 [0.5, 0.5])

atmos-pres = BbnNode(variable(1, 'atmos-pres', ['high', 'low']),
 [0.5, 0.5])

allergies = BbnNode(variable(2, 'allergies', ['allergic', 'non-allergic']),
 [0.7, 0.3, 0.2, 0.8])

rain = BbnNode(variable(3, 'rain', ['rainy', 'sunny']),
 [0.9, 0.1, 0.7, 0.3, 0.3, 0.7, 0.1, 0.9])

grass = BbnNode(variable(4, 'grass', ['grass', 'no-grass']),
 [0.8, 0.2, 0.3, 0.7])

umbrellas = BbnNode(variable(5, 'umbrellas', ['on', 'off']),
 [0.99, 0.01, 0.80, 0.20, 0.20, 0.80, 0.01,
 0.99])

dog-bark = BbnNode(variable(6, 'dog-bark', ['bark', 'not-bark']),
 [0.8, 0.2, 0.1, 0.9])

eat-mood = BbnNode(variable(7, 'cat-mood', ['good', 'bad']),
 [0.05, 0.95, 0.95, 0.05])

cat-hide = BbnNode(variable(8, 'cat-hide', ['hide', 'show']),
 [0.20, 0.80, 0.95, 0.05, 0.95, 0.05, 0.70, 0.30])

`bbn = Bbn()` \

- `add-node (season) \`
- `add-node (atmos-pres) \`
- `add-node (allergies) \`
- `add-node (rain) \`
- `add-node (grass) \`
- `add-node (umbrellas) \`
- `add-node (dog-bark) \`
- `add-node (cat-mood) \`
- `add-node (cat-hide) \`
- `add-edge (Edge (season, allergies, EdgeType.DIRECTED)) \`
- `add-edge (Edge (season, umbrellas, EdgeType.DIRECTED)) \`
- ~~`add-edge (Edge (season, rain, EdgeType.DIRECTED)) \`~~
- `add-edge (Edge (atmos-pres, rain, EdgeType.DIRECTED)) \`
- `add-edge (Edge (rain, grass, EdgeType.DIRECTED)) \`
- `add-edge (Edge (rain, umbrellas, EdgeType.DIRECTED)) \`
- `add-edge (Edge (rain, dog-bark, EdgeType.DIRECTED)) \`
- `add-edge (Edge (rain, cat-mood, EdgeType.DIRECTED)) \`
- `add-edge (Edge (dog-bark, cat-hide, EdgeType.DIRECTED)) \`
- `add-edge (Edge (cat-mood, cat-hide, EdgeType.DIRECTED)) \`

→ `join-tree = InferenceController.apply (bbn)`

insert an observation reference.

`ev = EvidenceBuilder()` \

- `with-node(join-tree.get-bbn-node-by-name('season')) \`
- `with-evidence('winter', 1.0) \`
- `build ()`

`join-tree.set-observation(ev)`

#print the marginal probabilities.

for node in join-tree.get_bbn_nodes() :

 potential = join-tree.get_bbn_potential(node)

 print(node)

 print(potential)

 print('----->')

(*) ① season | winter, summer .

0 = winter | 11,00000

0 = summer | 0.00000 .

----->

2 | allergies | allergic, non-allergic

2 = allergic | 0.70000

2 = non-allergic | 0.30000 .

----->

3 | rain | rainy, sunny .

3 = rainy | 0.80000 .

3 = sunny | 0.20000

----->

4 | grass | grass, no-grass

4 = grass | 0.70000

4 = no-grass | 0.30000

----->

1 | atmos-pres | high, low

1 = high | 0.50000

1 = low | 0.50000 .

----->

5 | umbrellas | on, off .

5 = on | 0.95200

5 = off | 0.04800

6 | dog-bark | bark, not-bark.

6 = bark | 0.66000

6 = not-bark | 0.34000.

- - - - - →

7 | cat-mood | good, bad.

7 = good | 0.23000.

7 = bad | 0.77000

- - - - - →

8 * cat-hide | hide, show.

8 = hide | 0.8750.

8 = Show | 0.1250.

→ join-tree = InferenceController.apply(bbn)

insert an observation evidence.

ev = EvidenceBuilder() \

- with-node (join-tree.get-bbn-node-by-name('season')) \
- with-evidence ('winter', 1.0) \
- build()

ev2 = EvidenceBuilder() \

- with-node (join-tree.get-bbn-node-by-name('dog-bark')) \
- with-evidence ('not-bark', 1.0) \
- build()

join-tree.set-observation(ev)

join-tree.set-observation(ev2)

print the marginal probabilities
 for node in join-tree, get-bbn-nodes();
 potential = join-tree.get-bbn-potential(node)
 print(node)
 print(potential)
 print('----->')

(#) 0 | season | winter, summer .

0 = winter | 1.00000

0 = Summer | 0.00000

----->

2 | allergies | allergic, non-allergic -

2 = allergic | 0.70000.

2 = non-allergic | 0.30000

----->

3 | rain | rainy, sunny .

3 = rainy | 0.47059

3 = sunny | 0.52941

----->

4 | grass | grass, no grass

4 = grass | 0.53529

4 = no-grass | 0.46471

----->

11 atmos-pres | high, low .

1 = high | 0.39706

1 = low | 0.60294

----->

5 | umbrellas | on, off -

5 = on | 0.88941

5 = off | 0.11059

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6 | dog-bark | bark, not-bark.

6 = bark | 0.00000

6 = not-bark | 1.00000

- - - - - →

7 | cat-mood | good, bad

7 = good | 0.52647.

7 = bad | 0.47353

- - - - - →

8 | cat-hide | hide, show

8 = hide | 0.83162

8 = show | 0.16838

- - - - - →

(7) Supervised Learning

→ `print(__doc__)`
`import matplotlib.pyplot as plt -`
`from sklearn import datasets, svm, metrics`
`from sklearn.model_selection import train_test_split -`

→ `digits = datasets.load_digits()`
`_, axes = plt.subplots(nrows=1, ncols=4, figsize=(10,3))`
`for ax, image, label in zip(axes, digits.images, digits.target):`
 `ax.set_axis_off()`
 `ax.imshow(image, cmap=plt.cm.gray_r, interpolation='nearest')`
 `ax.set_title('Training : %.1f %i' % (label))`

(*) Training:0 Training:1 Training:2 Training:3
 0 1 2 3

→ #flatten the images
`n_samples = len(digits.images)`
`data = digits.images.reshape((n_samples, -1))`

#create a classifier: a support vector classifier.
`clf = svm.SVC(gamma=0.001)`

split data into 50% train and 50% test subsets.
`X_train, X-test, y-train, y-test = train-test-split(`
 `data, digits.target, test_size=0.5, shuffle=False)`

Learn the digits on the train subset.

clf . fit (X-train, y-train)

predict the value of the digit on the test subset

Predicted = clf.predict (X-test)

→ axes = plt.subplots (nrows=1, ncols=4, figsize=(10,3))

for ax, image, prediction in zip (axes, X-test, predicted):
ax.set_axis_off()

image = image.reshape(8,8)

ax.imshow (image, cmap=plt.cm.gray_r, interpolation='nearest')

ax.set_title (f'Prediction: {prediction}').

(*) Prediction: 8	Prediction: 8	Prediction: 4	Prediction: 9
8	8	4	9

→ print(f"Classification report for classifier {clf}: \n {metrics.classification_report(y-test, predicted)} \n")

(*) Classification report for classifier SVC (gamma = 0.001):

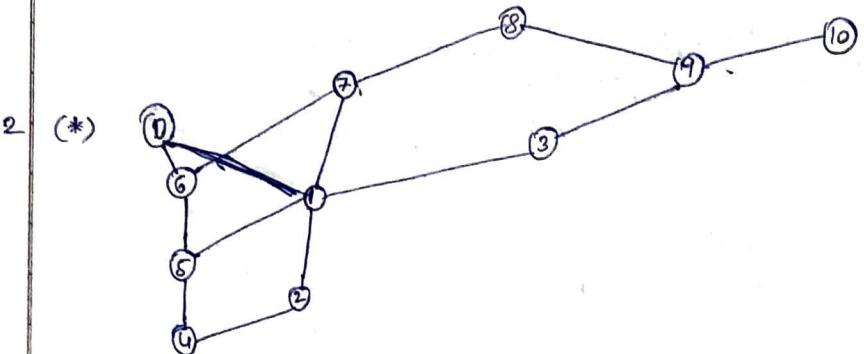
	precision	recall	f1-score	support
0	1.00	0.99	0.99	88
1	0.99	0.97	0.98	91
2	0.99	0.99	0.99	86.
3	0.98	0.87	0.92	91
4	0.99	0.96	0.97	92
5	0.95	0.97	0.96	91
6	0.99	0.99	0.99	91
7	0.96	0.99	0.97	89
8	0.94	1.00	0.97	88
9	0.93	0.98	0.95	92

Accuracy			0.97	899
Macro avg	0.97	0.97	0.97	899
Weighted avg.	0.97	0.97	0.97	899.

→ disp = metrics. plot_confusion_matrix (clf, X-test, y-test)
 disp.figure_.suptitle ("confusion matrix")
 print (f"confusion matrix: \n {disp.confusion_matrix}")
 plt.show()

(*) Confusion matrix:

```
[ [ 87  0  0  0  1  0  0  0  0  0 ]
  [ 0  88  1  0  0  0  0  0  1  1 ]
  [ 0  0  85  1  0  0  0  0  0  0 ]
  [ 0  0  0  79  0  3  0  4  5  0 ]
  [ 0  0  0  0  88  0  0  0  0  4 ]
  [ 0  0  0  0  0  88  1  0  0  2 ]
  [ 0  1  0  0  0  0  90  0  0  0 ]
  [ 0  0  0  0  0  0  1  0  88  0 ]
  [ 0  0  0  0  0  0  0  0  0  88 ]
  [ 0  0  0  1  0  0  0  0  0  90 ] ]
```

(8) Reinforcement Learning.

- 3 (*)
- (0,1)
 - (1,5)
 - (5,6)
 - (5,4)
 - (1,2)
 - (1,3)
 - (9,10)
 - (2,4)
 - (0,6)
 - (6,7)
 - (8,9)
 - (7,8)
 - (1,7)
 - (3,9)

→ import numpy as np
import pylab as pl
import networkx as nx

→ edges = [(0,1), (1,5), (5,6), (5,4), (1,2), (1,3),
(9,10), (2,4), (0,6), (6,7), (8,9),
(7,8), (1,7), (3,9)]

goal = 10
G = nx.Graph()

G.add_edges_from(edges)

pos = nx.spring_layout(G)

nx.draw_networkx_nodes(G, pos)

nx.draw_networkx_edges(G, pos)

nx.draw_networkx_labels(G, pos)

pl.show()

→ MATRIX-SIZE = 11

M = np.matrix(np.ones(shape=(MATRIX-SIZE, MATRIX-SIZE)))
M *= -1

for point in edges:

print(point)

if point[1] == goal:

M[point] = 100

else:

M[point] = 0

[-1.	0.	-1.	-1.	-1.	-1.	0.	-1.	-1.	-1.	-1.]
[0.	-1.	0.	0.	-1.	0.	-1.	0.	-1.	-1.	-1.]
[-1.	0.	-1.	-1.	0.	-1.	-1.	-1.	-1.	-1.	4.]
[-1.	0.	-1.	-1.	-1.	-1.	-1.	-1.	-1.	0.	-1.]
[-1.	-1.	0.	-1.	-1.	0.	-1.	-1.	-1.	-1.	-1.]
[-1.	0.	-1.	-1.	0.	-1.	0.	-1.	-1.	-1.	-1.]
[0.	-1.	-1.	-1.	0.	-1.	0.	-1.	-1.	-1.	-1.]
[-1.	0.	-1.	-1.	-1.	0.	-1.	0.	-1.	-1.	-1.]
[-1.	-1.	-1.	-1.	-1.	-1.	-1.	0.	* 4.	0.	-1.]
[-1.	-1.	-1.	0.	-1.	-1.	-1.	0.	-1.	100.	0.]
[-1.	-1.	-1.	-1.	-1.	-1.	-1.	-1.	-1.	0.	100.]

4 (*) 0

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1

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if point [o] = - goal :
 M[point [:: -1]] = 100

else :

$$M[\text{point} \{:: -1\}] = 0$$

```
M[goal, goal] = 100  
print(M)
```

$\Rightarrow Q = \text{np. matrix}(\text{np. zeros}((\text{MATRIX-SIZE}, \text{MATRIX-SIZE}))$

$$\gamma = 0.75$$

initial-state = 1

def available - actions(state);

Current-state-row = MCstate,]

`available_action = np.where((current_state_row >= 0) * 1)`
return `available_action`.

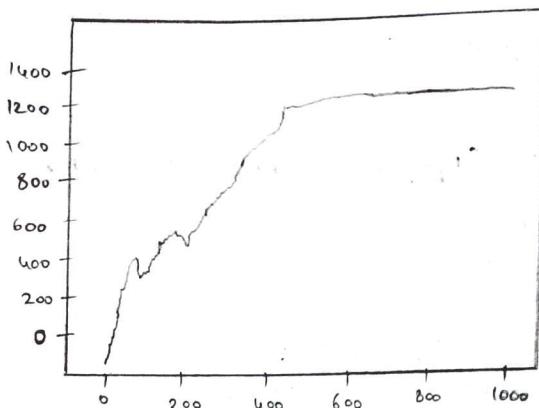
`available-action = available-actions (initial-state)`

```
def sample_next_action(available_actions_range):
```

```
next_action = int(np.random.choice(available_actions))  
return next_action
```

action = sample next-action (available-action)

5 (*) Most efficient path :
 $[0, 1, 3, 9, 10]$

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```

def update (current_state, action, gamma):
    max_index = np.where (Q[action, :] == np.max(Q[action, :]))
    if max_index.shape[0] > 1:
        max_index = int(np.random.choice(max_index, size=1))
    else:
        max_index = int(max_index)
    max_value = Q[action, max_index]
    Q[current_state, action] = M[current_state, action] + gamma * max_value
    if (np.max(Q) > 0):
        return (np.sum(Q / np.max(Q)*100))
    else:
        return (0)

update (initial_state, action, gamma)

```

→ Scores = []
for i in range(1000):
 current_state = np.random.randint(0, int(Q.shape[0]))
 available_action = available_actions(current_state)
 action = sample_next_action(available_action)
 score = update (current_state, action, gamma)
 scores.append(score)

current_state = 0
steps = [current_state]

while current_state != 10 :

 next_step_index = np.where(Q[current_state, :] == np.max(Q[current_state, :]))[1]

 if next_step_index.shape[0] > 1:

 next_step_index = int(np.random.choice(next_step_index, size=1))

 else :

 next_step_index = int(next_step_index)

 steps.append(next_step_index)

 current_state = next_step_index

print("Most efficient path:")

print(steps)

pl.plot(scores)

pl.xlabel('No. of iterations')

pl.ylabel('Reward gained')

pl.show()

(c) Artificial neural network with Back Propagation.

→ import numpy as np.

```
def sigmoid(x):
    return 1.0/(1.0 + np.exp(-x))
```

```
def sigmoid_prime(x):
    return sigmoid(x)*(1.0 - sigmoid(x))
```

```
def tanh(x):
    return np.tanh(x)
```

```
def tanh_prime(x):
    return 1.0 - x**2.
```

```
class NeuralNetwork:
```

```
    def __init__(self, layers, activation = 'tanh'):
        if activation == 'sigmoid':
            self.activation = sigmoid.
```

```
            self.activation_prime = sigmoid_prime.
```

```
        elif activation == 'tanh':
            self.activation = tanh.
```

```
            self.activation_prime = tanh_prime.
```

```
    self.weights = [ ]
```

```
    for i in range(1, len(layers) - 1):
        r = 2 * np.random.random((layers[i-1] + 1,
```

```
                                layers[i] + 1)) - 1
```

```
        self.weights.append(r)
```

$r = 2^* np.random.random((layers[i+1], layers[i+1])) - 1$

self.weights.append(r)

def fit(self, X, y, learning_rate=0.5, epochs=100000):

ones = np.atleast_2d(np.ones(X.shape[0]))

X = np.concatenate((ones.T, X), axis=1)

for k in range(epochs):

if k % 10000 == 0:

print('epochs:', k)

i = np.random.randint(X.shape[0])

a = [x[i]]

for l in range(len(self.weights)):

dot_value = np.dot(a[l], self.weights[l])

activation = self.activation(dot_value)

a.append(activation)

error = y[i] - a[-1]

deltas = [error * self.activation_prime(a[-1])]

for l in range(len(a) - 2, 0, -1):

deltas.append(deltas[-1].dot(self.weights[l].T) *

self.activation_prime(a[l]))

deltas.reverse()

for i in range(len(self.weights)):

layer = np.atleast_2d(a[i])

delta = np.atleast_2d(deltas[i])

self.weights[i] += learning_rate * layer.T.dot(delta)

Teacher's Signature _____

def predict(self, x):

a = np.concatenate((np.ones(1), T, np.array(x)))

for l in range(0, len(self.weights)):

a = self.activation(np.dot(a, self.weights[l]))

return a

if __name__ == '__main__':

nn = NeuralNetwork([2, 2, 1])

x = np.array([[0, 0],

[0, 1],

[1, 0],

[1, 1]])

y = np.array([0, 1, 1, 0])

nn.fit(x, y)

for e in x:

print(e, nn.predict(e))

(*) epochs : 0
epochs : 10 000
epochs : 20 000
epochs : 30 000
epochs : 40 000
epochs : 50 000
epochs : 60 000
epochs : 70 000
epochs : 80 000
epochs : 90 000

[0, 0] [-0.00533844]

[0, 1] [0.99779847]

[1, 0] [0.99770682]

[1, 1] [0.00568913]

(10) CHATBOT

- pip install chatterbot
 - pip install --upgrade chatterbot-coprus
 - pip install --upgrade chatterbot.

 - from chatterbot import chatbot
 from chatterbot.trainers import ListTrainer.
 my_bot = ChatBot('PyBot', read_only=True,
 logic_adapters=[{'chatterbot.logic.
 MathematicalEvaluation',
 'chatterbot.logic.BestMatch'})

 - Small_talk = ['hi there!',
 'hi!',
 'how do you do?',
 'how are you?',
 'i'm cool.',
 'fine, you?',
 'always cool.',
 'i'm ok.',
 'glad to hear that.',
 'i'm fine',
 'glad to hear that',
 'i feel awesome',
 'excellent, glad to hear that',
 'not so good',
 'sorry to hear that',
 'what's your name?',
 'i'm pybot. Ask me a math question, please.]
- Teacher's Signature _____

math_talk_1 = ['pythagorean theorem',
 'a squared plus b squared equals c squared']

math_talk_2 = ['law of cosines',
 ' $c^2 = a^2 + b^2 - 2 * a * b * \cos(\gamma)$ ']

→ list_trainer = ListTrainer(my-bot)
 for item in (small_talk, math_talk_1, math_talk_2):
 list_trainer.train(item)

(*) list_trainer : [#####] 100%.
 List Trainer : [#####] 100%.
 List Trainer : [#####] 100%.

→ print(my-bot.get_response('glad to hear that'))
 (*) i'm fine

→ print(my-bot.get_response("i feel awesome today"))
 (*) excellent, glad to hear that,

→ print(my-bot.get_response("what's your name?"))
 (*) i'm pybot. ask me a math question, please.

→ print(my-bot.get_response("pythagorean theorem"))
 (*) a squared plus b squared equals c squared.

→ from chatterbot.trainers import chatterBotCorpusTrainer
corpus_trainer = chatterBotCorpusTrainer('my-bot')
corpus_trainer.train('chatterbot.corpus.english')

(*) training ai.yml : [# # # # # # #] 100%.

training bot_profile.yml : 1

training computers.yml :

training conversations.yml :

training emotion.yml :

training food.yml :

training gossip.yml :

training greetings.yml :

training health.yml :

training history.yml :

training humor.yml :

training literature.yml :

training money.yml :

training movies.yml :

training politics.yml :

training psychology.yml :

training science.yml :

training sports.yml :

training trivia.yml .

→ print (my-bot.get_response("movies"))

(*) what kind of movies do you like?

→ from chatterbot import chatbot
from chatterbot.trainers import ListTrainer

chatbot = chatBot('CBIT')
trainer = ListTrainer(chatbot)
trainer.train(['hi, can I help you find a course',
 'sure i'd love to find you a course',
 'your course has been selected'])

response = chatbot.get_response("I want a course")
print(response)

(*) List Trainer : [# # # # # # # #] 100%
sure i'd love to find you a course

(II) Operations on text data.(a) Removal of punctuations in the given string

→ punctuations = " !(){};:'"\, <>./?@#\$%^&*~"

my-str = input ("Enter a string :")

no-punct = ""

for char in my-str :

if char not in punctuations :

no-punct = no-punct + char.

print (no-punct)

(*) Enter a string : Hello!!!, They said -- and went.

Hello they said and went.

(b) Generation of string tokens

→ import secrets

→ secrets.randbelow(2)

Secrets. randbelow(10)

secrets. randbelow(1)

secrets. randbelow(9)

(*) 1

→ Secrets. randbits(12)

Secrets. randbits(2)

Secrets. randbits(4)

secrets. randbits(8)

(*) 188

→ colour = ['red', 'blue', 'green', 'purple', 'yellow']
 secrets.choice(colour)

(*) 'blue'

→ Secrets.token - bytes (8)

(*) b'P\x80\x92\x05f3\x9c\xf5'

→ b'\x1b9\x8e\x83\x08\xb2g\x17'

(*) b'\x1b9\x8e\x83\x08\xb2g\x17'

→ secrets.token - hex (16)

(*) '0a68045533f550f3d8ad80e2dded82b'

→ Secrets.token - urlSafe(16)

(*) 'uVyVdGIAghQvP6muW46uw'

→ import string # alphanumeric 10 digit password.

import secrets

alphabet = string.ascii_letters + string.digits

password = ''.join(secrets.choice(alphabet) for i in range(10))

print(password)

(*) uAgidwPvwD

→ import string

import secrets

alphabet = string.hexdigits + string.punctuation

password = ''.join(secrets.choice(alphabet) for i in range(10))

print(password)

(*) -}[@]}][`"

→ import string
 import secrets
 alphabet = string.ascii_letters + string.digits
 while True:
 password = ''.join(secrets.choice(alphabet) for i in range(10))
 if (any(c.islower() for c in password) and any(c.isupper()
 for c in password) and any(c.isdigit() for c in password)):
 break

print(password)
 (*) OHmNr ThYZP

→ import string
 import secrets
 alphabet = string.ascii_letters + string.digits.
 while True:
 password = ''.join(secrets.choice(alphabet) for i in range(10))
 if (sum(c.isupper() for c in password) >= 2 and sum(c.isdigit()
 for c in password) >= 2):
 break.

print(password)
 (*) US126 dF8Pq.

→ import secrets
 animal = ['horse', 'elephant', 'monkey', 'donkey', 'goat', 'chicken',
 'duck', 'mouse']
 fruit = ['apple', 'banana', 'peach', 'orange', 'papaya', 'watermelon',
 'durian']
 electronic = ['computer', 'laptop', 'smartphone', 'battery', 'charger',
 'cable']

Vegetable = ['cabbage', 'lettuce', 'spinach', 'celery', 'cucumber', 'eggplant']
'turnip'

password = set()

while True :

 password.add(secrets.choice(word-list))

 if len(password) >= 4:

 break.

print(*.join(password))

(*) battery peach donkey smartphone

→ import secrets

url = 'https://mywebsite/reset?key=' + secrets.token_urlsafe()

print(url)

(*) https://mywebsite/reset?key=ia-icSM2Ahrs3o5kohREJ5unpbHuy

(12) Operations using nltk.

(a) Removal of stop words for a given passage from a text file

→ import nltk

nltk.download('stopwords')

(*) [nltk-data] Downloading package Stopwords to /root/nltk-data...
[nltk-data] unzipping corpora/stopwords.zip.
true

→ import nltk

nltk.download('punkt')

(*) [nltk-data] Downloading package punkt to /root/nltk-data...
[nltk-data] unzipping tokenizers/punkt.zip.
true

→ import nltk.

from nltk.corpus import stopwords

from nltk.tokenize import word_tokenize

set(stopwords.words('english'))

text = """ He determined to drop his litigation with the monastery & relinquish his claims to the wood-cutting & fishery rights at once. He was the more ready to do this because the rights had become much less valuable, and he had indeed the vaguest idea where the wood and river in question were. """

stop-words = set (stop words. words('english'))

word-tokens = word_tokenize(text)

filtered-sentence = []

for w in word-tokens:

if w not in stop-words:

filtered-sentence.append(w)

```
print ("\\n\\n Original Sentence \\n\\n")
```

```
print (" ".join (word-tokens))
```

```
print ("\\n\\n Filtered Sentence \\n\\n")
```

```
print (" ".join (filtered-sentence))
```

(*) original sentence

He determined to drop his litigation with the monastery, and relinquish his claims to the wood-cutting and fishing rights at once.

He was the more ready to do this because the rights had become much less valuable, and he had indeed the vaguest idea where the wood and river in question were.

Filtered sentence

He determined drop litigation monastery, relinquish claims wood-cutting fishing rights. He ready because rights become much less valuable, indeed vaguest idea.
wood river question.

(b) stemming for a given sentence

→ from nltk.stem import PorterStemmer

st = PorterStemmer()

text = ['where did he learn to dance like that?']

'His eyes were dancing with humor.'

'she shook her head and danced away'

'alex was an excellent dancer']

output = []

for sentence in text :

 output.append(" ".join([st.stem(i) for i in
 sentence.split(")]))

for item in output :

 print(item)

print("-" * 50)

print(st.stem('jumping'), st.stem('jumps'), st.stem('jumped'))

(*) where did he learn to dance like that?

hi eye were danc with humor.

she shook her head and danc away

alex wa an exel dancer.

jump jump jump

(c) POS tagging for a given sentence to classify text data.

→ import nltk.

→ nltk.download('brown')

nltk.download('averaged-perceptron-tagger')

→ text = word_tokenize("And now for something completely different")

nltk.pos_tag(text)

(*) [(('And', 'CC'),
 ('now', 'RB'),
 ('for', 'IN'),
 ('something', 'NN'),
 ('completely', 'RB'),
 ('different', 'JJ'))]

→ text = word_tokenize("They refuse to permit us to obtain
 the refuse permit")

nltk.pos_tag(text)

(*) [(('They', 'PRP'),
 ('refuse', 'VBP'),
 ('to', 'TO'),
 ('permit', 'VB'),
 ('us', 'PRP'),
 ('to', 'TO'),
 ('obtain', 'VB'),
 ('the', 'DT'),
 ('refuse', 'NN'),
 ('permit', 'NN'))]

→ `text = nltk.Text(word.lower())` for word in `nltk.corpus.
brown.words()`
`text.similar('woman')`

(*) man time day year car moment world house family
child country by state job place way war girl
work word.

→ `text.similar('bought')`

(*) made said done put had seen found given left
heard - was been brought set got that took in
told felt .

→ `text.similar('over')`

is on to of and for with from at by that info
as up out down through is all about .