

1. This starting method typically allows a motor to develop 150% of its rated _____ while the VFD is drawing less than 50% of its rated current from the mains in the low speed range.
 - a. **Torque**
 - b. Energy
 - c. Force
 - d. Angular momentum
2. The setting for the speed of a VFD is known as which of the following:
 - a. Setpoint
 - b. Control Point
 - c. **Reference**
 - d. Speed Point
 - e. All of the above are common names for the speed setting.
3. Assuming no friction losses, if a VFD is operating a fan at 30Hz, $\frac{1}{2}$ the full speed, Which of the following is the correct power consumption?
 - a. 50% power consumption
 - b. 33% power consumption
 - c. 25% power consumption
 - d. **12.5% power consumption**
 - e. 6.7% power consumption
4. Inside the VFD, acceleration, is also known as which of the following:
 - a. Increase Speed
 - b. Increase Setpoint
 - c. Speed UP
 - d. Run-Up
 - e. **Ramp-Up**
5. 21. One external switch is attached to the VFD. This switch is for starting and stopping the VFD. A potentiometer is also wired to the VFD and it changes the speed of the motor. This type of control arrangement is known as which of the following?
 - a. Local or Hand Control
 - b. **Remote Control**
 - c. Cascade Control
 - d. Master/Slave Control
 - e. Closed Loop Control
6. 29. On a Closed Loop system using a VFD, the output starts to oscillate between minimum and maximum speed. Which of the following might correct the problem?
 - a. Increase Proportional Gain
 - b. **Decrease Proportional Gain**
 - c. Make Action Normal
 - d. Make Action Inverse
 - e. Turn Derivative
7. Motor used for elevators is generally
 - a. synchronous motor
 - b. **induction motor**

- c. capacitor starts single phase motor
 - d. any of the above.
8. For high frequency choppers the device that is preferred is
- a. Thyristor
 - b. TRIAC
 - c. Transistor**
 - d. GTO.
9. An electric drive consists of
- a. motor, transmitting shaft and control equipment**
 - b. motor and load
 - c. motor, control equipment and load
 - d. motor, supply system and load.
10. In induction motor, greater the number of poles
- a. Lesser the speed**
 - b. Greater the speed
 - c. Lesser the frequency
 - d. All of these
11. For driving high inertia loads best type of induction motor suggested is
- a. Slip ring type**
 - b. Squirrel-cage type
 - c. Any of the above
 - d. None of the above
12. The efficiency of an induction motor can be expected to be nearly
- a. 60 to 90 %
 - b. 80 to 90 %**
 - c. 95 to 98 %
 - d. 99 %
13. The starting torque of a three-phase induction motor can be increased by
- a. Increasing slip
 - b. Increasing current
 - c. Both (A) and (B)**
 - d. None of the above
14. An induction motor is
- a. Self-starting with zero torque
 - b. Self-starting with high torque
 - c. Self-starting with low torque**
 - d. Non-self-starting
15. The shape of the torque/slip curve of induction motor is
- a. Parabola
 - b. Hyperbola
 - c. Rectangular parabola**
 - d. Straight line

16. The good power factor of an induction motor can be achieved if the average flux density in the air gap is
- Absent
 - Small
 - Large**
 - Infinity
17. The 'cogging' of an induction motor can be avoided by
- Proper ventilation
 - Using DOL starter
 - Autotransformer starter
 - Having number of rotor slots more or less than the number of stator slots (not equal)**
18. A change of 4% of supply voltage to an induction motor will produce a change of approximately
- 4% in the rotor torque
 - 8% in the rotor torque
 - 12% in the rotor torque
 - 16% in the rotor torque**
19. The torque developed by a 3-phase induction motor least depends on
- Rotor current
 - Rotor power factor
 - Rotor e.m.f.
 - Shaft diameter**
20. In case of the induction motors the torque is
- Inversely proportional to (V-slip)
 - Directly proportional to (slip)²
 - Inversely proportional to slip
 - Directly proportional to slip**
21. The low power factor of induction motor is due to
- Rotor leakage reactance
 - Stator reactance
 - The reactive lagging magnetizing current necessary to generate the magnetic flux
 - All of the above**
22. If a 3-phase supply is given to the stator and rotor is short circuited rotor will move
- In the opposite direction as the direction of the rotating field
 - In the same direction as the direction of the field**
 - In any direction depending upon phase sequence of supply
 - None of these
23. The speed of a squirrel-cage induction motor can be controlled by all of the following except
- Changing supply frequency
 - Changing number of poles
 - Changing winding resistance**

- d. Reducing supply voltage
24. If any two phases for an induction motor are interchanged
- a. **The motor will run in reverse direction**
 - b. The motor will run at reduced speed
 - c. The motor will not run
 - d. The motor will burn
25. The torque of a rotor in an induction motor under running condition is maximum
- a. At the unit value of slip
 - b. At the zero value of slip
 - c. **At the value of the slip which makes rotor reactance per phase equal to the resistance per phase**
 - d. At the value of the slip which makes the rotor reactance half of the rotor
26. The maximum torque in an induction motor depends on
- a. Frequency
 - b. Rotor inductive reactance
 - c. Square of supply voltage
 - d. **All of the above**
27. In which of the following reason induction motor operation is stable?
- a. **Low Slip region**
 - b. High slip region
 - c. Any of the two
 - d. None of the above
28. At starting, rotor reactance of a 3-phase induction motor is as compared to rotor resistance.
- a. Small
 - b. Equal to
 - c. **Large**
 - d. None of the above
29. If the slip of a 3-phase induction motor increases, the p.f. of the rotor circuit is
- a. **Decreased**
 - b. Remain unchanged
 - c. Increased
 - d. None of the above
30. If the air gap between the rotor and stator of a 3-phase induction motor is increased, then
- a. No-load current is increased
 - b. Leakage reactance is decreased
 - c. **Leakage reactance is increased✓**
 - d. Any of the above