

# WT-EDKSOM6ULX Kernel Compilation Method

Revise history:

Version	Date	Log
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## Contents

WT-EDKSOM6ULX Kernel Compilation Method .....	1
1 . Construction of Development Environment .....	3
1.1、Get source file .....	3
1.2、Get the development SDK .....	4
2. Compile u-boot and kernel .....	5
2.1、compile u-boot .....	5
2.2、Compile kernel .....	5
3. Update u-boot and kernel .....	5
3.1 update u-boot .....	5
3.2 update kernel .....	6
3.3 Use mfgtools .....	6

## 1 . Construction of Development Environment

Create a work directory:

```
mkdir /home/industio_work  
cd /home/industio_work
```

### 1.1、Get source file

- Download uboot source:

Download link: `git clone http://git.freescale.com/git/cgit.cgi/imx/uboot-imx.git`

After download, enter the source directory "uboot-imx":

```
cd uboot-imx
```

Checkout v2016 branch:

```
git checkout imx_v2016.03_4.1.15_2.0.0_ga
```

Download uboot patch:

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/UBOOT-PATCH/0001-evk-board-first-commit.patch
```

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/UBOOT-PATCH/0002-update-CONFIG\_ENV\_OFFSET.patch
```

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/UBOOT-PATCH/0003-add-512M-ddr-cfg-and-config.patch
```

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/UBOOT-PATCH/0004-update-fec-and-bootdelay.patch
```

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/UBOOT-PATCH/0005-add-power-on-from-onoff-key-select-lcd-resolution.patch
```

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/UBOOT-PATCH/0006-update-boot\_evk.dtb-boot\_edk.dtb-boot\_evk.img-boot\_e.patch
```

Merge patch: use command "**git am -s**"

```
git am -s 0001-evk-board-first-commit.patch
```

```
git am -s 0002-update-CONFIG_ENV_OFFSET.patch
```

```
...
```

```
git am -s 0006-update-boot_evk.dtb-boot_edk.dtb-boot_evk.img-boot_e.patch
```

- Download kernel source file

```
git clone http://git.freescale.com/git/cgit.cgi/imx/linux-imx.git
```

Enter kernel directory : linux-imx

```
cd linux-imx
```

Checkout branch:

```
git checkout imx_4.1.15_2.0.0_ga
```

Download kernel patch:

```
wget https://github.com/industio/WT-EDKSOM6ULX-Linux/raw/master/KERNEL-
```

[PATCH/0001-edk-board-first-commit.patch](#)

Merge patch:

```
git am -s 0001-edk-board-first-commit.patch
```

## 1.2、Get the development SDK

Enter the work directory:

```
cd /home/industio_work
```

Download the SDK :

Download link: [https://releases.linaro.org/components/toolchain/binaries/4.9-2017.01/arm-linux-gnueabihf/gcc-linaro-4.9.4-2017.01-i686\\_arm-linux-gnueabihf.tar.xz](https://releases.linaro.org/components/toolchain/binaries/4.9-2017.01/arm-linux-gnueabihf/gcc-linaro-4.9.4-2017.01-i686_arm-linux-gnueabihf.tar.xz)

Decompression:

```
sudo tar xjvf gcc-linaro-4.9.4-2017.01-i686_arm-linux-gnueabihf.tar.xz -C /opt/industio
```

Add environment variables to PATH:

Method 1:

Configure environment variables and edit configuration scripts,

```
#vi environment-setup_hf
```

```
GCC_PATH=/opt/industio/gcc-linaro-4.9.4-2017.01-i686_arm-linux-gnueabihf
GCC_CC=arm-linux-gnueabihf
```

```
export ARCH=arm
export CROSS_COMPILE=$GCC_CC-
export PATH=$GCC_PATH/bin:$GCC_PATH/bin/$GCC_CC:$PATH
```

Run: `source environment-setup_hf`

Method 2: add the environment variables to profile

eg:

`vi .profile` add the following contents to the end of the file.

```
export PATH=$PATH:/opt/industio/gcc-linaro-4.9.4-2017.01-i686_arm-linux-gnueabihf/bin
export ARCH=arm
export CROSS_COMPILE= arm-linux-gnueabihf
```

**Note:** If this method is used to compile QTs through qmake, make, it is necessary to ensure that the current system does not have qmake.

Check whether the environment is in effect:

```
which arm-linux-gnueabihf-gcc
```

## 2. Compile u-boot and kernel

### 2.1、 compile u-boot

Enter uboot-imx:

```
cd /home/industio_work/uboot-imx
```

- For Nandflash version:

```
make mx6ull_14x14_evk_nand_defconfig
```

```
make
```

Final Generation: **u-boot.imx**

Note: If you want to compile the generated files into a directory, the method is as follows (for example, to generate the current "build" directory), here take Nand version as an example:

```
make mx6ull_14x14_evk_nand_defconfig O=build
```

```
make O=build
```

### 2.2、 Compile kernel

```
cd /home/industio_work/linux-imx
```

```
make wt_edksom6ull_defconfig
```

```
make -j4
```

 (J4 represents multithreaded compilation, and 4 is the number of host kernels)

Final Generation : **zImage** and **dtb**

**zImage** directory: **arch/arm/boot/zImage**

nand version dtb file directory: **arch/arm/boot/dts/imx6ull-14x14-evk-gpmi-weim.dtb**

emmc version dtb file directory: **arch/arm/boot/dts/imx6ull-14x14-evk-emmc.dtb**

Note: If you want to compile the generated files into a directory, the method is as follows (for example, to generate the current "build" directory),

```
make wt_edksom6ull_defconfig O=build
```

```
make O=build
```

## 3. Update u-boot and kernel

### 3.1 update u-boot

Firstly, put the u-boot.imx file generated at 2.1 placed to the SD card root directory, insert the SD card into the EVK board and mounted. Mount to the /mnt directory for example.

Enter the /mnt directory and then execute the following commands:

#### 3.1.1 For Nandflash version

```
mount -t debugfs debugfs /sys/kernel/debug
flash_erase /dev/mtd0 0 0
kobs-ng init -x -v --chip_0_device_path=/dev/mtd0 u-boot.imx
```

### 3.2 update kernel

#### 3.2.1 For Nandflash version:

After Kernel compilation is completed, executing `make Zi` generates `boot_edk.img` and `boot_edk.dtb` files in the `/home/industio_work/linux-imx` directory. Put these two files in the root directory of TF card, insert it into the EVK board, and power on, kernel files will be automatically updated.

### 3.3 Use mfgtools

We can also use “mfgtools” to update u-boot and kernel, but “uuu” is not supported. For the usage of “mfgtool”, please refer to the online materials.