

Examples of Mathematical Programs

(JSS30 Exercises Day01a)

Classification: Mathematical Programming

	Search-space \mathcal{S}	Degree of nonlinearity
Linear Programming (LP)	\mathbb{R}^d	linear
Quadratic Programming (QP)*	\mathbb{R}^d	quadratic**
Nonlinear programming (NLP)	\mathbb{R}^d	nonlinear
Integer programming (IP)	\mathbb{Z}^d	arbitrary
Integer linear programming (ILP)*	\mathbb{Z}^d	linear
Mixed Integer Linear Programming (MILP)	$\mathbb{R}^d \times \mathbb{Z}^r$	linear
Mixed Integer Nonlinear programming (MINLP)	$\mathbb{R}^d \times \mathbb{Z}^r$	nonlinear
Continuous unconstrained optimization: $\mathcal{S} = \mathbb{R}^n, n_g = 0$		nonlinear

*A QP is also an NLP; A ILP is also a IP.

A quadratic function is of the form:

$$c_0 + b_1x_1 + \dots + b_dx_n + a_{1,1}x_1x_1 + a_{1,2}x_1x_2 + \dots + a_{d,d}x_dx_d + x^T A x$$

For the comprehensive authoritative classification of INFORMS by Dantzig, see:

<http://glossary.computing.society.informs.org/index.php?page=nature.html>

Multiobjective Mathematical Program

Let x_1, \dots, x_d denote d , c_1, \dots, c_n , and b_1, \dots, b_q be defined as previous. A multiobjective mathematical programming problem (MOP) has the form:

$$\begin{array}{ll} f_1(x_1, \dots, x_d) & \rightarrow \min \\ & \vdots \\ f_m(x_1, \dots, x_d) & \rightarrow \min \end{array}$$

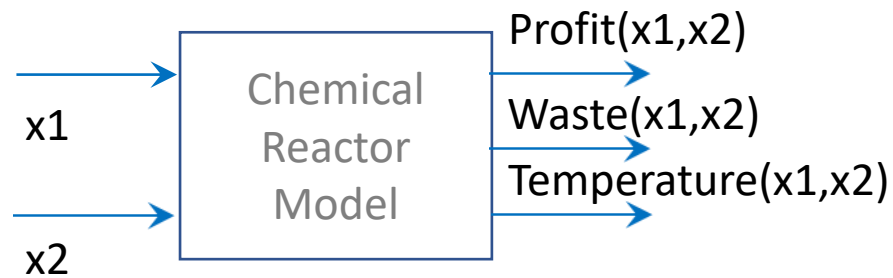
subject to

$$\begin{array}{ll} g_1(x_1, \dots, x_d) & \geq c_1 \\ & \vdots \\ g_n(x_1, \dots, x_d) & \geq c_n \\ h_1(x_1, \dots, x_d) & = b_1 \\ & \vdots \\ h_q(x_1, \dots, x_d) & = b_q \end{array}$$

For $m > 1$ one can always add the term 'Multiobjective', e.g. Multiobjective LP, Multiobjective MIP, etc..

Example 1: Mathematical Program for Reactor

Chemical Reactor



Profit to be maximized, while temperature and waste must not exceed certain thresholds.

How to formulate this as a mathematical program?

- Decision variables: Concentrations of educts:

$$x_1 = c_1 / \left[\frac{g}{l} \right], \quad x_2 = c_2 / \left[\frac{g}{l} \right]$$

- Mathematical Program:
- $$f(x_1, x_2) = \frac{\text{Profit}(x_1, x_2)}{[\text{€}]}$$

subject to

$$g_1(x_1, x_2) = \frac{\text{Temp}(x_1, x_2) - T_{\max}}{[^\circ\text{C}]} \leq 0$$

$$\frac{g_2(x_1, x_2) - W_{\max}}{\left[\frac{kg}{h} \right]} \leq 0$$

$$(x_1, x_2) \in [0,1] \times [0,1]$$

Example 2: Constrained 0/1 Knapsack Problem



Picture: © Michael Emmerich (instructor)

The total value of the items in the knapsack (in [\$]) should be maximized, while its total weight (in [kg]) should not exceed MAXWEIGHT. Here v_i is the value of item i in [\$] and w_i is its weight in [kg]. $i=1, \dots, d$ are indices of the items.

$$f_1(x_1, \dots, x_d) = \sum_{i=1}^d \frac{v_i}{[\$]} x_i \rightarrow \max$$

$$g_1(x_1, \dots, x_d) = \sum_{i=1}^d \frac{w_i}{[kg]} x_i - MAXWEIGHT \leq 0$$

$$x_i \in \{0,1\}, i = 1, \dots, n$$

What is the role of the binary variables here?

What type of mathematical programming problem is this?

Can this also be formulated as a quadratic programming problem?

Example: Multiobjective 0/1 Knapsack Problem

The total value of the items in the knapsack (in [\$]) should be maximized, while its total weight (in [kg]) should be minimized.



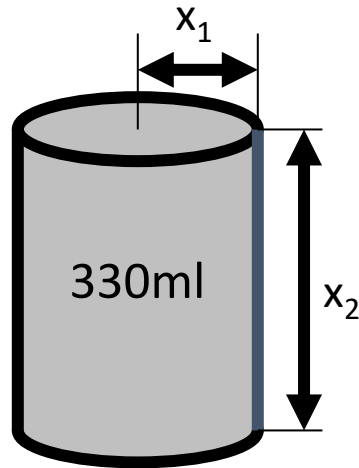
$$f_1(x_1, \dots, x_d) = \sum_{i=1}^d \frac{v_i}{[\$]} x_i \rightarrow \max$$

$$f_2(\mathbf{x}) = \sum_{i=1}^d \frac{w_i}{[kg]} x_i \rightarrow \min$$

$$x_i \in \{0,1\}, i = 1, \dots, n$$

Example: Equality Constraint for Tin Problem

Minimize the area of surface A for a cylinder that contains $V = 330$ ml sparkling juice! $x_1 = \text{radius}/[\text{cm}^2]$, $x_2 = \text{height}/[\text{cm}^2]$

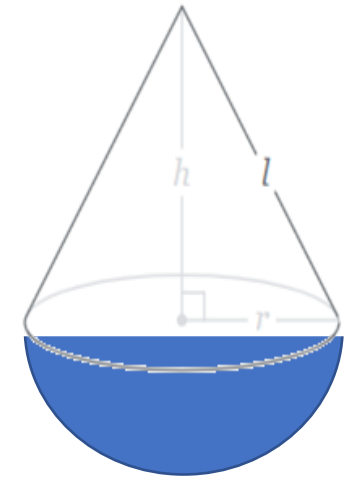


Problem sketch

$$\begin{aligned} f(\mathbf{x}) &= 2\pi x_1 x_2 + 2\pi (x_1)^2 \rightarrow \min \\ h(\mathbf{x}) &= 2\pi x_2 (x_1)^2 = 330 \\ \mathbf{x} &\in \left[\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \infty \\ \infty \end{pmatrix} \right] \subset \mathbb{R} \end{aligned}$$

$$V = \pi r^2 \frac{h}{3}$$

$$A = \pi r (r + \sqrt{h^2 + r^2})$$



Exercise: Formulate the problem for icecream cones as a mathematical programming problem! Surface of waffle to be 100ml Volume maximized (1/2 sphere+cone volume)

Some interesting research question: Find optimal shapes or given constraints on geometry.

For instance: Convex hull of N points with minimal surface and maximal volume.

Example: Knapsack Problem with Cardinality Constraint

The total value of the items in the knapsack (in [\$]) should be maximized, while its total weight (in [kg]) should be below MAXN and at most MAXN items can be chosen.



$$f_1(x_1, \dots, x_d) = \sum_{i=1}^d \frac{v_i}{[\$]} x_i \rightarrow \max$$

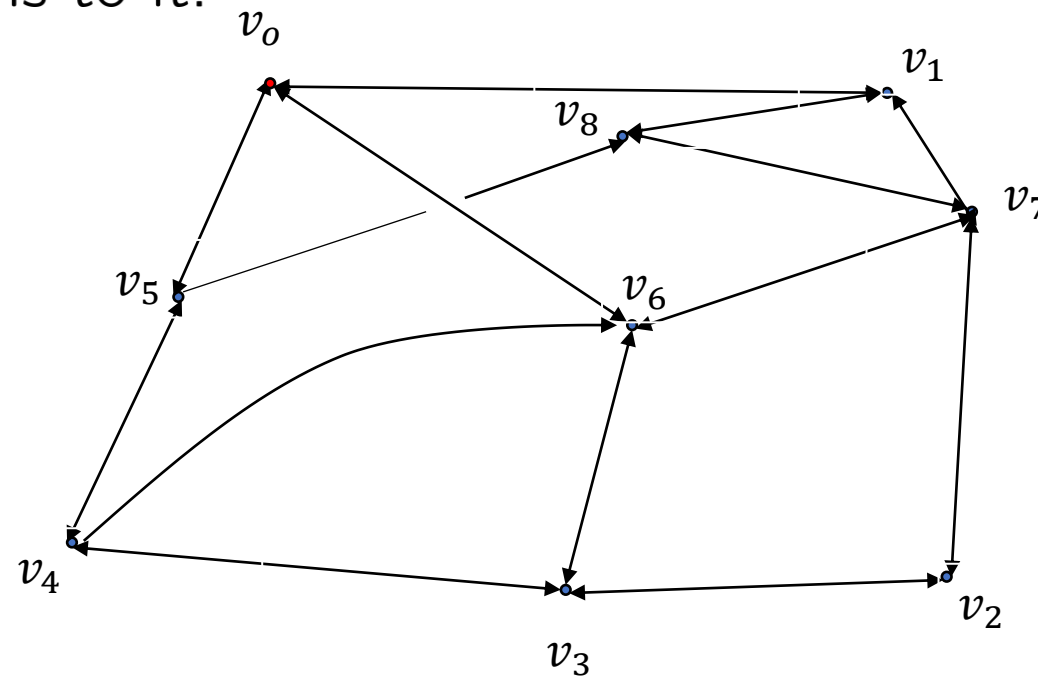
$$g_1(x_1, \dots, x_d) = \sum_{i=1}^d \frac{w_i}{[kg]} x_i - MAXWEIGHT \leq 0$$

$$g_2(x_1, \dots, x_d) = \sum_{i=1}^d x_i \leq MAXN$$

$$x_i \in \{0,1\}, i = 1, \dots, d$$

Example: Traveling Salesperson Problem

Given a distance matrix, find a tour of a vehicle that visits every city exactly once and starts from a depot and returns to it.



This can be easily described, but how to model this in terms of discrete (binary) variables and (constraint) functions that depend on them?

Encoding of a TSP tour

City 1	City 2	City 3	City 4
1	0	0	0
0	1	0	0
0	0	0	1
0	0	1	0

This matrix encodes the tour

$$0 \rightarrow 1 \rightarrow 2 \rightarrow 4 \rightarrow 3 \rightarrow 0$$

$$\sum_{i=1}^{n-1} \sum_{j=1}^n \sum_{k=1}^n d_{j,k} x_{i,j} x_{i+1,k} + \sum_{i=1}^n x_{1,i} d_{0,i} + \sum_{i=1}^n x_{n,i} d_{i,0} \rightarrow \min$$

subject to

$$\forall i \in 1, \dots, n : \sum_{j=1}^n x_{i,j} = 1$$

$$\forall j \in 1, \dots, n : \sum_{i=1}^n x_{i,j} = 1$$

$$x_{i,j} \in \{0, 1\}^{n \times n}$$

Recall. Previous slide

City 1	City 2	City 3	City 4
1	0	0	0
0	1	0	0
0	0	0	1
0	0	1	0

This matrix encodes the tour

0 → 1 → 2 → 4 → 3 → 0



Here $d_{i,j}$ denotes the distance from i to j . and 0 is the index of the depot. If $x_{i,j} = 1$ and $x_{i+1,k} = 1$ then the vehicle drives in the i -th step from j to k .

Exercise: How does this equation change if one is starting at node 0 and the tour needs to end in other depot, say node n ?

Mathematical Programming Models: Exercise

Question: How to solve problems of the following kind with an LP solver:

MIN
MAX
Trick

$$\max\{u_1(x_1, \dots, x_n), \dots, u_m(x_1, \dots, x_n)\} \rightarrow \min$$

where $u_1 \dots u_m$ are linear functions of the type
 $u_i(\dots) = a_{i1} x_1 + \dots a_{in} x_n$

Answer:

QP
Trick

Let us assume the problem $a_1 x_1 \dots a_m x_m \rightarrow \min$
s.t. $w_1 x_1 + \dots w_n x_n \leq c, x_i \in \{0,1\}, i = 1 \dots n$

How can we formulate it as a nonlinear problem with continuous variables?

Answer:

Mathematical Programming Models

Question: How to solve problems of the following kind with an LP solver:

MIN

MAX

Trick

$$\max\{u_1(x_1, \dots, x_n), \dots, u_m(x_1, \dots, x_n)\} \rightarrow \min$$

where $u_1 \dots u_m$ are linear functions of the type

$$u_i(\dots) = a_{i1}x_1 + \dots + a_{in}x_n$$

$$f(x_1, \dots, x_n, x_{n+1}) = x_{n+1} \rightarrow \min$$

$$\text{Answer: } s.t. a_{i1}x_1 + \dots + a_{in}x_n \leq x_{n+1}, i = 1, \dots, m$$

QP

Trick

Let us assume the problem $a_1x_1 + \dots + a_nx_n \rightarrow \min$

$$s.t. w_1x_1 + \dots + w_nx_n \leq c, x_i \in \{0,1\}, i = 1 \dots n$$

How can we formulate it as a continuous problem?

Answer:

$$(1 - x_i)x_i = 0, i = 1, \dots, n$$

$$x_i \in IR$$

Placement of unit discs on the square – mixed integer problem – ‘Big M trick’

How to formulate the problem of placing as many unit discs of radius 1.5m possible on a square of side length 100meter? The unit discs may not overlap.

Answer: Choose $n = (100 \times 100) / (2\pi \cdot 10^2)$

$$f(b_1, \dots, b_n, x_1, \dots, x_n, y_1, \dots, y_n) = \sum b_i \rightarrow \max$$

$$g_1(\mathbf{b}, \mathbf{x}) = b_i b_j \sqrt{\{(x_i - x_j)^2 + (y_i - y_j)^2\}} \leq 1.5$$

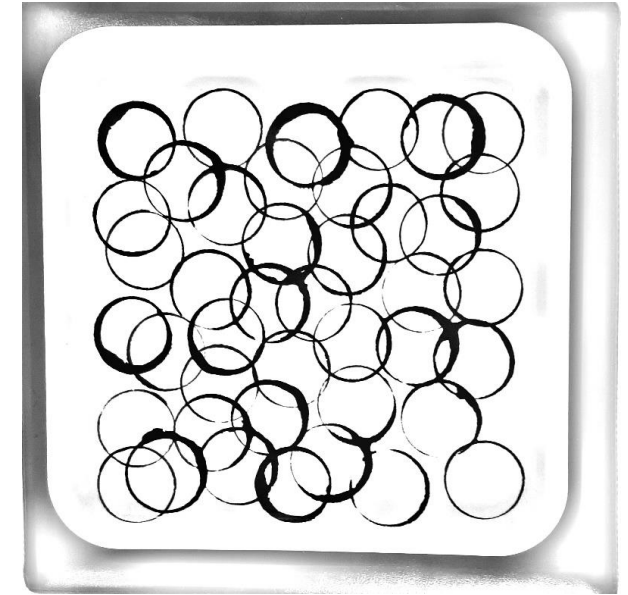
$$i = 1, \dots, n-1, j = i+1, \dots, n$$

$$b_i \in \{0,1\}$$

$$x_i \in [10,90]$$

$$y_i \in [10,90]$$

- n is upper bound for number of discs that fit.
- Only if $b_i = 1$ and $b_j = 1$, the distance constraint is checked, otherwise it is always satisfied (inactive discs cannot overlap)
- But: Highly non-linear!



Unit disc problem: Infeasible design due to overlap.

Alternative QP formulation (big M trick):

$$g_1'(\mathbf{b}, \mathbf{x}) = (x_i - x_j)^2 + (y_i - y_j)^2 \leq 2.25 + M(1 - b_i) + M(1 - b_j)$$

Two tricks are used here:

- (1) *Big M*: choose an M so big that whenever $x_i = 0$ or $x_j = 1$ then g_1' is satisfied. **What is the minimal value for M ?**
- (2) Omit the square root by taking the square on both sides of g_1 equation. Values are always positive.

Exercise: Linear Programming

Making Mugs and Bowls

Mr. Asep makes mugs and bowls. It takes 4 minutes to make a mug and 3 minutes to make a bowl. A mug consists of 1kg of clay and a bowl requires 1.5kg. of clay. He has 20 hours available for making the mugs and bowls and has 450 kg. of clay on hand. He makes a profit of \$2 on each mug and \$3 on each bowl.

How many mugs and how many bowls should he make in order to maximize her profit? Solve graphically and/or with LP Solve.

x = number of produced mugs

y = number of produced bowls

This homework is only for exercise and not graded. The solution will be discussed in the next lecture.

<https://online-optimizer.appspot.com/?model=builtin:default.mod>



Timetabling example (pyomo)

<https://towardsdatascience.com/schedule-optimisation-using-linear-programming-in-python-9b3e1bc241e1>



Model Parameters

$C = \{c_1, \dots, c_n\}$ set of all cases assigned to consultant

$S = \{s_1, \dots, s_m\}$ set of all upcoming theatre sessions assigned

ST_s = start time of session s

$\Delta T_{C,c}$ = duration of case c

$\Delta T_{S,s}$ = duration of session s

$D_{C,c}$ = deadline of case c

$D_{S,s}$ = date of session s

K_{max} = maximum theatre session utilisation (e.g. 0.85)

Decision variables

$$x_{c,s} = \begin{cases} 1 & \text{if case } c \text{ is assigned to session } s \\ 0 & \text{otherwise} \end{cases}$$

t_c = start time of case c

u_s = utilisation of session s

Decision variables

$$x_{c,s} = \begin{cases} 1 & \text{if case } c \text{ is assigned to session } s \\ 0 & \text{otherwise} \end{cases}$$

t_c = start time of case c

u_s = utilisation of session s

Objective Function

$$\text{maximise } \sum_{s=1}^m u_s$$

Constraints

If $x_{c,s} = 1$ then $t_c \geq ST_s$

If $x_{c,s} = 1$ then $t_c + \Delta T_{C,c} \leq ST_s + \Delta T_{S,s}$

$$\sum_{s=1}^m x_{c,s} \leq 1 \quad \forall c \in C$$

If $x_{c,s} = 1$ then $D_{S,s} \leq D_{C,c}$

If $x_{c_1,t_1} + x_{c_2,t_2} = 2$ then $[t_{c_1} + \Delta T_{C,c_1} \leq t_{c_2}] \vee [t_{c_2} + \Delta T_{C,c_2} \leq t_{c_1}]$

$$u_s = \frac{1}{\Delta T_{S,s}} \sum_{c=1}^n x_{c,s} \Delta T_{C,c}$$

$$x_{c,s} \in \{0,1\}, \quad 0 \leq u_s \leq K_{max}, \quad 0 \leq t_c \leq 1440$$

