

Prashanth Ravichandar

rprash99@gmail.com | (213) 561-8227 | [LinkedIn](#) | [Github](#) | [Website](#)

EDUCATION

University of Southern California

M.S. in Computer Science (Honors)

August 2022 – May 2024

4.0/4.0

Indian Institute of Technology Guwahati

B.Tech. in Engineering Physics, Minor in Computer Science and Engineering

2016 – 2020

9.11/10.00 (Rank 1)

EXPERIENCE

Student Researcher - Dynamic Robotics and Control Laboratory, USC

July 2023 - Present

Mentor: Prof. Quan Nguyen

Los Angeles

- Enhancing exploration and planning efficiency for complex, unseen tasks through reinforcement learning.
- Developing a hierarchical task planner for agile locomotion in bipedal robots using a pre-trained controller.

Research Intern - Robotic Embedded Systems Laboratory, USC

June 2023 - Present

Mentor: Prof. Gaurav Sukhatme

Los Angeles

- Working on small and efficient neural network policies for memory-constrained robots.
- Exploring parameter prediction for visual control policies using transformer-based graph hypernetworks and RL.

Senior Technology Associate - Morgan Stanley

August 2020 – July 2022

Mortgages, Wealth Management Technology

Mumbai

- Improved raw read speeds for risk calculations by 15x using distributed caching (Redis and Apache Ignite).
- Upgraded a .NET Core application from a monolithic to a microservices architecture using domain-driven design.

Research Intern - Indian Institute of Science

May – August 2019

Mentor: Prof. Aditya Gopalan

Bengaluru

- Investigated the problem of sequential detection of change in the distribution of data with adaptive measurements.
- Performed a literature survey along with a preliminary problem formulation, in the context of multi-armed bandits.

TECHNICAL SKILLS

Languages: Python, JavaScript, C++, C, MATLAB, C#, SQL, TypeScript, HTML/CSS, LaTeX

Libraries/Frameworks: PyTorch, MuJoCo, JAX, ROS, Nvidia Isaac Gym, Pandas, NumPy, Matplotlib, Scipy, Flask, Angular

Tools: Docker, Git, Linux

PROJECTS

Controller for Unitree A1 Quadruped Robot

GitHub 

Course Project: Robot dynamics and control

- Designed controllers for Unitree A1 quadruped robot in MATLAB Simscape to perform walking, turning, running, stair climbing and obstacle avoidance.
- Developed and implemented QP and MPC controllers, trotting gait sequence, a linear trajectory for walking, a cycloid trajectory for running and a 5th-order polynomial trajectory for stair climbing.

Masked Autoencoders for Adversarial Purification

GitHub 

Course Project: Deep Learning and its Applications

- Designed and implemented an adversarial image purification model using fine-tuned Masked Autoencoders (MAEs) to restore perturbed images to their original form, rendering adversarial attacks ineffective.
- Conducted experiments on the ImageNet dataset, successfully mitigating adversarial attacks generated by Gaussian noise and the Fast Gradient Sign Method (FGSM).

Analysis of Surface Names for entities in Wikipedia

GitHub 

Bachelor's Thesis under Prof. Amit Awekar, Dept. of CSE, IIT Guwahati

- Analyzed the characteristics of incorrectly mapped links in Wikipedia pages and explored solutions to correct them.
- Created a novel dataset to aid in further research to provide contextual information of errors.

Atari Pong - OpenAI gym

GitHub 

- Trained an agent to play the Atari game - Pong, using policy gradients, with raw game pixels as input.

Line Follower Robot

TechKriti, IIT Kanpur

- Led the development of a line follower robot using an Arduino board and a PID controller.

KEY COURSES

Mathematics: Linear Algebra, Advanced Calculus, Graphs and Matrices

Computer Science: Analysis of Algorithms, Computer Systems, Computer Architecture, Software Engineering

Artificial Intelligence: Fundamentals of AI, Machine Learning, Deep Learning, Convolutional Neural Networks (CS231n Stanford), Reinforcement Learning (David Silver), Autonomous Decision-Making

Robotics: Robotics, Robot Learning, Robot Dynamics and Control

Miscellaneous: Game Theory, Computational Physics

ACHIEVEMENTS

- **USC Computer Science Master's Honors Program:** Selected for the honors program for maintaining a GPA of 3.9 and above.
- **Institute Silver Medal 2020:** Received the Institute Silver Medal for securing **1st rank** in the Department of Physics, IIT Guwahati
- **Institute Merit Scholarship, IIT Guwahati:** Received a scholarship for best academic performance in the class in the academic year 2018-19
- **Inter IIT Tech Meet 2018:** Secured **Bronze medal** in the Star Cluster Identifier event, amongst the 23 IITs participating
- **M.P.Birla Institute of Fundamental Research:** Graded excellent at the Summer School in Astronomy & Astrophysics, 2014
- **Hindustani Talavadya Junior Grade in Tabla - 2012:** Secured first class
- **21st National Chess Championship - 2007:** Ranked 158 on the merit list in the Under 9 category

EXTRACURRICULAR ACTIVITIES

Viterbi Graduate Mentor, USC

Jan 2023 - Dec 2023

- Mentored 3 Master's students over the spring and fall semesters. Helped new graduate students adjust to life at USC and provided guidance on achieving academic and professional goals. Nominated for the **Outstanding Mentor Award**.

Club Secretary, Astronomy Club, IIT Guwahati

April 2018 - 2019

- Supervised the financial and technical planning and growth of the club. Led the development of projects including constructing a planetarium, astronomical data analysis, star spectroscopy, space balloon, and radio astronomy.

Organizer, Techniche, IIT Guwahati

September 2016 - 2017

- Organized the Exhibitions and Industrial Conclave modules of the annual techno-management festival. Interacted with prominent industrialists from Bosch, IBM, and Dell as well as several research groups from USA, Bangladesh and India.

Volunteer, Prashanthi Balamandira Trust

October 2015 - Present

- Participated in several activities such as serving breakfast to children at government schools, providing COVID relief kits in slums, developing a website to help deliver free educational content, and translating Sanskrit verses from ancient Indian texts.