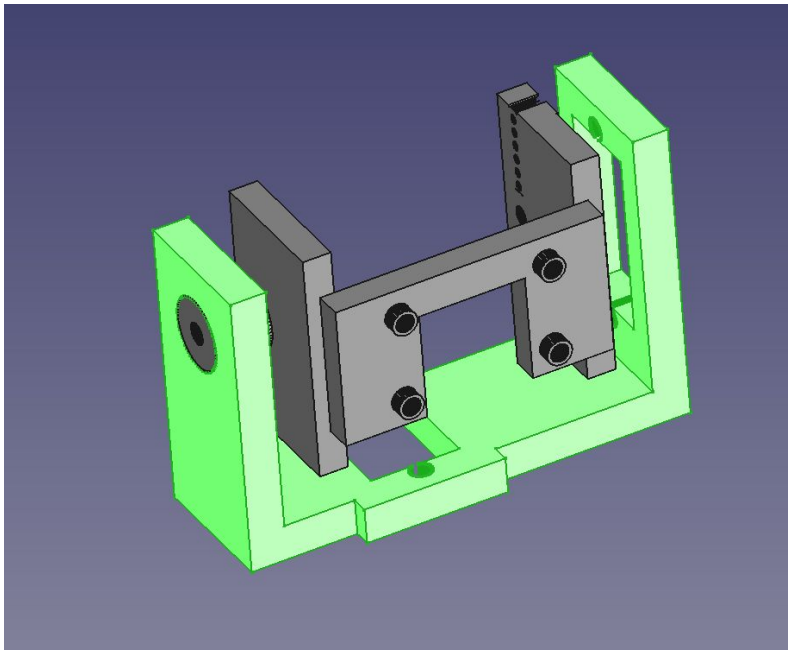
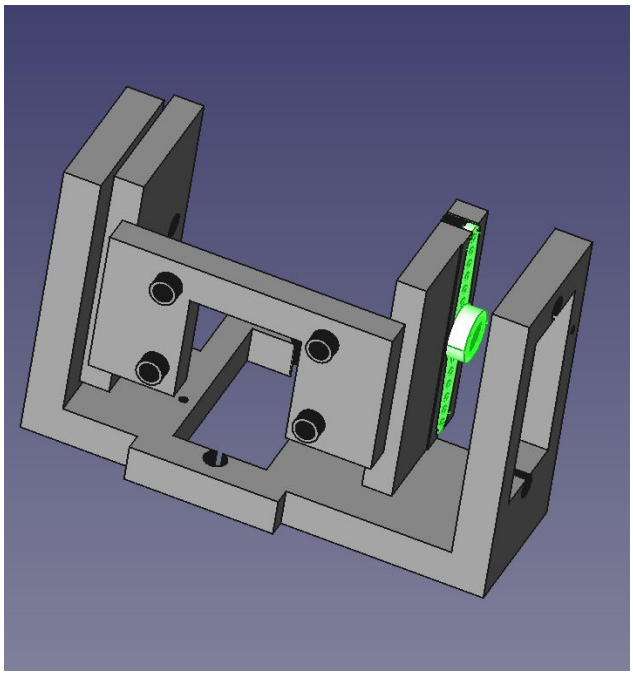
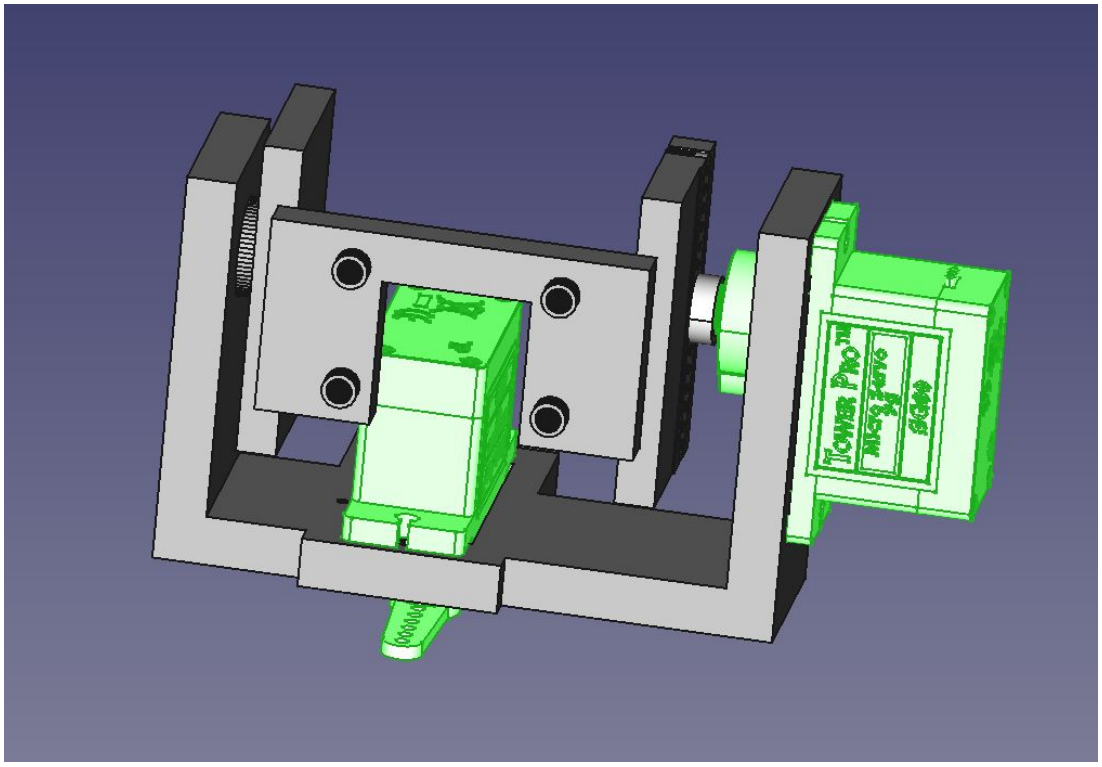
Step 1:
Insert the *Camera Mount Component V2 - PCB Holder.stl* into the *Camera Mount Component V2 - Tilt Holder.stl*



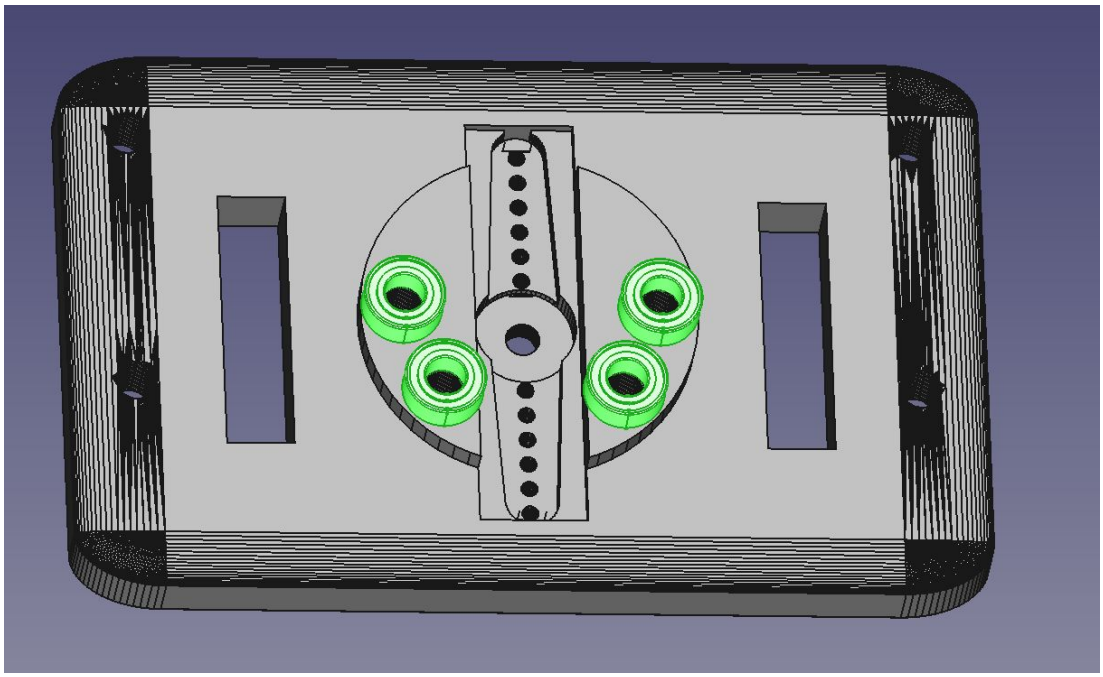
Step 2: Affix the tilt servo horn into the *Camera Mount Component V2 - PCB Holder.stl* with glue.



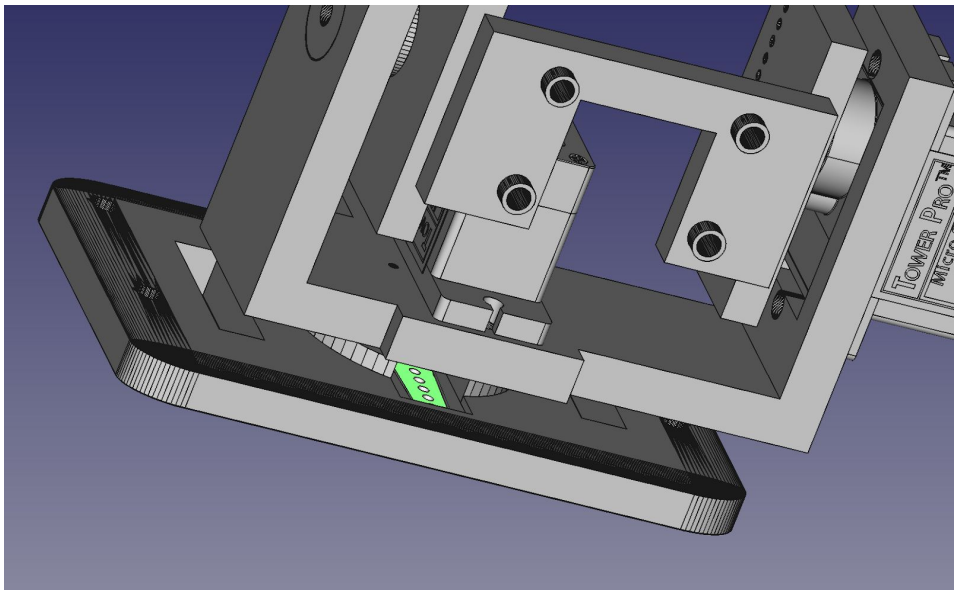
Step 3: Add the two servos in position. Fasten the horns with servo screws provided.



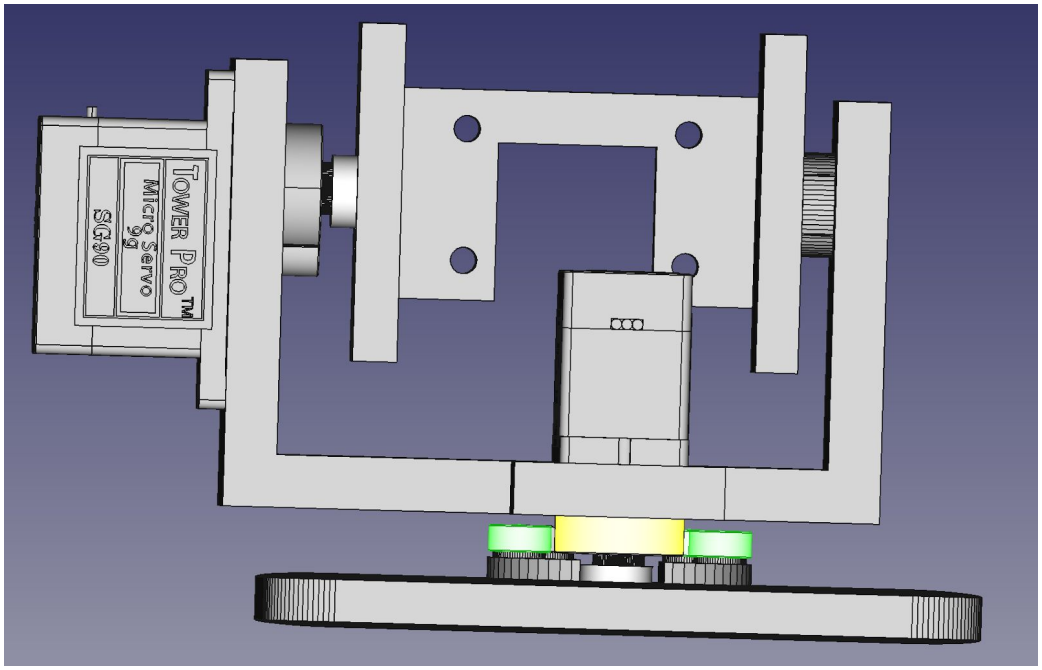
Step 4: Take the four 673ZZ bearings (OD6MM ID3MM Height2_5MM) and fasten them with #2-56 x 1/2“ with the *Camera Mount Component V2 - Pan Holder.stl.*



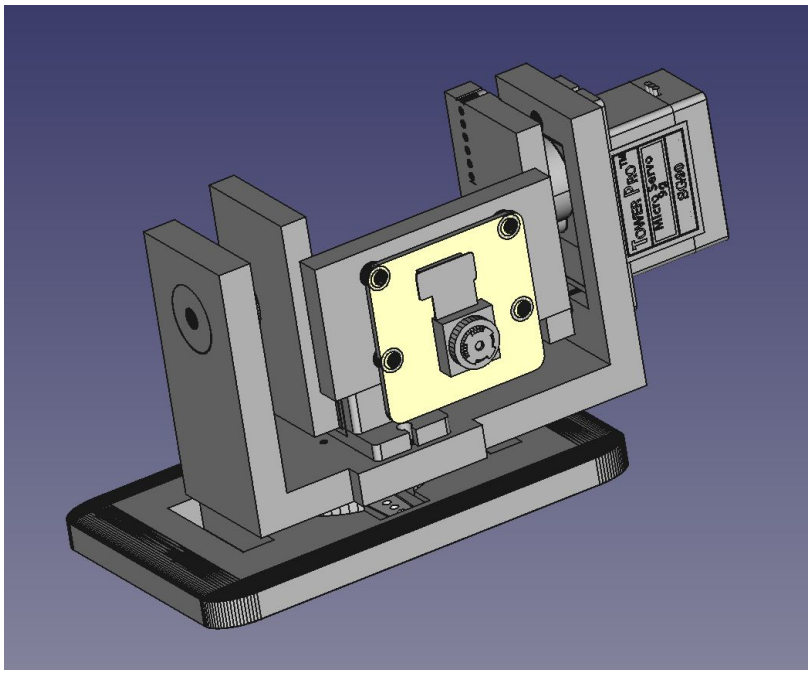
Step 5: Apply some glue on the pan servo horn and place it inside the slot *Camera Mount Component V2 - Pan Holder.stl.*



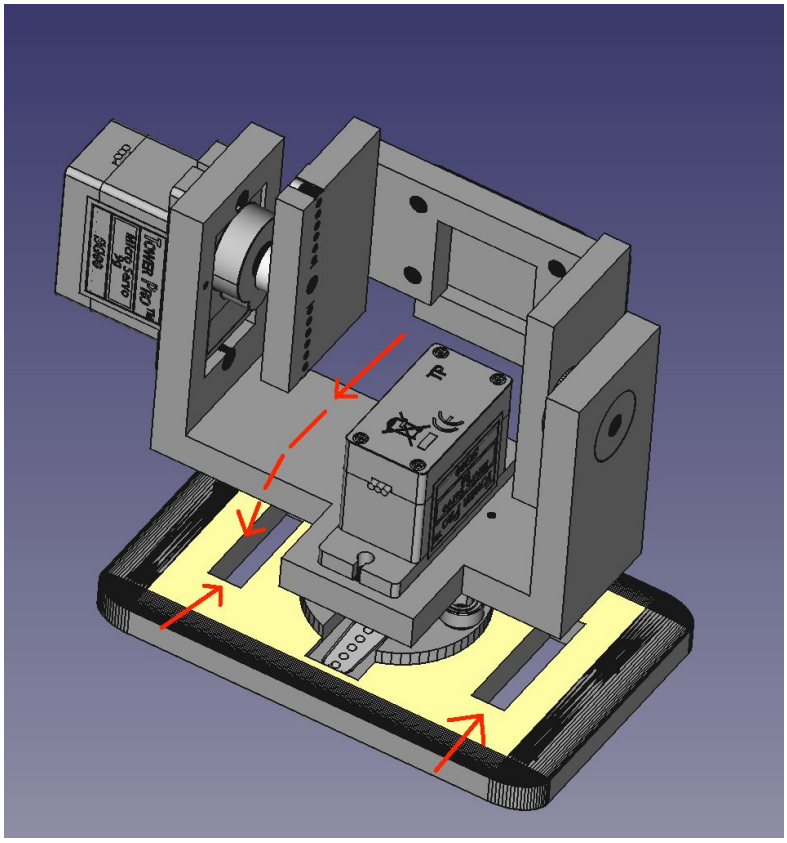
The neck of the servo should rub against the edge of the bearings (bearings shown in green and neck in yellow)



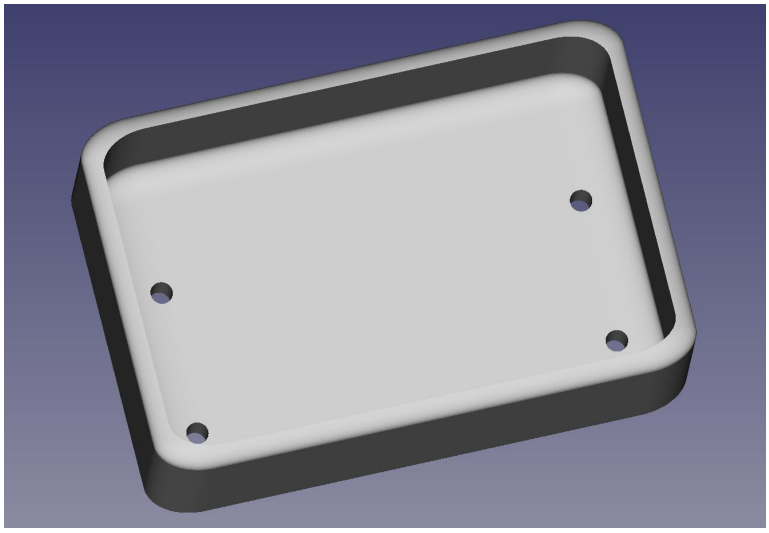
Step 6: Fasten the Raspberry Pi Camera V2 on the *Camera Mount Component V2 - PCB Holder.stl*



The cables can pass through the slots shown below



Step 7: If you are using a Raspberry pi zero, then use the *Camera Mount Component V2 - Base Holder* to mount the board. Otherwise ignore this step.



Step 8: If applicable, Fasten the *Camera Mount Component V2 - Pan Holder.stl* assembly over Camera Mount Component V2 - Base Holder to complete the setup.