DEPARTMENT OF MATHEMATICS IIT GUWAHATI

MA 473 Computational Finance Lab - VDate: 27.08.2024

Consider the following Black-Scholes PDE for European call:

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$$\begin{cases} \frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + (r-\delta)S \frac{\partial V}{\partial S} - rV = 0, & (0,\infty) \times (0,T], \ T>0 \\ V(S,t) = 0, & \text{for } S=0, \\ V(S,t) = S - Ke^{-r(T-t)}, & \text{for } S \to \infty \\ \text{with the terminal condition } V(S,T) = \max(S-K,0). \end{cases}$$
 wing transformation

With the following transformation

$$\left\{ \begin{array}{l} S=Ke^x,\quad t=T-\frac{2\tau}{\sigma^2},\quad q:=\frac{2r}{\sigma^2},\quad q_\delta:=\frac{2(r-\delta)}{\sigma^2},\\ V(s,t)=V\left(Ke^x,\,T-\frac{2\tau}{\sigma^2}\right)=:v(x,\tau), \text{ and}\\ v(x,\tau)=:K\exp\left\{-\frac{1}{2}(q_\delta-1)x-\left[\frac{1}{4}(q_\delta-1)^2+q\right]\tau\right\}y(x,\tau) \end{array} \right.$$

the above Black-Scholes PDE becomes the following 1-D heat conduction parabolic PDE:

$$\begin{cases} \frac{\partial y}{\partial \tau} = \frac{\partial^2 y}{\partial x^2}, \ x \in \mathbb{R}, \ \tau \ge 0, \\ \\ y(x,0) = y_0(x) = \max\left\{\exp(\frac{x}{2}(q_\delta + 1)) - \exp(\frac{x}{2}(q_\delta - 1)), 0\right\}, \ x \in \mathbb{R}, \\ \\ y(x,\tau) = 0, \ \text{for} \ x \to -\infty, \\ \\ y(x,\tau) = \exp\left(\frac{1}{2}(q_\delta + 1)x + \frac{1}{4}(q_\delta + 1)^2\tau\right) \ \text{for} \ x \to \infty. \end{cases}$$

Solve the transformed PDE using the method of vertical lines (MOL), and address the resulting system of first-order ODEs in time using the following schemes: explicit Euler, implicit Euler, and secondorder Runge-Kutta methods (with an appropriately chosen step size).

The values of the parameters are $\sigma = 0.3$, K = 10, r = 0.06, and T = 1. The exact solution of the transformed equation is given by

$$y(x,\tau) = \frac{1}{2\sqrt{\pi \tau}} \int_{-\infty}^{\infty} y_0(s) e^{-(x-s)^2/4\tau} ds$$

The output files should contain the following for above problem:

- a) Plot the numerical solutions at the final time level.
- b) Draw the surface plot of the numerical solutions.
- c) Use the exact solution to calculate the error. Use the loglog plot to show the order of convergence, that is, Δx vs. Max. abs. error.