

Case 2

$$\text{rank}(A) = r < m$$

$$(AP)e_1 \xrightarrow{\text{line}} (AP)e_1 \quad \text{and why?}$$

$$AP - \alpha e = \begin{pmatrix} 0 & 0 \\ 0 & R_2 \end{pmatrix} \begin{bmatrix} x & x^{m-1} \\ R_1 & R_2 \end{bmatrix} x$$

$$\therefore = \begin{bmatrix} 0, R_1 \\ 0, 0 \end{bmatrix} \begin{bmatrix} 0, R_2 \\ 0, 0 \end{bmatrix}$$

$Q_1, R_1 \rightarrow$  will preserve rank of  $R_1$   $\&$  ( $\because Q_1$  is orthogonal)

$\downarrow$   
orthogonal matrix preserves rank of a matrix or split matrix on split

$$[(AP)]_{1-\infty} \xrightarrow{(AP)} = [0, \infty]$$

(in our context  
chaos in  
existing hierarchical  
structure)

26/9/24

HSS-217

Kaliyuga:

chaos/  
lawless news

MA-473

26/9/24

for non singular matrix  $A$ ,

$$Ax = b$$

$$x = A^{-1}b \rightarrow \text{costly}$$

$$2x^{(n)} \xrightarrow[n \rightarrow \infty]{} \tilde{x}$$

$$x^{(n)} \approx \tilde{x}$$

For diagonal dominance

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$x^{(0)} = (x_1^{(0)}, x_2^{(0)}, x_3^{(0)})$$

$$x_1^{(k+1)} = \frac{(b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)})}{a_{11}}$$

Jacobi  
iterative

$$\left\{ \begin{array}{l} x_2^{(k+1)} = \frac{(b_2 - a_{21}x_1^{(k)} - a_{23}x_3^{(k)})}{a_{22}} \\ x_3^{(k+1)} = \frac{(b_3 - a_{31}x_1^{(k)} - a_{32}x_2^{(k)})}{a_{33}} \end{array} \right.$$

Gauss Seidel      use  $(k+1)^{\text{th}}$  values for  $x_2$  &  $x_3$ .

~~A must be~~

$$Ax = b$$

$$Mx = (M - A)x + b$$

M = pre-conditioner

M is non-singular,

$$x = (I - M^{-1}A)x + M^{-1}b$$

$$x = g(x) \quad \text{fixed pt iteration}$$

where

$$x^{(k+1)} = (I - B)x^{(k)} + B^{-1}b$$

$$\|B\|_2 < 1 \quad \Rightarrow \quad \|B\|_\infty < 1$$

$$\rho(B) < 1 \Leftrightarrow$$

B: iterative method

x will converge

$$\rho(B) = \max |x_i|$$

spectral radius.

$$A = D - L - U$$

$\Rightarrow$  For Jacobi  $M = D$

Gauss Seidel, ~~not~~

consider pre-conditioner,  $M = D$  then  $M^{-1} = L + U$

$$Dx^{(k)} = (L+U)x^{(k)} + b$$

$$x^{(k+1)} = \underbrace{D^{-1}}_{B} (L+U) x^{(k)} + D^{-1}b \rightarrow \text{Jacobi}$$

$$\text{where, } B = D^{-1}(L+U)$$

$$\rho(B) < 1, \text{ provided } \|A\| \leq 1$$

if  $A$  is not ~~re~~ defined

$$M = D - L, \quad (D - L)x^{(k+1)} = Ux^{(k)} + b$$

$$M^{-1}A = U, \quad x^{(k+1)} = \underbrace{(D-L)^{-1}Ux^{(k)} + (D-L)^{-1}b}_{B} \rightarrow \text{Gauss-Seidel}$$

$$\rho(B) < 1, \text{ for } \|A\| \leq 1$$

the convg of the Gauss Seidel

In order to speed up the convg of the Gauss Seidel  
we can introduce parameters  $\omega R$  (Successive over relaxation)

$$M = \frac{1}{\omega R} D - L \quad \{ \text{SOR (Successive over relaxation)}$$

$$M - A = \left(1 - \frac{1}{\omega_k}\right) D + U$$

$$\left(\frac{D}{\omega_k} - L\right)x^{(n)} = \left[\left(1 - \frac{1}{\omega_k}\right)D + U\right]x^{(k)} + b$$

$$\Rightarrow x^{(n)} = \left(\frac{D}{\omega_k} - L\right)^{-1} \left[\left(1 - \frac{1}{\omega_k}\right)D + U\right]x^{(k)} + \left(\frac{D}{\omega_k} - L\right)^{-1}b$$

stopping criterion,

$$\|x - \tilde{x}\| < \epsilon_{tol}$$

↓  
must be known before

$$g^{(n)} = b - Ax^{(n)}, \text{ if } \|g^{(n)}\| \rightarrow 0 \text{ as } n \rightarrow \infty$$

$$\text{if } \|g^{(n)}\| < \text{TOL} = 10^{-8} \text{ (stop)}$$

$$\text{if } \|x^{(n)} - x^{(n+1)}\| \rightarrow 0 \text{ as } n \rightarrow \infty$$

Cauchy seq

in corresponding

to Jacobi  
iterat.

$$\omega_{opt} = \frac{\epsilon}{1 + \sqrt{1 - \rho(B)}}$$

have no impri

The case of the American option we have  
the side cond'n is  $y \geq g$  at each iterat

correction vector

$$z = x^{(k)} - x^{(k+1)}$$

$$g_i^{(k)} = b - \sum_{j=1}^i a_{ij} x_j^{(k)} - a_{ii} x_i^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k+1)}$$

$$x_i^{(k)} = \bar{x}_i^{(k)} + \omega_k \frac{g_i^{(k)}}{a_{ii}}$$

NOW,

$$Ax = \hat{b} = b - Ag$$

PSOR (Projected SOR),  $x_i^{(k)} = \max \{0, x_i^{(k)} + \omega_k \frac{g_i^{(k)}}{a_{ii}}\}$

$$\theta y_i = g_i^{(k)} + a_{ii} (x_i^{(k)} - x_i^{(k-1)})$$

since the Cryer's problem has a unique min<sup>m</sup>  
which ensures the convg PSOR.

$$\nabla G^T \phi(x_i, z_j)$$

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### Print & Censorship

higher power / authoritative gets threatened  
when there is a potential contest that can  
overthrow their influence / control.

Initial an uprising started in India  
against the English press, killing  
of the English company by the English press  
among the English press for years of allegations  
against the East India company by the English press.

MA-973

Recap:

$$\begin{cases} -u'' = f \\ u(0) = 0 = u(1) \end{cases} \quad u \in C^1(\bar{\Omega})$$

$v \in \mathcal{E}'(\Omega)$

$$-\int u'' v \, dx = \int f v \, dx$$

$u', v'$ : weak derivatives

$$\Rightarrow -\int v \, du' = \mathbb{E}(uv)'_0 + \int u' v \, dx = \int f \, dx$$

$u \in L^2(\Omega) \rightarrow$   $\alpha$ : desbezne  $\overset{(a)}{\rightarrow}$   
 $u$ : bdd measurable  $\delta^n$

$$\int_a^b f(x) \, dx = \underbrace{\sum_{i=0}^n f(x_i) h}_{\text{Riemann integral}}$$

$$L^2(\Omega) = \{u \in \mathbb{R} : \int_{\Omega} |u(x)|^2 \, dx < \infty\}$$

$$v \in L^2, u' \in L^2$$

$$u \in H^1(\Omega)$$

$$H^1(\Omega) = \{u \in L^2(\Omega), u' \in L^2(\Omega)\}$$

$$\mathcal{E}'(\Omega) \subseteq L^2(\Omega)$$

$\text{Supp } u \in \mathcal{E}^\infty(\Omega), v \in \mathcal{E}_0^\infty(\Omega)$

$$\textcircled{1} \int_{\Omega} D^\alpha u(x) v(x) dx = (-1)^{|\alpha|} \int_{\Omega} u(x) D^\alpha v(x) dx$$

(integrate by parts)  $|\alpha| \leq k;$

$$v \in \mathcal{E}_0^\infty(\Omega)$$

$\int_{\Omega} v \in L^2(\Omega)$

$$\textcircled{2} \int_{\Omega} w_\alpha(x) v(x) dx = (-1)^{|\alpha|} \int_{\Omega} p u(x) D^\alpha v(x) dx + v \in \mathcal{E}_0^\infty(\Omega)$$

Comparing the RHS  $\textcircled{1}$  &  $\textcircled{2}$   
 $w_\alpha(x) = D^\alpha u(x)$ , since  $v \in L^2(\Omega)$  the derivative  
 is unknown in the weak sense (in the weak derivative)

$$\Omega = (1, 1)$$

$$u(x) = 1 \times 1$$

$$v(x) = \begin{cases} +1 & x > 0 \\ -1 & x < 0 \end{cases}$$

$$\operatorname{sgn}(x) = \begin{cases} +1 & x > 0 \\ -1 & x < 0 \\ 0 & x = 0 \end{cases}$$

$$\int_1^1 1 \times 1 v dx = - \int_1^0 x v dx + \int_0^1 x v dx$$

For  $L^p(\Omega)$   $\mathcal{F}$ 's

$k > 0, p \in [1, \infty]$

$\omega_p^k(\Omega) = \{u \in L^p(\Omega), D^\alpha u \in L^p(\Omega), |\alpha| \leq k \text{ is}$

known as Sobolev's space

$$\|\cdot\|_{\omega_p^k(\Omega)} = \left( \sum_{|\alpha| \leq k} \|D^\alpha u\|_{L^p(\Omega)} \right)^{1/p}, \quad 1 \leq p \leq \infty$$

$p=2$ , ~~the~~ will be defined through the inner prod.  
The norm will be defined

$$\omega_2^k(\Omega) = \{u \in L^2, D^\alpha u \in L^2\}$$

$$(u, v) = \sum_{|\alpha| \leq k} (D^\alpha u, D^\alpha v)$$

~~Hilbert space.~~

$$H^k(\Omega) = \omega_2^k(\Omega)$$

$$H^k(\Omega) = \{u \in L^2(\Omega), \frac{\partial u}{\partial x_j} \in L^2(\Omega) \quad j=1, \dots, m\}$$

here  $\frac{\partial u}{\partial x_j}$  denotes the weak derivative of  $u$ .

$$u \in L^2 \quad u \in L^2$$

$$\|u\|_{H^1(\Omega)} = \left( \|u\|_{L^2(\Omega)}^2 + \sum_{|\alpha|=1} \left\| \frac{\partial^\alpha u}{\partial x^\alpha} \right\|_{L^2(\Omega)}^2 \right)^{1/2}$$

$$H^2_0 = \{u \in H^2(\Omega) : u=0, \partial\Omega\}$$

$$\begin{cases} -u'' = f \\ u(0)=0, u(1)=1 \end{cases} \Rightarrow H_E^1(\Omega) = \{u \in H^1(\Omega) \\ u(0)=0, u(1)=1\}$$

absorbing

$$\begin{aligned} u'(0) &= 0 \\ u'(1) &= 5 \\ u(0) + u'(0) &= 1 \\ u(1) + u'(1) &= -5 \end{aligned}$$

$$-\int u' v dx = \int f v dx$$

$$= -(uv')_0 + \int v' u dx = \int fv dx$$

$$u(0)v(1) - v(0)u'(0) + \int v' u dx = \int fv dx$$

$$\|u\|_{H^1(\Omega)} = \left( \|u\|_{C(\Omega)}^2 + \sum_{|\alpha|=1} \left\| \frac{\partial^\alpha u}{\partial x^\alpha} \right\|_1^2 \right)^{1/2}$$

$$H^2_0 = \{u \in H^2(\Omega) : u=0, \partial\Omega\}$$

$$\begin{cases} -u'' = f \\ u(0)=0, \quad u(1)=1 \end{cases} \Rightarrow H_E^1(\Omega) = \{u \in H^1(\Omega) : u(0)=0, u(1)=1\}$$

abstrakt schreib

$$\begin{aligned} u'(1) &= 5 \\ u(0) + u'(0) &= 1 \\ u(1) + u'(1) &= -5 \end{aligned}$$

$\int f u' dx$

$$-\int u'' v dx = \int f v dx$$

$$= -(v u')_0 + \int v' u dx = \int f v dx$$

$$v(1)u'(1) - v(0)u'(0) + \int v' u dx = \int f v dx$$

$\rightarrow v \in H_E^1(\Omega)$

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$$u^n = f$$

$$-\int u' v dx = \int f v dx$$

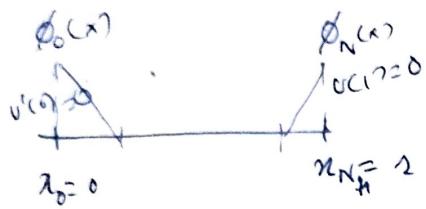
$$\forall v \in H_E^1(\Omega)$$

$$\begin{cases} u'(0) = \alpha \\ u'(1) = \beta \end{cases}$$

$$\int u' v' dx = [uv]_0^1 = f v dx$$

$$H_E^1(\Omega) = \{u \in H^1(\Omega) : u(0) = 0\}$$

$$\begin{cases} u'(0) = \alpha, u'(1) \\ = \beta \end{cases}$$



$$u_n(x) = \sum_{i=1}^n u_i \phi_i(x) \rightarrow \text{Dirichlet B.V.P}$$

$$\phi_i(u_i) = \begin{cases} 1 & i=1 \\ 0 & \text{o.w.} \end{cases}$$

$$u_n(x) = \sum_{i=0}^{Nn} u_i \phi_i(x) \rightarrow \text{Neumann}$$

$$\int_{x_0}^{x_1} \phi'_0(x) \phi_1(x) dx + \int_{x_N}^{x_{NN}} \phi'_M \phi_N(x) dx \neq 0, 0 \quad \text{for other nodal pts}$$

Robin:  $-u'' = f$

$$H_R^1(\Omega) = \{u \in H^1(\Omega), u(0) - u'(0) = \alpha \\ u(1) + u'(1) = \beta\}$$

$$\begin{cases} u(0) - u'(0) = \alpha \\ u(1) + u'(1) = \beta \end{cases}$$

$$\text{Find } v \in H_R^1(\Omega)$$

$$\int u' v dx$$

$$= \int \partial_x g v dx + \dots$$

$$\forall v \in H_R^1(\Omega)$$

Obstacle problem :

① Find  $u \in \mathcal{E}^1(\Omega)$  s.t.

$$u''(u-g) = 0 \quad -u'' \geq 0 \quad u-g \geq 0$$
$$u(1) = u(0) = 0$$

Consider the obstacle problem in order to solve the obstacle problem by finite element we will define the space by the following set

$$\mathcal{K} = \left\{ v \in \mathcal{E}^1[0,1] : v(1) = v(0) = 0, v(x) \geq g(x) + x \in \mathbb{R} \right\}$$

&  $v$  is piecewise  $\frac{d}{dx}$

(Set of competing  $v$ 's)

Find  $u \in \mathcal{K}$

the sol<sup>n</sup>  $u$  of obstacle problem ①  $\Rightarrow u \in \mathcal{K}$  &

for any  $v \in \mathcal{K}$

$$-u''(v-g) \geq 0$$

The finite element formulation tells

from ①

$$\int_0^1 -u''(v-g) dx \geq 0 \quad \forall v \in \mathcal{K}$$

$$\int_0^1 -u''(u-g) dx = 0 \rightarrow ③$$

$$\text{②} - ③ \Rightarrow \int_0^1 -u''(v-u) dx \geq 0 \rightarrow ④$$

$$\forall v \in \mathcal{K}$$

from ④ doesn't explicitly contain  $\phi$  where as  
 it is inside the space  $K$

$$\int_1^1 -d(v')^{(v-u)} dx \geq 0,$$

$$[-v'(x-u)]_1^1 + \int_1^1 v'(v-u) dx \geq 0$$

since  $v, v' \in K$

$$u(x) = v(x)$$

$$u(1) = v(1)$$

weak formulation, find  $\int_1^1 u \in K$  st

$$⑤ \int_1^1 v'(v-u) dx \geq 0 \quad \forall v \in K$$

Since in eq. ⑥ is unknown we will have

if we consider any approx soln  $w \in K$

$$\int_1^1 w'(v-w) dx \geq 0 \quad \forall w \in K$$

$$\sum_{i=1}^N \int_1^1 \phi_i'(x) (\phi_i'(x) - \phi_i'(x)) dx \geq 0 \quad \forall \phi_i$$

$$w_n(x) = \sum_{i=0}^{Nn} w_i \phi_i(x)$$

⑤ is a minimization problem

$$\text{when } v = u \quad \int v' (v - u)' dx = 0$$

$\therefore$  ineq ⑤ is a minimization problem

Implementation

→ Discretize time

Consider the American,

$$y_\tau = y_{\min} \quad \cancel{\text{if}}$$

$$(y_\tau - y_{\min})(y - g) = 0$$

$$y_\tau - y_{\min} \geq 0$$

$$y - g \geq 0 \quad \underbrace{\text{main constraint}}$$

$$y(n, 0) = g(n, 0)$$

$$y(x_{\min}, \tau) = g(x_{\min}, \tau)$$

$$y(n_{\max}, \tau) = g(n_{\max}, \tau)$$

$$y \in \mathbb{S}^2, \omega \cdot \tau \leq 0$$

piecewise  $\mathbb{S}^0 \}$

(admissible  $y^n$ )

$$K = \left\{ y \in \mathbb{S}^0 : \frac{\partial y}{\partial n} \leq 0 \right\}$$

$$y(n, \tau) \geq g(n, \tau) \quad \forall n, \tau$$

$$y(n, 0) = g(n, 0), \quad y(x_{\min}, \tau) = g(x_{\min}, \tau) = g(n_{\min}, \tau)$$

$$y(n_{\max}, \tau) = g(n_{\max}, \tau)$$

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$$v \geq g; \quad \frac{\partial y}{\partial x} = \frac{\partial y}{\partial x^*} \geq 0$$

$$\int_{x_{\min}}^{x_{\max}} \left( \frac{\partial y}{\partial x} - \frac{\partial y}{\partial x^*} \right) (v-g) dx \geq 0 \quad (1)$$

$$\int_{x_{\min}}^{x_{\max}} \left( \frac{\partial y}{\partial x} - \frac{\partial y}{\partial x^*} \right) (y-g) dx \geq 0 \quad (2)$$

$$(1) \& (2) \Rightarrow \int_{x_{\min}}^{x_{\max}} \left( \frac{\partial y}{\partial x} - \frac{\partial y}{\partial x^*} \right) (y-v) dx \geq 0$$

Integration by parts gives

$$\Rightarrow \int_{x_{\min}}^{x_{\max}} \left[ \frac{\partial y}{\partial x} (v-y) + \frac{\partial y}{\partial x} \left( \frac{\partial v}{\partial x} - \frac{\partial y}{\partial x} \right) \right] dx \\ \left[ \frac{\partial y}{\partial x} (v-y) \right]_{x_{\min}}^{x_{\max}} \geq 0 \quad (\because v, y \in \mathbb{K})$$

at boundary

$$\int_{x_{\min}}^{x_{\max}} \left[ \frac{\partial y}{\partial x} (v-y) + \frac{\partial y}{\partial x} \left( \frac{\partial v}{\partial x} - \frac{\partial y}{\partial x} \right) \right] dx \geq 0 \rightarrow (3)$$

if  $v=y$   $\stackrel{(*)}{=} 0$ , therefore (3) is a minimization problem.

$$I(y; v) = \int_{x_{\min}}^{x_{\max}} \left[ \frac{\partial y}{\partial x} (v-y) + \frac{\partial y}{\partial x} \left( \frac{\partial v}{\partial x} - \frac{\partial y}{\partial x} \right) \right] dx \geq 0$$

$\forall v \in \mathbb{K}$

$$\min_{y \in \mathbb{K}} I(y; v) = I(y, y) = 0$$

For Am optn we require the soln  $\hat{G}$  is  $\mathcal{E}^2$

& we expect our soln  $\hat{y}$  s.t  $\min_{\theta \in \mathcal{E}} I(G; u) = 0$

$$y = \sum w_i \phi_i(x) = \sum w_i(\tau) \phi_i(x) \quad \left. \right\} \textcircled{4}$$

$$v = \sum v_i \phi_i(n) = \sum v_i(\tau) \phi_i(n)$$

Using  $\textcircled{4}$  on  $\textcircled{3}$ , we get

$$\int_{x_{\min}}^{x_{\max}} \left[ \sum \frac{dw}{d\tau} \phi_i + \times \sum (v_i - w_i) \phi_i(n) + \sum w_i(\tau) \phi_i(x) \left( \sum (v_j(\tau) - w_j(\tau)) \phi_j(n) \right) \right] dx \geq 0$$
$$- \sum_i \sum_j \frac{dw_i}{d\tau} (v_i - w_j) \underbrace{\int \phi_i(n) \phi_j(n) dx}_B + \sum_i \sum_j w_i (v_i - w_j) \underbrace{\int \phi_i \phi_j' dx}_A \geq 0$$

$$\left( \frac{dw}{d\tau} \right)^T B (v - w) + w^T A (v - w) \geq 0$$

$$B = \int \phi_i \phi_i' dx$$

$$A = \int \phi_i' \phi_j' dx$$

$$\Rightarrow (v - w)^T \left[ \frac{B dw}{d\tau} + A w \right] \geq 0 \rightarrow \textcircled{5}$$

Ineq in ⑤ can be discretized by θ-method.

$$\theta \in [0, 1]$$

$$(\varphi^{(n)} - \omega^{(n)}) \left[ B \frac{1}{\delta t} (\omega^{(n)} - \omega^{(n)}) + \theta A \omega^{(n)} + (1-\theta) A \omega^{(n)} \right] \geq 0$$

$\theta = 0 \rightarrow$  explicit Euler

$\theta = \frac{1}{2} \rightarrow$  Crank-Nicholson.

$\theta = 1 \rightarrow$  implicit Euler.

$$(\varphi^{(n)} - \omega^{(n)}) \left[ (B + \Delta t \theta A) \omega^{(n)} + (1-\theta) (B - \Delta t (1-\theta) A) \omega^{(n)} \right] \geq 0$$

$$\eta = (B - \Delta t (1-\theta) A) \omega^{(n)}$$

$$C = B + \Delta t \theta A$$

$$\Rightarrow (\varphi^{(n)} - \omega^{(n)})^T (C \omega^{(n)} - \eta) \geq 0$$

For side cond.,  $\hat{y}(x_i, \tau) \geq g(x_i, \tau)$

$$\sum w_i(\tau) \phi_i(w) \geq g(x_i, \tau) - \eta$$

$$\textcircled{2} \Rightarrow w_i(\tau) \geq g(x_i, \tau)$$

$$\phi_i(w_i) = \begin{cases} 1 & i = \\ 0 & \text{otherwise} \end{cases}$$

$$w^{(n)} \geq g^{(n)}$$

$$\theta = \gamma_2 \quad w^{(0)}$$

$$\text{for } n=1:N$$

$$\left\{ \begin{array}{l} r = (\beta - \delta \tau (1-\theta) A) w^{(n)} \\ + \varphi g \end{array} \right.$$

$$\Rightarrow (B - \lambda I)^T (A_0 - \lambda) \geq 0, w \geq g$$

In order to incorporate the side conditions one has to use  
the PSOR

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Sewing Machines & Modern India  
informal sector  $\rightarrow$  small units especially in poorer areas where larger industries produce their products

$$\Rightarrow \text{only } \lambda$$

$$Av = \lambda v \quad v^T A v = \lambda v^T v = \lambda \|v\|_2^2$$

$$\overline{v^T A v} = \bar{\lambda} \|v\|_2^2$$

$$v^T A^* v = \bar{\lambda} \|v\|_2^2$$

$$v^T A v = \bar{\lambda} \|v\|_2^2 = \lambda \|v\|^2 \Rightarrow \bar{\lambda} = \lambda \Rightarrow \lambda \in \mathbb{R}$$

Hermitean matrix  $\Leftrightarrow$  Real eigenvalue

$\Rightarrow$  eigen vectors are also real

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$$\text{FEM} \quad r = (B - \Delta T(1-\theta)A)w^{(n)}$$

$$C = B + \Delta T \theta A$$

$$\forall \theta \geq 0, \quad (\theta - \omega)^T (C\omega - \lambda) \geq 0 \quad \text{wzg.}$$

$\Updownarrow$

Replco

$$Aw - b \geq 0, \quad \omega \geq g$$

FDM

$$A = C, \quad b = \lambda$$

$$C\omega - g \geq 0, \quad \omega \geq g$$

$$(C\omega - g)^T (\omega - g) = 0$$

$$\cancel{\omega - g} \quad (Aw - b)^T (\omega - g) = 0$$

temperature



$$\phi_i = \begin{cases} \frac{x_i - x_{i+1} - \alpha_i}{x_i - x_n} & x_i \leq x \leq x_n \\ \frac{x_i - \alpha_i}{x_i - x_n} & x_{i+1} \leq x \leq x_i \\ 0 & \text{else} \end{cases}$$

~~FDM~~  $\leftrightarrow$  ~~FEM~~

( $\Rightarrow$ )  $\lambda_1, \nu \neq 2g$

$\omega - \lambda > 0, \omega \geq g$

$(\nu - \omega) \text{ converges to } \omega \geq g, (\omega - g)^T (\omega - \lambda) \geq 0$

Supp soln of FEM

Supp assume  $w$  satisfies FDM  $\Rightarrow w \geq g$

(middle cond'n is true)

$$w^T (\omega - g) = (\nu - \omega)^T (\omega - \lambda)$$

$$= (\nu - \omega)^T (\omega - \lambda)$$

$$- (\omega - g)^T (\omega - \lambda)$$

$$\geq 0 \Rightarrow (\nu - \omega)^T (\omega - \lambda) \geq 0$$

FDM  $\rightarrow$  FEM

$\Rightarrow$  ~~if  $\omega > g$~~  Supp  $w$  is a soln of FEM  $\Rightarrow w \geq g$

$$(\omega - g)^T (\omega - g) \geq 0 \quad \& \quad (\nu - \omega)^T (\omega - \lambda) \geq 0$$

$$\nu^T (\omega - \lambda) \geq \omega^T (\omega - \lambda)$$

$$g^T (\omega - \lambda) \geq \omega^T (\omega - \lambda)$$

$$(\omega - g)^T (\omega - \lambda) \leq 0$$

$$\omega - \lambda \geq 0$$

(i) we have to prove  $\omega - \lambda \geq 0$  & min comp of  $w$

Supp min of  $(\omega - \lambda)$  is -ve & min comp of  $w$

is as large as possible

~~as possible~~

$$\nu^T (\omega - \lambda) \geq 0$$

$\downarrow$  becomes as small as for

$\therefore$  LHS is as small as possible which is a contradiction

$$\therefore (\omega - \lambda) \geq 0$$

$$(ii) (\omega - \lambda)^T (\omega - g) = 0$$

$$\omega^T g - \lambda^T \omega + \lambda^T g = 0 \Rightarrow \quad (i)$$

$$\text{replace } v = g \cdot \quad (\omega - g)^T (\omega - \lambda) \leq 0 - \quad (ii)$$

$$(\omega - g)^T (\omega - \lambda) \geq 0 \Rightarrow$$

$$(i) \& (ii) \Rightarrow (\omega - g)^T (\omega - \lambda) = 0$$

which tells the FEM & FDM are same giving  
the same soln for the basis elements.

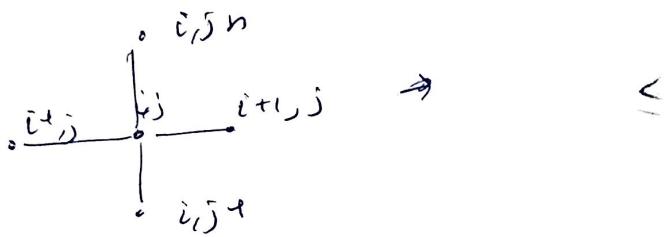
FDM we use C-N elem & num. quad (Chap 10)  
FE we used basis elem

In the implementation of FEM, we have to solve  $\omega = \lambda$  st  
to 2g using PSOR (enough side cond.)

## Exotic options (contd.)

$$\frac{\partial u}{\partial t} - \left( \frac{\partial u}{\partial x^2} + \frac{\partial u}{\partial y^2} \right) + \omega \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + bu = f(x, y, t)$$

↓  
Implementation       $\omega \in [0, 1]$        $\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix}$  → at each time  
beaux of 2-D      level



5-pt stencil } (contd)  
AD I       $(t^n, t^{n+1}), (t^n, t^{n+2}), (t^{n+1}, t^{n+2})$   
 $(t^n, t^{n+3}), (t^n, t^{n+4})$

$$(//) + (|||)$$

MA-423 Lab

4.2.20

$$A = randn(9, 5)$$

$\text{rank}(A)$  : numerical rank      but often very low  
but often actual rank.

$\gg \text{svd}(A) \rightarrow 5 \text{ non-zero columns}$

$$\varepsilon = 2^{\max(n, m)} \|A\|_2$$

$$A(:, 6:7) = A(:, [2, 4]) + A(:, [3, 5])$$

$$A(:, 6:7) \rightarrow (9 \times 2)$$

$$x^T y = \underbrace{(x_1 + 2x_2)}_{c} +$$

$$y^T x = y_1 x_1 + y_2 x_2 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$= x_1 y_1 + x_2 y_2$$

Power method & its variants Q. let  $[x_1 \ x_n]^T \in \mathbb{C}^n \setminus \{0\}$  be arbitrarily chosen. set  $v_{r_0} = x/||x||_\infty$  where  $s_0 = x_{r_0}^T x$  and  $\|x\|_\infty = ||x||_\infty$

$$v_{r_1} = \frac{Av_{r_0}}{s_0} = \frac{A(x/s_0)}{s_0} = \frac{Ax}{s_0 s_0} = \frac{\sum_{k=1}^n a_k c_k v_{r_0}}{s_0 s_0} = \frac{\lambda_2}{s_0 s_0} \left[ c_1 v_1 + \underbrace{\sum_{k=2}^n \frac{a_k c_k}{\lambda_2} v_k}_{\text{error}}$$

$$\det \tilde{q}_{r_j} = \frac{A^j x}{\lambda_1^j}, \quad j=1, \dots$$

$$v_{r_1} = \frac{x_1}{s_0 s_2} \tilde{q}_{r_1}, \quad v_{r_2} = \frac{x_2}{s_0 s_1 s_2} \tilde{q}_{r_2}, \quad v_{r_i} = \frac{A v_{r_{i-1}}}{s_i}$$

$$v_{r_j} = \frac{\sum_{k=0}^j s_k}{s_0} \tilde{q}_{r_j}, \quad \det M_j = \prod_{k=0}^j s_k / \lambda_1^j, \quad j=0, 1, \dots$$

$$\text{Then } v_{r_j} = \frac{\tilde{q}_{r_j}}{M_j}, \quad j=0, 1, \dots$$

$$\text{Let } i_j = \min \{1, \dots, n : q_{r_j}(i_j) = 2\}$$

$$\Rightarrow i_j = \min \{1, \dots, n : q_{r_j}(i_j) = 2\}$$

$$\begin{aligned} \textcircled{*} \quad \frac{\tilde{q}_{r_j}(i_j)}{M_j} &= q_{r_j}(i_j) = 1 \Rightarrow M_j = \tilde{q}_{r_j}(i_j) \\ &= \left[ \frac{A^{i_j} x}{\lambda_1^{i_j}} \right] c_{i_j} \\ &= \left[ c_1 v_1 + \underbrace{\sum_{k=2}^n \left( \frac{\lambda_k}{\lambda_1} \right)^{i_j} c_k v_k}_{\downarrow 0 \text{ as } j \rightarrow \infty} \right] c_{i_j} \end{aligned}$$

$$\therefore \lim_{j \rightarrow \infty} M_j = \lim_{j \rightarrow \infty} c_1 v_1 (i_j)$$

$$\Rightarrow \lim_{j \rightarrow \infty} \frac{\tilde{q}_{r_j}}{M_j} = \lim_{j \rightarrow \infty} \frac{c_1 v_1}{c_1 v_1 (i_j)} = \lim_{j \rightarrow \infty} \frac{v_1}{v_1 (i_j)}$$

$$\lim_{j \rightarrow \infty} \left\| \frac{\varphi_2}{\varphi_1(c_{ij})} \right\|_\infty = \lim_{j \rightarrow \infty} \|q_j\|_\infty = 1$$

$$\begin{aligned} \lim_{j \rightarrow \infty} Aq_j &= A \lim_{j \rightarrow \infty} q_j = \lim_{j \rightarrow \infty} \frac{\varphi_1}{\varphi_1(c_{ij})} = \lim_{j \rightarrow \infty} \frac{A\varphi_2}{\varphi_2(c_{ij})} \\ &= \lambda_2 \lim_{j \rightarrow \infty} \frac{\varphi_1}{\varphi_2(c_{ij})} \end{aligned}$$

$$\therefore \lim_{j \rightarrow \infty} Aq_j = \lambda_2 \lim_{j \rightarrow \infty} q_j = \lambda_2 \lim_{j \rightarrow \infty} q_j$$

$\therefore$  For large enough  $j$ ,  $Aq_j \approx \lambda_2 q_j$

$$\Rightarrow \|Aq_j\|_\infty \underset{\hookrightarrow \textcircled{1}}{\approx} |\lambda_2|, \quad |Aq_j(c_{ij})| \approx |\lambda_2 q_j(c_{ij})| = |\lambda_2| \quad \hookrightarrow \textcircled{2}$$

$$|\lambda_2 q_j(c_{ij})| \approx |\lambda_2 \varphi_j(c_{ij})| \leq |\lambda_2| \leq \|Aq_j\|_\infty \quad \forall i = 1, \dots, m$$

$$\text{For } \textcircled{1} \text{ or } \textcircled{2} \quad |Aq_j(c_{ij})| = \|Aq_j\|_\infty \quad \text{for } c \neq r_j$$

$$\textcircled{3} \Rightarrow |\lambda_2 q_j(c_{ij})| \leq |\lambda_2| = \|Aq_j\|_\infty$$

$$\textcircled{3} \Rightarrow |\lambda_2 q_j(c_{ij})| \leq |\lambda_2| = \|\lambda_2\|_\infty \quad \forall i = 1, \dots, m$$

If  $i \neq j$  by defn of  $c_{ij}$ ,  $|Aq_j(c_{ij})| \leq \|\lambda_2\|_\infty \quad \text{for large enough } i$

for large enough  $j$   $c_{ij}$  starts repeating for large enough  $j$

$$\sup_{j \rightarrow \infty} i_j = i_0$$

Then  $\lim_{j \rightarrow \infty} q_j = \ln \frac{v_1}{v_1(s_j)} = v_1/\theta_1(s_1) = \tilde{\theta}_1$  (dominant e.vectr of A)

$$\text{(i) } \lim_{j \rightarrow \infty} s_j = \gamma_2, \quad \lim_{j \rightarrow \infty} q_j = \tilde{\theta}_1 \Rightarrow \lim_{j \rightarrow \infty} \Delta q_j = \Delta \lim_{j \rightarrow \infty} q_j = \Delta \tilde{\theta}_1 = \lambda \hat{v}_1$$

$$\Rightarrow \lim_{j \rightarrow \infty} \frac{\Delta q_j}{s_j} = \lim_{j \rightarrow \infty} \frac{\lambda \hat{v}_1}{s_j}$$

$\underbrace{\Delta q_j}_{\Delta v_{jn}}$

$$\Rightarrow \lim_{j \rightarrow \infty} \frac{\Delta q_j}{s_j} = \lim_{j \rightarrow \infty} \frac{\lambda \hat{v}_1}{s_j} \Rightarrow \hat{\theta}_1 = \frac{\lambda \hat{v}_1}{\lim_{j \rightarrow \infty} s_j}$$

$$\lim_{j \rightarrow \infty} q_j = \hat{\theta}_1$$

the const. corresp to  $v_1 \neq 0$

\* rounding errors can make ~~err~~  
occur if  $G=0$  due to rounding errors.

### MA-423 Matlab Lab

$$A = U \Sigma V^T$$

~~if  $A = U \Sigma V^T$  then  $A = U \Sigma V^T (U \Sigma V)^T$~~

~~if  $n < m$ ,  $A = U \Sigma V^T$~~

~~if  $n > m$ ,  $A = U \Sigma V^T$~~

$$V^T V = I$$

$$U \Sigma V^T$$

$$U \Sigma V^T$$

$$U \Sigma V^T$$

$$U_{18 \times 6}, \quad S_{6 \times 6}, \quad V_{6 \times 6}$$

$$n = 18, \quad m = 6$$

$$n > m$$

$$w = U_{18 \times 6} \times V'_{6 \times 6}$$

$$R = U_{18 \times 6} \times S_{6 \times 6} \times U_{6 \times 18}$$

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### Exotic options

$$V(S_1, t) \rightarrow \frac{\partial V}{\partial t} + \frac{\sigma^2}{2} \frac{\partial^2 V}{\partial S^2} + (\alpha - r) S \frac{\partial V}{\partial S} - rV = 0$$

$$V(S_1, S_2, t) \rightarrow ?$$

$$dX_t = a dt + dw$$

$$dS_1 = \mu_1 S_1 dt + \sigma_1 S_1 dw^{(1)}$$

$$dS_2 = \mu_2 S_2 dt + \sigma_2 S_2 dw^{(2)}$$

$$E(dw^{(1)}, dw^{(2)}) = \rho dt$$

$$\Rightarrow \frac{\partial V}{\partial t} + \frac{1}{2} \sum_{i,j=1}^n p_{ij} \sigma_i \sigma_j S_i S_j \frac{\partial^2 V}{\partial S_i \partial S_j} +$$

$$\sum_{i=1}^n (\alpha - s_i) s_i \frac{\partial V}{\partial S_i} - rV = 0$$

$$\sum_{i=1}^n (\alpha - s_i) s_i \frac{\partial V}{\partial S_i} - rV = 0$$

$$S_L = (S_{\min}^1, S_{\min}^2) \times (S_{\max}^1, S_{\max}^2)$$

$$S_L \times [0, T]$$

$$\text{Cor}(ds_1, ds_2)$$

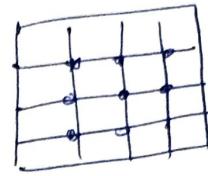
$$\text{Cor}(ds_1, ds_2) = E(a_1 dw^{(1)}, a_2 dw^{(2)}) = \rho a_1 a_2 dt$$

$$\text{Cor}(ds_1, ds_2)$$

$$\frac{\partial V}{\partial z} + \frac{1}{2} \sum \rho_{12} \alpha_1 \alpha_2 S_1 S_2 \left( \frac{\partial V}{\partial S_1} + \frac{\partial V}{\partial S_2} + \frac{\partial V}{\partial \alpha_1 \alpha_2} \right) + \dots$$

↓  
eq ①

$$\frac{\partial u}{\partial z} = \left( \frac{\partial u}{\partial x^2} + \frac{\partial u}{\partial y^2} \right) \rightarrow \text{eq } ②$$



$h^{1/4}$   
 $(Mn)^{\tilde{x}} (Nn)^{\tilde{y}}$

Discretization using CTS, BCS, CN.

$$\frac{U_{lm}^{nn} - U_{lm}^n}{h^2} = \frac{(U_{l+1,m}^{nn} - 2U_{lm}^{nn} + U_{l-1,m}^{nn})}{h^2} + \frac{(U_{l,m+1}^{nn} - 2U_{lm}^{nn} + U_{l,m-1}^{nn})}{h^2}$$

$$A = \begin{pmatrix} \text{main diag} & & \\ & \text{super diag} & \\ & & \text{sub diag} \end{pmatrix}$$

$$\frac{\partial V}{\partial S_1} = \frac{(U_{l+1,m} - 4U_{lm} + U_{l-1,m}) + U_{lm,n} + U_{lm,-1}}{h^2}$$

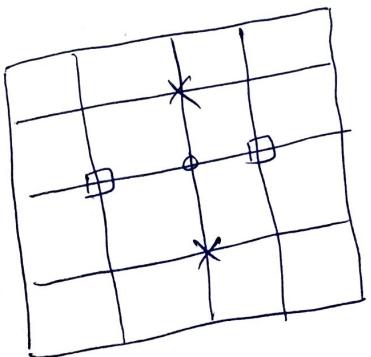
$$U_{lm} = \begin{pmatrix} l & m \\ l & m \\ l & m+1 \end{pmatrix}$$

$$S_{xy}^n U_{lm}^n = S_m^n U_{lm}^{nn} + \delta_y^m U_{lm}^{nn}$$

$$\frac{\partial u}{\partial x} = \frac{u_{x+1,m}^{n+1} - u_{x-1,m}^n}{2h} \quad (\text{C.D.I})$$

If we discretize the PDE's corresponding to the exterior opn bndry in ① or the 2D heat condng given in ① by any implicit scheme like B.I.Cs or C.W then the bandwidth of the matrix  $A$ , ( $Au = f$ ) will be large, therefore it takes enormous CPU time & memory to solve the sys of linear alg. eqns. In order to overcome these computational complexities Direct Implicit scheme) A.D.I Type (Alternating

$$v(x, y, t) = \phi^{(n,y)} T.$$



$t^n \rightarrow t^{n+1}$

$t^n \rightarrow t^{n+\frac{1}{2}} \rightarrow t^{n+1}$

(Canonical nine step)

$x$ : explicit  
 $y$ : implicit or vice versa

$x$ : implicit  
 $y$ : explicit

When we progress from time  $t^n$  to  $t^{n+1}$  we introduce an artificial time step at  $t^{n+1/2}$  & the whole scheme will be returned in the following manner.

$$t^n \rightarrow t^{n+1} \quad x: \text{explicit}, y: \text{implicit} \quad \text{or vice versa.}$$

$$t^{n+1/2} \rightarrow t^n \quad \cancel{x: \text{implicit}}, y: \text{explicit}$$

$$(100) = (100) + (100)$$

$$\frac{U_{l,m}^{n+1/2} - U_{l,m}^n}{(St/2)} = \left( \frac{U_{l,m}^{n+1/2} - 2U_{l,m}^n + U_{l,m}^{n-1/2}}{h^2} \right) +$$

$$\left( \frac{U_{l,m+1}^n - 2U_{l,m}^n + U_{l,m-1}^n}{h^2} \right) \rightarrow ③$$

$$\frac{U_l^{n+1} - U_l^{n+1/2}}{St/2} = \left( \frac{U_{l+1,m}^{n+1/2} - 2U_{l,m}^{n+1/2} + U_{l-1,m}^{n+1/2}}{h^2} \right) +$$

$$\left( \frac{U_{l,m+1}^{n+1} - 2U_{l,m}^{n+1} + U_{l,m-1}^{n+1}}{h^2} \right) \rightarrow ④$$

Starting from the given I.C's we can solve ③, by using the soln of ④ as the initial value for ④

$$-\tilde{\delta}_U(U^T \hat{A} U) \otimes^T = -\cancel{\delta_U(\hat{A} U)} - \underbrace{\delta_U(-\hat{A} U)}_{\cancel{\delta_U}} U^T$$

$$= \cancel{\delta_U U^T}$$

$$= \tilde{\delta}_U U^T \otimes \hat{U}$$

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recap:

$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial x^1} + \frac{\partial u}{\partial y^2}$$

$$t_n \rightarrow t_{n+1/2} \rightarrow t_{nn}$$

$$\sum_x u_{ij}^n = u_{i+1,j} - 2u_{ij}^n + u_{i-1,j}$$

$$\sum_y u_{ij}^n = u_{i,j+1} - 2u_{ij}^n + u_{i,j-1}$$

$$\frac{u_{lm}^{n+1/2} - u_{lm}^n}{\Delta t/2} = \frac{1}{h^2} \left[ \sum_x u_{lm}^{n+1/2} + \sum_y u_{lm}^n \right] \rightarrow \textcircled{5}$$

$$\frac{u_{lm}^{nn} - u_{lm}^{n+1/2}}{\Delta t/2} = \frac{1}{h^2} \left[ \sum_x u_{lm}^{nn} + \sum_y u_{lm}^{n+1/2} \right] \rightarrow \textcircled{6}$$

$\delta_u U_{lm}$

Form eq ③ of prr deduce.

$$\frac{U_{lm}^{n+1/2} - U_{lm}^n}{\Delta t/2} = \frac{1}{h^2} \left[ \frac{\partial}{\partial r} \left( U_{l+1,m}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l-1,m}^{n+1/2} \right) \right]$$

$$+ \left[ U_{l,mn}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l,mn}^n \right]$$

$$U_{lm}^{n+1/2} - U_{lm}^n = \frac{\Delta t}{2h^2} \left[ \begin{array}{l} U_{l+1,m}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l-1,m}^{n+1/2} \\ + U_{l,mn}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l,mn}^n \end{array} \right]$$

$$U_{lm}^{n+1/2} - U_{lm}^n = \alpha U_{l+1,m}^{n+1/2} - 2\alpha U_{lm}^{n+1/2} + (1-2\alpha) U_{l-1,m}^{n+1/2} \\ + 2\alpha U_{l,mn}^{n+1/2} - 2\alpha U_{lm}^{n+1/2} + \alpha U_{l,mn}^n$$

$$- \cancel{\alpha U_{l,mn}^n} + (1+2\alpha) U_{lm}^n \\ - \cancel{2\alpha U_{l,mn}^n}$$

Form eq ④

$$\cancel{- \alpha U_{l,mn}^n} \frac{U_{lm}^{n+1} - U_{lm}^{n+1/2}}{\Delta t/2} = \frac{1}{h^2} \left[ \begin{array}{l} U_{l+1,m}^{n+1/2} - 2U_{lm}^{n+1/2} + U_{l-1,m}^{n+1/2} \\ U_{l,mn}^{n+1} - 2U_{lm}^{n+1} + U_{l,mn}^n \end{array} \right]$$

$$- \cancel{\alpha U_{l,mn}^n} + (1+2\alpha) U_{lm}^n - \cancel{\alpha U_{l,mn}^{n+1}} = \alpha U_{l+1,m}^{n+1/2} + (1-2\alpha) U_{l-1,m}^{n+1/2} \\ + \alpha U_{l-1,m}^{n+1}$$

$$\Delta_1 U_{lm}^{n+1/2} = \beta_1 U_{lm}^n$$

$$\Delta_2 U_{lm}^{n+1} = \beta_2 U_{lm}^{n+1/2}$$

If we eliminate  $U_{lm}^{n+1/2}$  at the form the two eq's.

$$⑦ \quad -\left(1 - \frac{\alpha S_n}{2}\right) U_{lm}^{n+1/2} = \left(1 + \frac{\alpha S_y}{2}\right) U_{lm}^n$$

$$⑧ \quad -\left(1 - \frac{\alpha S_y}{2}\right) U_{lm}^n = \left(1 + \frac{\alpha S_x}{2}\right) U_{lm}^{n+1/2}$$

then we get,

$$\left(1 - \frac{\alpha S_x}{2}\right) \left(1 - \frac{\alpha S_y}{2}\right) U_{lm}^n = \left(1 + \frac{\alpha S_n}{2}\right) \left(1 + \frac{\alpha S_y}{2}\right) U_{lm}^{n+1/2}$$

$$\Rightarrow \left[ -\frac{\alpha}{2} (S_n + S_y) + \frac{\alpha^2}{4} S_n S_y \right] U_{lm}^{n+1/2} + \left[ +\frac{\alpha^2}{4} S_n S_y \right] U_{lm}^n \rightarrow ⑨$$

$$= \left\{ 1 + \frac{\alpha}{2} (S_n + S_y) \right\}$$

for  $\alpha = 2^{1/2}$

## O-scheme

$$\theta \left[ \frac{U_{l,m}^{n+1/2} - U_{l,m}^n}{\Delta t/2} \right] + (1-\theta) \left[ \frac{U_{l,m}^{n+1/2} - U_{l,m}^n}{\Delta t/2} \right]$$

$$= \frac{\theta}{h^2} \left[ U_{l,m+1}^{n+1/2} - 2U_{l,m}^{n+1/2} + U_{l,m}^{n+1/2} \right] \\ + U_{l,m+1}^n - 2U_{l,m}^n + U_{l,m}^n$$

$$\frac{U_{l,m}^{n+1/2} - U_{l,m}^n}{\Delta t} = \theta (S_n U_{l,m}^n + \delta_y U_{l,m}^n)/h^2 \\ + (1-\theta) (\delta_x U_{l,m}^{n+1/2} + \delta_y U_{l,m}^n)/h^2$$

$$\theta = 1/2 \rightarrow C.N, \quad \lambda = \Delta t/h^2$$

$$[1 - (1-\theta) (S_n + \delta_y)] U_{l,m}^n = [1 + \theta \frac{\lambda}{2} (S_n + \delta_y)] U_{l,m}^n \rightarrow ⑩$$

Comparing ⑨ & ⑩

we have  $\frac{\lambda}{2} S_n \delta_y$  as an extra term in ⑨

which presents in the ADI scheme.

The addition additional term which presents in the ADI scheme proportional to  ~~$\lambda^2$~~   $6(k^2 h^2)$  which is the

same order as  $C.N(\theta(k^2 h^2))$  scheme which is

2nd order in time & space & the scheme ⑨ is known as

the approximate falconzain.

$$\frac{\partial V}{\partial t} = \frac{\alpha_1}{2} \frac{\partial^2 V}{\partial S_1^2} + \frac{\alpha_2}{2} \frac{\partial^2 V}{\partial S_2^2} + \rho \alpha_1 \alpha_2 \frac{\partial^2 V}{\partial S_1 \partial S_2} + (\alpha - \alpha_1) \gamma \frac{\partial^2 V}{\partial S_1^2},$$

$$+ (\alpha - \alpha_2) \left\{ \frac{\partial^2 V}{\partial S_2^2} - \partial V = 0 \right.$$

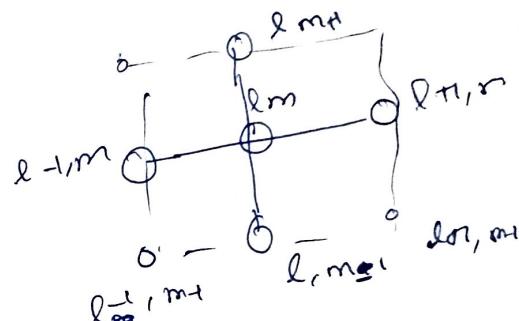
for  $V(S_1, S_2, t)$

~~we can find~~  $\rho = 0$  when  $\rho = \text{Cov}(\partial w_0^{(1)}, \partial w_0^{(2)})$

$$\delta_{S_1} \delta_{S_2} V_{lm}^n = ?$$

$$D^+ D^- V_{lm}^n = D^+ \left[ \frac{V_{l+1,m}^n - V_{lm}^n}{h} \right]$$

$$= \frac{V_{l+1,m}^n - V_{l,m}^n}{(S+1)h} - \frac{V_{l,m}^n - V_{l-1,m}^n}{(S+1)h}$$



$$\delta_{S_1} \delta_{S_2} = \frac{1}{2h} \left( \frac{V_{l+1,m}^n - V_{l-1,m}^n}{2h} \right)$$

$$= \frac{1}{9h} \left( V_{l+1,m+n} - V_{l-1,m+n} - V_{l+1,m-n} + V_{l-1,m-n} \right)$$

BDM

$$D^+ v_e = \frac{v_{e,n} - v_e}{h} \quad \text{if } v_e = (v_e - v_{e,1})/h$$

$$v(s,t) = V_m$$

$$D^- v_e = \frac{v_{e,n} - v_e}{eh}$$

$$\text{cts: } \frac{1}{T} \int_0^T s_e d\theta$$

$$v(s, \text{Avg}, t)$$

$s < t$

$$t_i = t_m$$

$$\text{dismu: } \frac{1}{m} \sum_{i=1}^m s_i$$

$$v(s_1, \Delta, t)$$

$$\frac{\partial v}{\partial t} + \frac{\alpha^2}{2} \frac{\partial^2 v}{\partial s^2} + (\lambda - s) \frac{\partial v}{\partial s} + \frac{s^2 v}{2A} - \lambda v = 0$$

if we evaluate the underlying at diff time  
 insmus  $t_i = t_m$  the corresponding value  
 can take either the arithmetic  
 $s_{t_1} s_{t_m}$  or the one  
 or the geometric mean. if we consider the  
 ex. here we have integr.

$$R_{O_1} = \begin{bmatrix} \alpha_{11} & & \\ & \ddots & \\ & & \alpha_{nn} \end{bmatrix} \left[ \begin{array}{c|c} \delta_i & \\ \hline & I_{n-2} \end{array} \right]$$

Applying this tech. on the  $i^{th}$  we get  ~~$A_i$~~   $\rightarrow$   
 ~~$A_i$~~  as upp Hess. & so  $A_i$  as upp Hess  
matrix on every  $i^{th}$

MA-473 If we sample the underlying asset  $s_t$  time interval  
at discrete time intervals with equidistant Then we  
we obtain  $s_{t_1}, s_{t_2}, \dots, s_{t_n}, s_{t_n}$ .

$V_m \in N$  can consider avg as arithmetic mean

$$\frac{1}{n} \sum_{i=1}^n s_{t_i} = \frac{h}{T} \sum_{i=1}^n s_{t_i} = A \rightarrow ① \text{ or if the time}$$

$$h = T/h \quad \text{interval is cts}$$

instead of the arithmetic mean

$$\hat{s} = \frac{1}{T} \int_0^T s_t dt \rightarrow ② \quad \text{for both discrete}$$

we can consider the geo. mean

$$\left( \prod_{t=1}^n s_{t_i} \right)^{1/n} = \exp \left( \frac{1}{n} \log \prod_{t=1}^n s_{t_i} \right) \rightarrow ③$$

Discrete:

$$= \exp \left( \frac{1}{n} \sum_{t=1}^n \log s_{t_i} \right) \rightarrow ④$$

$$GTS: \quad \hat{s} = \exp \left( \frac{1}{T} \int_0^T \log s_t dt \right) \rightarrow ⑤$$

$$S_0 A = \hat{S} = S_t = \frac{1}{t} \int_0^t f(S, \theta) d\theta$$

$V(S, t) \rightarrow \text{European}$

$V(S, A, t) \rightarrow \text{Asian}$

In the Asian option with avg  $\hat{S}$  with the underlying asset

$S_t \otimes$ ,  $t < T$

$(\hat{S} - K)^+ \rightarrow \text{avg price call}$

$(K - \hat{S})^+ \rightarrow \text{avg price put}$

$(S_T - \hat{S}) \rightarrow \text{single call}$

$(\hat{S} - S_T) \rightarrow \text{single put}$

Consider this case  $^{189}$ :

Let us denote the avg  $A_t = \int_0^t f(S_\theta, \theta) d\theta$

Instead of reg SDE, will have

$$dA_t = a_A(t) dt + b_A dw_t \quad a_A = f(S_t, t) \quad b_A = 0$$

$$dV_t = \left( \frac{\partial V}{\partial t} + g_A \frac{\partial V}{\partial S} + \frac{\sigma^2}{2} \frac{\partial^2 V}{\partial S^2} + f(S_t, t) \frac{\partial V}{\partial A} \right) dt + \alpha \frac{\partial V}{\partial S} dw_t$$

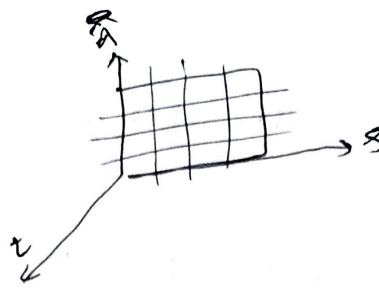
$$\therefore \frac{\partial V}{\partial t} + \frac{\partial V}{\partial S} \frac{\partial S}{\partial A} + g_A \frac{\partial V}{\partial S} + f(S_t, t) \frac{\partial V}{\partial A} - \alpha V = 0 \quad \rightarrow (1)$$

$$\therefore \frac{\partial V}{\partial t} + \frac{\partial V}{\partial S} \frac{\partial S}{\partial A} + g_A \frac{\partial V}{\partial S} + f(S_t, t) \frac{\partial V}{\partial A} - \alpha V = 0 \quad \text{extra term} \\ - \alpha V \cdot$$

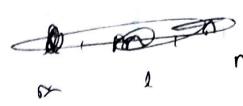
Black-Scholes like pde

Applies

BTCS, ~~C-N~~



SS, SR, ST



We can consider simplest case.

BTCS:

$$\frac{V_{m+1}^{nn} - V_{lm}^{nn}}{SR} + \frac{\alpha}{2} S_m^2 \left( \frac{V_{m+1}^{nn} - V_{lm}^{nn}}{2S^2} - V_{lm}^{nn} \right) + g(S_m, z_{nn}) \otimes \frac{V_{lm}^{nn} - V_{m+1}^{nn}}{SA} = 0$$

$+ g S_m$

$- g V_{lm}^{nn}$

$$\checkmark \frac{V_{l,m}^{nn} - V_{lim}^{nn}}{SR} + \frac{\alpha}{2} S_m^2 \left( \frac{V_{lim}^{nn} - 2V_{lim}^{nn} - V_{l,m}^{nn}}{2S^2} \right) + g(S_m, z_{nn}) \otimes \frac{V_{l,m}^{nn} - V_{lim}^{nn}}{SA}$$

$+ g S_m$

$- g V_{lim}^{nn}$

$$- g V_{lim}^{nn} = 0$$

when  $f(S, t)$  is linear then we can reduce  
the 2D BS like pde into 1D pde (dim-red<sup>n</sup>)

Consider the BS like pde ( $\mathcal{F}$ ) in 2D domain

$$V(S, A, t) \quad S > 0, \quad A > 0, \quad 0 \leq t \leq T$$

in the particular case when  $f(S, t) = S$  we  
can reduce the dim to 1D. Let us consider  
the European Arithmetic Avg strike call with  
payoff  $(S_T - \hat{S})^+ = (S_T - \frac{1}{T} A_T)^+ = S_T (1 - \frac{1}{T} \int_0^T S_\theta d\theta)^+$

Let us denote  $R_T = \frac{1}{T} \int_0^T S_\theta d\theta$ ,  $A_T = R_T / S_T$

$$S_T (1 - \frac{1}{T} R_T)^+ = \cancel{S_T H(R_T, t)}$$

$$V(S, A, t) = \cancel{S - H(R, t)}$$

where  $H$  is a fn of  $R$  &  $t$  &  $R$  is an  
independent variable

$$dR_t = \cancel{R_t + S_t} dt \quad R_{t+S_t} \neq R_t$$

$$\begin{aligned} dR_t &= \cancel{R_t + S_t} dt + R_t \\ \therefore \quad \left\{ \begin{array}{l} R_{t+S_t} = dR_t + R_t \\ dS_t = \cancel{\mu S_t} dt + \sigma S_t dW_t \\ dR_t = (1 + (\alpha - \mu)) R_t dt - \sigma R_t dW_t \end{array} \right. \end{aligned}$$

HSS-217

Date: 23/10/24

## Everyday Tech. - Gramophone

- ① What made the new sound space modern?
- Its mobility, it's able to listen to any sound anywhere.
- ② Became a commodity
- ③ In a phy env you need to be at a particular place & time to listen to a particular sound, the sound space with the new sound space transformed this relationship with ~~time~~ space & time by ~~making~~ making it possible to listen to any sound ~~at~~ anywhere at any time.

MA-973

Date: 22/10/24

From our class,

$$V(S, A, t) = S \cdot H(R, t)$$

$$A_t = S_k R_t$$

$$A = S \cdot R$$

Transformation:

$$V(S, A, t) = V(S, R, t) = S \cdot H(R, t), R = \frac{A}{S}$$

$$V_t = SH_t$$

$$V_S = H(R, t) + S H_R$$

$$V_{SS} =$$

$$= \frac{\partial H}{\partial R} \left( -\frac{A}{S^2} \right) + 1 - \frac{A}{S} \frac{\partial H}{\partial R} + 1$$

~~$$\frac{\partial V}{\partial t} + \left( \frac{\partial V}{\partial S} \right) \frac{\partial S}{\partial R}$$~~

$$V_{SS} =$$

~~$$H_R$$~~

$$\Rightarrow H_R \left( -\frac{A}{S^2} \right) + H_R + S \cdot H_{RR} \left( -\frac{A}{S^2} \right)$$

$$V_A = S H_R \cdot \frac{1}{S} = H_R$$

$$= -\frac{H_R}{S^2} + H_R - \frac{H_{RR} A}{S^2}$$

Substituting in original eqn

$$\frac{\partial H}{\partial t} + \frac{\sigma^2}{2} R^2 \frac{\partial^2 H}{\partial R^2} + (1 - \alpha k) \frac{\partial H}{\partial R} = 0$$

For the bddy cond'n  $R \rightarrow \infty$  we obtain from the payoff  $H(R_T, T) = (1 - \frac{1}{T} R_T)^+$

$$R_T \rightarrow \infty \quad H(R_T, T) = 0$$

$R_L = \frac{1}{S^t} \int_0^t S_\theta d\theta$ , the integral  $R_L$  is bdd'd

As  $S \rightarrow \infty, R \rightarrow \infty$

This is the European call  $\Rightarrow S \rightarrow 0, H(R, t) = 0, R \rightarrow \infty$   
exercise the European call  $\Rightarrow$  we cannot

Date: 25/10/29

$$\Delta_0 = \Delta, \quad \Delta_0 = Q_0 R_0 \quad (R_0 \geq 0 \forall i=1, \dots, n) \quad \Delta_i := R_i Q_i \\ = Q_i^* R_0 Q_0$$
$$\Delta_1 = Q_1 R_1 \quad (R_1 \geq 0 \forall i=1, \dots, n)$$
$$\Delta_2 = R_2 Q_1 \\ = Q_1^* R_1 Q_1$$

converges  
→ schur form of  $P$

$\Delta_1, \Delta_2$

Date: 25/10/24

Recap:  $\frac{\partial H}{\partial t} + \frac{\alpha}{2} \frac{\partial^2 H}{\partial R^2} + (\lambda R) \frac{\partial H}{\partial R} = 0$

bdry cond<sup>r</sup>:  $R=0, R \rightarrow \infty$

$R \rightarrow \infty, S \rightarrow \infty$   $R_T \rightarrow \infty$

$R \rightarrow 0 ?$

$$dR_2 = (1 + (\alpha - \mu) R_t) dt + \alpha R_T d\omega_t \rightarrow \textcircled{c}(1)$$

$$\Rightarrow dR_0 = dt$$

$$|_{R_T=0}$$

$R \rightarrow \infty$

For the left hand bdry cond<sup>r</sup> then  
some difficulties for eg  $R_0=0$  then  
obtain  $dR_0 = dt \Rightarrow R_T$  won't

i.e. we can expect  $R_T$  to be 0.

Therefore to obtain the bdry cond<sup>r</sup> at  $R=0$ , we use  
the pde directly.

(assumed:  $\frac{\partial R}{2} \frac{\partial H}{\partial R} \rightarrow 0$ )

$$\textcircled{1} \Rightarrow \frac{\partial H}{\partial t} + \frac{\partial^2 H}{\partial R^2} = 0$$

provided the 2nd derivative of  $H$  or  $H$  is bdded.  
If  $\alpha$  is bdded we can draw the conclusion that  
 $\frac{\partial H}{2} \frac{\partial^2 H}{\partial R^2} \rightarrow 0$

$$\text{Supp } \frac{\partial H}{\partial R} \quad \text{Supp } \frac{\partial^2 R^2}{2} \frac{\partial H}{\partial R^2} = \text{const}$$

$$\frac{\partial H}{\partial R} = O(\frac{1}{R})$$

$$\frac{\partial H}{\partial R} = \frac{C}{R}$$

$$\frac{\partial H}{\partial R} = C \int R^{-2} dR = \frac{C R^{-1}}{-1} + C_1$$

$$\text{or } H = \frac{C}{R} + C_1 R$$

as  $R \rightarrow 0$   $H$  is unbound, but we assumed it's bounded  
 which is a contradiction

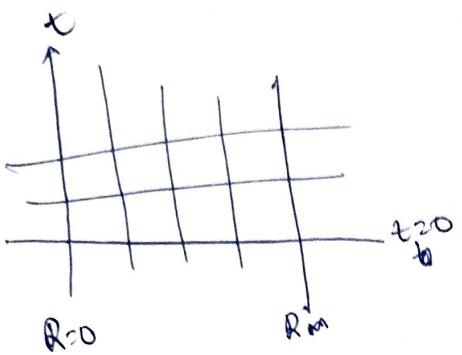
$$\therefore \frac{\partial^2 H}{\partial R^2} \rightarrow 0 \text{ as } R \rightarrow 0 \quad (\text{when } H \text{ is bounded})$$

$$\left. \begin{array}{l} \text{at } R=0 \\ \text{at } R \rightarrow \infty \end{array} \right\} H(R, t) = 0 \quad \left. \begin{array}{l} \frac{\partial H}{\partial R} + \frac{\partial H}{\partial t} = 0 \\ \end{array} \right\} (*)$$

$$H(R_t, t) = \left( 1 - \frac{R_t}{t} \right)^+$$

$$\frac{H_m^{n+1} - H_m^n}{St} + \frac{H_{m+1}^{n+1} - H_m^{n+1}}{SR} = 0$$

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$$D^+ D^+ H_m^n = D^+ \left( \frac{H_{m+1}^{n+1} - H_m^n}{SR} \right)$$

$$\frac{\partial H}{\partial R} \Big|_{R=0} = \frac{-3H_0^n + 4H_1^n - H_2^n + 6S^n}{2SR}$$

Since we obtain  $H$

$$v(S, A, t) = S H(C, t)$$

When we have discrete avg  $t_1, t_2, \dots, t_m$   
 $s_{t_1}, s_{t_2}, \dots, s_{t_m}$

The past hist or discrete  $m$ .

If suppose we determine the underlying at the then

discrete  $m$  not at  $t_1, t_2, \dots, t_m$   
 the another way avg  $\Delta t_k = \frac{\sum_{i=1}^k s_{t_i}}{k}$   $k=1, \dots, M$

$\downarrow$   
 $(*)$

(\*) can be re-written as an update from the prev one.  $A_{tk} = \underbrace{A_{tk-1}}_K + \frac{s_{tk}}{k}$

$$= A_{tk-1} + \frac{1}{k} (s_{tk} - A_{tk}) \rightarrow (1)$$

$t=T \rightarrow t=0$  (top to bottom)  
it is more appropriate to have the integration in backward  
time,  $A_{tk} = \cancel{A_{tk-1}} + \frac{A_{tk}}{(k)} + \cancel{\frac{1}{k}(A_{tk}-s_{tk})}$

$$A_{tk-1} = A_{tk} + \frac{1}{(k)} (A_{tk} - s_{tk}) \rightarrow (2)$$

from (1) & (2) we can obs that  $A_{tk}$  is const  
between the sampling times & it jumps at  $t_k$  with  
 $y_{kt} (A_{tk} - s_{tk})$

$$\bar{A}(s) = A^+(s) + \left(\frac{1}{k}\right) (A^+(s) - s) \quad s = s_k$$

where  $A^-, A^+$  denote the values of  $A$  immediately  
before & after sampling of  $t_k$ .

From the No-Arbitrage principle we can note that  
the continuity of  $V(s_t, A_t, t)$  for any realization  
of random walk.

$$v(s, A^+, t_k) = V(s, \bar{A}, t_k) \rightarrow (+)$$

For any fixed  $s, A$  ~~eq~~ ( $\dagger$ ) define a jump at  $v$   
at the sampling  $t_k$ .

From  $\frac{\partial V}{\partial A} = 0$  of the jump condit

For the numerical calculations if we discretize  $A$ -axis into discrete values  $A_1 \dots A_J$  consecutive then for each time period  $[t_n, t_{n+1})$  two samplings  $t_{n+1} \rightarrow t_k$  is independent of  $A$ , because  $A_t$  is piecewise const, therefore  $\frac{\partial V(A)}{\partial A} = 0$

Therefore we obtain  $J$  no. of 1-D Pde, ~~all~~ all

~~can be~~ integrated separately / independently for  $t_n \rightarrow t_{n+1}$

which is more suitable for parallel computing

Date: 28/10/29

SDE (stochastic differential eqns)

derivative form:

$$\begin{cases} y' = f(y) + \epsilon \in [0, 1] \\ y(0) = \alpha \end{cases}$$

Differential form (since derivative may not exist)

$$M(n, y) dy dt$$

$$+ N(n, y) dy = 0$$

$$\begin{cases} SDE \\ \end{cases} dx(t) = a(t, x) dt + b(t, x) d\omega_t$$

$x(0) = x_0$

$$\int_0^t dx(s) = \int_0^t a(s, x) ds + \int_0^t a(s, x) d\omega_s$$

$$x(t) - x_0 = \int_0^t a(s, x) ds + \int_0^t a(s, x) d\omega_s$$

BS SDE:  $dx = \mu x dt + \alpha x d\omega_t$

$$x_{t+} = (x_t + \frac{\alpha^2}{2})$$

$$\int_a^b f(x) dx = \sum_{i=0}^n f(x^*) \Delta x$$

Riemann integral

$x^* \in [x_i, x_{i+1}]$

$$\int_a^b f(w) d\omega_t = \sum_{i=0}^n f(t_i) \Delta \omega_i$$

$\Delta \omega_i = \omega_{i+1} - \omega_i$

$= \beta_i \sqrt{\Delta t}$

$f: \text{deterministic}$

$$\sum_{i=1}^n \int_{t_{i-1}}^{t_i} f(s) d\omega_s$$

$\beta_i \in N(0, 1)$

BS SDE:  $dx = \mu x dt + \alpha x d\omega_t$

$$x(t) = \exp \left\{ \left( \mu - \frac{\alpha^2}{2} \right) t + \alpha \omega_t \right\}$$

$$J = \int_0^t f(t) d\omega_t \quad (\text{Hot's integral})$$

$$dJ = f d\omega_t$$

$$Y = f(t, x)$$

$$dY = f_t dt + f_x dx + \frac{1}{2} f_{xx} dx dx$$

where  $dx dx$  can be interpreted by using identities

$$dt dt = 0, \quad dt dw = 0 \quad dw_t dw_t = dt$$

B.S diffusion eqn soln:

$$X(t) = X_0 e^{(\mu - \frac{\sigma^2}{2})t + \alpha w_t} \quad Y = (\mu - \frac{\sigma^2}{2})t + \alpha w_t$$

~~$$\partial X(t) = X_0 e^{\cancel{t}} \times \cancel{e^{\cancel{w_t}}} \quad Y$$~~

$$dY = (\mu - \frac{\sigma^2}{2}) dt + \alpha d\omega_t$$

$$dY dY = \sigma^2 dt$$

~~$\partial X \partial$~~   
putting  ~~$\partial X = f$~~

~~$$dY dY = f_x dx + \frac{1}{2} f_{xx} dx dx$$~~

~~$$dx = X_0 e^Y dy + X_0 e^Y dY dy$$~~

$$dx = X_0 e^Y \left[ \left( \mu - \frac{\sigma^2}{2} \right) dt + \alpha d\omega_t \right] + X_0 e^Y \sigma^2 dt$$

$$x_0 e^{\left( \mu - \frac{\alpha^2}{2} \right) t + \alpha dw_t} \left[ (\mu - \frac{\alpha^2}{2}) dt + \alpha d\omega_t + \tilde{\alpha} d\tau \right]$$

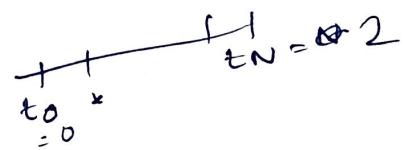
$$\text{if } X_0 = x_0 e^{(\mu - \tilde{\alpha})t + \theta d\omega_t} \left[ (\mu + \frac{\alpha^2}{2}) d\tau + \tilde{\alpha} d\omega_t \right] + x_0$$

In principle it is difficult to obtain closed form analytical solns for SDEs, therefore one has to seek numerical approximate soln for SDEs

[See del 3rd chp]

$$\Delta Y_N \quad h = 2^{k-1}$$

$$\begin{cases} y'(t) = f(t, y) ; \quad t \in [0, 1] \\ y(0) = \alpha \end{cases}$$



$$\int_{t_0}^{t_N} y'(s) ds = \int_{t_0}^{t_N} f(s, y(s)) ds$$

$$\Rightarrow y_{NN} - y_N = f(t_N, y_N) h$$

Euler Maruyama

$$\begin{aligned} dx(t) &= a(t, x) dt + b(t, x) d\omega_t, \quad t \in [0, T] \\ x(0) &= x_0 \end{aligned}$$

$$h = T/N$$

Integrate ~~step by step~~  $\int_{t_n}^{t_{n+1}}$   $b(t_n) d\omega_t$

$$\int_{t_n}^{t_{n+1}} dx(s) = \int_{t_n}^{t_{n+1}} \cancel{x(s)} a(s, x(s)) ds + \int_{t_n}^{t_{n+1}} \cancel{b(s, x(s))} dw_s$$

$$x(t_{n+1}) - x(t_n) = a(t_n, x_n) \Delta t + b(t_n, x_n) \Delta w_n$$

$\Delta w_n$

$$z_i \in \mathcal{N}(0, 1)$$

$$\Delta w_n = z_i \sqrt{\Delta t}$$

Euler  $T-E = O(h)$   
 $(LHS - RHS)$

F-E Euler Mariana

$\Delta w = O(\sqrt{t})$   
Because of the jammed B.M the order of Euler Mariana  
scheme gets diminished by  $\frac{1}{2}$ .

$$O(\sqrt{h}) \xrightarrow{?} O(h)$$

next goal: