**Gesture controlled robot receiver section**

**ARDUINO**

**2 8**

**3 9**

**4 10**

**5 11**

**MOROR DRIVER**

**D0.0 M0.0**

**D0.1 M0.1**

**D1.0 M1.0**

**D1.1 M1.1**

**RF RECEIVER 10**

**11**

**12**

**13**

**DB7**

**DB6**

**DB5**

**DB4**

**E**

**RS**

L

C

D

**RF TX**

**10**

**11**

**12**

**13**

**Transmitter section of gesture controlled Robot**

**Vcc 2**

**GND 3**

**A0 4**

**A1 5**

**A2 11**

**A3 12**

**ARDUINO**

**7**

**8**

**9**

**10**

**Vcc**

**ACCELEROMETER Gnd**

**X**

**Y**

**Z**