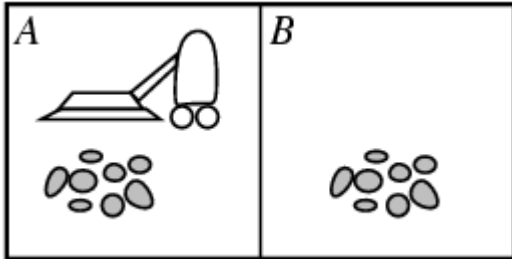For Lab session:

Write a python code that receives the command from user and executes the command for vacuum cleaner as follows

Percepts: location and contents

Actions: *Left , Right , Suck , NoOp, Show state*

Example Usage Flow of the program

>>> ShowState

```
I am at A
A is Dirty
B is Dirty
```

>>Right

```
I am at B
A is Dirty
B is Dirty
```

>>Suck

```
I am at B
A is Dirty
B is Clean
```