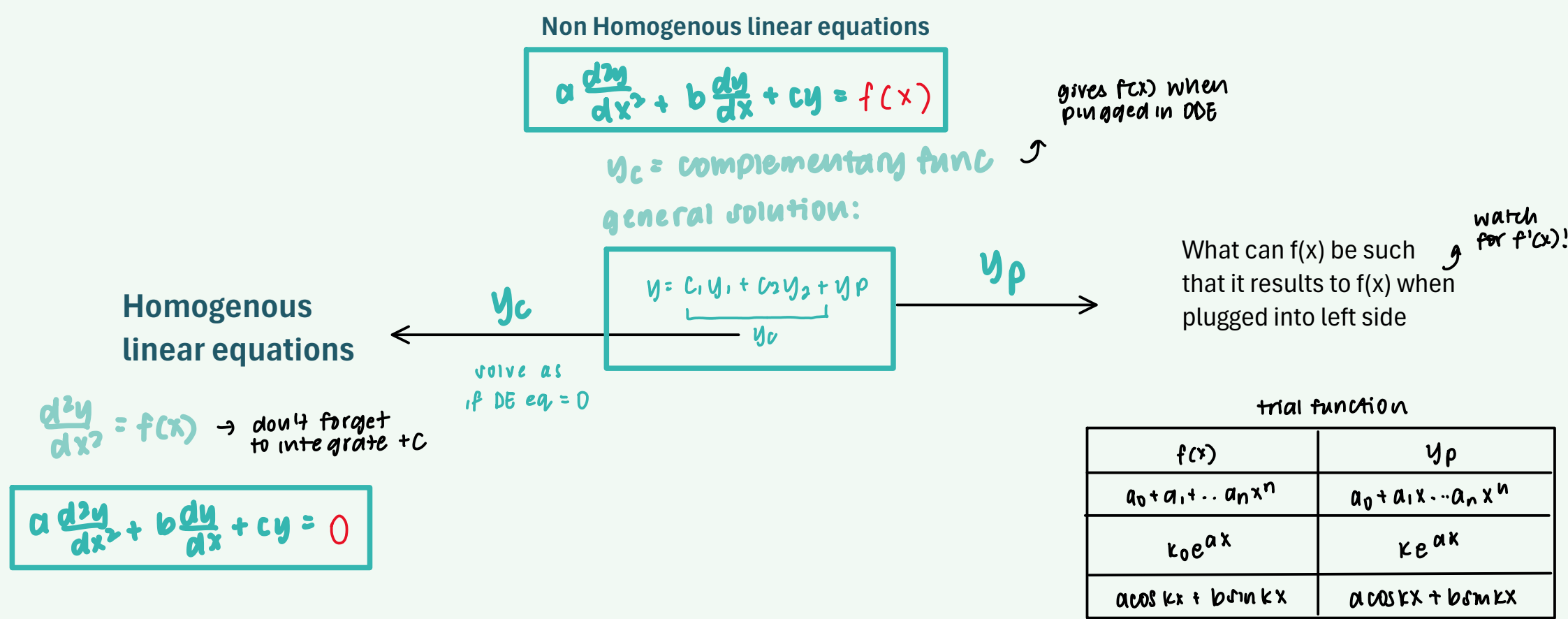


2ND ORDER DIFFERENTIAL EQUATIONS

↳ basically contains  $\frac{d^2y}{dx^2}$



general sol:  $y = Ae^{m_1x} + Be^{m_2x}$   
where  $m_1, m_2$  are the roots of  $am^2 + bm + c$   
characteristic equation

1)  $m_1 \neq m_2$

eg:  $\frac{d^2y}{dx^2} - \frac{dy}{dx} = 2$   
 $m^2 - m = 2 \quad y = Ae^{-x} + Be^{2x}$   
 $m: -1 \text{ or } 2$

2)  $m_1 \neq m_2$  (not real)

$y = e^{\alpha x} (A \cos \beta x + B \sin \beta x)$   
proof:  $e^{i\theta} = \cos \theta + i \sin \theta$

3)  $m_1 = m_2$  (real)

$y = (A + Bx) e^{mx}$

eg.  $\frac{d^2y}{dx^2} + 4 \frac{dy}{dx} + 4y = 16e^{2x}$

$y_c$   
char eq:  $m^2 + 4m + 4 = 16e^{2x}$   
 $(m+2)^2 = 16e^{2x}$   
 $y_c = (A+Bx)e^{-2x}$

$y_p$   
 $kx^2e^{-2x}$   
 $y_p' = k(2x e^{-2x} - 2x e^{-2x})$   
 $y_p'' = k(2 - 8x + 4x^2)e^{-2x}$   
 $k e^{-2x} [(2 - 8x + 4x^2) + 4(2x - 2x^2) + 4x^2] = 16e^{-2x}$   
 $k = 8$

$y = \underbrace{(Ax+B)e^{-2x}}_{y_c} + \underbrace{8x^2e^{-2x}}_{y_p}$

modeling oscillation kinematics

Real life Application

• Hooke's Law

$F_R = -kx = mx''$

$\frac{d^2x}{dt^2} + \frac{k}{m}x = 0$

$x = A \cos(\omega t - \phi)$

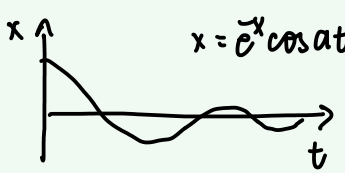
• Damping

$mx'' + \underbrace{\hspace{1cm}}_{\text{opposing force}} = -kx$  ← damping constant  
let  $x$  = displacement

$mx'' = -kx + (-cx')$

Frict on mass    restoring force by spring    force by dash board } prevent the door from slamming when closed (loud)

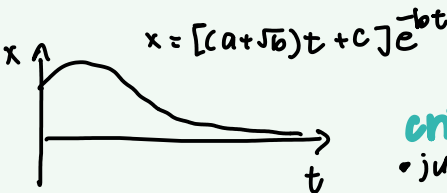
$\frac{d^2x}{dt^2} + \frac{c}{m}(\frac{dx}{dt}) + \frac{k}{m}x = 0$



underdamping

- not periodic
- door oscillates
- trigo function

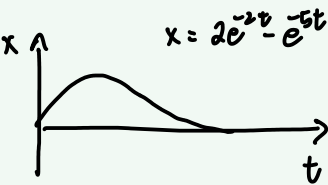
$D < 0$



critical damping

- just enough for body to reach equilibrium
- ideal door
- always contains decreasing exponential function

$D = 0$



overdamping

- $x \rightarrow 0$  in a gradual manner

$D > 0$