

Egitura Aljebraikoa

D. Barne-eragileta: $A \times A$ eragileta egin eta A emaitza A multzoan baldin badago.

$$\begin{aligned} * : A \times A &\rightarrow A \\ (a, b) &\mapsto a * b \\ a, b &\in A \end{aligned}$$

Propietateak:

- elkarlortasuna: $(a * b) * c = a * (b * c)$

- trinkortasuna: $a * b = b * a$

- elementu neutroa: $a * e = a$

- elementu simetrikoa: $a * a' = a' * a = e$

Biderketan idatzkera: $a' = a^{-1}$ alderantzizkora.

\emptyset " " : $a' = -a$ aritmetikoa.

- Elementu Sinplifikagarria: $a * x = y * a \Rightarrow x = y$

- Elementu idempotentea: Bere bururekin biderketu eta berbera ematen.

Cayley-ren taula, \mathbb{Z}_3 ko kongruentzia:

$+$	0	1	2
0	0	1	2
1	1	2	0
2	2	0	1

\mathbb{Z}_3 Elementu neutroa, trinkortze-legea

		$a+b$	0	1	2
0	0	0	0	1	2
	1	1	1	2	0
	2	2	2	0	1
1	0	1	1	2	0
	1	2	2	0	1
	2	0	0	1	2
2	0	2	2	0	1
	1	0	0	1	2
	2	1	1	2	0

a	b	0	1	2
0	0	0	1	2
1	0	0	1	2
2	0	0	1	2

Aufgabe 1

①

a)

$$* : \mathbb{Z} \times \mathbb{Z} \rightarrow \mathbb{Z}, \text{ Binäre-Operation? } (\mathbb{Z}, +)$$

$$x, y \in \mathbb{Z} \rightarrow x * y \in \mathbb{Z}?$$

$$x, y, z \in \mathbb{Z} \rightarrow 3x, 2y \in \mathbb{Z} \Rightarrow$$

$(\mathbb{Z}, +)$

$$\Rightarrow 3x + 2y \in \mathbb{Z}$$

Elemente-besetzung betonen du?

$$x, y, z \in \mathbb{Z} \quad (x * y) * z = x * (y * z)$$

$$(x * y) * z = (2x + 3y) * z = 2(2x + 3y) + 2z = 4x + 6y + 2z$$

$(\mathbb{Z}, +), (\mathbb{Z}, \{-0, 1\})$

$$x * (y * z) = x * (3y + 2z) = 3x + 2(3y + 2z) = 3x + 6y + 4z$$

Elemente-assoziativ?

$$\forall x \in \mathbb{Z} \quad \exists e \in \mathbb{Z} \quad x * e = e * x = x$$

$$x * e = \boxed{3x + 2e = x}$$

$$3x + 2e = x \Rightarrow 2x + 2e = 0 \Rightarrow \boxed{e = -x}$$

triviale legge?

$$x \leftarrow y = 3x + 2y \\ y \leftarrow x = 3y + 2x \quad \#$$

b)

$$\mathbb{Q} \times \mathbb{Q} \longrightarrow \mathbb{Q}$$

$$x, y \in \mathbb{Q} \quad x \oplus y \in \mathbb{Q}$$

$$x \oplus y = x, y, 1 \in \mathbb{Q} \Rightarrow x + y + 1 \in \mathbb{Q}$$

$$(\mathbb{Q}, +)$$

$$(\mathbb{Q} - \{0\}, \cdot)$$

Elaborata? \rightarrow Elabore-legge

$$\forall x, y, z \in \mathbb{Q} \quad x \oplus (y \oplus z) = (x \oplus y) \oplus z$$

$$x \oplus (y \oplus z) = x \oplus (yz + 1) = \cancel{xyz} x(yz + 1) + 1 = xyz + x + 1$$

$$(x \oplus y) \oplus z = (xy + 1) \oplus z = (xy + 1) \cdot z + 1 = xyz + z + 1$$

Elemento neutro?

$$x \oplus e = xe + 1 = x$$

$$xe + 1 = x \Rightarrow e = \frac{x-1}{x} \Rightarrow x \neq 0$$

Es. degli. elemento neutro

Egitura Algebrakalk

Barne-erregikek

$(A, *)$ taldea

$(A, *, \cdot) \begin{cases} \text{Erregikuna} \\ \text{Gorputza} \end{cases}$

Kanpoko-erregikek

$(V, \oplus, *)$ Bektore-espazioa

V, K

$* : K \times V \rightarrow V$

$(k, v) \leadsto k * v \in V$

1. (V, \oplus) talde trinkorra

2. $(K, +, \cdot)$ Gorputza

$(V, \oplus, *)$ Bektore-espazioa

1. $\forall k \in K \quad \forall \bar{v}_1, \bar{v}_2 \in V$

$$k * (\bar{v}_1 \oplus \bar{v}_2) = \underbrace{k * \bar{v}_1}_{\in V} \oplus \underbrace{k * \bar{v}_2}_{\in V}$$

2. $\forall k_1, k_2 \in K \quad \forall \bar{v} \in V \quad (k_1 + k_2) * \bar{v} = \underbrace{k_1 * \bar{v}}_{\in V} \oplus \underbrace{k_2 * \bar{v}}_{\in V}$

3. $k_1, k_2 \in K \quad \forall \bar{v} \in V$

$$(k_1 \cdot k_2) * \bar{v} = k_1 * (\underbrace{k_2 * \bar{v}}_{\in V})$$

4. $1 \in K$ (unitatea) $\forall \bar{v} \in V \quad 1 * \bar{v} = \bar{v}$

1. $0 \in K$ (zeroa) $\forall \bar{v} \in V \quad 0 * \bar{v} = \bar{0}$

$0 * \bar{v} = (0 + 0) * \bar{v} = 0 * \bar{v} \oplus 0 * \bar{v} = \bar{0}$ Bektore espazioaren definizioaren propietate.
 \uparrow
 $0 \in K = \text{zero}$

$$\bar{0} \in V \Rightarrow 0 * \bar{v} \oplus \bar{0} = 0 * \bar{v} \oplus 0 * \bar{v} = \bar{0} \oplus \bar{0} = 0 * \bar{v}$$

sinplifikazioa

2. $\vec{0} \in V$ (zero Vektor), $\forall k \in K \quad k * \vec{0} = \vec{0}$

$$k * \vec{0} = (k * k) * \vec{0} = k * \vec{0} \oplus k * \vec{0}$$

$$k * \vec{0} = k * \vec{0} \oplus k * \vec{0} \Rightarrow \vec{0} = k * \vec{0}$$

3.

$$\forall k \in K \quad \forall \vec{v} \in V \quad k * \vec{v} = \vec{0} \Leftrightarrow k = 0 \vee \vec{v} = \vec{0}$$

\Rightarrow

$$k = 0 \vee \vec{v} = \vec{0} \Rightarrow k * \vec{v} = \vec{0} \quad \text{1. et 2.}$$

\Rightarrow

Denn aus $k \neq 0$ folgt $k * \vec{v} = \vec{0} \Rightarrow \vec{v} = \vec{0}$

$(K, +, \cdot)$ Körper $\Rightarrow \exists k^{-1} \in K$

$$(k * \vec{v}) = \vec{0} \Rightarrow k^{-1} * (k * \vec{v}) = k^{-1} * \vec{0} \Rightarrow (k^{-1} * k) * \vec{v} = k^{-1} * \vec{0}$$

Definiereigenschaften

$$\Rightarrow 1 * \vec{v} = k^{-1} * \vec{0} \Rightarrow \vec{v} = k^{-1} * \vec{0} \Rightarrow \vec{v} = \vec{0}$$

K Körper

Definiereigenschaften

$$4. \forall \vec{v} \in V \quad (-1) * \vec{v} = -\vec{v}$$

(V, \oplus) Abelsche

$$(1) * \vec{v} = \vec{v} \Rightarrow (-1) * \vec{v} \oplus \vec{v} = -\vec{v} \oplus \vec{v} \Rightarrow (-1) * \vec{v} \oplus \vec{v} = -\vec{v} \oplus \vec{v} \Rightarrow (-1) * \vec{v} = -\vec{v} \quad \text{Abelsche}$$

Beispiel - assoziativ aditiv

$$R: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$(k, \vec{v}) \mapsto k \cdot \vec{v}$$

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix} \in \mathbb{R}^2$$

$$k=3 \in \mathbb{R}$$

$$3 \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$$

$$R: \mathbb{R} \times M \rightarrow M$$

$$(k, \vec{v}) \mapsto k \cdot \vec{v}$$

$$\begin{pmatrix} 1 & 1 \\ 2 & 3 \end{pmatrix} \in M$$

$$k=3 \in \mathbb{R}$$

$$3 \cdot \begin{pmatrix} 1 & 1 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} 3 & 3 \\ 6 & 9 \end{pmatrix} \in M$$

$$(V, \oplus, +)$$

$$W = \{(\lambda, x) \in \mathbb{R}^2 / x = \lambda\} \quad W \subseteq \mathbb{R}^2?$$

$$\forall w_1, w_2 \in W \quad \forall k_1, k_2 \in \mathbb{R}$$

$$k_1 w_1 + k_2 w_2 \in W$$

$$w_1, w_2 \in W \Rightarrow w_1 = \begin{pmatrix} x_1 \\ x_1 \end{pmatrix} \quad w_2 = \begin{pmatrix} x_2 \\ x_2 \end{pmatrix}$$

$$k_1 w_1 + k_2 w_2 = k_1 \begin{pmatrix} x_1 \\ x_1 \end{pmatrix} + k_2 \begin{pmatrix} x_2 \\ x_2 \end{pmatrix} = \begin{pmatrix} k_1 x_1 \\ k_1 x_1 \end{pmatrix} + \begin{pmatrix} k_2 x_2 \\ k_2 x_2 \end{pmatrix} = \begin{pmatrix} k_1 x_1 + k_2 x_2 \\ k_1 x_1 + k_2 x_2 \end{pmatrix} \in W$$

①

a)

$$W = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 / x_1 = 0 \right\}$$

$$\forall w_1, w_2 \in W \quad \forall k_1, k_2 \in \mathbb{R} \quad k_1 w_1 + k_2 w_2 \in W$$

$$k_1 \begin{pmatrix} 0 \\ x_2 \\ x_3 \end{pmatrix} + k_2 \begin{pmatrix} 0 \\ x_2 \\ x_3 \end{pmatrix} \in W = \begin{pmatrix} 0 \\ k_1 x_2 \\ k_1 x_3 \end{pmatrix} + \begin{pmatrix} 0 \\ k_2 x_2 \\ k_2 x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ k_1 x_2 + k_2 x_2 \\ k_1 x_3 + k_2 x_3 \end{pmatrix} \in W$$

b)

$$W = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 / x_1 = 1 \right\}$$

$$\forall w_1, w_2 \in W \quad \forall k_1, k_2 \in \mathbb{R} \quad k_1 w_1 + k_2 w_2 \in W$$

$$k_1 w_1 + k_2 w_2 = k_1 \begin{pmatrix} 1 \\ x_2 \\ x_3 \end{pmatrix} + k_2 \begin{pmatrix} 1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} k_1 \\ k_1 x_2 \\ k_1 x_3 \end{pmatrix} + \begin{pmatrix} k_2 \\ k_2 x_2 \\ k_2 x_3 \end{pmatrix} = \begin{pmatrix} k_1 + k_2 \\ k_1 x_2 + k_2 x_2 \\ k_1 x_3 + k_2 x_3 \end{pmatrix} \notin W$$

Es da betrachtet.

c)

$$W = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 / x_1 = 0 \vee x_2 = 0 \right\} \Rightarrow w_1 = \begin{pmatrix} 0 \\ x_2 \\ x_3 \end{pmatrix} \quad w_2 = \begin{pmatrix} x_1 \\ 0 \\ x_3 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ k_1 x_2 \\ k_1 x_3 \end{pmatrix} + \begin{pmatrix} k_2 x_1 \\ 0 \\ k_2 x_3 \end{pmatrix} = \begin{pmatrix} k_2 x_1 \\ k_1 x_2 \\ k_1 x_3 + k_2 x_3 \end{pmatrix} \notin W$$

g)

$$\bar{x} = (1, 1, 0) \text{ da } \bar{y} = (2, 0, 1)$$

$$\bar{w}_1, \bar{w}_2 \in W$$

$$\bar{w}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad \bar{w}_2 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned} k_1 \cdot \bar{w}_1 + k_2 \cdot \bar{w}_2 &= k_1 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + k_2 \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} k_1 \\ k_1 \\ 0 \end{pmatrix} + \begin{pmatrix} 2k_2 \\ 0 \\ k_2 \end{pmatrix} = \begin{pmatrix} k_1 + 2k_2 \\ k_1 \\ k_2 \end{pmatrix} \\ &= \alpha (k_1 \bar{x} + k_2 \bar{y}) + \beta (k_1' \bar{x} + k_2' \bar{y}) = \alpha k_1 \bar{x} + \beta k_1' \bar{x} + k_2 \bar{y} + \beta k_2' \bar{y} = \\ &= \underbrace{(\alpha k_1 + \beta k_1')}_{\in \mathbb{R}} \bar{x} + \underbrace{(\alpha k_2 + \beta k_2')}_{\in \mathbb{R}} \bar{y} \in W \end{aligned}$$

$$V = \left\{ \begin{pmatrix} \bar{k} \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} \bar{k} \\ -1 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$$N(A) = \{ \bar{x} \in \mathbb{R}^2, A\bar{x} = \bar{0} \} \subset \mathbb{R}^2$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$r(A) = 2$$

$$\begin{cases} k_1 + k_2 = 0 \\ -k_2 = 0 \end{cases}$$

$$\bar{b} = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} \in S$$

$$\boxed{A\bar{x} = \bar{b}}$$

$$\bar{b} = k_1 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + k_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} \Rightarrow \bar{S} = \begin{pmatrix} k_1 \\ k_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix}$$

$$|A| = 2 < 3 = n$$

Sistema batereagorri Indeterminatu.

$$\begin{cases} k_1 + k_3 = x_1 \\ k_2 + k_3 = x_2 \end{cases}$$

$$\vec{S}_0 = \vec{S}_p + \vec{S}_n$$

$$\vec{S}_n \begin{cases} k_1 + k_3 = 0 \\ k_2 + k_3 = 0 \end{cases}$$

$$S_n = k_3 \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

\Rightarrow Oinerrizko

Aldagai ask: k_1, k_2

Aldagai askuek: k_3

$$\begin{cases} k_1 = -k_3 \\ k_2 = -k_3 \end{cases}$$

$$\vec{S}_p = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} \quad \begin{matrix} k_1 = x_1 \\ k_2 = x_2 \end{matrix}$$

$$\vec{S}_0 = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} + k_3 \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\vec{S} \notin \langle \vec{v}_1, \vec{v}_2 \rangle$$

$$\begin{pmatrix} 1 & 1 \\ 0 & -1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} \bar{x} \\ k_1 \\ k_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \bar{x} \\ k_1 \\ k_2 \end{pmatrix} \quad \text{Batereagorri}$$

③

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 + c_4 \vec{v}_4 = \vec{0}$$

$$c_1 \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + c_3 \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} + c_4 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} \xrightarrow{E_2(-1)} \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} \xrightarrow{E_2(1)} \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix} \xrightarrow{E_4(-1)} \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad r(A) = 3$$

$$r(A) = 3 < 4$$

Systeme Battergerie indeterminat

④

a) $A \cdot \vec{x} = \vec{0}$

$$\begin{pmatrix} 1 & 1 & 3 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{pmatrix} \begin{pmatrix} k_1 \\ k_2 \\ k_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 3 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{pmatrix} \xrightarrow{E_2(-1)} \begin{pmatrix} 1 & 1 & 3 \\ 0 & 1 & -2 \\ 2 & 1 & 1 \end{pmatrix} \xrightarrow{E_3(-2)} \begin{pmatrix} 1 & 1 & 3 \\ 0 & 1 & -2 \\ 0 & -1 & -5 \end{pmatrix} \xrightarrow{E_{23}(1)} \begin{pmatrix} 1 & 1 & 3 \\ 0 & 1 & -2 \\ 0 & 0 & -2 \end{pmatrix} \quad r(A) = 3 = n$$

S.B.D

$$k_1 = k_2 = k_3 = k_4 = 0$$

$$\forall M_a \in M \quad \exists \varepsilon \in M \quad M_a + \varepsilon = \varepsilon + M_a = M_a$$

$$M_a = xI + yA \quad x, y \in \mathbb{Q}$$

$$\varepsilon = e_1 I + e_2 A \Rightarrow \varepsilon = 0I + 0A = 0$$

$$\begin{aligned} M_a + \varepsilon &= (xI + yA) + (e_1 I + e_2 A) = \\ &= (x+e_1)I + (y+e_2)A = M \end{aligned}$$

$$\Rightarrow \begin{cases} x + e_1 = x \Rightarrow e_1 = 0 \\ y + e_2 = y \Rightarrow e_2 = 0 \end{cases}$$

$$M_a' = x'I + y'A$$

$$M_a + M_a' = M_a' + M_a = 0$$

$$\begin{aligned} M_a + M_a' &= (xI + yA) + (x'I + y'A) = \\ &= (x+x')I + (y+y')A = 0 \end{aligned}$$

$$\Rightarrow \begin{cases} x+x' = 0 \Rightarrow x' = -x \\ y+y' = 0 \Rightarrow y' = -y \end{cases}$$

$$M_a' = (-x)I + (-y)A$$

$$M_a + M_a' = (xI + yA) + (-x)I + (-y)A = (x-x)I + (y-y)A = 0I + 0A = 0$$

triviale-lemma

$$\forall M_1, M_2 \in M \quad M_1 + M_2 = M_2 + M_1$$

$$M_1 = x_1 I + y_1 A$$

$$M_2 = x_2 I + y_2 A \quad x_1, x_2, y_1, y_2 \in \mathbb{Q}$$

$$\begin{aligned} M_1 + M_2 &= (x_1 I + y_1 A) + (x_2 I + y_2 A) = (x_1 + x_2)I + (y_1 + y_2)A = (x_2 + x_1)I + (y_2 + y_1)A = \\ &= (x_2 I + y_2 A) + (x_1 I + y_1 A) = M_2 + M_1 \end{aligned}$$

Algebra

⑩

$$x, y \in \mathbb{Q}$$

$$M = \left\{ \begin{pmatrix} x-3y & 4y \\ -4y & x+3y \end{pmatrix} / x, y \in \mathbb{Q} \right\}$$

$(M, +, \cdot)$ Gruppo?

$(M, +)$ talde abeldarra?

(M, \cdot) talde abeldarra?
o Matritzen konmutatibitate.

Banaldorra Betulaketa-erakidea

$$+ : M \times M \rightarrow M$$

$$(M_1, M_2) \mapsto M_1 + M_2 \in M$$

$$M_1 = \begin{pmatrix} x-3y & 4y \\ -4y & x+3y \end{pmatrix} = \begin{pmatrix} x & 0 \\ 0 & x \end{pmatrix} + \begin{pmatrix} -3y & 4y \\ -4y & 3y \end{pmatrix} = x \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + y \begin{pmatrix} -3 & 4 \\ -4 & 3 \end{pmatrix} = x_1 I_1 + y_1 A$$

$$M_2 = x_2 I_1 + y_2 A$$

$x_1, y_1, x_2, y_2 \in \mathbb{Q}$ $(\mathbb{Q}, +, \cdot)$ Erakidea da. Ondorioa, $x_1 + x_2 \in \mathbb{Q}$

$$M_1 + M_2 = (x_1 I_1 + y_1 A) + (x_2 I_1 + (y_2 I_1 + y_2 A)) = (x_1 + x_2) I_1 + (y_1 + y_2) A$$

Eitartze-legea

$$\forall M_1, M_2, M_3 \in M$$

$$M_1 \cdot (M_2 + M_3) = (M_1 + M_2) \cdot M_3$$

$$\begin{aligned} M_1 \cdot (M_2 + M_3) &= (x_1 I_1 + y_1 A) \cdot [(x_2 I_1 + y_2 A) + (x_3 I_1 + y_3 A)] = (M_1 + M_2) \cdot M_3 = [(x_1 I_1 + y_1 A) + (x_2 I_1 + y_2 A)] \cdot (x_3 I_1 + y_3 A) \\ &= (x_1 I_1 + y_1 A) \cdot [(x_2 + x_3) I_1 + (y_2 + y_3) A] = (x_3 I_1 + y_3 A) \cdot [(x_1 + x_2) I_1 + (y_1 + y_2) A] \\ &= (x_1 + (x_2 + x_3)) I_1 + (y_1 + (y_2 + y_3)) A = (x_3 + (x_1 + x_2)) I_1 + (y_3 + (y_1 + y_2)) A \\ &= (x_1 + x_2 + x_3) I_1 + (y_1 + y_2 + y_3) A = (x_3 + x_1 + x_2) I_1 + (y_3 + y_1 + y_2) A \end{aligned}$$

$$= x_1 x_2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} -3(x_1 x_2 + x_2 x_1) - 7x_1 x_2 & 4(x_1 x_2 + x_2 x_1) \\ -4(x_1 x_2 + x_2 x_1) & 3(x_1 x_2 + x_2 x_1) + 7x_1 x_2 \end{pmatrix} =$$

$$= x_1 x_2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} -3x_1 x_2 - 7x_1 x_2 & 0 \\ 0 & 7x_1 x_2 \end{pmatrix} + \begin{pmatrix} -3(x_1 x_2 + x_2 x_1) & 4(x_1 x_2 + x_2 x_1) \\ -4(x_1 x_2 + x_2 x_1) & 3(x_1 x_2 + x_2 x_1) + 7x_1 x_2 \end{pmatrix} =$$

$$= x_1 x_2 \mathbb{I} + \begin{pmatrix} -7 & 0 \\ 0 & 7 \end{pmatrix} + (x_1 x_2 + x_2 x_1) A$$

$$M_1 M_2 = (x_1 x_2 \mathbb{I} + (x_1 x_2 \mathbb{I} + A) + (x_1 x_2 A \mathbb{I} + x_1 x_2 A^2)$$

$$A^2 = \begin{pmatrix} -3 & 4 \\ -4 & 3 \end{pmatrix} \begin{pmatrix} -3 & 4 \\ -4 & 3 \end{pmatrix} = \begin{pmatrix} -3 & 0 \\ 0 & -3 \end{pmatrix} \Rightarrow A^2 = -3\mathbb{I}$$

$$M_1 M_2 = (x_1 x_2 \mathbb{I} + (x_1 x_2 \mathbb{I} + A) + (x_1 x_2 A \mathbb{I} + x_1 x_2 A^2) = (x_1 x_2 \mathbb{I} + 7(x_1 x_2 \mathbb{I} + (x_1 x_2 + x_2 x_1) A)$$

Cartan-lemma

$$M_1, M_2, M_3 \in \mathfrak{M}$$

$$M_1 \cdot (M_2 \cdot M_3) = M_1 \cdot M_2 \cdot M_3$$

$$M_1 = x_1 \mathbb{I} + \gamma_1 A$$

$$M_2 = x_2 \mathbb{I} + \gamma_2 A$$

$$M_3 = x_3 \mathbb{I} + \gamma_3 A$$

$$M_1 \cdot M_2 = (x_1 x_2 \mathbb{I} - 7\gamma_1 \gamma_2 \mathbb{I} + (x_1 \gamma_2 + x_2 \gamma_1) A$$

$$M_2 \cdot M_3 = (x_2 x_3 \mathbb{I} - 7\gamma_2 \gamma_3 \mathbb{I} + (x_2 \gamma_3 + x_3 \gamma_2) A$$

$$M_1 \cdot (M_2 \cdot M_3) = (x_1 \mathbb{I} + \gamma_1 A) [(x_2 x_3 \mathbb{I} - 7\gamma_2 \gamma_3 \mathbb{I} + (x_2 \gamma_3 + x_3 \gamma_2) A] =$$

$$= x_1 [(x_2 x_3 - 7\gamma_2 \gamma_3) \mathbb{I} + (x_2 \gamma_3 + x_3 \gamma_2) A] + \gamma_1 [(x_2 x_3 - 7\gamma_2 \gamma_3) A \mathbb{I} + (x_2 \gamma_3 + x_3 \gamma_2) A^2] =$$

$$= [x_1 (x_2 x_3 - 7\gamma_2 \gamma_3) - 7\gamma_1 (x_2 \gamma_3 + x_3 \gamma_2)] \mathbb{I} + [x_1 (x_2 \gamma_3 + x_3 \gamma_2) + \gamma_1 (x_2 x_3 - 7\gamma_2 \gamma_3)] A$$

Algebra

10)

$$M \times M \rightarrow M$$

$$M_1 \times M_2 \rightarrow M_1 \cdot M_2 \in M?$$

$$M_1 = x_1 I + y_1 A \quad x_1, y_1 \in \mathbb{Q}$$

$$M_2 = x_2 I + y_2 A \quad x_2, y_2 \in \mathbb{Q}$$

$$M_1 = \begin{pmatrix} x_1 - 3y_1 & 4y_1 \\ -4y_1 & x_1 + 3y_1 \end{pmatrix}$$

$$M_2 = \begin{pmatrix} x_2 - 3y_2 & 4y_2 \\ -4y_2 & x_2 + 3y_2 \end{pmatrix}$$

$$M_1 \cdot M_2 = \begin{pmatrix} (x_1 - 3y_1)(x_2 - 3y_2) - 4y_1 \cdot 4y_2 & (x_1 - 3y_1)(4y_2) + 4y_1(x_2 + 3y_2) \\ (-4y_1)(x_2 - 3y_2) + (x_1 + 3y_1)(-4y_2) & (-4y_1)(4y_2) + (x_1 + 3y_1)(x_2 + 3y_2) \end{pmatrix}$$

$$(M_1 M_2)_{11} = (x_1 - 3y_1)(x_2 - 3y_2) - 4y_1(-4y_2) = x_1 x_2 - 3y_2 x_1 - 3y_1 x_2 + 16y_1 y_2 + 9y_1 y_2 =$$

$$= x_1 x_2 - 3y_2 x_1 - 3y_1 x_2 + 25y_1 y_2$$

$$(M_1 M_2)_{12} = (x_1 - 3y_1)(4y_2) + 4y_1(x_2 + 3y_2) = 4y_2 x_1 - 12y_1 y_2 + 4y_1 x_2 + 12y_1 y_2 = 4y_2 x_1 + 4y_1 x_2$$

$$(M_1 M_2)_{21} = (-4y_1)(x_2 - 3y_2) + (x_1 + 3y_1)(-4y_2) = -4y_1 x_2 + 12y_1 y_2 - 4y_2 x_1 - 12y_1 y_2 = -(4y_1 x_2 + 4y_2 x_1)$$

$$(M_1 M_2)_{22} = -4y_1(4y_2) + (x_1 + 3y_1)(x_2 + 3y_2) = -16y_1 y_2 + x_1 x_2 + 3y_2 x_1 + 3y_1 x_2 + 9y_1 y_2 =$$

$$= x_1 x_2 + 3y_2 x_1 + 3y_1 x_2 - 7y_1 y_2$$

$$= \begin{pmatrix} x_1 x_2 - 3y_2 x_1 - 3y_1 x_2 - 2y_1 y_2 & 4y_2 x_1 + 4y_1 x_2 \\ -(4y_1 x_2 + 4y_2 x_1) & x_1 x_2 + 3y_2 x_1 + 3y_1 x_2 - 7y_1 y_2 \end{pmatrix}$$

$$M_1 M_2 = \begin{pmatrix} x_1 x_2 & 0 \\ 0 & x_1 x_2 \end{pmatrix} + \begin{pmatrix} -3x_1 y_2 - 3y_1 x_2 - 2y_1 y_2 & 4x_1 y_2 + 4x_2 y_1 \\ -4x_1 y_2 - 4x_2 y_1 & 3x_1 y_2 + 3x_2 y_1 + 7y_1 y_2 \end{pmatrix} =$$