

AG35 Series QuecOpen **GNSS API Reference Manual**

Automotive Module Series

Version: 1.0

Date: 2020-09-08

Status: Released



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About the Document

Revision History

Version	Date	Author	Description
1.0	2020-09-08	Raigor ZHAO	Initial

Contents

About the Document	2
Contents	3
Table Index	5
1 Introduction	6
2 GNSS Features Overview	7
2.1. GNSS Features	7
2.2. GNSS Performance	7
3 GNSS APIs	9
3.1. Header File Path	9
3.2. Example Path	9
3.3. API Overview	9
3.4. API Description	10
3.4.1. QL_LOC_Client_Init	10
3.4.2. QL_LOC_Client_Deinit	11
3.4.3. QL_LOC_AddRxIndMsgHandler	11
3.4.3.1. QL_LOC_RxIndMsgHandlerFunc_t	11
3.4.4. QL_LOC_Set_Indications	12
3.4.5. QL_LOC_Set_Position_Mode	13
3.4.5.1. QL_LOC_POS_MODE_INFO_T	13
3.4.6. QL_LOC_Start_Navigation	14
3.4.7. QL_LOC_Stop_Navigation	15
3.4.8. QL_LOC_Get_Current_Location	15
3.4.8.1. QL_LOC_LOCATION_INFO_T	16
3.4.9. QL_LOC_Delete_Aiding_Data	17
3.4.9.1. E_QL_LOC_DELETE_AIDING_DATA_TYPE_T	18
3.4.10. QL_LOC_InjectTime	20
3.4.10.1. QL_LOC_INJECT_TIME_INT0_T	20
3.4.11. QL_LOC_InjectLocation	21
3.4.11.1. QL_LOC_INJECT_LOCATION_INT0_T	21
3.4.12. QL_LOC_Xtra_InjectData	22
3.4.13. QL_LOC_Xtra_InjectFile	22
3.4.14. QL_LOC_Agps_SetServer	23
3.4.14.1. QL_LOC_AGPS_SERVER_INT0_T	23
3.4.15. QL_LOC_Install_supl_cert	24
3.4.16. QL_LOC_unInstall_supl_cert	25
3.4.17. QL_LOC_Set_Auto_Inject_Xtra	25
3.4.18. QL_LOC_Xtra_GetValidity	26
4 Callback Data	27
4.1. Satellite Status Data	27

4.2.	General Satellite Data	28
5	gpsOneXTRA Assistance Technology	29
5.1.	gpsOneXTRA Features	29
5.2.	gpsOneXTRA Data Downloading.....	29
5.3.	gpsOneXTRA Data Injection	29
6	SUPL for AGPS.....	30
6.1.	SUPL Description	30
6.2.	Implementation of SUPL	30
6.3.	Example	30
7	Appendix A References.....	33

Table Index

Table 1: Positioning Performance 7

Table 2: API Overview 9

Table 3: Terms and Abbreviations 33

1 Introduction

Global navigation satellite system (GNSS) is a general term describing any satellite constellation that provides positioning, navigation, and timing (PNT) services on a global or regional basis. GNSS can also refer to augmentation systems.

- Global navigation satellite systems include GPS, GLONASS, BeiDou and Galileo.
- Regional navigation satellite systems include QZSS and NavIC (IRNSS).
- Satellite-based augmentation systems (SBAS) include WAAS, SDCM, EGNOS, MSAS, GAGAN

This document introduces how to realize the GNSS feature of Quectel AG35 series module in QuecOpen® solution, through GNSS APIs in SDK provided by Quectel.

2 GNSS Features Overview

Quectel AG35 series QuecOpen module integrates the IZat Gen8C GNSS engine which supports GPS, BeiDou, GLONASS and Galileo systems. This, coupled with SUPL and gpsOneXTRA Assistance technologies, allows the module to provide quicker, more accurate and more dependable positioning.

This chapter introduces the supported GNSS features and performance of Quectel AG35 series QuecOpen module.

2.1. GNSS Features

- Supports multi-constellation GNSS systems including GPS, GLONASS, BeiDou, Galileo and QZSS.
- Supports SBAS including WAAS, EGNOS, MSAS and GAGAN.
- Supports gpsOneXTRA Assistance technology to deliver more accurate positioning with greater sensitivity.
- Supports AGPS such as SUPL to improve the startup performance such as TTFF.
- Supports precise point positioning and DGPS.
- Supports output positioning information in multiple frequencies, such as 1 Hz, 2 Hz, 5 Hz and 10 Hz.

2.2. GNSS Performance

Table 1: Positioning Performance

Item	Performance	Comment
2D positioning accuracy (50%, 68%, 95%)	< 2 m, < 2.5 m, < 5 m	Standalone mode in open sky
3D positioning accuracy (50%, 68%, 95%)	< 2.5 m, < 3 m, < 6 m	Standalone mode in open sky
Number of channels tracked simultaneously	40	
TTFF @ cold start	29 s	Standalone mode in open sky
TTFF @ warm start	27 s	Standalone mode in open sky

TTFF @ hot start	1 s	Standalone mode in open sky
Reacquisition time after a loss of lock of 30 s	≈ 1 s	In open sky
Reacquisition time after a loss of lock of 5 mins	≈ 2 s	In open sky
Acquisition sensitivity (cold start, 95%)	> -149 dBm	Cold start; 300 s timeout value
Tracking sensitivity	> -163 dBm	Standalone or MSB mode
Velocity accuracy (68%, 95%)	0.15 m/s, 0.3 m/s	Drive in a straight line at 30 m/s
Heading accuracy (68%, 95%)	0.2 deg, 0.5 deg	Drive in a straight line at 30 m/s
Maximum speed	1852 km/h	

NOTE

For details about positioning mode, refer to **Chapter 3.4.5.1**.

3 GNSS APIs

3.1. Header File Path

The header file path: *ql-ol-sdk/ql-ol-extsdk/include/ql_mcm_gps.h*.

3.2. Example Path

The example path: *ql-ol-sdk/ql-ol-extsdk/example/example_gps.c*.

3.3. API Overview

Table 2: API Overview

Function	Description
<i>QL_LOC_Client_Init()</i>	Initializes a GNSS client.
<i>QL_LOC_Client_Deinit()</i>	Deregisters a GNSS client.
<i>QL_LOC_AddRxIndMsgHandler()</i>	Registers a callback function to process GNSS data.
<i>QL_LOC_Set_Indications()</i>	Sets callback data.
<i>QL_LOC_Set_Position_Mode()</i>	Sets position configuration items.
<i>QL_LOC_Start_Navigation()</i>	Starts GNSS.
<i>QL_LOC_Stop_Navigation()</i>	Stops GNSS.
<i>QL_LOC_Get_Current_Location()</i>	Gets current location data.
<i>QL_LOC_Delete_Aiding_Data()</i>	Deletes GNSS aiding data.

<code>QL_LOC_InjectTime()</code>	Injects UTC time to GNSS.
<code>QL_LOC_InjectLocation()</code>	Injects location data to GNSS.
<code>QL_LOC_Xtra_InjectData()</code>	Injects gpsOneXTRA data to GNSS.
<code>QL_LOC_Xtra_InjectFile()</code>	Injects gpsOneXTRA file to GNSS.
<code>QL_LOC_Agps_SetServer()</code>	Sets SUPL server address and port.
<code>QL_LOC_Install_supl_cert()</code>	Installs an SUPL certificate.
<code>QL_LOC_unInstall_supl_cert()</code>	Uninstalls an SUPL certificate.
<code>QL_LOC_Set_Auto_Inject_Xtra()</code>	Sets automatic injection of gpsOneXTRA data.
<code>QL_LOC_Xtra_GetValidity()</code>	Queries the validity of injected gpsOneXTRA data.

NOTES

1. The APIs introduced in this document are not applicable to the module that supports QDR and PPE. For details, please contact Quectel Technical Support (support@quectel.com).
2. Never call any of the above GNSS APIs in any callback function.

3.4. API Description

3.4.1. QL_LOC_Client_Init

This function initializes a GNSS client to create a GNSS session.

● Prototype

```
int QL_LOC_Client_Init(loc_client_handle_type *ph_loc);
```

● Parameter

ph_loc:

[Out] The handle that is returned after the GNSS client is initialized and the GNSS session is created.
This parameter is used in subsequent GNSS APIs.

● Return Value

0 Created a GNSS session successfully.
Others Failed to create a GNSS session.

3.4.2. QL_LOC_Client_Deinit

This function deregisters a GNSS client to release the GNSS session.

- **Prototype**

```
int QL_LOC_Client_Deinit(loc_client_handle_type *ph_loc);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

- **Return Value**

0 Released the GNSS session successfully.

Others Failed to release the GNSS session.

3.4.3. QL_LOC_AddRxIndMsgHandler

This function registers a callback function to process GNSS data.

- **Prototype**

```
int QL_LOC_AddRxIndMsgHandler(QL_LOC_RxIndMsgHandlerFunc_t handlerPtr, void* contextPtr);
```

- **Parameter**

handlerPtr:

[In] The callback function used to process GNSS data.

contextPtr:

[In] The parameters required by the callback function. See **Chapter 3.4.3.1**.

- **Return Value**

0 Registered the callback function successfully.

Others Failed to register the callback function.

3.4.3.1. QL_LOC_RxIndMsgHandlerFunc_t

This callback function processes the GNSS data.

● Prototype

```
typedef void (*QL_LOC_RxIndMsgHandlerFunc_t)
(
    loc_client_handle_type ph_loc,
    E_QL_LOC_NFY_MSG_ID_T e_msg_id,
    void *pv_data,
    void *contextPtr
);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

e_msg_id:

[In] Callback data ID.

pv_data:

[In] Callback data. See **Chapter 4** for the details.

contextPtr:

[In] Customized data.

● Return Value

None.

3.4.4. QL_LOC_Set_Indications

This function sets the callback data.

● Prototype

```
int QL_LOC_Set_Indications(loc_client_handle_type ph_loc, int bit_mask);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

bit_mask:

[In] Bit mask of callback data. It is defined as below:

LOC_IND_LOCATION_INFO_ON	(1 << 0)	//Location data.
LOC_IND_STATUS_INFO_ON	(1 << 1)	//GNSS engine status data.

LOC_IND_SV_INFO_ON	(1 << 2)	//Satellites related data.
LOC_IND_NMEA_INFO_ON	(1 << 3)	//NMEA sentences.
LOC_IND_CAP_INFO_ON	(1 << 4)	//Not supported
LOC_IND_UTC_TIME_REQ_ON	(1 << 5)	//Request of UTC time injection
LOC_IND_XTRA_DATA_REQ_ON	(1 << 6)	//Request of gpsOneXTRA data injection
LOC_IND_AGPS_DATA_CONN_CMD_REQ_ON	(1 << 7)	//Not supported
LOC_IND_NI_NFY_USER_RESP_REQ_ON	(1 << 8)	//Not supported

● Return Value

0 Set callback data successfully.
 Others Failed to set callback data.

3.4.5. QL_LOC_Set_Position_Mode

This function sets positioning configuration items.

● Prototype

```
int QL_LOC_Set_Position_Mode(loc_client_handle_type ph_loc, QL_LOC_POS_MODE_INFO_T *pt_mode);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

pt_mode:

[In] Positioning configuration items. See **Chapter 3.4.5.1**.

● Return Value

0 Set positioning configuration items successfully.
 Others Failed to set positioning configuration items.

3.4.5.1. QL_LOC_POS_MODE_INFO_T

The structure of positioning configuration items is defined as below:

```
typedef struct
{
    E_QL_LOC_POS_MODE_T mode; //Positioning mode. Only standalone and MSB are supported
    E_QL_LOC_POS_RECURRENCE_T recurrence; //Positioning recurrence mode.
    uint32_t min_interval; //Positioning interval. Unit: ms.
    uint32_t preferred_accuracy; //Horizontal positioning accuracy. Unit: meter.
```

```
uint32_t          preferred_time;          //Positioning timeout. Unit: ms.
}QL_LOC_POS_MODE_INFO_T;
```

● Parameter

Type	Parameter	Description
E_QL_LOC_POS_MODE_T	<i>mode</i>	Positioning mode. <i>E_QL_LOC_POS_MODE_STANDALONE</i> : Standalone mode. <i>E_QL_LOC_POS_MODE_MS_BASED</i> : MSB mode (speed up positioning). <i>E_QL_LOC_POS_MODE_MS_ASSISTED</i> : MSA mode (not supported currently).
E_QL_LOC_POS_RECURRENCE_T	<i>recurrence</i>	Positioning recurrence mode. <i>E_QL_LOC_POS_RECURRENCE_PERIODIC</i> : Periodic positioning. <i>E_QL_LOC_POS_RECURRENCE_SINGLE</i> : Single positioning.
uint32_t	<i>min_interval</i>	Positioning interval. Unit: ms. Valid values are 100, 200, 500 and multiplies of 1000.
uint32_t	<i>preferred_accuracy</i>	Horizontal positioning accuracy. Unit: meter.
uint32_t	<i>preferred_time</i>	Positioning timeout. Unit: ms.

3.4.6. QL_LOC_Start_Navigation

This function starts the GNSS.

● Prototype

```
int QL_LOC_Start_Navigation(loc_client_handle_type ph_loc);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

● Return Value

0 Started GNSS successfully.

Others Failed to start GNSS.

3.4.7. QL_LOC_Stop_Navigation

This function stops the GNSS.

- **Prototype**

```
int QL_LOC_Stop_Navigation(loc_client_handle_type ph_loc);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

- **Return Value**

0 Stopped GNSS successfully.

Others Failed to stop GNSS.

3.4.8. QL_LOC_Get_Current_Location

This function gets the current location data.

- **Prototype**

```
int QL_LOC_Get_Current_Location(loc_client_handle_type ph_loc, QL_LOC_LOCATION_INFO_T  
*pt_loc_info, int timeout_sec);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

pt_loc_info:

[Out] Location data. See **Chapter 3.4.8.1**.

timeout_sec:

[In] Positioning timeout. Unit: ms.

- **Return Value**

0 Got location data successfully.

Others Failed to get location data.

3.4.8.1. QL_LOC_LOCATION_INFO_T

The structure of location data is defined as below:

```
typedef struct
{
  uint32_t    size;
  E_QL_LOC_LOCATION_VALID_FLAG flags;
  E_QL_LOC_ULP_LOCATION_SOURCE position_source;
  double      latitude;
  double      longitude;
  double      altitude;
  float       speed;
  float       bearing;
  float       accuracy;
  int64_t     timestamp;
  int32_t     is_indoor;
  float       floor_number;
  uint32_t    raw_data_len;
  uint8_t     raw_data[QL_LOC_GPS_RAW_DATA_LEN_MAX];
  char        map_url[QL_LOC_GPS_LOCATION_MAP_URL_SIZE + 1];
  uint8_t     map_index[QL_LOC_GPS_LOCATION_MAP_IDX_SIZE];
}QL_LOC_LOCATION_INFO_T;
```

● Parameter

Type	Parameter	Description
uint32_t	size	Size of this structure.
E_QL_LOC_LOCATION_VALID_FLAG	flags	<p>Data validity indication.</p> <p>If the mask is 1, it means the data in this structure is valid, and 0 indicates invalid. The value is a combination of the following masks.</p> <p><i>E_QL_LOC_LOCATION_LAT_LONG_VALID</i>: Longitude and latitude.</p> <p><i>E_QL_LOC_LOCATION_ALTITUDE_VALID</i>: Altitude.</p> <p><i>E_QL_LOC_LOCATION_SPEED_VALID</i>: Speed.</p> <p><i>E_QL_LOC_LOCATION_BEARING_VALID</i>: Bearing.</p> <p><i>E_QL_LOC_LOCATION_ACCURACY_VALID</i>: Positioning accuracy.</p> <p><i>E_QL_LOC_LOCATION_SOURCE_INFO_VALID</i>: Not supported.</p> <p><i>E_QL_LOC_LOCATION_IS_INDOOR_VALID</i>: Not supported.</p>

		<i>E_QL_LOC_LOCATION_FLOOR_NUMBE_VALID</i> : Not supported. <i>E_QL_LOC_LOCATION_MAP_URL_VALID</i> : Not supported. <i>E_QL_LOC_LOCATION_MAP_INDEX_VALID</i> : Not supported.
<i>E_QL_LOC_ULP_LOCATION_SOURCE</i>	<i>position_source</i>	Location data source.
double	<i>latitude</i>	Latitude. Range: -90 to 90. Unit: degree.
double	<i>longitude</i>	Longitude. Range: 0–180. Unit: degree.
double	<i>altitude</i>	Altitude. Unit: meter.
float	<i>speed</i>	Speed. Range: 0–540. Unit: m/s.
float	<i>bearing</i>	Bearing. Range: 0–360. Unit: degree.
float	<i>accuracy</i>	Horizontal accuracy. Unit: meter.
int64_t	<i>timestamp</i>	UTC time. Unit: ms.
int32_t	<i>is_indoor</i>	Indoor or not. (Invalid data)
float	<i>floor_number</i>	Floor number. (Invalid data)
int32_t	<i>raw_data_len</i>	Length of raw data. Range: 0–256. (Invalid data)
uint8_t	<i>raw_data</i>	Raw data. (Invalid data)
char	<i>map_url</i>	(Invalid data)
uint8_t	<i>map_index</i>	(Invalid data)

3.4.9. QL_LOC_Delete_Aiding_Data

This function deletes the GNSS aiding data.

● Prototype

```
int QL_LOC_Delete_Aiding_Data( loc_client_handle_type ph_loc, E_QL_LOC_DELETE_AIDING_DATA_TYPE_T flags);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

flags:

[In] Specifies the type of data to be deleted. See **Chapter 3.4.9.1**.

● Return Value

0 Deleted GNSS aiding data successfully.

Others Failed to delete GNSS aiding data.

NOTE

This function takes a certain time to delete the specified data, so wait for at least 2 seconds before calling the next API.

3.4.9.1. E_QL_LOC_DELETE_AIDING_DATA_TYPE_T

The enumeration of GNSS aiding data to be deleted is defined as below:

```
typedef enum
{
    E_QL_LOC_DELETE_EPHEMERIS      = (1 << 0),    /**< Delete ephemeris data. */
    E_QL_LOC_DELETE_ALMANAC        = (1 << 1),    /**< Delete almanac data. */
    E_QL_LOC_DELETE_POSITION       = (1 << 2),    /**< Delete position data. */
    E_QL_LOC_DELETE_TIME           = (1 << 3),    /**< Delete time data. */
    E_QL_LOC_DELETE_IONO           = (1 << 4),    /**< Delete IONO data. */
    E_QL_LOC_DELETE_UTC            = (1 << 5),    /**< Delete UTC data. */
    E_QL_LOC_DELETE_HEALTH         = (1 << 6),    /**< Delete health data. */
    E_QL_LOC_DELETE_SVDIR          = (1 << 7),    /**< Delete SVDIR data. */
    E_QL_LOC_DELETE_SVSTEER        = (1 << 8),    /**< Delete SVSTEER data. */
    E_QL_LOC_DELETE_SADATA         = (1 << 9),    /**< Delete SA data. */
    E_QL_LOC_DELETE_RTI            = (1 << 10),   /**< Delete RTI data. */
    E_QL_LOC_DELETE_CELLDB_INFO    = (1 << 11),   /**< Delete cell DB information. */
    E_QL_LOC_DELETE_ALMANAC_CORR   = (1 << 12),   /**< Delete almanac correction
data. */
    E_QL_LOC_DELETE_FREQ_BIAS_EST  = (1 << 13),   /**< Delete frequency bias estimate.
*/
    E_QL_LOC_DELETE_EPHEMERIS_GLO  = (1 << 14),   /**< Delete ephemeris GLO data.
*/
    E_QL_LOC_DELETE_ALMANAC_GLO    = (1 << 15),   /**< Delete almanac GLO data. */
    E_QL_LOC_DELETE_SVDIR_GLO      = (1 << 16),   /**< Delete SVDIR GLO data. */
    E_QL_LOC_DELETE_SVSTEER_GLO    = (1 << 17),   /**< Delete SVSTEER GLO data.
*/
    E_QL_LOC_DELETE_ALMANAC_CORR_GLO= (1 << 18),   /**< Delete almanac correction
GLO data. */
}
```

```

    E_QL_LOC_DELETE_TIME_GPS      = (1 << 19),    /**< Delete time GPS data. */
    E_QL_LOC_DELETE_TIME_GLO      = (1 << 20),    /**< Delete time GLO data. */
    E_QL_LOC_DELETE_ALL           = 0xFFFFFFFF,    /**< Delete all location data. */
}E_QL_LOC_DELETE_AIDING_DATA_TYPE_T;

```

● Parameter

Parameter	Description
<i>E_QL_LOC_DELETE_EPHEMERIS</i>	Deletes ephemeris data.
<i>E_QL_LOC_DELETE_ALMANAC</i>	Deletes almanac data.
<i>E_QL_LOC_DELETE_POSITION</i>	Deletes location data.
<i>E_QL_LOC_DELETE_TIME</i>	Deletes time information.
<i>E_QL_LOC_DELETE_IONO</i>	Deletes ionospheric data.
<i>E_QL_LOC_DELETE_UTC</i>	Deletes UTC data.
<i>E_QL_LOC_DELETE_HEALTH</i>	Deletes satellite health status data.
<i>E_QL_LOC_DELETE_SVDIR</i>	Deletes satellite direction data.
<i>E_QL_LOC_DELETE_SVSTEER</i>	Deletes satellite rotation speed data.
<i>E_QL_LOC_DELETE_SADATA</i>	Deletes satellite data.
<i>E_QL_LOC_DELETE_RTI</i>	Deletes RTI data.
<i>E_QL_LOC_DELETE_CELLDB_INFO</i>	Deletes cell database data.
<i>E_QL_LOC_DELETE_ALMANAC_CORR</i>	Deletes almanac correction data.
<i>E_QL_LOC_DELETE_FREQ_BIAS_EST</i>	Deletes frequency bias estimation.
<i>E_QL_LOC_DELETE_EPHEMERIS_GLO</i>	Deletes GLONASS ephemeris data.
<i>E_QL_LOC_DELETE_ALMANAC_GLO</i>	Deletes GLONASS almanac data.
<i>E_QL_LOC_DELETE_SVDIR_GLO</i>	Deletes GLONASS satellite direction data.
<i>E_QL_LOC_DELETE_SVSTEER_GLO</i>	Deletes GLONASS satellite rotation speed data.
<i>E_QL_LOC_DELETE_ALMANAC_CORR_GLO</i>	Deletes GLONASS almanac correction data.
<i>E_QL_LOC_DELETE_TIME_GPS</i>	Deletes GPS time data.
<i>E_QL_LOC_DELETE_TIME_GLO</i>	Deletes GLONASS time data.

`E_QL_LOC_DELETE_ALL`

Deletes all data.

3.4.10. QL_LOC_InjectTime

This function injects the UTC time to GNSS engine. Injecting UTC time before starting GNSS with `QL_LOC_Start_Navigation()` can speed up positioning.

● Prototype

```
int QL_LOC_InjectTime( loc_client_handle_type ph_loc, QL_LOC_INJECT_TIME INTO_T *pt_info);
```

● Parameter

ph_loc:

[In] The handle returned by `QL_LOC_Client_Init()`.

pt_info:

[In] UTC time data to be injected. See **Chapter 3.4.10.1**.

● Return Value

0 Injected the UTC time successfully.

Others Failed to inject the UTC time.

NOTE

The difference between the injected time and current UTC time should be less than 10 seconds, otherwise the positioning time will be increased.

3.4.10.1. QL_LOC_INJECT_TIME INTO_T

The structure of the injected UTC time is defined as below:

```
typedef struct
{
    int64_t time;           /**< Inject time.*/
    int64_t time_reference; /**< Time reference.*/
    int32_t uncertainty;    /**< Uncertainty.*/
}QL_LOC_INJECT_TIME INTO_T;
```

● Parameter

Type	Parameter	Description
int64_t	<i>time</i>	The current UTC time, that is the number of milliseconds that have elapsed since 00:00:00 UTC on January 1, 1970.
int64_t	<i>time_reference</i>	Invalid parameter. Set it to 0.
int32_t	<i>uncertainty</i>	Time accuracy. Set it to 3500. Unit: ms.

3.4.11. QL_LOC_InjectLocation

This function injects the location data to GNSS engine.

● Prototype

```
int QL_LOC_InjectLocation( loc_client_handle_type ph_loc, QL_LOC_INJECT_LOCATION_INTO_T
*pt_info);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

pt_info:

[In] Location data to be injected. See **Chapter 3.4.11.1**.

● Return Value

0 Injected the location data successfully.

Others Failed to inject the location data.

3.4.11.1. QL_LOC_INJECT_LOCATION_INTO_T

The structure of the location data to be injected is defined as below:

```
typedef struct
{
    double latitude; /**< Latitude.*/
    double longitude; /**< Longitude.*/
    float accuracy; /**< Accuracy.*/
}QL_LOC_INJECT_LOCATION_INTO_T;
```

- **Parameter**

Type	Parameter	Description
double	<i>latitude</i>	Latitude. Unit: degree.
double	<i>longitude</i>	Longitude. Unit: degree.
float	<i>accuracy</i>	Accuracy. Unit: meter.

3.4.12. QL_LOC_Xtra_InjectData

This function injects the gpsOneXTRA assistance data to GNSS engine.

- **Prototype**

```
Int QL_LOC_Xtra_InjectData(loc_client_handle_type ph_loc, char *data, int length);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

data:

[In] gpsOneXTRA data.

length:

[In] Length of gpsOneXTRA data.

- **Return Value**

0 Injected the gpsOneXTRA data successfully.

Others Failed to inject the gpsOneXTRA data.

3.4.13. QL_LOC_Xtra_InjectFile

This function injects the gpsOneXTRA file to GNSS engine.

- **Prototype**

```
int QL_LOC_Xtra_InjectFile( loc_client_handle_type ph_loc, char *filename);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

filename:

[In] gpsOneXTRA file.

- **Return Value**

0 Injected the gpsOneXTRA file successfully.

Others Failed to inject the gpsOneXTRA file.

3.4.14. QL_LOC_Agps_SetServer

This function sets the SUPL server address and port.

- **Prototype**

```
int QL_LOC_Agps_SetServer(loc_client_handle_type ph_loc, QL_LOC_AGPS_SERVER_INTOT * pt_info);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

pt_info:

[In] SUPL server address and port. See **Chapter 3.4.14.1**.

- **Return Value**

0 Set the SUPL server address and port successfully.

Others Failed to set the SUPL server address and port.

3.4.14.1. QL_LOC_AGPS_SERVER_INTOT

The structure of SUPL server address and port is defined as below:

```
typedef struct
{
    E_QL_LOC_AGPS_TYPE_T    e_agps_type;                               /**< AGPS
type.*/
    char                    host_name[QL_LOC_SEVER_ADDR_LENGTH_MAX + 1]; /**< Host
name.*/
```



```
uint32_t      port;                                /**< Port.*/
}QL_LOC_AGPS_SERVER_INT0_T;
```

● Parameter

Type	Parameter	Description
E_QL_LOC_AGPS_TYPE_T	<i>e_agps_type</i>	Protocol type.
char	<i>host_name</i>	Server address.
uint32_t	<i>port</i>	Port.

3.4.15. QL_LOC_Install_supl_cert

This function installs an SUPL certificate.

● Prototype

```
int QL_LOC_Install_supl_cert(loc_client_handle_type ph_loc,
                             uint8_t  suplCertificateId,
                             uint16_t suplCertificateLen,
                             const char* suplCertificatePtr);
```

● Parameter

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

suplCertificateId:

[In] SUPL certificate ID. Customized parameter. Range: 0–9.

suplCertificateLen:

[In] Length of the SUPL certificate. Unit: byte.

suplCertificatePtr:

[In] Certificate content.

● Return Value

0 Installed the SUPL certificate successfully.

Others Failed to install the SUPL certificate.

3.4.16. QL_LOC_unInstall_supl_cert

This function uninstalls an SUPL certificate.

- **Prototype**

```
int QL_LOC_unInstall_supl_cert(loc_client_handle_type ph_loc, mcm_gps_supl_cert_slot_t_v01 s  
suplCertificateId);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

suplCertificateId:

[In] SUPL certificate ID. Range: 0–9.

- **Return Value**

0 Uninstalled the SUPL certificate successfully.

Others Failed to uninstall the SUPL certificate.

3.4.17. QL_LOC_Set_Auto_Inject_Xtra

This function sets automatic injection of gpsOneXTRA data after the previous data is expired.

- **Prototype**

```
int QL_LOC_Set_Auto_Inject_Xtra(loc_client_handle_type ph_loc, unsigned int autoInject);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

autoInject:

[In] Whether to enable automatic injection of gpsOneXTRA data after the previous data is expired.

0 Disable

1 Enable

- **Return Value**

0 Set successfully.

Others Failed to set.

3.4.18. QL_LOC_Xtra_GetValidity

This function queries the validity of the injected gpsOneXTRA data.

- **Prototype**

```
int QL_LOC_Xtra_GetValidity(loc_client_handle_type ph_loc,  
                           uint64_t* startTimeUtc,  
                           uint16_t* durationHour);
```

- **Parameter**

ph_loc:

[In] The handle returned by *QL_LOC_Client_Init()*.

startTimeUtc:

[Out] gpsOneXTRA file start time, that is the number of seconds that have elapsed since 00:00:00 UTC on January 1, 1970.

durationHour:

[Out] Effective duration of a gpsOneXTRA file. Unit: hour.

- **Return Value**

0 Got the validity of the injected gpsOneXTRA data successfully.

Others Failed to get the validity of the injected gpsOneXTRA data.

4 Callback Data

This chapter introduces the callback data of `QL_LOC_RxIndMsgHandlerFunc_t()`.

4.1. Satellite Status Data

The structure of satellite status `QL_LOC_SV_STATUS_T` is defined as below:

```
typedef struct
{
    uint32_t          size;                /**< Set to the size of
    mcm_gps_sv_status_t. */
    int               num_sv;             /**< Number of SVs
    currently visible. */
    QL_LOC_SV_INFO_T  sv_list[QL_LOC_GPS_SUPPORT_SVS_MAX]; /**< Contains an
    array of SV information. */
    uint32_t          ephemeris_mask;     /**< Bitmask indicating
    which SVs have ephemeris data. */
    uint32_t          almanac_mask;       /**< Bitmask indicating
    which SVs have almanac data. */
    uint32_t          used_in_fix_mask;    /**< Bitmask indicating which
    SVs were used for computing the most recent position fix. */
}QL_LOC_SV_STATUS_T;
```

● Parameter

Type	Parameter	Description
uint32_t	<i>size</i>	Size of this structure.
int	<i>num_sv</i>	Number of the visible satellites.
<i>QL_LOC_SV_INFO_T</i>	<i>sv_list</i>	Satellite number. Range: 0–32. See Chapter 4.2 .
uint32_t	<i>ephemeris_mask</i>	Bitmask indicating whether there is valid ephemeris.
uint32_t	<i>almanac_mask</i>	Bitmask indicating whether there is valid almanac.
uint32_t	<i>used_in_fix_mask</i>	Bitmask indicating whether the satellite is used in

positioning.

4.2. General Satellite Data

The structure of general satellite data *QL_LOC_SV_INFO_T* is defined as below:

```
typedef struct
{
    uint32_t    size;           /**< Set to the size of mcm_gps_sv_info_t. */
    int         prn;           /**< Pseudo-random number for the SV. */
    float       snr;           /**< Signal-to-noise ratio. */
    float       elevation;      /**< Elevation of the SV in degrees. */
    float       azimuth;        /**< Azimuth of the SV in degrees. */
}QL_LOC_SV_INFO_T;
```

● Parameter

Type	Parameter	Description
uint32_t	<i>size</i>	Size of this structure.
int	<i>prn</i>	Satellite ID.
float	<i>snr</i>	Signal to noise ratio. Range: 0–99.
float	<i>elevation</i>	Satellite elevation angle. Range: 0–90. Unit: degree.
float	<i>azimuth</i>	Satellite azimuth angle. Range: 0–360. Unit: degree.

5 gpsOneXTRA Assistance Technology

5.1. gpsOneXTRA Features

Quectel AG35 series QuecOpen module applies gpsOneXTRA Assistance technology to speed up GNSS positioning. This technology has the following features.

- Expands capabilities of standalone GNSS.
- Provides assistance data, such as almanac, ephemeris, ionospheric data and satellite data.
- Supports GPS, GLONASS, BeiDou and Galileo navigation systems.
- Injects gpsOneXTRA data to reduce TTFF by 10–18 s, achieving an average TTFF of 18–30 s.

5.2. gpsOneXTRA Data Downloading

The gpsOneXTRA data can be obtained from either of the following addresses:

<http://xtrapath4.izatcloud.net/xtra2.bin>

<http://xtrapath5.izatcloud.net/xtra2.bin>

<http://xtrapath6.izatcloud.net/xtra2.bin>

<http://xtrapath4.izatcloud.net/xtra3grc.bin>

<http://xtrapath5.izatcloud.net/xtra3grc.bin>

<http://xtrapath6.izatcloud.net/xtra3grc.bin>

5.3. gpsOneXTRA Data Injection

Make sure the following conditions are satisfied before injecting the gpsOneXTRA data by calling `QL_LOC_Xtra_InjectData()`.

- 1) GNSS is cold started, or the gpsOneXTRA data has expired.
- 2) Start the GNSS by calling `QL_LOC_Start_Navigation()`.
- 3) Inject the UTC time by calling `QL_LOC_InjectTime()`.

6 SUPL for AGPS

6.1. SUPL Description

AGPS significantly improves the TTFF of a GPS system. Quectel AG35 series QuecOpen module supports AGPS based on SUPL 2.0.

Secure User Plane Location (SUPL) is an Enabler that utilizes existing standards where available and possible, to transfer assistance data and positioning data over a User Plane bearer, such as IP, to aid network and SET based positioning technologies in the calculation of a SET's position.

NOTE

SUPL is available only when it is supported by the third-party service provider.

6.2. Implementation of SUPL

Follow the steps below to implement SUPL:

1. Call `QL_LOC_Agps_SetServer()` to set SUPL server address and port.
2. Call `QL_LOC_Install_supl_cert()` to install SUPL certificate obtained from the third-party service provider.
3. Start GNSS in MSB mode.

After implementing SUPL, the cold start TTFF is about 10 s in open sky.

6.3. Example

```
include <ql_oe.h>
int main(int argc, char *argv[])
{
```

```
int          ret          = E_QL_OK;
int          h_loc        = 0;
int          bitmask      = 0;
QL_LOC_POS_MODE_INFO_T  t_mode      = {0};
QL_LOC_LOCATION_INFO_T  t_loc_info  = {0};

/*Init gnss client*/
ret = QL_LOC_Client_Init(&h_loc);
/*Registe callback*/
ret = QL_LOC_AddRxIndMsgHandler(ql_loc_rx_ind_msg_cb, (void*)h_loc);

/* Set what we want callbacks for */
ret = QL_LOC_Set_Indications(h_loc, 511);

/* Set position mode */
t_mode.mode          = E_QL_LOC_POS_MODE_MS_BASED;
t_mode.recurrence     = E_QL_LOC_POS_RECURRENCE_PERIODIC;
t_mode.min_interval   = 1000; //report nmea frequency 1Hz
t_mode.preferred_accuracy = 50; // <50m
t_mode.preferred_time  = 90; // 90s
ret = QL_LOC_Set_Position_Mode(h_loc, &t_mode);
/*Set Supl server*/
QL_LOC_AGPS_SERVER_INFO_T agps_server;
agps_server.e_agps_type = E_QL_LOC_AGPS_TYPE_SUPL;
strcpy(agps_server.host_name, "supl-test.qxwz.com");
agps_server.port = 7275;
ret = QL_LOC_Agps_SetServer(h_loc, &agps_server);

/*Set Supl server*/
ret = QL_LOC_Install_AgpsCert(h_loc, "123456789", 10);
printf("QL_LOC_Install_AgpsCert ret %d\n", ret);
sleep(2);

ret = QL_LOC_Start_Navigation(h_loc);
printf("QL_LOC_Start_Navigation ret=%d\n", ret);

while(1)
{
    int finish_flag = 0;
    printf("Wait and handle event ! You can input -1 to exit: ");
    scanf("%d", &finish_flag);
    if(finish_flag == -1)
    {
        break;
    }
}
```



```
    }  
}  
ret = QL_LOC_Stop_Navigation(h_loc);  
printf("QL_LOC_Stop_Navigation ret=%d\n", ret);  
  
ret = QL_LOC_Client_Deinit(h_loc);  
printf("QL_LOC_Client_Deinit ret=%d\n", ret);  
  
}
```

7 Appendix A References

Table 3: Terms and Abbreviations

Abbreviation	Description
AGPS	Assisted Global Positioning System
API	Application Programming Interface
DB	Data Base
DGPS	Differential Global Positioning System
EGNOS	European Geostationary Navigation Overlay Service
GAGAN	GPS Aided Geo Augmented Navigation
GLONASS	Global Navigation Satellite System (Russia)
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
IRNSS	Indian Regional Navigation Satellite System
MSA	Mobile Station Assisted
MSAS	Multi-functional Satellite Augmentation System (Japan)
MSB	Mobile Station Based
NavIC	Navigation with Indian Constellation
PPE	Precise Positioning Engine
QDR	Qualcomm Dead Reckoning
QZSS	Quasi-Zenith Satellite System
RTI	Real Time Integration
SA	Satellite
SBAS	Satellite-Based Augmentation System

SDCM	System of Differential Correction and Monitoring
SDK	Software Development Kit
SET	SUPL Enabled Terminal
SUPL	Secure User Plane Location
TTFF	Time To First Fix
UTC	Coordinated Universal Time
WAAS	Wide Area Augmentation System
