view_frames Result Recorded at time: 1611110962.169 fiducial_100 world Broadcaster: /robot_state_publisher Broadcaster: /marker_tf Average rate: 10000.000 Hz Average rate: 10.199 Hz Most recent transform: 0.000 (1611110962.169 sec old) Most recent transform: 1611110962.173 (-0.004 sec old) Buffer length: 0.000 sec Buffer length: 4.804 sec link_base marker Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1611110962.145 (0.024 sec old) Buffer length: 4.900 sec link1 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1611110962.145 (0.024 sec old) Buffer length: 4.900 sec link2 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1611110962.145 (0.024 sec old) Buffer length: 4.900 sec link3 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1611110962.145 (0.024 sec old) Buffer length: 4.900 sec link4 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1611110962.145 (0.024 sec old) Buffer length: 4.900 sec link5 Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1611110962.145 (0.024 sec old) Buffer length: 4.900 sec link6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1611110962.169 sec old) Buffer length: 0.000 sec link_eef Broadcaster: /realsense_tf Average rate: 10.195 Hz Most recent transform: 1611110962.261 (-0.092 sec old) Buffer length: 4.904 sec camera_link Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1611110962.169 sec old) Most recent transform: 0.000 (1611110962.169 sec old) Most recent transform: 0.000 (1611110962.169 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec $camera_aligned_depth_to_color_frame$ camera_depth_frame camera_color_frame Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1611110962.169 sec old) Most recent transform: 0.000 (1611110962.169 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_depth_optical_frame camera_color_optical_frame