Introduction to Statistics - Young Researchers Fellowship Program

Lecture 3 - Introduction to probability

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Why probability?

Why probability?

- Probability is a foundational concept in inferential statistics.
- It is related to the idea that because it is hard to access the entire population, we can use a sample to make inferences about the population.
- We then take a sample, which is thought to be representative of the population, and use it to make inferences about the population.

Why probability?

- However, even if we ensure the sample is similar to the population based on theoretical knowledge, we would never expect that it is exactly the same.
 - There will always be some difference, potentially due to random variation, which make the sample different from the population.
- Probability is the mathematical tool that allows us to quantify the uncertainty associated with the sample.
 - How far are we from the population?
 - If there are significant differences, are we looking for an unrepresentative sample?
 - Is a sample mean fundamentally different from the population mean?
- All the questions above can be answered using the concepts of probability.

Basic probability concepts

- A measure of the likelihood through which an event will occur.
- For example: when seeing gray clouds, we might think that it will rain. The probability of rain is higher when we see gray clouds.
 - However, it is not certain that it will rain. It might rain, or it might not (it is uncertain).

- There are two main approaches to calculate probability:
 - Frequentist approach
 - Bayesian approach
- The frequentist approach is based on the idea that probability is the long-run frequency of an event.
 - For example, the probability of getting a head when flipping a coin is 0.5 because in the long run, half of the flips will be heads.
- This means that frequentist probability will calculate a probability based on past data

$$Probability = \frac{Number of times an event occurred}{Total number of trials}$$

- Another major approach to probability is the Bayesian approach (pronounced "bay-zee-an").
- The Bayesian approach is based on the idea that probability is a a measure of the degree of belief that an event will occur.
 - Hence, it is like a measure of how "good" our information is.
- We won't focus Bayesian approaches on this module, but it is good to know that it exists, and researchers have devoted a lot of time to it.
 - Typically, we will want to understand frequentist approaches first and gain mathematical intuition before we move to Bayesian approaches.

- Two major rules govern probability:
- **1** All probabilities are between 0 and 1.
 - A probability of 0 means that the event will never happen (0% chance).
 - A probability of 1 means that the event will always happen (100%) chance).
 - This means probabilities are always in proportion form, but can be easily converted to percentages.
- The sum of the probabilities for all possible outcomes of an event must sum to 1.
 - In an exam, you'd have two outcomes: pass or fail (assuming no other "weird" outcomes).
 - The probability of passing plus the probability of failing must sum to 1.
 - This means 100% of outcomes are covered in the "possible outcomes" set, each with a probability.

- Two typical examples often emerge when discussing probability:
 - Flipping a "fair" coin
 - Rolling a "fair" die
- A fair coin is a coin that has an equal probability of landing on heads or tails.
- So, because there is 1 head and 1 tail, the probability of getting a head is 1/2, and the probability of getting a tail is 1/2.

$$(P(H)) = \frac{Number of heads}{Total number of outcomes} = \frac{1}{2}$$

$$(P(T)) = \frac{Number of tails}{Total number of outcomes} = \frac{1}{2}$$

Probability: the world of board games

- The other common example is rolling a die.
- A die has 6 faces, each with a number from 1 to 6.
- The probability of getting a 1 is 1/6, the probability of getting a 2 is 1/6, and so on.

Probability: the world of board games

- It is common to also see drawing a card from a deck of cards as an example of probability.
- Decks of cards have 52 cards, with 4 suits (hearts, diamonds, clubs, and spades) and 13 cards in each suit.
- Special cards include the King, Queen, the Jack, and the Ace.
 - There are 4 of each of these cards in the deck.
 - The probability of drawing a King is 4/52, the probability of drawing a Queen is 4/52, and so on.

- There is specific terminology and definitions in probability that must be understood before we move forward.
- An experiment is a process that generates well-defined outcomes, and we're interested in probabilities associated with these outcomes.
 - For example, flipping a coin, rolling a die, or drawing a card from a deck.
- An **event** is a subset of the outcomes of an experiment.
 - For example, in flipping a coin, the event of getting a head is a subset of the outcomes of the experiment.

The lingo: experiments, events, outcomes and sample spaces

- In simple experiments, we often see "events" covering one outcome, and not more.
 - However, events can "group" outcomes in a specific way.
 - E.g. the event of getting an even number when rolling a die. This event covers outcomes 2, 4, and 6.
- The **sample space** is the set of all possible outcomes of an experiment.
 - For example, when flipping a coin, the sample space is $\{H, T\}$.
 - When rolling a die, the sample space is $\{1, 2, 3, 4, 5, 6\}$.

- Probability is closely related to set theory.
 - Sets are collections of objects, and in probability, we often think of events as sets of outcomes.
- Thus, it is common to see notation from set theory in probability.
 - \blacksquare A set is denoted by curly braces, e.g. $\{1, 2, 3, 4, 5, 6\}$.
 - We use letters to denote sets, e.g. A, B, C, etc.
 - We use set operations to calculate probabilities.
 - We use Venn diagrams to visualize probabilities.
- Set theory operators, such as belongs to (\in) , union (\cup) , intersection (\cap) , and complement (') are used in probability.
 - These often also come in terms of logical operators, such as "and" and "or".

Basic operations in probability

- There are three basic operations in probability:
 - Union
 - Intersection
 - Complement

- The union of two events A and B is the event that either A or B or both occur.
 - Meaning that any two of them can occur, but not necessarily both.
 - The union of A and B is denoted by $A \cup B$ (set theory notation).
 - The probability of the union of A and B is denoted by $P(A \cup B)$.
- Example: what is the probability of getting one or two when rolling a die?
 - Notice the use of "or" in the question. Union is often associated with the "OR" logical operator.
 - This can be written as $P(A \cup B)$, where A is the event of getting a 1 and B is the event of getting a 2.

Venn Diagrams

- A Venn diagram is a visual representation of sets and their relationships.
- In probability, we often use Venn diagrams to visualize the union of two events.
- The union of two events is the shaded area in the Venn diagram that covers both events.

Union in a Venn diagram

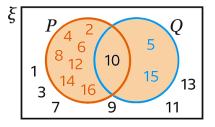


Figure 1: Union in a Venn diagram. Source: BBC Bitesize

 $P \cup Q = \{2, 4, 6, 8, 12, 14, 16, 10, 5, 15\}$

- The intersection of two events A and B is the event that *both* A and B occur.
 - Meaning that both events must occur.
 - The intersection of A and B is denoted by $A \cap B$ (set theory notation).
 - The probability of the intersection of A and B is denoted by $P(A \cap B)$.
- Example: what is the probability of getting an even number and a number less than 4 when rolling a die?
 - Intersection is often associated with the "AND" logical operator.

Intersection in a Venn diagram

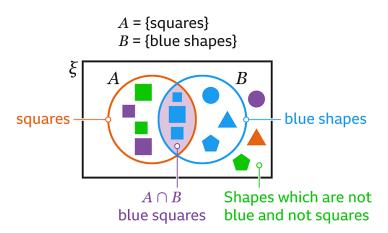


Figure 2: Intersection in a Venn diagram. Source: BBC Bitesize

- The complement of an event A is the event that A does *not* occur.
 - Meaning that the event does not happen.
 - The complement of A is denoted by A' (set theory notation).
 - The probability of the complement of A is denoted by P(A').
- Example: what is the probability of not getting a 1 when rolling a die?
 - The complement of getting a 1 is not getting a 1.
 - The complement of an event is often associated with the "NOT" logical operator.
- It is often very easy to calculate the complement of an event, as it is the whole minus the probability of the event.

$$P(A') = 1 - P(A)$$

Complement in a Venn diagram

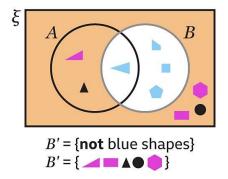


Figure 3: Complement in a Venn diagram. Source: BBC Bitesize

Computing the probability of union: mutually exclusive events and the addition rule

- To actually calculate a probability associated with the union of two events, we need to know a little bit more about the nature of the events.
- For instance, in the die example, the events of getting a 1 and getting a 2 are **mutually exclusive**
 - This means that the events cannot happen at the same time.
 - The probability of the union of mutually exclusive events is the sum of the probabilities of the events.

Union under mutually exclusive events

$$P(A \cup B) = P(A) + P(B)$$

where A and B are mutually exclusive events.

Computing the probability of union: non-mutually exclusive events and the addition rule

- However, if the events are not mutually exclusive, we need to consider the probability of the intersection of the events.
- Events that might not be mutually exclusive happen very often. For instance, what is the probability of going to the beach and getting a sunburn?
 - These events are not mutually exclusive, as you can go to the beach and get a sunburn at the same time.

Union under non-mutually exclusive events

- If we apply the "formula" above, we will overcount the probability of the intersection of the events.
- Example: the probability of finding a company that is both in Pichincha, and is listed as active.
 - If we know the probability of finding companies in Pichincha, it will include those listed as active and otherwise.
 - If we know the probability of finding companies listed as active, it will include those in Pichincha and otherwise.
- Summing these two without doing anything else will overcount the probability of finding a company that is both in Pichincha and is listed as active.
 - Solution: subtract the probability of the intersection of the events.

Union under non-mutually exclusive events: the addition rule

■ The probability of the union of two events is given by the addition rule:

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

- This is a broad formula that can be applied to any two events, whether they are mutually exclusive or not.
 - The intersection of two mutually exclusive events is 0, so the formula simplifies to the one we saw before.

- There is no direct way to calculate the probability of the intersection of two events unless we know more
- Some cases emerge:
 - If we know the union of two events and their associated probabilities, we can calculate the probability of the intersection by rearranging the addition rule
 - If we know the events are mutually exclusive, the probability of the intersection is 0
 - If we know events are *independent*, there is a direct way to calculate the probability of the intersection.

- Two events are independent if the occurrence of one event does not affect the occurrence of the other event.
- For example, the probability of getting a head when flipping a coin is independent of the probability of getting a 1 when rolling a die.
 - Basically means the events are not related.
- If two events are independent, the probability of the intersection of the events is the product of the probabilities of the events.
 - This is called the multiplication rule.

Independence: the multiplication rule

■ If two events are independent, the probability of the intersection of the events is given by the multiplication rule:

$$P(A \cap B) = P(A) \times P(B)$$

when A and B are independent events.

Conditional probability

- Conditional probability is the probability of an event given that another event has occurred.
- We are interested in this because once an event has occurred, the probability of another event might change.
 - This is somewhat of a Bayesian idea: once we obtain new information, our beliefs might change.

Conditional probability

- For instance, we are interested in knowing the probability of finding an active company, *given* that the company is in Pichincha.
 - This is different from the probability of finding an active company in general.
- This is a conditional probability: the condition is that the company is in Pichincha.
 - lacktriangle This is denoted by P(A|B), where A is the event of finding an active company and B is the event of finding a company in Pichincha.

Conditional probability formula

- The conditional probability of event A given event B is denoted by P(A|B).
- The formula for conditional probability is:

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

- Following our above example:
 - A is the event of finding an active company.
 - B is the event of finding a company in Pichincha.
- We find active companies in Pichincha (the intersection of the events) and divide by the probability of finding a company in Pichincha.
- Conditionality is the theoretical probability concept of "subsetting" a sample space based on the occurrence of another event.
 - So, we are theorizing our use of filter() in R.

Conditional probability: independence

- Conditional probability is a key concept for independence: if two events are truly independent, the conditional probability of one event given the other is the same as the probability of the event (without the condition).
 - This is since conditioning on the other event does not change the probability of the event.
- Example: if we know that a die roll gives an even number, what is the probability of getting a 2 in a second roll?
 - Two die rolls are independent events (from our logical understanding of the experiment)
 - So, the probability of getting a 2 in the second roll is the same as the probability of getting a 2 any time we roll a die.

Conditional probability: independence

■ The general rule is that for any two independent events A and B:

$$P(A|B) = P(A)$$

$$P(B|A) = P(B)$$

The multiplication rule for independent events

- If two events are independent, the probability of the intersection of the events is the product of the probabilities of the events.
 - This is the multiplication rule for independent events.
 - It will only apply if the events are independent!

$$P(A \cap B) = P(A) \times P(B)$$

The multiplication rule for independent events

■ For instance, if we know the probability of getting a head when flipping a coin is 0.5, and the probability of getting a 1 when rolling a die is 1/6, we can calculate the probability of getting a head and a 1.

$$P(\mathsf{Head} \cap 1) = P(\mathsf{Head}) \times P(1) = 0.5 \times \frac{1}{6} = \frac{1}{12}$$

- This is a very powerful rule that can be used to calculate the probability of the intersection of independent events.
- Notice that I don't use my companies' example here, as the events are likely not independent.
 - Active companies may tend to be in Pichincha as it is the capital
 - This underscores the need to actually understand the nature of the events, or the data generating process.

Random variables and probability distributions

Probability distributions

- Probability distributions are a way to describe the likelihood of different outcomes in an experiment.
- This means that we can use our laws of probability to construct more sophisticated models.
 - These models will describe the likelihood of different outcomes.

- In statistical inference, we will move away from simple experiments like flipping coins and rolling dice.
- Our experiments will be related to the process of sampling.
 - Sampling complies with laws of probability, as every event (one specific sample) is a subset of the sample space (the population), and such sample will look like the population, but subject to random variation.
- Probability distributions will help us understand the likelihood of different outcomes in our samples, by constructing a model of the process of sampling (i.e. the probability distribution).
 - These probability distributions are based on guesses about how the population behaves.
 - If our guess is good, the sample will behave according to the probability distribution. Otherwise, it won't and we will have to revise our guess (another probability distribution).

Random variables

- Random variables (RVs) numerically describe the outcomes of an experiment.
 - Because they are random, the numerical value of the random variable is uncertain, hence the name.
- Two major types of random variables:
 - Discrete random variables (e.g. the number of heads when flipping a coin)
 - Continuous random variables (e.g. the height of a person)
- lacksquare Random variables are denoted by capital letters, e.g. X, Y, Z.

Probability distributions of RVs

- The fact that these are random does not mean that we cannot describe them or predict their behavior.
- RVs will have a probability distribution, since numerical outcomes that they might take have associated probabilities.
- The probability distribution of a random variable is a *function* that describes the likelihood of different outcomes.
 - This function will assign a probability to each possible outcome of the random variable.

Discrete random variables

- Discrete random variables are random variables that can take on a finite number of values.
 - It is finite because we can count the number of values the random variable can take (even if it is a large number).
- For example, the number of heads when flipping a coin is a discrete random variable.
 - It can take on values 0 or 1.

The PDF of RVs (love the jargon or perish!)

- A probability density function (PDF) is a function that describes the likelihood of different outcomes of a random variable.
- \blacksquare Denoted by f(x), where x is the value of the random variable, and the output of the function f is the probability of the random variable taking on that value.
- For discrete random variables, the PDF is often called the probability mass function (PMF), but the idea is the same.
- We won't always have a function that takes an equation form.
 - Discrete RVs will often have a table of probabilities which is called the PDF (f)
 - Continuous RVs will often have a function that describes the likelihood of different outcomes.

Building the PDF of a discrete RV: the example of a fair coin

The fair coin example (getting a head) has a simple enough PDF. See below:

Value of the random variable	Probability
0	0.5
1	0.5

- Notice that the value of the random variable \$X# is the number of heads when flipping a coin.
- The probability of getting a head is 0.5, and the probability of getting a tail is 0.5.
 - Getting 0 heads in this experiment is the same as getting a tail.

Building the PDF of a discrete RV: the example of a fair die

The fair die example (rolling a die) has a more complex PDF. See below:

Value of the random variable	Probability
1	1/6
2	1/6
3	1/6
4	1/6
5	1/6
6	1/6

- In this case, the value of the random variable *X* is the number that comes up when rolling a die.
- The probability of getting a 1 is 1/6, the probability of getting a 2 is

The Cumulative Distribution Function (CDF)

- The cumulative distribution function (CDF) is a function that describes the probability that a random variable is **less than or equal** to a certain value.
- Denoted by F(x), where x is the value of the random variable, and the output of the function F is the probability that the random variable is less than or equal to x.
- The CDF is a very useful function that can be used to calculate probabilities of ranges of values of the random variable.

- The CDF of a discrete random variable is built by summing the probabilities of the random variable being less than or equal to a certain value.
- For the coin example, the CDF is as follows:

Value of the random variable	Probability	Cumulative Probability
0	0.5	0.5
1	0.5	1.0

- The probability of getting 0 heads or less is simply 0.5.
 - This is the probability of getting a tail.
- Notice how the probability of getting one head OR less is 1.
 - This is a union of the events of getting 0 heads and getting 1 head.
 - P(X < 1) = P(X = 0) + P(X = 1) = 0.5 + 0.5 = 1.0

Expected value of a discrete RV

- The expected value of a random variable is something like the "average" value of the random variable.
- To obtain averages for RVs which are discrete, we multiply each possible value of the random variable by its probability, and sum these products.

$$E(X) = \sum_{i} x_i \cdot P(X = x_i)$$

■ For the coin example, the expected value is:

$$E(X) = 0 \cdot 0.5 + 1 \cdot 0.5 = 0.5$$

- This means that the expected value of the number of heads when flipping a coin is 0.5.
- Does this make sense? It will often happen that the expected value is not a possible value of the random variable.
 - This is because the expected value is a measure of central tendency, and not necessarily a possible value of the random variable.
- In an intuitive sense, the expected value is the value we would expect to get if we repeated the experiment many, many times, and took the average of the outcomes.

Variance of a discrete RV

- The variance of a random variable is a measure of how spread out the values of the random variable are.
- To calculate the variance of a discrete random variable, we calculate the expected value of the squared difference between the random variable and its expected value.

$$\operatorname{Var}(X) = E((X - E(X))^2) = \sum_i (x_i - E(X))^2 \cdot P(X = x_i)$$

Example: variance of a coin

■ For the coin example, the variance is:

$$\mathrm{Var}(X) = (0-0.5)^2 \cdot 0.5 + (1-0.5)^2 \cdot 0.5 = 0.25$$

- This means that the variance of the number of heads when flipping a coin is 0.25.
- Once again, higher variance means that the values of the random variable are more spread out.

Laws of expected value and variance

- When working with expected values and variances, there are some laws that can be useful as shorthands.
- For any constants a and b:

$$E(aX + b) = aE(X) + b$$

$$\mathsf{Var}(aX+b)=a^2\mathsf{Var}(X)$$

- There is a specific detail about the PDF of continuous random variables: the probability of the random variable taking on a specific value is 0.
- This is because continuous random variables can take on an infinite number of values, and the probability of any one value is 0.
 - Why infinite? Because we can always find a value between two values (i.e. with a lot of decimals).
- Intuitively, think that whenever we have a continuous random variable, it is extremely unlikely that we will get a specific value.
 - Measurements are never perfect. We can never measure a person's height to the exact millimeter, hence, we can't even know the exact value of the random variable.

The PDF of continuous RVs

- The PDF of a continuous random variable is a function that describes the likelihood of different outcomes of the random variable.
- This PDF is often a complicated equation in function form.
- We don't really work with PDFs, rather, we work with the CDF of the random variable.

- The CDF of a continuous random variable is a function that describes the probability that the random variable is less than or equal to a certain value.
- \blacksquare In this context, this can be understood as a function F(x) that always gives you the area under the curve of the PDF up to a certain value x.
- Hence, the CDF is an integral of the PDF.

$$F(x) = \int_{-\infty}^{x} f(t)dt$$

where f(t) is the PDF of the random variable.

Expected value of a continuous RV

- The expected value of a continuous random variable is calculated in the same way as for discrete random variables.
- We multiply each possible value of the random variable by its probability, and sum these products. However, this time, we use an integral instead of a sum.

$$E(X) = \int_{-\infty}^{\infty} x \cdot f(x) dx$$

■ Don't worry about these! We need not calculate these by hand. In an applied context, we just need to know what PDFs and CDFs are.

Variance of a continuous RV

- The variance of a continuous random variable is calculated in the same way as for discrete random variables.
- We calculate the expected value of the squared difference between the random variable and its expected value. However, this time, we use an integral instead of a sum.

$$\operatorname{Var}(X) = \int_{-\infty}^{\infty} (x - E(X))^2 \cdot f(x) dx$$

The normal distribution

- There are several continuous probability distributions, but the most common is the normal distribution
 - Also know as the Gaussian distribution or the bell curve.
- Why is the normal distribution the most common?
 - Flexibility and simplicity:
 - The normal distribution is easy to handle and does not require complex mathematical tools.
 - 2 Common in real-world data:
 - Many variables are approximately normally distributed, making it practical for various applications.

The normal distribution

- Key properties of the normal distribution:
 - Symmetric and bell-shaped.
 - Completely determined by two parameters:
 - Mean (μ) : Determines the center of the distribution.
 - Standard deviation (σ) : Determines the spread or width of the distribution.
 - The mean and standard deviation define the shape of the distribution.

The PDF of the normal distribution

■ The PDF of the normal distribution is given by the formula:

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}}e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

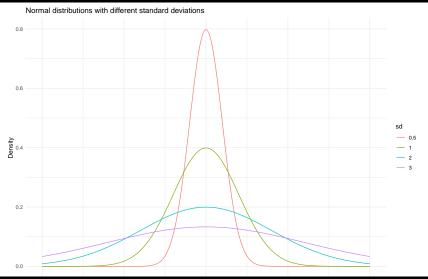
which will not give you an actual number, but a probability density.

- The equation uses the **mean** (μ) and **standard deviation** (σ) to determine the likelihood of different outcomes.
- Although the formula looks complex, it has been extensively studied and is widely available in software tools.
 - No need to calculate it by hand or memorize it!

How μ and σ affect the normal distribution

- lacktriangle Different values of σ affect how flat or peaked the distribution is.
 - \blacksquare A small σ means the distribution is tall and thin.
 - lacktriangle A large σ means the distribution is short and wide.
- \blacksquare Larger values of σ mean that the distribution is more spread out.
 - Less data will be close to the mean, and more data will be far from the mean.

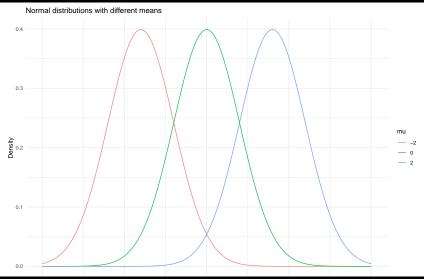
Different normal distributions under varying σ



How μ and σ affect the normal distribution

- Values of affect the center of the distribution.
 - lacksquare A larger μ means the distribution is shifted to the right.
 - lacktriangle A smaller μ means the distribution is shifted to the left.
- This doesn't really affect the shape of the distribution, but rather where the center of the distribution is.

Different normal distributions under varying μ



Properties of the normal distribution

- 1 The normal distribution is symmetric around the mean.
 - This means that the probability of a value being above the mean is the same as the probability of a value being below the mean.
 - This makes the mean the "center" of the distribution, as it is also the median and mode.
- 2 The mean can take any value, no restrictions on it being negative
- 3 The standard deviation must be positive, as a measure of spread and the root of the variance.
- The area under the curve of the normal distribution is 1.
 - This means that we're looking at the CDF between $-\infty$ and ∞ , so it should sum to 1 (100% of all outcomes).

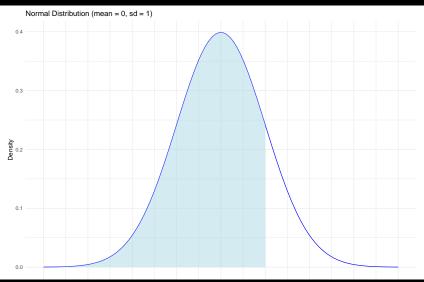
The CDF of the normal distribution

■ The CDF of the normal distribution is given by the formula:

$$F(x) = \int_{-\infty}^{x} f(t)dt$$

- We never need to do this by hand! We can use software tools to calculate the CDF of the normal distribution.
- However, it must be clear that CDFs are often defined as the area under the curve up to a certain value of the random variable.
 - They answer the question "what is the probability that the random variable is less than or equal to a certain value?"

The CDF of the normal distribution



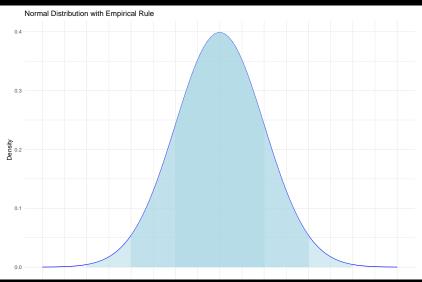
The CDF of the normal distribution: the empirical rule

- The empirical or the 68-95-99.7 rule is a rule of thumb that describes the proportion of values that fall within a certain number of standard deviations from the mean in a normal distribution.
- It is a direct consequence of the properties of the normal distribution, and the use of the CDF for probabilities which are easier to calculate.

The empirical rule

- The empirical rule states that for a normal distribution:
 - Approximately 68% of the data falls within one standard deviation of the mean.
 - Approximately 95% of the data falls within two standard deviations of the mean.
 - Approximately 99.7% of the data falls within three standard deviations of the mean.

The empirical rule



- The **standard normal distribution** is a normal distribution with $\mu = 0$ and $\sigma = 1$.
 - This is a very common distribution in statistics.
- The PDF of the standard normal distribution is given by the formula:

$$f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2}$$

- This is the normal distribution with $\mu = 0$ and $\sigma = 1$.
- \blacksquare The standard normal distribution is often denoted by Z.

distribution.

All normal distributions can be standardized to the standard normal

■ We do this with our beloved z-scores.

$$z = \frac{x - \mu}{\sigma}$$

- This z-score tells us how many standard deviations a value is from the mean.
- So, if a distribution is normal and we transform it to a standard normal distribution, we can use the standard normal distribution to calculate probabilities.

- R has built-in functions to work with the normal distribution.
- The dnorm() function calculates the PDF of the normal distribution.
 - It takes the value of the random variable, the mean, and the standard deviation as arguments.
 - The use of d in the function name is a convention in R to denote the density function.
- We would use dnorm() to calculate the likelihood of different outcomes of the random variable.
 - Also to plot the PDF of the normal distribution.

Using R with the normal distribution

- The pnorm() function calculates the CDF of the normal distribution.
 - It takes the value of the random variable, the mean, and the standard deviation as arguments.
 - The use of p in the function name is a convention in R to denote the cumulative distribution function.
- This is the most useful function with exercises!

Using R with the normal distribution: exercises with pnorm()

- Exercise 1: Calculate the probability of a standard normal random variable being less than 1.96.
- Exercise 2: Calculate the probability of a standard normal random variable being greater than -1.64.
- Exercise 3: Calculate the probability of a standard normal random variable being between -1.96 and 1.96.

- The qnorm() function calculates the quantiles of the normal distribution.
 - It takes the probability, the mean, and the standard deviation as arguments.
 - The use of q in the function name is a convention in R to denote the quantile function.
- This is useful when we want to find the value of the random variable that corresponds to a certain probability.
- This is otherwise known as the inverse CDF

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- Consider the following for a std. normal RV:
- Exercise 1: Find the value of a standard normal random variable that corresponds to the 95th percentile.
- Exercise 2: Find the value of a standard normal random variable that corresponds to the 10th percentile.
- Exercise 3: What RV value corresponds to a cumulative probability of 0.5?

- Because we always end up calculating probabilities with the standard normal distribution, we have a table of probabilities for the standard normal distribution which is often used.
- The table gives the probability that a standard normal random variable is less than a certain value.
- Basically, instead of calculating a CDF with pnorm(), we can look up the value in the table.
 - Need to do "inverse lookups" with the table.