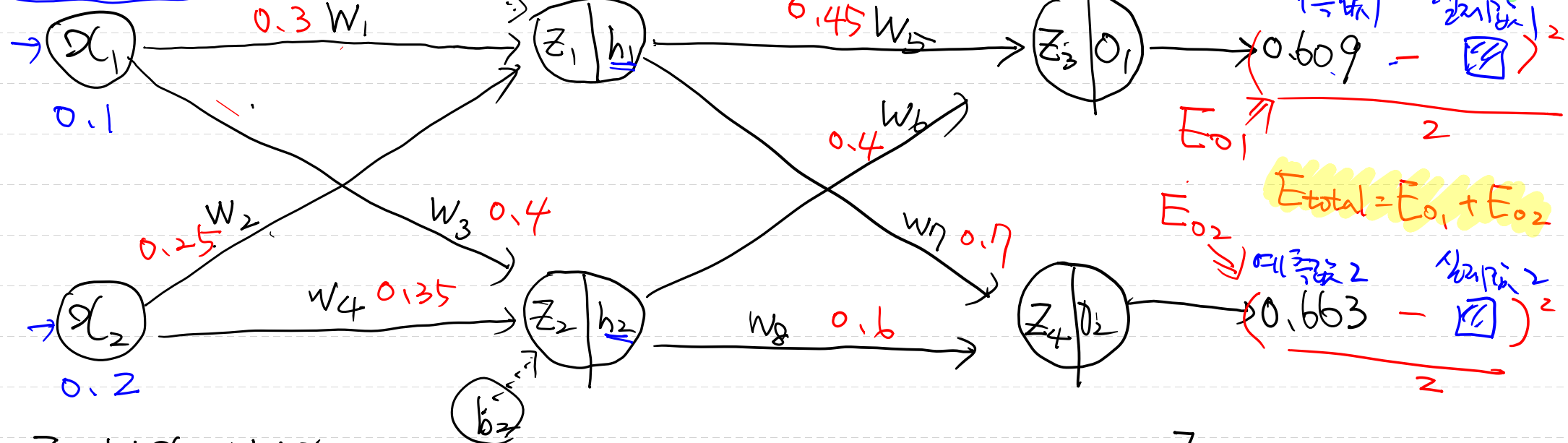


~~| x_1 | x_2 | y_1 | y_2 |
|-------|-------|-------|-------|
| 0 | 0 | 0 | 0 |
| 1 | 1 | 1 | 1 |~~

4. $\frac{1}{2} \sum (z_i - a_i)^2$

Cost 함수 = MSE 사용



$$\begin{cases} z_1 = W_1 x_1 + W_2 x_2 = 0.3 \times 0.1 + 0.25 \times 0.2 = 0.08 \\ z_2 = W_3 x_1 + W_4 x_2 = 0.4 \times 0.1 + 0.35 \times 0.2 = 0.11 \end{cases}$$

$$\begin{cases} z_3 = 0.444 \\ z_4 = 0.680 \end{cases}$$

$$\begin{cases} h_1 = \text{sigmoid}(z_1) = \frac{1}{1 + e^{-0.08}} = 0.519 \\ h_2 = \text{sigmoid}(z_2) = \frac{1}{1 + e^{-0.11}} = 0.527 \end{cases}$$

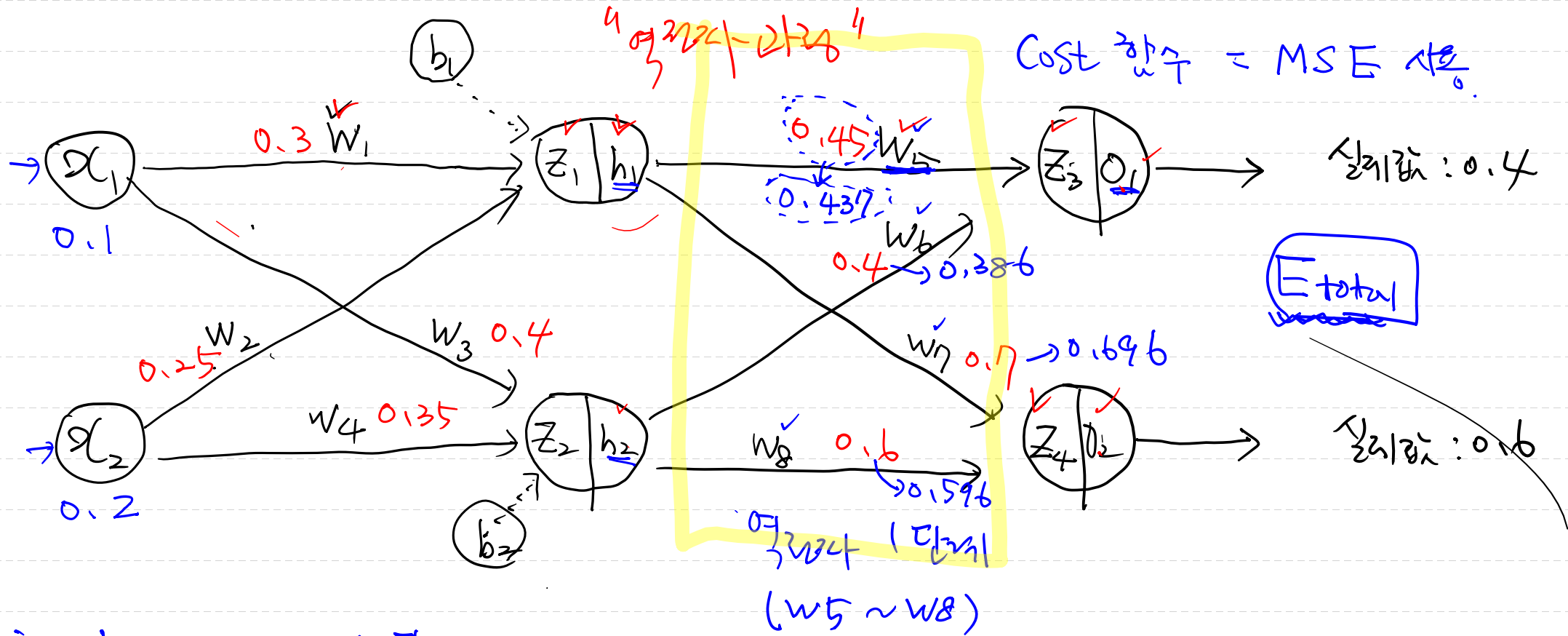
$$\begin{cases} o_1 = \text{sigmoid}(z_3) = 0.609 \\ o_2 = \text{sigmoid}(z_4) = 0.663 \end{cases}$$

$$E_{01} = \frac{1}{2} (\text{예측값}_1 - \text{실제값}_1)^2 = 0.021$$

$$E_{02} = \frac{1}{2} (\text{예측값}_2 - \text{실제값}_2)^2 = 0.002$$

$$\therefore E_{\text{total}} = 0.023$$

$$E_{\text{total}} = E_{01} + E_{02}$$

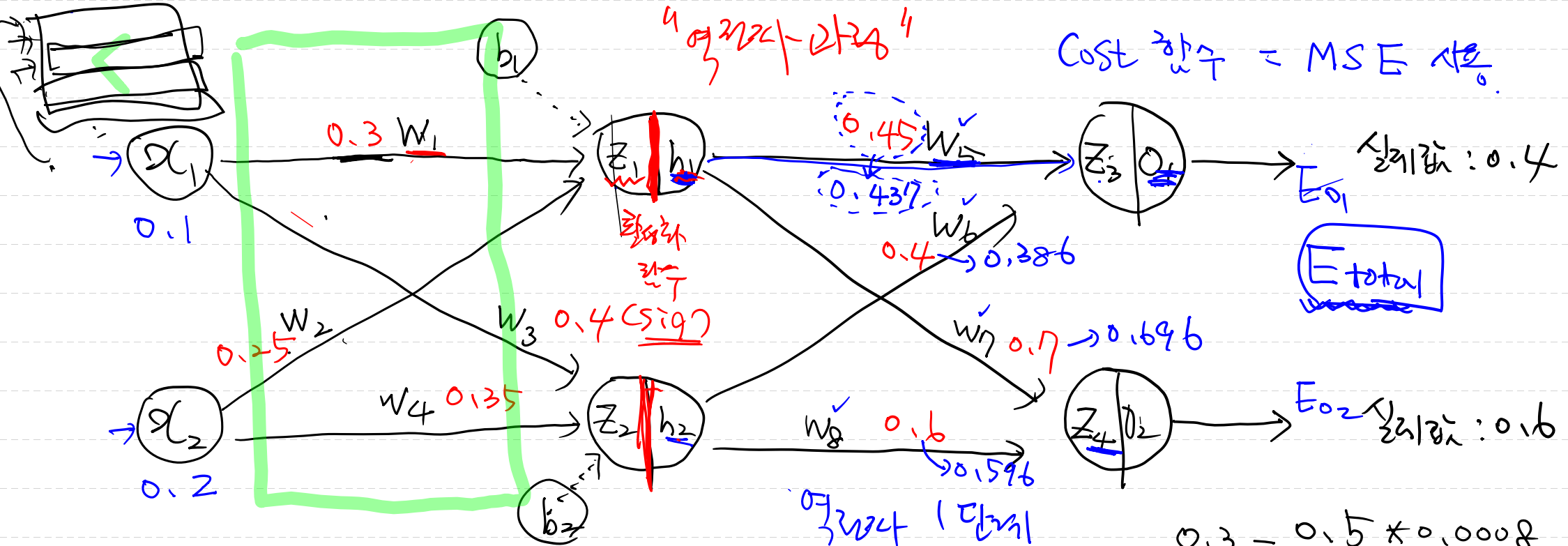


* w_5 업데이트 (경사하강법, 학습률 0.5)

$$\Rightarrow \frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial O_1} * \frac{\partial O_1}{\partial z_3} * \frac{\partial z_3}{\partial w_5} = 0.209 * 0.238 * 0.519 = 0.0259$$

$$w_5^o = w_5 - \alpha * \frac{\partial E_{total}}{\partial w_5}$$

$$0.437 = 0.45 - 0.5 * 0.0259$$



* w_1 업데이트 (연역법칙, 체인룰)

$$\frac{\partial E_{total}}{\partial w_1} = \frac{\partial E_{total}}{\partial h_1} * \frac{\partial h_1}{\partial z_1} * \frac{\partial z_1}{\partial w_1}$$

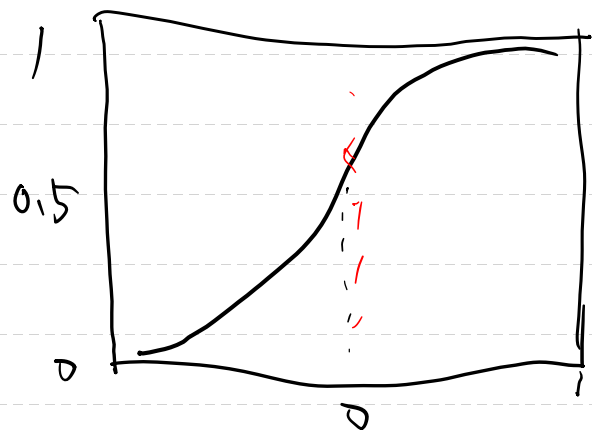
$$w_1' = w_1 - \alpha * \frac{\partial E_{total}}{\partial w_1}$$

$$= 0.3 - 0.5 * 0.0008$$

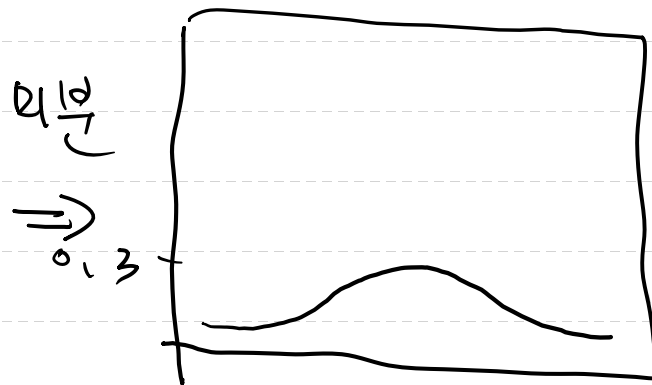
$$= 0.031 * 0.250 * 0.1 = 0.0008$$

$$\frac{\partial E_{total}}{\partial h_1} = \frac{\partial E_{o1}}{\partial h_1} + \frac{\partial E_{o2}}{\partial h_1} \Rightarrow \begin{cases} \frac{\partial E_{o1}}{\partial h_1} = \frac{\partial E_{o1}}{\partial z_3} * \frac{\partial z_3}{\partial h_1} = 0.022 \\ \frac{\partial E_{o2}}{\partial h_1} = \frac{\partial E_{o2}}{\partial z_4} * \frac{\partial z_4}{\partial h_1} = 0.009 \end{cases}$$

$$0.031 = 0.022 + 0.009$$



시그모이드



이분 후 시그모이드

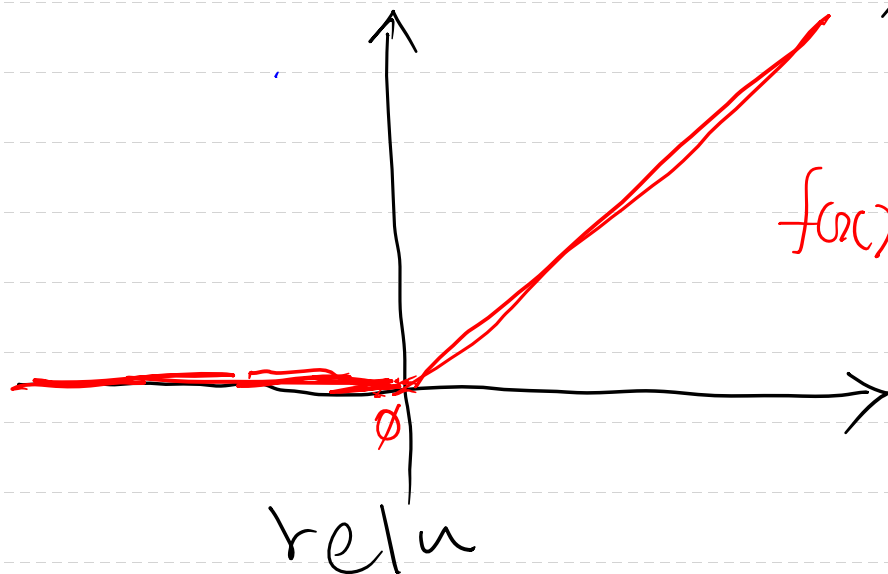
이분 후 ...
=>

기울기가
사라짐
($\phi'(2.4)$)

=> vanishing
gradient
문제 발생

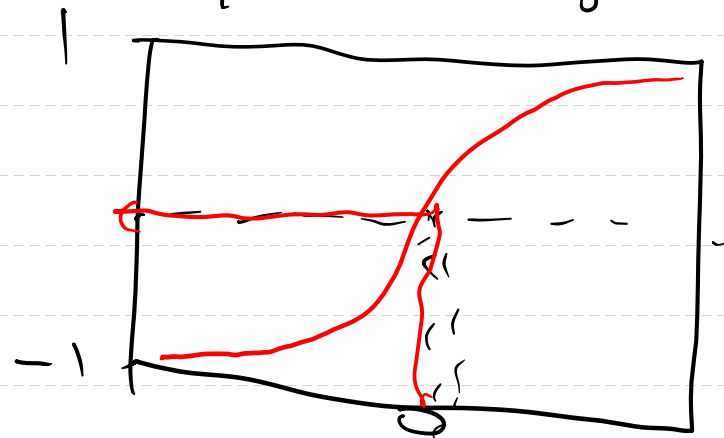
정답: 기울기 문제가 생기는 sigmoid를 안 씀

* relu (보통 relu) 시그스



$$f(x) = \begin{cases} x & (x > 0) \\ 0 & (x \leq 0) \end{cases}$$

* 하이퍼볼릭 탄젠트는
(~~tanh~~ tanh)
hyperbolic tangent



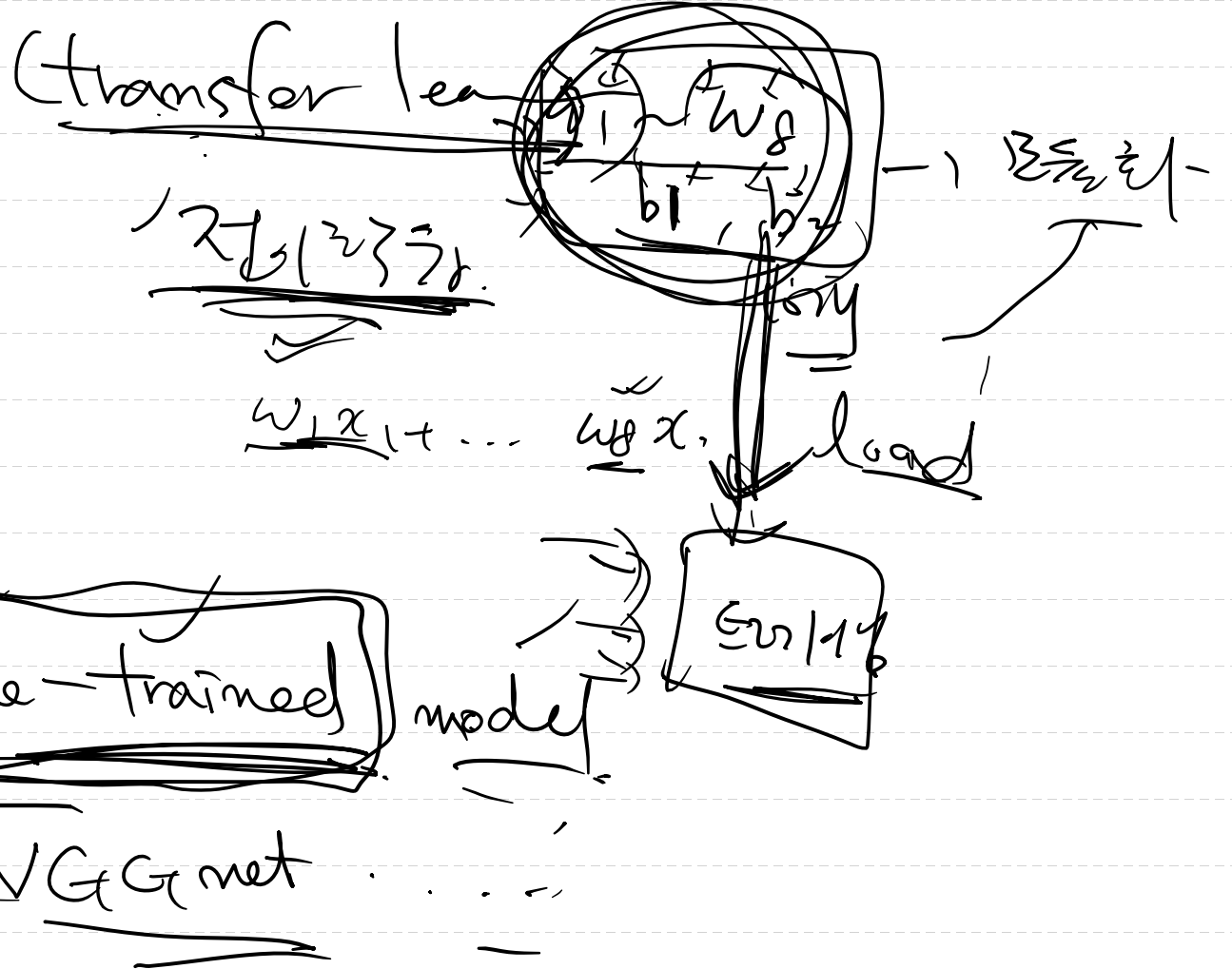
기타 특징

① 데이터 기반

② 특징공학 중요

③ 간단한 구조

④ 데이터가 중요



Keras : 간편식 구축

한글형 api

Sequential model

(100% 간편식 구축)

(70% 정답
30% 정답)

1. 데이터셋 생성 (훈련, 검증, 테스트)

2. 모델 생성 (신경망 모델 생성 → 데이터 추가 가능)

→ 층 수 = 2 레이어를 쌓아서
모델 생성
(0.1, 0.1, 0.1)

Dense 레이어

Sequential
레이어

3. 학습 방법 설정 (Cost 함수, SGD, ...)

Compile 함수

4. 모델 학습 (시작)

fit 함수

→ 학습 시 훈련, 검증 데이터 = cost, acc 확인
epoch 설정 ??

5. 모델 평가 (시작)

evaluate 함수

6. 모델 예측 Predict 함수

