

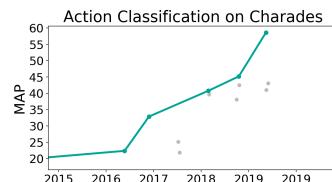
행동 인식 / 검출

Action Classification

Papers with Code - Charades Benchmark (Action Classification)

The current state-of-the-art on Charades is AssembleNet. See a full comparison of 14 papers with code.

 <https://paperswithcode.com/sota/action-classification-on-charades>



성능비교

표.1

| # RANK | Aa MODEL | # MAP | # YEAR |
|--------|---|-------|--------|
| 1 | <u>AssembleNet</u> | 58.6 | 2019 |
| 2 | <u>AssembleNet-101</u> | 58.6 | 2019 |
| 3 | <u>SlowFast</u> | 45.2 | 2018 |
| 4 | <u>HAF+BoW/FV/OFF halluc. +MSK×8/PN</u> | 43.1 | 2019 |
| 5 | <u>LFB</u> | 42.5 | 2018 |
| 6 | <u>PA3D +(GCN + I3D + NL I3D)</u> | 41 | 2019 |
| 7 | <u>PoTion +(GCN + I3D + NL I3D)</u> | 40.8 | 2018 |
| 8 | <u>STRG</u> | 39.7 | 2018 |
| 9 | <u>EvaNet</u> | 38.1 | 2018 |
| 10 | <u>I3D</u> | 32.9 | 2017 |
| 11 | <u>MultiScale TRN</u> | 25.2 | 2017 |
| 12 | <u>Asyn-TE</u> | 22.4 | 2016 |
| 13 | <u>CoViAR</u> | 21.9 | 2017 |
| 14 | <u>2-Strm</u> | 18.6 | 2014 |

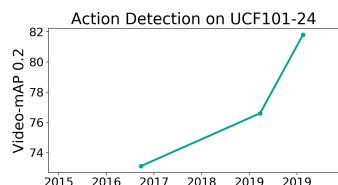
- AssembleNet 는 가장 성능이 높지만 공개된 소스코드는 없음
- SlowFast, LFB는 소스코드에 학습하는 부분도 제공함

Action Detection

Papers with Code - UCF101-24 Benchmark (Action Detection)

The current state-of-the-art on UCF101-24 is MOC. See a full comparison of 5 papers with code.

➡ <https://paperswithcode.com/sota/action-detection-on-ucf101-24>



성능비교

표.2

| # RANK | Aa MODEL | # MAP | # VIDEO-MAP 0.5 | # VIDEO-MAP 0.75 | # VIDEO-MAP 0.2 | # VIDEO-MAP 0.1 | # YEAR |
|--------|------------------------------|-------|-----------------|------------------|-----------------|-----------------|--------|
| 1 | <u>MOC</u> | 0 | 0 | 0 | 81.8 | 0 | 2020 |
| 2 | <u>STEP</u> | 0 | 0 | 0 | 76.6 | 83.1 | 2019 |
| 3 | <u>T-CNN</u> | 0 | 0 | 0 | 73.1 | 77.9 | 2017 |
| 4 | <u>Ours(MOC)</u> | 27.7 | 53.9 | 28.5 | 0 | 0 | 2020 |
| 5 | <u>two-in-one two stream</u> | 22.02 | 0 | 0 | 0 | 0 | 2019 |

- 최고 성능 모델 : MO

표.3

| Aa Metric Name | ≡ Value | ≡ Global Rank |
|-----------------------|---------|---------------|
| <u>Video-mAP 0.5</u> | 53.9 | # 1 |
| <u>Video-mAP 0.75</u> | 28.5 | # 1 |
| <u>Video-mAP 0.2</u> | 81.8 | # 1 |

결론

- 성능과 빠른 테스트를 위해서 MOC > LFB > SlowFast 순서로 진행
- MOC GitHub

MCG-NJU/MOC-Detector

Pytorch implementation of Actions as Moving Points (ECCV 2020). View each action instance as a trajectory of moving points. Visualization results on validation set. (GIFs will take a

➡ <https://github.com/MCG-NJU/MOC-Detector>



- LFB GitHub

wei-tim/YOWO

PyTorch implementation of the article " You Only Watch Once: A Unified CNN Architecture for Real-Time Spatiotemporal Action Localization". In this work, we present

 <https://github.com/wei-tim/YOWO>



- SlowFast GitHub

facebookresearch/SlowFast

PySlowFast is an open source video understanding codebase from FAIR that provides state-of-the-art video classification models with efficient training. This repository includes

 <https://github.com/facebookresearch/SlowFast>



[SlowFast](#)

SlowFast

1. DataSets

1.1 Train

ex. Kinetics

- 동영상 파일(height : 256)
 - 필요한 소스 코드
 - 다운로드

activitynet/ActivityNet

This repository is intended to host tools and demos for ActivityNet - activitynet/ActivityNet

👉 <https://github.com/activitynet/ActivityNet/tree/master/Crawler/Kinetics>



- 필수기능 : youtube-dl
- 전처리

facebookresearch/video-nonlocal-net

We have prepared one copy of the Kinetics dataset. To obtain the dataset, please email xiaolonw@cs.cmu.edu. Our copy includes

👉 <https://github.com/facebookresearch/video-nonlocal-net/blob/master/DATASET.md>



- 과정1 : 라벨링 리스트(classids.json) 기준으로 각 동영상 경로당 라벨링 숫자 매칭된 txt파일 생성
- 과정2 : 동영상을 height를 256 pixel로 조정
- csv 파일 3개(train / val / test)

<동영상 파일 저당된 경로> <라벨링에 매칭이 되는 숫자>

ex.

/root/SlowFast/Datasets/sample_val_256/applauding/-r8c7F4t0I8_000054_000064.mp4 3

▲ 이슈 사항

- 데이터셋 용량이 너무 커서 서버에 저장하기 힘듬(대안으로 샘플로 약 10개로 테스트 진행)
- 전처리한 전체 데이터셋 요청함(xiaolonw@cs.cmu.edu)

1.2 Inference

- 동영상 파일
- 라벨링 파일(.json)
 - class name ~ id mapping
 - {"class_name1": id1, "class_name2": id2, ...}
 - CHECKPOINT_FILE_PATH (더 파악해야 함)

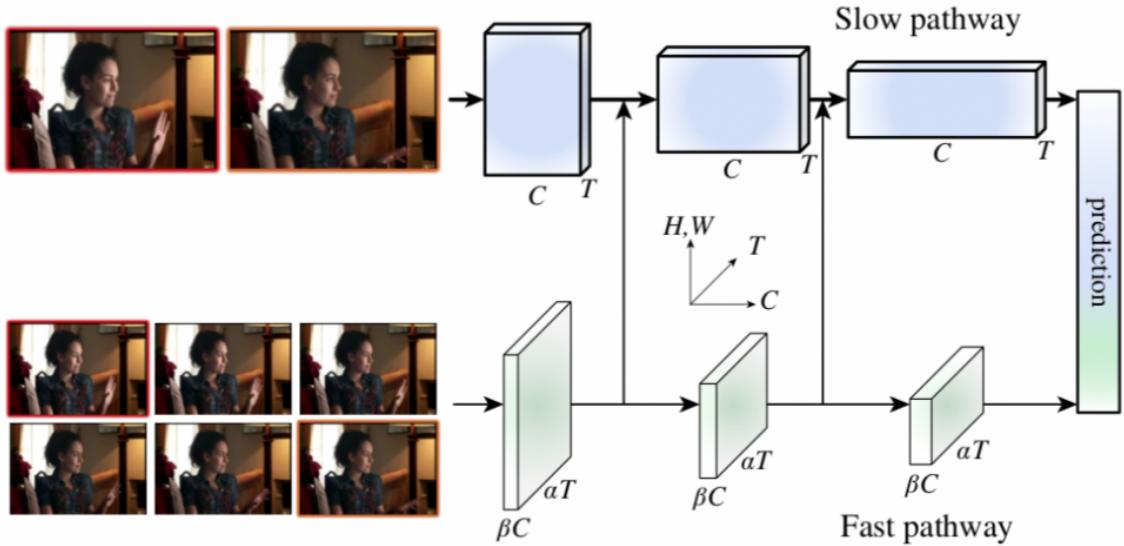
1.2.1 output

- 동영상

특징

- detection은 detectron2(<https://github.com/facebookresearch/detectron2>)를 사용하는 것으로 보임

2. Model



- Backbone
 - 2D
 - ResNet50 또는 ResNet101로 진행
 - Two-Stream Method(Slow, Fast)
- Idea
 - 사람 망막의 작동을 모방해서 Two-Stream 방식으로 설계
 - 사람의 시각 시스템은 공간과 움직임 두 가지를 인식하는 부분이 별도 존재
 - M-Cells : 움직임 \rightarrow Fast
 - P-Cells : 공간 구조, 색 \rightarrow Slow
 - 기능 비율 \rightarrow M-Cells : P-Cells = Fast : Slow = 2 : 8 동일하게 설정

MOC 모델 데이터 구조

추론 데이터

- 동영상 W / H 사이즈 제약은 없음
 - Default로 288 x 288로 사이즈 조정해서 입력(Output은 원본 사이즈로 나옴)
- 입력 비디오 : .mp4 ⇒ 1차 변환 : .jpg ⇒ 추론 : .pkl ⇒ 이미지에 그리기 : .jpg ⇒ 합치기 : .avi
- Pre-trained Model (UFC 데이터로 학습 / 7초 단위로 동영상 분할) 동영상이 7초 내외가 아니면 에러가 발생

```
(MOC) root@c8802d0806ad:~/MOC-Detector/src/vis# python vis_det.py --vname test2.mp4 --inference_dir ../../inference/myvideo/test2
start extracting frames
create rgb model
loaded ../../experiment/result_model/ucf_dla34_K7_rgb_coco.pth, epoch 0
Traceback (most recent call last):
  File "vis_det.py", line 174, in <module>
    det()
  File "vis_det.py", line 157, in det
    stream_inference(opt)
  File "vis_det.py", line 125, in stream_inference
    detector = MOCdetector(opt)
  File "../detector/stream_moc_det.py", line 29, in __init__
    self.rgb_model_backbone, self.rgb_model_branch = load_inference_model(self.rgb_model_backbone, self.rgb_model_branch, opt.rgb_
  File "../MOC_utils/model.py", line 84, in load_inference_model
    branch.load_state_dict(state_dict, strict=False)
  File "/root/miniconda3/envs/MOC/lib/python3.5/site-packages/torch/nn/modules/module.py", line 719, in load_state_dict
    self.__class__.__name__, "\n\t".join(error_msgs))
RuntimeError: Error(s) in loading state_dict for MOC_Det:
    size mismatch for branch.hm.0.weight: copying a param of torch.Size([256, 1920, 3, 3]) from checkpoint, where the shape is
    size mismatch for branch.mov.0.weight: copying a param of torch.Size([256, 1920, 3, 3]) from checkpoint, where the shape is
    size mismatch for branch.mov.2.bias: copying a param of torch.Size([60]) from checkpoint, where the shape is torch.Size([1
    size mismatch for branch.mov.2.weight: copying a param of torch.Size([60, 256, 1, 1]) from checkpoint, where the shape is
(MOC) root@c8802d0806ad:~/MOC-Detector/src/vis#
```

- 참고

CRCV | Center for Research in Computer Vision at the University of Central Florida

There will be a workshop in ICCV'13 with UCF101 as its main competition benchmark: The First International Workshop on Action Recognition with Large Number of Classes. Click here to check the published results on UCF101 (updated October 17, 2013) UCF101 is an action

 <https://www.crcv.ucf.edu/data/UCF101.php>



학습 데이터

- 입력 데이터
 - 동영상을 K초 단위로 분할한 그냥 이미지 (ex. K = 7)
 - K초 단위로 분할한 Flow 이미지(위의 이미지와 1:1 매칭)
 - 라벨링 파일(.pkl)

라벨링

- 행동인식(flow 영상)
- 바운딩 박스(.pkl)

```
"""
Abstract class for handling dataset of tubes.

Here we assume that a pkl file exists as a cache. The cache is a dictionary with the following keys:
  labels: list of labels
  train_videos: a list with nsplits elements, each one containing the list of training videos
  test_videos: idem for the test videos
  nframes: dictionary that gives the number of frames for each video
```

```

resolution: dictionary that output a tuple (h,w) of the resolution for each video
gttubes: dictionary that contains the gt tubes for each video.
    Gttubes are dictionary that associates from each index of label, a list of tubes.
    A tube is a numpy array with nframes rows and 5 columns, <frame number> <x1> <y1> <x2> <y2>.
"""

```

- gttubes : 분할한 영상에 대한 프레임별 이미지에 대한 바운딩 박스 정보
 - 구조 : <label name>/<dir name> : {label idx: [frameNum, Xmin, Ymin, Xmax, Ymax]}

```

{'Skiing/v_Skiing_g06_c07':
  {16: [array([[ 1., 199., 61., 239., 125.],
   [ 2., 199., 61., 239., 125.],
   [ 3., 190., 65., 231., 126.],
   ...,
   [298., 166., 61., 211., 120.],
   [299., 162., 61., 207., 120.],
   [300., 162., 61., 207., 120.]], dtype=float32)]},
  ...
}

```

- sample(확인결과)

