Sandro Cumani

sandro.cumani@polito.it

Politecnico di Torino

Discriminative Linear Models – Logistic Regression

Logistic regression, despite its name, is a discriminative approach for classification

Rather than modeling the distribution of observed samples X|C, we directly model the class posterior distribution C|X

We need to define a model for the class posterior distribution $P(C=c|\pmb{X}=\pmb{x})$

Discriminative Linear Models – Logistic Regression

For a 2-class problem, we have seen that the Gaussian model with tied covariance provides log-likelihood ratios that are linear functions of our data

$$l(\mathbf{x}) = \log \frac{f_{X|C}(\mathbf{x}|h_1)}{f_{X|C}(\mathbf{x}|h_0)} = \mathbf{w}^T \mathbf{x} + c$$

and the class log-posterior probability ratio is

$$\log \frac{P(C = h_1 | \mathbf{x})}{P(C = h_0 | \mathbf{x})} = \log \frac{f_{X|C}(\mathbf{x} | h_1)}{f_{X|C}(\mathbf{x} | h_0)} + \log \frac{\pi}{1 - \pi} = \mathbf{w}^T \mathbf{x} + b$$

The prior information (including possible non-uniform costs) has been absorbed in the bias term b.

Classification rules take the form of linear functions

We now adopt a complementary approach: we assume that our decision rule should be a linear rule represented by (w,b)

Given w and b, we can compute the expression for the posterior class probability as

$$P(C = h_1 | \mathbf{x}, \mathbf{w}, b) = e^{(\mathbf{w}^T \mathbf{x} + b)} P(C = h_0 | \mathbf{x}, \mathbf{w}, b)$$
$$= e^{(\mathbf{w}^T \mathbf{x} + b)} (1 - P(C = h_1 | \mathbf{x}, \mathbf{w}, b))$$

Solving for $P(C = h_1 | x, w, b)$ we obtain

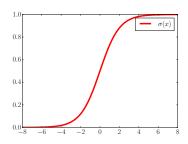
$$P(C = h_1 | \mathbf{x}, \mathbf{w}, b) = \frac{e^{(\mathbf{w}^T \mathbf{x} + b)}}{1 + e^{\mathbf{w}^T \mathbf{x} + b}} = \frac{1}{1 + e^{-(\mathbf{w}^T \mathbf{x} + b)}} = \sigma(\mathbf{w}^T \mathbf{x} + b)$$

where

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

is called sigmoid function (or logistic function)

Sigmoid function:



Some properties of $\sigma(x)$ that will come useful later

- $\bullet \ 1 \sigma(x) = \sigma(-x)$
- $\frac{d\sigma(x)}{dx} = \sigma(x) (1 \sigma(x))$

The expression $P(C = h_1 | x, w, b) = \sigma(w^T x + b)$ provides a model that allows computing the posterior probabilities for h_1 and h_0

The model assumes that decision rules are linear surfaces (hyperplanes) orthogonal to w. The model parameters are (w,b)

If we knew (w,b) then we could compute the predictive distribution for the class labels $P(C=h_1|x,w,b)$

We have seen an indirect way of computing (\mathbf{w}, b) with a generative model

• The tied covariance Gaussian feature model, combined with application class prior, can be cast as a linear decision rule of the form $\mathbf{w}^T\mathbf{x} + b \leqslant 0$

However, in the following we are interested to find an alternative way to estimate an effective classification rule that does not require an explicit model of the feature vectors distribution

We thus ignore generative models for X and concentrate directly on the form of the class posterior probabilities

Again, we follow a frequentist approach, i.e. compute an estimate for w and b from a set of training samples

We assume we have a labeled dataset

$$\mathcal{D} = [(\boldsymbol{x}_1, c_1), \dots (\boldsymbol{x}_n, c_n)]$$

We also assume that feature vectors and corresponding class labels are independent and identically distributed (i.i.d.). given the model parameters (we made the same assumption for generative models):

$$[(X_i,C_i)\perp \!\!\!\perp (X_j,C_j)]|\boldsymbol{\theta}$$

Here θ are the model parameters $\theta = (w, b)$

As for generative models, the complete-data likelihood for θ consists of the joint density of the observed training set variables, given the parameter vector θ :

$$\mathcal{L}(\boldsymbol{\theta}) = f_{\boldsymbol{X}_1...\boldsymbol{X}_n,C_1...C_n|\boldsymbol{\theta}}(\boldsymbol{x}_1...\boldsymbol{x}_n,c_1...c_n|\boldsymbol{\theta})$$

Since we assume i.i.d. observations, we can factorize the likelihood as

$$\mathcal{L}(\boldsymbol{\theta}) = f_{\boldsymbol{X}_1...\boldsymbol{X}_n, C_1...C_n | \boldsymbol{\theta}}(\boldsymbol{x}_1 ... \boldsymbol{x}_n, c_1 ... c_n | \boldsymbol{\theta})$$

$$= \prod_{i=1}^n f_{\boldsymbol{X}, C | \boldsymbol{\theta}}(\boldsymbol{x}_i, c_i | \boldsymbol{\theta})$$

The difference with respect to generative models is in the way we represent the joint density $f_{X,C|\theta}$:

$$f_{X,C|\theta}(\mathbf{x}_i,c_i) = P(C=c_i|X=\mathbf{x}_i,\theta)f_X(\mathbf{x}_i)$$

Note that, since classification requires computing posterior class probabilities, and we are defining an explicit model for such terms, we do not need to explicitly provide an expression for the marginal feature density $f_X(X)$

The complete-data log-likelihood becomes

$$\log \mathcal{L}(\boldsymbol{\theta}) = \log \prod_{i=1}^{n} f_{\boldsymbol{X},C|\boldsymbol{\theta}}(\boldsymbol{x}_{i}, c_{i}|\boldsymbol{\theta})$$
$$= \sum_{i=1}^{n} \log P(C = c_{i}|\boldsymbol{X}_{i} = \boldsymbol{x}_{i}, \boldsymbol{\theta}) + \sum_{i=1}^{n} \log f_{\boldsymbol{X}}(\boldsymbol{x}_{i})$$

As for generative models, we can estimate the model parameters by following a Maximum Likelihood approach

$$oldsymbol{ heta}_{\mathit{ML}} = rg \max_{oldsymbol{ heta}} \log \mathcal{L}(oldsymbol{ heta})$$

Since the model parameters θ influence only the first sum, optimization of the log-likelihood corresponds to the maximization of the conditional probability of the observed dataset labels, given the observed feature vectors and the model parameters

$$\ell(\boldsymbol{\theta}) = \sum_{i=1}^{n} \log P(C = c_i | \boldsymbol{X}_i = \boldsymbol{x}_i, \boldsymbol{\theta})$$

We now need to explicit our model in the expression for ℓ

We assume that the label for class h_1 is 1, and the label for class h_0 is 0

Our model specifies the probabilities for observed class labels in terms of w and b:

$$y_i = P(C_i = 1 | \mathbf{x}_i, \mathbf{w}, b) = \sigma(\mathbf{w}^T \mathbf{x}_i + b)$$

It follows that

$$P(C_i = 0 | \mathbf{x}_i, \mathbf{w}, b) = 1 - y_i = 1 - \sigma(\mathbf{w}^T \mathbf{x}_i + b) = \sigma(-\mathbf{w}^T \mathbf{x} - b)$$

We note that $C_i|x_i, w, b$ follows a Bernoulli distribution

$$C_i|\mathbf{x}_i, \mathbf{w}, \mathbf{b} \sim \operatorname{Ber}\left(\sigma(\mathbf{w}^T\mathbf{x}_i + b)\right) = \operatorname{Ber}(y_i)$$

The conditional probability of the class labels, i.e. our objective function, is thus given by

$$\ell(\mathbf{w}, b) = \log \prod_{i=1}^{n} P(C_i = c_i | \mathbf{x}_i, \mathbf{w}, b)$$

$$= \log \prod_{i} y_i^{c_i} (1 - y_i)^{(1 - c_i)}$$

$$= \sum_{i=1}^{n} [c_i \log y_i + (1 - c_i) \log(1 - y_i)]$$

Our goal is the maximization of ℓ , which corresponds to the maximization of the likelihood function, i.e., a Maximum Likelihood solution. We thus seek w^* , b^* that maximize $\ell(w,b)$:

$$\mathbf{w}^*, b^* = \arg\max_{\mathbf{w}, b} \ell(\mathbf{w}, b) = \arg\max_{\mathbf{w}, b} \sum_{i=1}^{n} [c_i \log y_i + (1 - c_i) \log(1 - y_i)]$$

We can show that the ML solution is also the solution that minimizes the average cross-entropy between the distribution of observed and predicted labels

Rather than maximizing $\ell(\mathbf{w}, b)$, we can minimize

$$J(\mathbf{w}, b) = -\ell(\mathbf{w}, b) = \sum_{i=1}^{n} -\left[c_{i} \log y_{i} + (1 - c_{i}) \log(1 - y_{i})\right]$$

The expression

$$H(c_i, y_i) = -[c_i \log y_i + (1 - c_i) \log (1 - y_i)]$$

represents the binary *cross—entropy* between the distribution of observed and predicted labels for the *i*-th sample

More in general, let P and Q be two distributions over the same domain

The cross-entropy between the two distributions is defined as

$$H(P,Q) = -\mathbb{E}_{P(x)} \left[\log Q(x) \right]$$

For discrete distributions, this can be expressed as

$$H(P,Q) = -\sum_{x \in \mathcal{S}} P(x) \log Q(x)$$

In our case, P is the empirical distribution of class labels, from the point of view of an observer \mathcal{E} who knows the actual label:

$$P(C_i = 1 | \mathbf{X}_i = \mathbf{x}_i, \mathcal{E}) = \begin{cases} 1 & \text{if } c_i = 1 \\ 0 & \text{if } c_i = 0 \end{cases}$$
$$P(C_i = 0 | \mathbf{X}_i = \mathbf{x}_i, \mathcal{E}) = \begin{cases} 0 & \text{if } c_i = 1 \\ 1 & \text{if } c_i = 0 \end{cases}$$

or, equivalently

$$P(C_i = 1 | X_i = x_i, \mathcal{E}) = c_i$$
, $P(C_i = 0 | X_i = x_i, \mathcal{E}) = 1 - c_i$

i.e., a Bernoulli distribution with parameter c_i

Distribution Q is the distribution for the predicted labels according to our recognizer \mathcal{R}

$$Q(c) = P(C_i = c | X_i = x_i, \mathcal{R}(w, b))$$

i.e.

$$Q(1) = P(C_i = 1 | X_i = x_i, \mathcal{R}(w, b)) = y_i = \sigma(w^T x_i + b)$$

$$Q(0) = P(C_i = 0 | X_i = x_i, \mathcal{R}(w, b)) = 1 - y_i = 1 - \sigma(w^T x_i + b)$$

Logistic regression looks for the minimizer of the average crossentropy between the distribution for the training set labels of an evaluator $\mathcal E$ who knows the real label and the distribution for the training set labels as predicted by the model $\mathcal R(w,b)$ itself

The cross-entropy is a measure of goodness of the predictions, and the evaluation is performed over the training data itself

The cross-entropy, as a function of Q, is minimized when Q = P

The cross–entropy can also be interpreted as a measure of the difference between P and Q

In our case, it measures how different is the predicted distribution $\mathrm{Ber}(y_i)$ from the empirical label distribution $\mathrm{Ber}(c_i)$ (the distribution of the evaluator \mathcal{E})

Minimization of the average cross-entropy means we are looking for conditional label distributions as similar (on average) as possible to the empirical one, given the model constraints (i.e., a linear classification rule)

Alternatively, as we have seen, we can regard the process as maximization of the likelihood for the observed labels

Another interesting interpretation of the logistic regression objective can be obtained by rewriting the cross-entropy in terms of $z_i = 2c_i - 1$

The terms z_i still represent class labels, however for samples of class h_1 we have $z_i = 1$, whereas for samples of class h_0 we have $z_i = -1$:

$$z_i = \begin{cases} 1 & \text{if } c_i = 1 \\ -1 & \text{if } c_i = 0 \end{cases}$$

The objective function that we want to minimize corresponds to the sum of n terms

$$J(\mathbf{w},b) = \sum_{i} H(c_i, y_i)$$

where

$$H(c_i, y_i) = -[c_i \log y_i + (1 - c_i) \log(1 - y_i)]$$

Note that $H(c_i, y_i)$ is a function of c_i , but also of w, b and x_i , since

$$y_i = \sigma(\mathbf{w}^T \mathbf{x}_i + b)$$

Let $s_i = \mathbf{w}^T \mathbf{x}_i + b$. In terms of z_i we can rewrite H as

$$H(c_{i}, y_{i}) = -\left[c_{i} \log y_{i} + (1 - c_{i}) \log(1 - y_{i})\right]$$

$$= \begin{cases} -\log \sigma(s_{i}) & \text{if } c_{i} = 1 \ (z_{i} = 1) \\ -\log (1 - \sigma(s_{i})) = -\log \sigma(-s_{i}) & \text{if } c_{i} = 0 \ (z_{i} = -1) \end{cases}$$

$$= -\log \sigma(z_{i}s_{i})$$

$$= -\log \sigma\left(z_{i}(\mathbf{w}^{T}\mathbf{x}_{i} + b)\right)$$

$$= \log\left(1 + e^{-z_{i}(\mathbf{w}^{T}\mathbf{x}_{i} + b)}\right)$$

The objective function can thus be rewritten as

$$J(\mathbf{w}, b) = \sum_{i=1}^{n} H(c_i, y_i)$$

$$= \sum_{i=1}^{n} \log \left(1 + e^{-z_i(\mathbf{w}^T \mathbf{x}_i + b)} \right)$$

$$= \sum_{i=1}^{n} l\left(z_i(\mathbf{w}^T \mathbf{x}_i + b) \right)$$

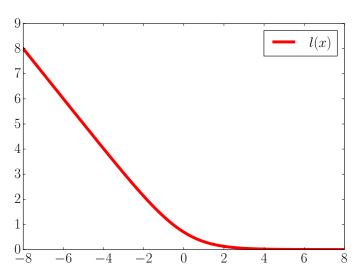
where

$$l(x) = \log\left(1 + e^{-x}\right)$$

is the logistic loss function.

Our goal is to find the minimizer of J(w, b)

Logistic loss



We can interpret the function as the cost of the prediction made with model (w,b) for each sample

Remember that the log-posterior class probability ratio for sample x_i is

$$\log \frac{P(C_i = 1 | \boldsymbol{X}_i = \boldsymbol{x}_i)}{P(C_i = 0 | \boldsymbol{X}_i = \boldsymbol{x}_i)} = \boldsymbol{w}^T \boldsymbol{x}_i + b = s_i$$

The decision rule takes the form $s_i \leq 0$

Since $s_i = \mathbf{w}^T \mathbf{x}_i + b$, decision rules are linear hyperplane orthogonal to the vector \mathbf{w}

 s_i is related to the distance of the sample x_i from the separating surface

When s_i is positive, our classifier is favoring class h_1 , whereas negative s_i means we are classifying the sample as belonging to class h_0 .

The cost we pay for each sample is $l(z_i s_i)$

- The prediction and the actual class agree: $z_i = 1, s_i > 0$ or $z_i = -1, s_i < 0$. Then $z_i s_i > 0$, and we pay a low cost. The cost becomes exponentially smaller (asymptotically) as the absolute value of s_i increases (we move away from the separation surface)
- The prediction and the actual class disagree: $z_i = 1, s_i < 0$ or $z_i = -1, s_i > 0$. Then $z_i s_i < 0$, and we pay a cost that increases (asymptotically) linearly with s_i

We can thus interpret the logistic regression objective as a measure of an empirical risk¹. Our goal is minimizing the empirical risk

More in general, empirical risk minimization is a framework for the estimation of classification models which aims at minimizing an empirical risk function over our training data

Generalized risk minimization problem: minimize the risk $R(\theta)$

$$R(\boldsymbol{\theta}) = \sum_{i} l(\boldsymbol{w}, \boldsymbol{x}_{i}, \boldsymbol{z}_{i})$$

where l is called loss (or cost) function, and θ are the parameters of the classification model, e.g. $\theta = (w, b)$ in our case.

¹Empirical because it's computed on the observed samples

Logistic regression solutions cannot be computed in closed form

We will resort to numerical solvers

A numerical solver iteratively looks for the minimizer of a function

We will use the L-BFGS algorithm

The algorithm requires a function that computes the loss and its gradient with respect to w and b

In the laboratory we will see how to implement the minimization

If classes are linearly separable, the logistic regression solution is not defined

Linearly separable classes: there exist w and b such that all training samples lie on the correct side of the corresponding separation surface ($z_i > 0 \iff s_i > 0$)

In this case, we can make the values of s_i arbitrarily high by simply increasing the norm of w (and changing accordingly the value of b)

As we increase $\|w\|$, the loss becomes lower, thus we are decreasing the objective function

The function does not have a minimum, but has an infimum $\inf J(w,b)=0$, corresponding to $\|w\|\to\infty$

To make the problem solvable again, we can look for solutions with small norm by introducing a norm penalty to the objective function

The penalty is called regularization term

The objective function that we minimize is

$$\tilde{R}(\boldsymbol{w},b) = \frac{\tilde{\lambda}}{2} \|\boldsymbol{w}\|^2 + \sum_{i=1}^{n} \log \left(1 + e^{-z_i(\boldsymbol{w}^T \boldsymbol{x}_i + b)}\right)$$

where $\tilde{\lambda}$ is a hyper-parameter that allows specifying the relative weight of the regularization term

Alternatively, we look for the minimizer of

$$R(\mathbf{w}, b) = \frac{\lambda}{2} ||\mathbf{w}||^2 + \frac{1}{n} \sum_{i=1}^{n} \log \left(1 + e^{-z_i(\mathbf{w}^T \mathbf{x}_i + b)} \right)$$

where the risk is *averaged* over all samples, and λ is the regularization coefficient.

 λ is a hyper-parameter, and should be selected as to optimize the performance of the classifier

Note that λ cannot be computed by minimizing R with respect to λ , as we would obtain the trivial solution $\lambda=0$

The selection of good values for λ should thus be based on other approaches, such as cross-validation

The model is called regularized Logistic Regression, and is an example of a regularized risk minimization problem

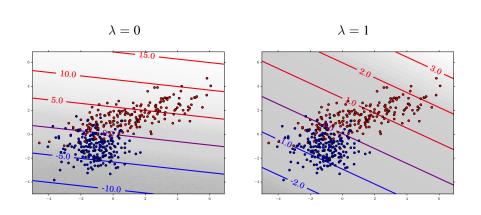
$$R(\mathbf{w},b) = \Omega(\mathbf{w},b) + \frac{1}{n} \sum_{i=1}^{n} l(\mathbf{x}_i, z_i, \mathbf{w}, \mathbf{b})$$

The regularization term Ω (in our case $\frac{\lambda}{2} \| \mathbf{w} \|^2$) can be interpreted as a term that favors simpler solutions (we will see explicitly why small norm of \mathbf{w} can be interpreted as a simpler solution when discussing Support Vector Machines)

Regularization allows reducing the risk of over-fitting the training data

Of course, if λ is too large, we will obtain a solution that has small norm, but is not able to well separate the classes

On the other hand, if λ is too small, we will get a solution that has good separation on the training set, but may have poor classification accuracy for unseen data (i.e. poor generalization)



Some considerations:

- The non-regularized model is invariant to linear transformations of the feature vectors.
- The regularized version of the model, on the other hand, is not invariant.
- It is therefore useful, in some cases, to pre-process data so that dynamic ranges of different features are similar
- Cross-validation can help in identifying good pre-processing strategies

Common preprocessing strategies that may be worth trying:

- Center the data (either using the training set, or a weighted mean e.g. the average of class means): $x'_i = x_i \mu$
- Standardize variances (e.g. divide each feature by its own standard deviation computed over the training set): $x'_{i,[j]} = x_{i,[j]}/\sigma_{[j]}$
- Whiten the covariance matrix (i.e. normalize variances while making features uncorrelated): $x_i' = Ax_i$, where $A = \Sigma^{\frac{1}{2}}$ and Σ is the training set covariance (a variation consists in replacing Σ with the within-class covariance)
- L2 (or length) normalization: $x_i' = \frac{x_i}{\|x_i\|}$ (often after centering and whitening)

The logistic regression score can be interpreted as the logarithm of the ratio between class posterior probabilities

The model parameters have been trained as to optimize the probability of the training set labels

Therefore, the model will implicitly reflect the empirical class prior of the training set

The model posterior probabilities are thus suited for applications whose effective prior is close to the empirical training set prior, but may provide poor performance for different applications

To soften this issue, we can recover a score that behaves like a log-likelihood ratio by subtracting from the score s the empirical prior log-odds of the training set $\log \frac{n_T}{n_F}$

$$s_{llr} = \boldsymbol{w}^T \boldsymbol{x} + b - \log \frac{n_T}{n_F} = \boldsymbol{w}^T \boldsymbol{x} + b - \log \frac{\pi_{emp}^{tr}}{1 - \pi_{emp}^{tr}}$$

We can then use s_{llr} as a log-likelihood ratio

For a given application $(\pi_T,1,1)$ we can compute decisions by comparing $s_{llr} \leqslant -\log \frac{\pi_T}{1-\pi_T}$

While this allows for effective decisions for the model (w,b), the orientation of w is still optimized for the training set empirical prior

Changing the threshold allows us to select a better decision rule, but only among hyperplanes that are orthogonal to w

If we know the application prior π_T before training the model, then it may be preferable to directly optimize the separation rule for the target application prior

The model is sometimes called prior-weighted logistic regression:

$$R(w) = \frac{\lambda}{2} ||w||^2 + \frac{\pi_T}{n_T} \sum_{i|z_i=1} l(z_i s_i) + \frac{1 - \pi_T}{n_F} \sum_{i|z_i=-1} l(z_i s_i)$$

Logistic Regression

The standard logistic regression model corresponds to the prior-weighted logistic regression model trained with the training set empirical prior π_{emp}^{tr}

Also in this case, we can compute a IIr-like score

$$s_{llr} = \mathbf{w}^T \mathbf{x} + b - \log \frac{\pi_T}{1 - \pi_T}$$

that can then be employed to estimate optimal decisions for other applications, should the need arise

Logistic Regression

We test the model on MNIST digit pairs (e.g. 0 vs 1, 0 vs 2, ...)

MNIST — Average Pairwise EER for Logistic Regression

DimRed	$\lambda = 0$	$\lambda = 0.00001$	$\lambda = 0.001$	$\lambda = 0.1$	Tied Gau
RAW [768]	1.7%	1.4%	1.2%	2.0%	_
PCA [50]	1.4% 1.3%	1.4%	1.4%	2.1%	1.7% 1.5%
. 6/1[100]	1.070	1.270	1.270	2.070	1.070

LogReg obtains better performance than the Gaussian model

Regularization is important, especially when we do not reduce the dimensionality (we have more parameters to estimate, so over-fitting is more sever)

If we regularize too much the model performs poorly again

We now consider a problem with K classes, labeled from 1 to K

To extend the Logistic Regression model to multiclass tasks we start again from the form of the posterior probabilities of the Linear Gaussian classifier with uniform priors

$$\log P(C = j|\mathbf{x}) = \mathbf{w}_i^T \mathbf{x} + \mathbf{b}_j + k(\mathbf{x})$$

where k(x) collects terms that depend on the sample x, but not on the class j.

It follows that, as a function of the class,

$$P(C=j|\mathbf{x}) \propto e^{\mathbf{w}_j^T\mathbf{x}+\mathbf{b}_j}$$

Since we have a closed-set classification problem, then

$$\sum_{j=1}^{K} P(C=j|\mathbf{x}) = 1$$

The normalization factor for P(C = j|x) is thus

$$\sum_{j=1}^{K} e^{\mathbf{w}_{j}^{T}\mathbf{x} + \mathbf{b}_{j}}$$

and the posterior probability correponds to

$$P(C = k|\mathbf{x}) = \frac{e^{\mathbf{w}_k^T \mathbf{x} + b_k}}{\sum_j e^{\mathbf{w}_j^T \mathbf{x} + b_j}}$$

Function
$$f(s) = \left[\frac{e^{s_1}}{\sum_j e^{s_j}}, \dots, \frac{e^{s_K}}{\sum_j e^{s_j}}\right]$$
 is called softmax

Given the model parameters

$$\mathbf{W} = \begin{bmatrix} \mathbf{w}_1 & \dots & \mathbf{w}_K \end{bmatrix} , \quad \mathbf{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_K \end{bmatrix}$$

the logistic regression model allows computing the probability of each class

$$P(C = k | \boldsymbol{W}, \boldsymbol{b}, \boldsymbol{x}) = \frac{e^{\boldsymbol{w}_k^T \boldsymbol{x} + b_k}}{\sum_j e^{\boldsymbol{w}_j^T \boldsymbol{x} + b_j}}$$

If we consider sample x_i , its class posterior distribution is thus a categorical distribution

$$C_i|\mathbf{W},\mathbf{b},\mathbf{X}_i=\mathbf{x}_i\sim \mathrm{Cat}(\mathbf{y}_i)$$

where

$$\mathbf{y}_{ik} = \frac{e^{\mathbf{w}_k^T \mathbf{x}_i + b_k}}{\sum_i e^{\mathbf{w}_i^T \mathbf{x}_i + b_i}}$$

As for the binary case, we can express the log-probability of the training class labels as

$$\ell(\boldsymbol{W}, \boldsymbol{b}) = \sum_{i=1}^{n} \log P(C_i = c_i | \boldsymbol{X}_i = \boldsymbol{x}_i, \boldsymbol{W}, \boldsymbol{b})$$

Remember that the categorical density $P(C_i = c_i | X_i = x_i, W, b)$ can be expressed using a 1-of-K encoding, as

$$\log P(C_i = c_i | \boldsymbol{X}_i = \boldsymbol{x}_i, \boldsymbol{W}, \boldsymbol{b}) = \log P(C_i = c_i | \boldsymbol{y}_i) = \sum_{k=1}^K \boldsymbol{z}_{ik} \log \boldsymbol{y}_{ik}$$

where z_i is a vectors that has all component equal to 0, except for the index c_i which is equal to 1

$$z_i = [0 \dots 0, 1, 0 \dots 0]$$
 , $z_{ik} = \begin{cases} 1 & \text{if } c_i = k \\ 0 & \text{otherwise} \end{cases}$

The labels log-probability can thus be expressed as

$$\ell(\boldsymbol{W}, \boldsymbol{b}) = \sum_{i=1}^{n} \sum_{k=1}^{K} z_{ik} \log \boldsymbol{y}_{ik}$$

The terms y_{ik} are, again,

$$\mathbf{y}_{ik} = \frac{e^{\mathbf{w}_k^T \mathbf{x}_i + b_k}}{\sum_j e^{\mathbf{w}_j^T \mathbf{x}_i + b_j}}$$

and represent the distribution for the class labels according to the Logistic Regression model

As for the binary case, the expression

$$H(z_i, \mathbf{y}_i) = -\sum_{k=1}^K z_{ik} \log \mathbf{y}_{ik}$$

represents the (multiclass) cross-entropy between the observed and predicted label distributions for sample x_i

As for the binary case, we estimate W and b as to maximize the likelihood for the training labels

The ML solution is again the solution that minimizes the (average) cross-entropy:

$$\arg \max_{\boldsymbol{W},\boldsymbol{b}} \ell(\boldsymbol{W},\boldsymbol{b}) = \arg \max_{\boldsymbol{W},\boldsymbol{b}} \left[-\sum_{i=1}^n H(z_i,\boldsymbol{y}_i) \right] = \arg \min_{\boldsymbol{W},\boldsymbol{b}} \sum_{i=1}^n H(z_i,\boldsymbol{y}_i)$$

Compared to the binary case, the model is over-parametrized (i.e., we can add a constant vector to all terms w_i without changing the model)

In particular, for a 2-class problem, if we subtract w_2 from both w_1 and w_2 , we recover exactly the binary logistic regression objective.

Finally, as for the binary class, we can cast the problem as a minimization of a loss function

We rewrite the objective in terms of class labels c as

$$J(\boldsymbol{W}, \boldsymbol{b}) = -\sum_{i=1}^{n} \sum_{k=1}^{K} z_{ik} \log y_{ik}$$

$$= -\sum_{i=1}^{n} \log \frac{e^{\boldsymbol{w}_{c_{i}}^{T} \boldsymbol{x}_{i} + b_{c_{i}}}}{\sum_{c'=1}^{K} e^{\boldsymbol{w}_{c'}^{T} \boldsymbol{x} + b_{c'}}}$$

$$= \sum_{i=1}^{n} \left[\log \left(\sum_{c'=1}^{K} e^{\boldsymbol{w}_{c'}^{T} \boldsymbol{x} + b_{c'}} \right) - \boldsymbol{w}_{c_{i}}^{T} \boldsymbol{x}_{i} - b_{c_{i}} \right]$$

$$= \sum_{i=1}^{n} l(\boldsymbol{x}_{i}, c_{i}, \boldsymbol{W}, \boldsymbol{b})$$

l is also called softmax loss

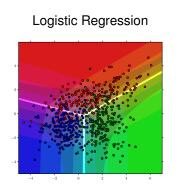
Again, we can add a regularization term to reduce over-fitting. We thus look for the minimizer of

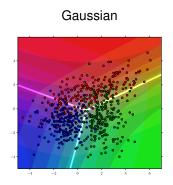
$$R(\mathbf{W}, \mathbf{b}) = \Omega(\mathbf{W}) + \frac{1}{n} J(\mathbf{W}, \mathbf{b})$$

Different regularizers can be used, for example

$$\Omega(\mathbf{w}_1,\ldots,\mathbf{w}_N) = \frac{1}{2} \sum_i \|\mathbf{w}_i\|^2$$

Again, we can replace the average cross-entropy with prior-weighted average cross entropy to account for priors that are different from the empirical training set prior





MNIST — Error rates for Logistic Regression

DimRed	$\lambda = 0$	$\lambda = 0.00001$	$\lambda = 0.001$	$\lambda = 0.1$	Tied Gau
RAW [768]	8.0%	7.4%	7.9%	12.9%	–
PCA [50]	8.8%	8.8%	8.9%	13.3%	12.6 %
PCA [100]	7.8%	7.8%	8.2%	12.9%	12.3%
PCA+LDA [9]	10.9%	10.9%	11.0%	12.4%	12.3 %

The multiclass logistic regression performs better than the Gaussian model — indeed, the Gaussian assumption is not very accurate for the features we are considering. LogReg assumes linear separation, but does not assume a specific distribution for the features

Again, regularization is important, especially when the feature space is large

Linear logistic regression on MNIST performs better than our Tied-Covariance Gaussian classifier, however it's far worse than our non-linear Gaussian classifier

Remember that, for binary LR, we assumed linear separation surfaces

$$\log \frac{P(C = h_1 | \mathbf{x})}{P(C = h_0 | \mathbf{x})} = \mathbf{w}^T \mathbf{x} + b$$

which has the same form as the Gaussian classifier with tied covariance

For Gaussian classifier with non-tied covariances we have

$$\log \frac{P(C = h_1|\mathbf{x})}{P(C = h_0|\mathbf{x})} = \mathbf{x}^T \mathbf{A} \mathbf{x} + \mathbf{b}^T \mathbf{x} + c = s(\mathbf{x}, \mathbf{A}, \mathbf{b}, c)$$

The expression

$$s(\mathbf{x}, \mathbf{A}, \mathbf{b}, c) = \mathbf{x}^T \mathbf{A} \mathbf{x} + \mathbf{b}^T \mathbf{x} + c$$

is quadratic in x, however it is linear in A and b

Indeed, we can rewrite s(x, A, b, c) as

$$s(\mathbf{x}, \mathbf{A}, \mathbf{b}, c) = \langle \mathbf{x} \mathbf{x}^T, \mathbf{A} \rangle + \mathbf{b}^T \mathbf{x} + c$$

where $\langle \cdot, \cdot \rangle$ denotes the inner product

$$\langle \boldsymbol{A}, \boldsymbol{B} \rangle = \sum_{i} \sum_{j} \boldsymbol{A}_{ij} \boldsymbol{B}_{ij}$$

We can further express $\langle A, xx^T \rangle$ as

$$\langle A, xx^T \rangle = \text{vec}(xx^T)^T \text{vec}(A)$$

vec(M) is the operator that stacks the columns of matrix M

If we define

$$\phi(x) = \begin{bmatrix} \operatorname{vec}(xx^T) \\ x \end{bmatrix}$$

and

$$w = \begin{bmatrix} \operatorname{vec}(A) \\ b \end{bmatrix}$$

then the class log-posterior ratio can be expressed as

$$s(\mathbf{x}, \mathbf{w}, c) = \mathbf{w}^T \phi(\mathbf{x}) + c$$

We can thus train a LR model using feature vectors $\phi(x)$ rather than x

We will obtain a model that has linear separation surface in the space defined by the mapping ϕ

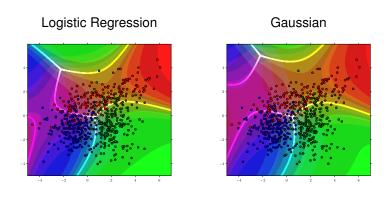
This space is also called expanded feature space

The LR model (both binary and multiclass) allows computing linear separation rules for the transformed features $\phi(x)$

Since expressions $\mathbf{w}^T \phi(\mathbf{x}) + c$ correspond to quadratic forms in the original feature space, we are actually estimating quadratic separation surfaces in the original space

In general, we can consider a transformation $\phi(x)$ of our feature space such that our classes are (approximately) linearly separable in the expanded feature space

We have to pay attention that the dimensionality of the expanded feature space can grow very quickly — For example, polynomial expansions of degree d result in a feature space of dimensionality $O(M^d)$, where M is the dimensionality of x.



MNIST — Average pairwise EER for LR with quadratic feature expansion

DimRed	$\lambda = 0$	$\lambda = 1e^{-5}$	$\lambda = 1e^{-3}$	$\lambda = 1e^{-1}$	Gaussian
PCA [50]	1.0%	1.0%	0.9%	1.5%	0.8%

MNIST — Multiclass error rates for LR with quadratic feature expansion

DimRed	$\lambda = 0$	$\lambda = 1e^{-5}$	$\lambda = 1e^{-3}$	$\lambda = 1e^{-1}$	Gaussian
PCA [50]	2.3%	1.9%	1.7%	3.1%	3.6%

Among possible non-linear methods we will consider, depending on the course (01URTOV / 01HERUU):

- Support Vector Machines, that allow defining linear models in an implicitly expanded feature space
- Neural networks, that allow jointly estimating a parametric transformation $\phi(x,\Pi)$ and a classification rule (w,b) in the expanded feature space