

Models for Non-Stationary Time Series: ARIMA Processes - Part I

Week VII: Video 19

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Our Roadmap

1 Key Ideas:

- **Intro and fundamental concepts (Ch. 1-2):** Means, autocovariances and autocorrelations of time series, and the concept of stationarity.
- **Estimating trends (Ch. 3):** Temporarily ignoring the rest of the variability in the series, how do we just estimate the mean trend?
- **Models for stationary time series (Ch. 4):** These are the bulk of the key time series models that will be useful to us: MA, AR and ARMA models.
- **Models for non-stationary time series (Ch. 5):** Differencing (ARIMA models), transformations, and adding non-zero mean terms.

2 Building a Model: Model specification (Ch. 6), Parameter estimation (Ch. 7), Model diagnostics (Ch. 8)

3 Forecasting (Ch. 9)

4 Other topics, as time permits.

Models for Non-Stationary Time Series: Introduction

In Chapter 4 (Week 5 & 6 videos), we considered only stationary time series (with zero means), and we developed several models for them: MA, AR and ARMA models.

In Chapter 5 (Week 7 videos), we consider what can be done when the process of interest is *not* stationary (or if it has a constant non-zero mean).

Some techniques we will learn:

- Differencing to obtain a stationary series from a non-stationary one (“ARIMA models”)
- Taking transformations to obtain a stationary series from a non-stationary one
- Adding a constant term if the mean is non-zero

Video 19 Learning Objectives

By the end of this video, we should be able to:

- Describe the importance of stationarity for an ARMA process
- Define an integrated autoregressive moving average process of orders p and q and degree d , i.e. $\text{ARIMA}(p,d,q)$
- Given a process that looks like an ARMA process, identify whether or not it is stationary. If not, use differencing to obtain a stationary process
- After using differencing to obtain a stationary process, identify the original process as an ARIMA process and identify the values of p , d and q

Why Is Stationarity Important?

Consider the following “AR(1)” model:

$$Y_t = 5Y_{t-1} + e_t$$

This model is not stationary, because: $|\phi| = |5| = 5 \not< 1$.

Why Is Stationarity Important?

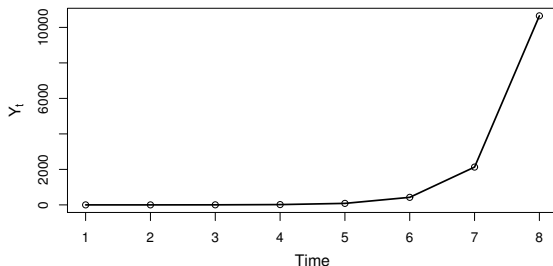
Consider the following “AR(1)” model:

$$Y_t = 5Y_{t-1} + e_t$$

This model is not stationary, because: $|\phi| = |5| = 5 \neq 1$.

In our Chapter 4 videos, we relied on stationarity in our derivations for the autocovariance and autocorrelation functions of the AR models.

Also: How does this “AR(1)” process behave?



Stationarity Through Differencing: Example 1

Recall: The **random walk process** is defined as

$$Y_t = Y_{t-1} + e_t$$

Its mean and autocovariance function are (Video 14, slides 13-14):

$$\mu_t = 0$$

$$\gamma_{t,s} = \min\{t, s\} \sigma_e^2$$

So, $\{Y_t\}$ is *not* weakly stationary.

(Note also: This is an “AR(1)” process with $\phi = 1$.)

Stationarity Through Differencing: Example 1 (cont'd)

Recall: The **differenced series** of a process $\{Y_t\}$ defined as

$$\nabla Y_t = Y_t - Y_{t-1}$$

Let $W_t = \nabla Y_t$. Then, for the random walk process:

$$Y_t = Y_{t-1} + e_t$$

$$Y_t - Y_{t-1} = e_t$$

$$W_t = e_t$$

So, $\{W_t\} = \{\nabla Y_t\}$ is weakly stationary!

Stationarity Through Differencing: Example 2

Consider the process:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

This appears to be an “ARMA(2,1)” process.

Stationarity Through Differencing: Example 2

Consider the process:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

This appears to be an “ARMA(2,1)” process.

However, the stationarity conditions are not met:

- The stationarity conditions for an ARMA(p,q) are the same as for the AR(p) model. When $p = 2$, these conditions are:

$$\phi_1 + \phi_2 < 1 \quad \& \quad \phi_2 - \phi_1 < 1 \quad \& \quad |\phi_2| < 1$$

Check: $\phi_1 + \phi_2 = 1.5 - 0.5 = 1 \not< 1$

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Can we transform this into a stationary process through differencing?

Stationarity Through Differencing: Example 2 (cont'd)

Let $W_t = \nabla Y_t$. Then:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

$$Y_t - Y_{t-1} = 0.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

$$W_t = 0.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

$$W_t = 0.5(Y_{t-1} - Y_{t-2}) + e_t - 0.1e_{t-1}$$

$$W_t = 0.5W_{t-1} + e_t - 0.1e_{t-1}$$

This looks like an ARMA(1,1).

Stationarity Through Differencing: Example 2 (cont'd)

Let $W_t = \nabla Y_t$. Then:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

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$$W_t = 0.5W_{t-1} + e_t - 0.1e_{t-1}$$

This looks like an ARMA(1,1).

Check the stationarity condition, for $p = 1$: $|\phi| = |0.5| = 0.5 < 1$ ✓

So, $\{W_t\} = \{\nabla Y_t\}$ is a stationary ARMA(1,1) process!

The ARIMA(p, d, q) Process

Definition: A process $\{Y_t\}$ is said to be an **integrated autoregressive moving average process of orders p and q and degree d** (i.e. **ARIMA(p, d, q)**) if:

The d^{th} difference $W_t = \nabla^d Y_t$ is a stationary ARMA(p, q) process.

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The d^{th} difference $W_t = \nabla^d Y_t$ is a stationary ARMA(p, q) process.

In other words:

$$\begin{aligned} W_t = & \phi_1 W_{t-1} + \phi_2 W_{t-2} + \cdots + \phi_p W_{t-p} \\ & + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \cdots - \theta_q e_{t-q} \end{aligned}$$

for some $\phi_1, \phi_2, \dots, \phi_p, \theta_1, \theta_2, \dots, \theta_q$.

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for some $\phi_1, \phi_2, \dots, \phi_p, \theta_1, \theta_2, \dots, \theta_q$.

In most cases, $d = 1$ or $d = 2$ will suffice.

If there are no AR terms in $\{W_t\}$: $\{Y_t\}$ is ARIMA($0, d, q$) = **IMA(d, q)**.

If there are no MA terms in $\{W_t\}$: $\{Y_t\}$ is ARIMA($p, d, 0$) = **ARI(p, d)**.

Re-Writing Y_t in Difference Equation Form

Suppose $\{Y_t\}$ is an ARIMA($p, 1, q$) process.

Then: $W_t = \nabla Y_t = Y_t - Y_{t-1}$.

Therefore:

$$W_t = \phi_1 W_{t-1} + \phi_2 W_{t-2} + \cdots + \phi_p W_{t-p} \\ + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \cdots - \theta_q e_{t-q}$$

$$Y_t - Y_{t-1} = \phi_1(Y_{t-1} - Y_{t-2}) + \phi_2(Y_{t-2} - Y_{t-3}) + \cdots + \phi_p(Y_{t-p} - Y_{t-p-1}) \\ + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \cdots - \theta_q e_{t-q}$$

$$Y_t = (1 + \phi_1)Y_{t-1} + (\phi_2 - \phi_1)Y_{t-2} + (\phi_3 - \phi_2)Y_{t-3} + \cdots \\ + (\phi_p - \phi_{p-1})Y_{t-p} - \phi_p Y_{t-p-1} \\ + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \cdots - \theta_q e_{t-q}$$

So, $\{Y_t\}$ can be written as a non-stationary “ARMA($p + 1, q$)” process.

This is called the **difference equation form** of the model.

Re-Writing Y_t in Difference Equation Form (cont'd)

Suppose $\{Y_t\}$ is an ARIMA($p, 2, q$) process.

Then:

$$\begin{aligned}W_t &= \nabla^2 Y_t \\&= \nabla(\nabla Y_t) \\&= \nabla(Y_t - Y_{t-1}) \\&= (Y_t - Y_{t-1}) - (Y_{t-1} - Y_{t-2}) \\&= Y_t - 2Y_{t-1} + Y_{t-2}\end{aligned}$$

Then, in its difference equation form, $\{Y_t\}$ can be written as a non-stationary “ARMA($p + 2, q$)” process.

Re-Writing Y_t in Difference Equation Form: Usefulness

We've seen that:

- An ARIMA($p, 1, q$) process can look like a non-stationary “ARMA($p + 1, q$)” process
- An ARIMA($p, 2, q$) process can look like a non-stationary “ARMA($p + 2, q$)” process

Re-Writing Y_t in Difference Equation Form: Usefulness

We've seen that:

- An ARIMA($p, 1, q$) process can look like a non-stationary “ARMA($p + 1, q$)” process
- An ARIMA($p, 2, q$) process can look like a non-stationary “ARMA($p + 2, q$)” process

Therefore:

- If we see a non-stationary ARMA process $\{Y_t\}$, and its *first difference* $\{W_t\} = \{\nabla Y_t\}$ turns out to be stationary, we should expect $\{W_t\}$ to have an AR order that is *one less* than that of the original process
- If we see a non-stationary ARMA process $\{Y_t\}$, and its *second difference* $\{W_t\} = \{\nabla^2 Y_t\}$ turns out to be stationary, we should expect $\{W_t\}$ to have an AR order that is *two less* than that of the original process

ARIMA($p, 1, q$) Example

Consider the process we saw earlier:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

This appears to be an “ARMA(2,1)” process.

However, the stationarity conditions are not met:

- The stationarity conditions for an ARMA(p, q) are the same as for the AR(p) model. When $p = 2$, these conditions are:

$$\phi_1 + \phi_2 < 1 \quad \& \quad \phi_2 - \phi_1 < 1 \quad \& \quad |\phi_2| < 1$$

Check: $\phi_1 + \phi_2 = 1.5 - 0.5 = 1 \not< 1$

ARIMA($p,1,q$) Example (cont'd)

Let $W_t = \nabla Y_t$. Then:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

$$Y_t - Y_{t-1} = 0.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

$$W_t = 0.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

$$W_t = 0.5(Y_{t-1} - Y_{t-2}) + e_t - 0.1e_{t-1}$$

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ARIMA($p, 1, q$) Example (cont'd)

Let $W_t = \nabla Y_t$. Then:

$$Y_t = 1.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

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$$W_t = 0.5Y_{t-1} - 0.5Y_{t-2} + e_t - 0.1e_{t-1}$$

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$$W_t = 0.5W_{t-1} + e_t - 0.1e_{t-1}$$

This looks like an ARMA(1,1).

Check the stationarity condition, for $p = 1$: $|\phi| = |0.5| = 0.5 < 1$ ✓

So, $\{W_t\} = \{\nabla Y_t\}$ is a stationary ARMA(1,1) process! (Notice: The AR order went down by one.)

Conclusion: $\{Y_t\}$ is an ARIMA(1,1,1) process!

ARIMA($p, 1, q$) Example 2

The random walk process is defined as

$$Y_t = Y_{t-1} + e_t$$

It looks like an “AR(1)” (i.e., “ARMA(1,0)”) process.

However, its stationarity condition is not met: $|\phi| = |1| = 1 \not< 1$

ARIMA($p, 1, q$) Example 2

The random walk process is defined as

$$Y_t = Y_{t-1} + e_t$$

It looks like an “AR(1)” (i.e., “ARMA(1,0)”) process.

However, its stationarity condition is not met: $|\phi| = |1| = 1 \not< 1$

Let $W_t = \nabla Y_t$. Then:

$$Y_t = Y_{t-1} + e_t$$

$$Y_t - Y_{t-1} = e_t$$

$$W_t = e_t$$

ARIMA($p,1,q$) Example 2

The random walk process is defined as

$$Y_t = Y_{t-1} + e_t$$

It looks like an “AR(1)” (i.e., “ARMA(1,0)”) process.

However, its stationarity condition is not met: $|\phi| = |1| = 1 \not< 1$

Let $W_t = \nabla Y_t$. Then:

$$Y_t = Y_{t-1} + e_t$$

$$Y_t - Y_{t-1} = e_t$$

$$W_t = e_t$$

This is just a white noise process, i.e. ARMA(0,0). It is stationary.

So, $\{W_t\} = \{\nabla Y_t\}$ is a stationary ARMA(0,0) process! (Notice: The AR order went down by one.)

Conclusion: $\{Y_t\}$ is an ARIMA(0,1,0) process!

ARIMA($p,2,q$) Example

Consider the following process:

$$Y_t = 2Y_{t-1} - Y_{t-2} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

This appears to be an “ARMA(2,2)” process.

However, the stationarity conditions are not met:

- Conditions for $p = 2$:

$$\phi_1 + \phi_2 < 1 \quad \& \quad \phi_2 - \phi_1 < 1 \quad \& \quad |\phi_2| < 1$$

- Check: $\phi_1 + \phi_2 = 2 - 1 = 1 \not< 1$

ARIMA($p, 2, q$) Example (cont'd)

Let $W_t = \nabla Y_t$. Then:

$$Y_t = 2Y_{t-1} - Y_{t-2} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$Y_t - Y_{t-1} = Y_{t-1} - Y_{t-2} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W_t = (Y_{t-1} - Y_{t-2}) + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W_t = W_{t-1} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

ARIMA($p, 2, q$) Example (cont'd)

Let $W_t = \nabla Y_t$. Then:

$$Y_t = 2Y_{t-1} - Y_{t-2} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$Y_t - Y_{t-1} = Y_{t-1} - Y_{t-2} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W_t = (Y_{t-1} - Y_{t-2}) + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W_t = W_{t-1} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

This looks like an ARMA(1,2).

Check the stationarity condition, for $p = 1$: $|\phi| = |1| = 1 \not< 1$

So, $\{\nabla Y_t\}$ is not stationary, either.

ARIMA($p, 2, q$) Example (cont'd)

Let $W'_t = \nabla^2 Y_t = \nabla W_t$. Then:

$$W_t = W_{t-1} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W_t - W_{t-1} = e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W'_t = e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

ARIMA($p,2,q$) Example (cont'd)

Let $W'_t = \nabla^2 Y_t = \nabla W_t$. Then:

$$W_t = W_{t-1} + e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W_t - W_{t-1} = e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

$$W'_t = e_t - 0.4e_{t-1} - 0.2e_{t-2}$$

This looks like an MA(2), i.e. ARMA(0,2). It is stationary.

So, $\{W'_t\} = \{\nabla^2 Y_t\}$ is a stationary ARMA(0,2) process! (Notice: The AR order went down by two from the original process.)

Conclusion: $\{Y_t\}$ is an ARIMA(0,2,2) process! This is also referred to as an IMA(2,2) process.

Final Comments

That's all for now!

In this video, we've seen some examples of how a non-stationary process can be transformed into a stationary process through differencing.

We've also defined the integrated autoregressive moving average process of orders p and q and degree d , i.e. $ARIMA(p,d,q)$.

Finally, we've seen some examples of how to identify an ARIMA process, and obtain stationarity through differencing.

Coming Up Next: Some more properties and examples of ARIMA processes.

Thank you!

References:

- [1] Cryer, J. D., & Chan, K. S. (2008). *Time series analysis: with applications in R*. Springer Science and Business Media.
- [2] Chan, K. S., & Ripley, B. (2020). TSA: Time Series Analysis. R package version 1.2.1.