# Models for Stationary Time Series:

**ARMA Processes** 

Week VI: Video 18

STAT 485/685, Fall 2020, SFU

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## Video 18 Learning Objectives

By the end of this video, we should be able to:

- Define an autoregressive moving average process of orders p and q, i.e. ARMA(p,q)
- Give the mean function, autocovariance function and autocorrelation function for the ARMA(1,1) process
- Recognize that ARMA(p,q) is a very general class of model, which can be used to describe many different types of time series behaviours

#### Autoregressive Moving Average Processes

Review: Moving average process of order q (i.e. MA(q)):

$$Y_t = e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \theta_3 e_{t-3} - \dots - \theta_q e_{t-q}$$

Autoregressive process of order p (i.e. AR(p)):

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + e_t$$

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Definition: An autoregressive moving average process of orders p and q (i.e. ARMA(p,q)) is defined as:

$$Y_{t} = \phi_{1} Y_{t-1} + \phi_{2} Y_{t-2} + \dots + \phi_{p} Y_{t-p} + e_{t}$$
$$-\theta_{1} e_{t-1} - \theta_{2} e_{t-2} - \dots - \theta_{q} e_{t-q}$$

(Also sometimes referred to as a "mixed autoregressive moving average process".)

#### Autoregressive Moving Average Processes (cont'd)

ARMA(p,q) process:

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This is a convenient model, because it incorporates:

- Linear combination of the past values of the variable (i.e., the "AR" part)
- Linear combination of white noise terms occurring at various times in the past (i.e., the "MA" part)

#### Autoregressive Moving Average Processes (cont'd)

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The  $e_t$ 's are assumed to be zero-mean white noise terms, with variance  $\sigma_e^2$ . They are independent of all past Y's.

AR and MA processes can be thought of as "special cases" of an ARMA process.

#### The ARMA(1,1) Process

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- Autocovariance function:

$$Y_{t-k}Y_{t} = \phi Y_{t-k}Y_{t-1} + Y_{t-k}e_{t} - \theta Y_{t-k}e_{t-1}$$

$$E(Y_{t-k}Y_t) = \phi E(Y_{t-k}Y_{t-1}) + E(Y_{t-k}e_t) - \theta E(Y_{t-k}e_{t-1})$$

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Note:

• 
$$E(Y_{t-k}Y_t) = Cov(Y_{t-k}, Y_t) + E(Y_{t-k})E(Y_t) = Cov(Y_{t-k}, Y_t) = \gamma_k$$

• 
$$E(Y_{t-k}Y_{t-1}) = Cov(Y_{t-k}, Y_{t-1}) = \gamma_{k-1}$$

$$\gamma_k = \phi \gamma_{k-1} + E(Y_{t-k}e_t) - \theta E(Y_{t-k}e_{t-1})$$

• Autocovariance function:

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#### Now:

• What about  $E(Y_{t-k}e_t)$ ?

If 
$$k = 0$$
:  $E(Y_t e_t) = E[(\phi Y_{t-1} + e_t - \theta e_{t-1})e_t] = E(e_t^2) = \sigma_e^2$   
(since  $e_t \perp \!\!\! \perp Y_{t-1}$ , and  $e_t \perp \!\!\! \perp e_{t-1}$ )

If k > 0:  $E(Y_{t-k}e_t) = 0$  (since  $e_t$  is independent of any past Y's)

Autocovariance function:

$$\gamma_k = \phi \gamma_{k-1} + E(Y_{t-k}e_t) - \theta E(Y_{t-k}e_{t-1})$$

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• What about  $E(Y_{t-k}e_{t-1})$ ?

If 
$$k = 0$$
:  $E(Y_t e_{t-1}) = E[(\phi Y_{t-1} + e_t - \theta e_{t-1})e_{t-1}] = \phi \sigma_e^2 - \theta \sigma_e^2$ 

If 
$$k = 1$$
:  $E(Y_{t-1}e_{t-1}) = \cdots = \sigma_e^2$ 

If 
$$k > 1$$
:  $E(Y_{t-k}e_{t-1}) = 0$ 

Autocovariance function:

$$\gamma_k = \phi \gamma_{k-1} + E(Y_{t-k}e_t) - \theta E(Y_{t-k}e_{t-1})$$

where

$$E(Y_{t-k}e_t) = \begin{cases} \sigma_e^2 & \text{for } k = 0\\ 0 & \text{for } k > 0 \end{cases}$$

$$E(Y_{t-k}e_{t-1}) = \begin{cases} (\phi - \theta)\sigma_e^2 & \text{for } k = 0\\ \sigma_e^2 & \text{for } k = 1\\ 0 & \text{for } k > 1 \end{cases}$$

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So:

$$\begin{cases} \gamma_0 = \phi \, \gamma_1 + \sigma_e^2 - \theta(\phi - \theta)\sigma_e^2 = \phi \, \gamma_1 + [1 - \theta(\phi - \theta)]\sigma_e^2 \\ \gamma_1 = \phi \, \gamma_0 - \theta\sigma_e^2 \\ \gamma_k = \phi \, \gamma_{k-1} & \text{for all } k \ge 2 \end{cases}$$

• Autocovariance function:

$$\gamma_k = \begin{cases} \frac{1 - 2\phi\theta + \theta^2}{1 - \phi^2} \sigma_e^2 & \text{for } k = 0 \\ \phi \, \gamma_0 - \theta \sigma_e^2 & \text{for } k = 1 \\ \phi \, \gamma_{k-1} & \text{for all } k \geq 2 \end{cases}$$

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Autocorrelation function:

$$\begin{cases} \rho_0 = 1\\ \rho_1 = \frac{\gamma_1}{\gamma_0} = \phi - \frac{\theta \sigma_e^2}{\gamma_0} = \dots = \frac{(1 - \phi \theta)(\phi - \theta)}{1 - 2\phi \theta + \theta^2}\\ \rho_k = \frac{\gamma_k}{\gamma_0} = \frac{\phi \gamma_{k-1}}{\gamma_0} = \phi \rho_{k-1} & \text{for all } k \ge 2 \end{cases}$$

Autocovariance function:

$$\gamma_k = \begin{cases} \frac{1 - 2\phi\theta + \theta^2}{1 - \phi^2} \sigma_e^2 & \text{for } k = 0\\ \phi \, \gamma_0 - \theta \sigma_e^2 & \text{for } k = 1\\ \phi \, \gamma_{k-1} & \text{for all } k \geq 2 \end{cases}$$

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So:

$$\rho_k = \begin{cases} 1 & \text{for } k = 0 \\ \phi^{k-1} \frac{(1-\phi\theta)(\phi-\theta)}{1-2\phi\theta+\theta^2} & \text{for all } k \ge 1 \end{cases}$$

Autocovariance function:

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So:

$$ho_k = egin{cases} 1 & ext{for } k = 0 \ \phi^{k-1} rac{(1-\phi heta)(\phi- heta)}{1-2\phi heta+ heta^2} & ext{for all } k \geq 1 \end{cases}$$

Notice: The correlation is exponentially decreasing in k!

#### The ARMA(p,q) Process: Properties

Autocorrelation function satisfies:

$$\rho_k = \phi_1 \rho_{k-1} + \phi_2 \rho_{k-2} + \dots + \phi_p \rho_{k-p}$$

The shape of  $\rho_k$  can look very different, depending on the values of the  $\phi$ 's and  $\theta$ 's.

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• It can be shown that the ARMA(p,q) is stationary if and only if each of the p roots of the AR characteristic equation is > 1 in absolute value:

$$1 - \phi_1 x - \phi_2 x^2 - \dots - \phi_p x^p = 0$$

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• The (stationary) ARMA(1,1) process can be re-written as:

$$Y_t = e_t + (\phi - \theta)[e_{t-1} + \phi e_{t-2} + \phi^2 e_{t-3} + \phi^3 e_{t-4} + \dots]$$

So, it is a general linear process with weights  $\psi_j = (\phi - \theta)\phi^{j-1}$ .

The general (stationary) ARMA(p,q) process can also be re-written as a general linear process (see pg. 79).

#### **Final Comments**

That's all for now!

In this video, we've learned about the autoregressive moving average process of orders p and q, i.e. ARMA(p,q).

We derived some properties for the special case of ARMA(1,1), and we learned about some properties of ARMA(p,q) as well.

We are now equipped with a very general class of time series models, which are useful for representing many, many different types of behaviour!

Next Week in STAT 485/685: Models for non-stationary time series.

## Thank you!

#### References:

- Cryer, J. D., & Chan, K. S. (2008). Time series analysis: with applications in R. Springer Science and Business Media.
- [2] Chan, K. S., & Ripley, B. (2020). TSA: Time Series Analysis. R package version 1.2.1.