



UNIVERSITÀ DEGLI STUDI DI TORINO
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**Ising Model Simulation with Monte Carlo
methods**

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Abstract

In this work is introduced the Last Mile problem and the Agent-Based modelling process. A solution for the Last Mile problem is proposed suggesting an active engagement of the population. Some estimation has been done in order to make the simulation suitable for representing the city of Turin and actual cost of the delivering process. Results show the robustness of the proposed solution both in economical and user's engagement terms, discussing also extreme situation.

Introduction

The Ising model is a well studied model in Statistical Mechanics which describes ferromagnetism phenomena. It is characterized by a microscopic configuration space based on D -dimensional lattice, that brings to macroscopic statistical quantities. Moreover it can easily generalize the concept of collective effects caused by binary valued points interacting in pairs; for this reason the Ising model became the core of the physics of complex systems. In the last decades computational methods have been applied to search a numerical solution for the 3D Ising model in order to fill the lack of an analytical solution. Alongside Metropolis algorithm became the most popular method of important sampling in MC. The basic idea of a weighted sampling based on the importance of a region determined a great step for the numerical solutions in general. Under these premises we want to outline the purpose this work wants to pursue: finding numerical solution of the ND -dimensional Ising model with Metropolis algorithm.

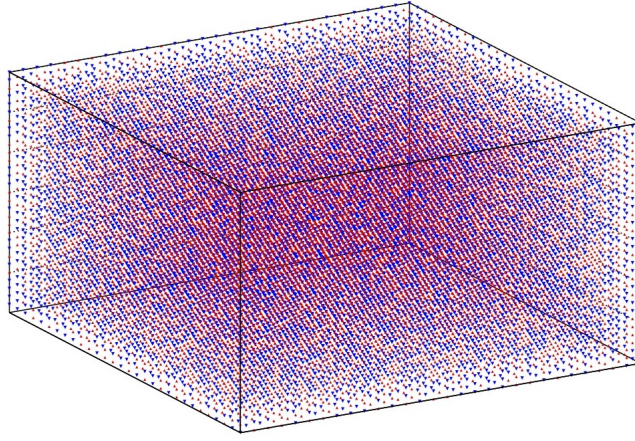


Figure 1: High temperature simulation of 3D Ising model

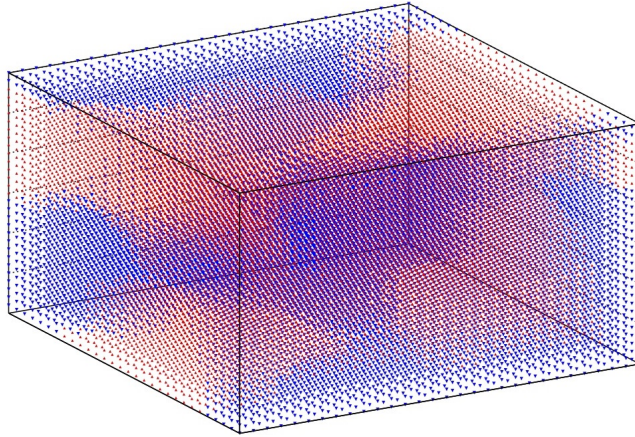


Figure 2: Low temperature simulation of 3D Ising model

1 Theory

1.1 Ising model and importance sampling

The Ising model is a physical-mathematical model characterized by a lattice of local spins in the $[-1; +1]$ domain. The correspondent energy is proportional to the quadratic interaction of near spins (σ_i):

$$H(q, \sigma) = \sum_{\langle i, m \rangle} -J\sigma_i\sigma_j \quad (1)$$

Where J is the energy interaction term and we sum over the neighbours.

The system has a macroscopic equilibrium state (macrostate) described by statistical quantities: number of spins N , lattice volume V , energy E , magnetization M . According to the Statistical Mechanics theory we consider the thermodynamic limit, i.e. $N, V \rightarrow \infty$ and $N/V = \text{const}$ in order to have negligible fluctuations on energy and magnetisation: $(\Delta E)^2 / \langle E \rangle = O(1/\sqrt{N})$. From a theoretical point of view we consider an ensemble of lattices, each one with a particular configuration of spins (microstate) that corresponds to the same macrostate; we underlying that all microstates are independent and equiprobable. The configuration space is described through the Hamiltonian formalism indeed, under ergodic hypothesis, the system visits all microstates. Moreover stationary hypothesis implies the existence of an equilibrium state in which the probability distribution of the microstates satisfies the Liouville theorem. These hypotheses bring respectively to the following statements:

1. In the $t \rightarrow \infty$ limit: the average (over all the ensemble) of a physical quantity is equal to the temporal average of that quantity.
2. The probability distribution of the microstates depends only on the Hamiltonian:

$$\rho(q, \sigma) \propto \exp\{-\beta H(q, \sigma)\} \quad (2)$$

Where q is the spin position on the lattice and β is the product of the Boltzmann constant and the temperature T of the system.

In a finite case the Ising model system is characterized by magnetization and energy fluctuations that brings us to consider it under canonical formalism. We define the partition function as follow: $Z = \sum_q \exp[-\beta H(q)]$. The model simulation can be done through Monte Carlo method, i.e. we generate a pseudo-random chain of numbers in order to extract a microstate sample (from all the configuration space) distributed by the following equilibrium distribution of probability:

$$P_{eq}(q) = \exp\{-\beta H(q)\} / Z \quad (3)$$

In practice we cannot compute the partition function, moreover an algorithm that search over all the phase space has not a great performance.

The Boltzmann's factor as probability of choosing a configuration gives a great improvement for the simulation. In this way we are not sampling all the configuration space but a selected and uniform distributed microstates collection. This approach is called *importance sampling* and it allows us to calculate physical quantities as the average number over the extracted configuration:

$$\langle E \rangle_N = \frac{1}{N} \sum_{i=1}^N E(q_i)$$

This intuition can be proved under ergodic hypothesis: in fact we can consider an evolving Ising system in which there is a spin flip at each time step. The temporal collection of microstates is a Markov chain with a transition probability (W) that leads the system to the unique equilibrium probability in the $t \rightarrow \infty$ limit. Indeed the ratio of the transition probability is:

$$\frac{W(q \rightarrow q')}{W(q' \rightarrow q)} = \frac{P_{eq}(q')}{P_{eq}(q)} = \exp\{\beta[E(q) - E(q')]\} \quad (4)$$

Where q and q' are respectively the configuration before the spin-flip and after. This implies the equivalence between importance sampling and random extraction. The arbitrary choose on $W(q \rightarrow q')$ determines the particular algorithm; for the Metropolis-Hastings algorithm:

$$W(q \rightarrow q') = \min\left\{1, \frac{P_r(q')P_{eq}(q')}{P_r(q)P_{eq}(q)}\right\} \quad (5)$$

Where $P_r(q)$ is the probability to be in the q configuration; we consider symmetric probability: $P_r(q) = P_r(q')$. In this way the configuration q' is more probable than q if $P_{eq}(q') > P_{eq}(q)$ and the step transition could occurs with the following probabilities and conditions:

$$\begin{cases} W(q \rightarrow q') = 1 & \Delta E \leq 0 \\ W(q \rightarrow q') = \exp\{-\beta\Delta E\} & \Delta E > 0 \end{cases}$$

Phase transition in Ising model

Magnetization in Ising model shows phase transition at a certain temperature called T_c . This means that the logarithm of the partition function has critical point of the first order in this point and two different statistical descriptions concurrently exist at T_c . Indeed the magnetization curve has two different fits before this point and after, that corresponds to inner configuration of spins: random that corresponds to $\langle M \rangle = 0$ and ordered with $\langle M \rangle \rightarrow +1/-1$.

2 Model

Lattice Implementation

A D-dimensional cubic Lattice with N spins along each edge is described by the array :

$$\mathbf{L} = (L_0, L_1, \dots, L_{N^D-1})$$

Let i denote the index of the array, $i = \{0, 1, \dots, N^D - 1\}$

L_i entry is a boolean variable, $L_i = \{0, 1\}$ represents respectively spin-down and spin-up by convention

Let i -spin denote the spin represented by L_i entry.

The cartesian coordinates $\mathbf{a} = (a_0, a_1, \dots, a_{D-1})$ of the i -spin can be computed from index i if a convention is set on the Lattice arrangement, which in our Model is the following:

Origin O of the D-dimensional space is a spin-vertex of the cubic Lattice, each edge starting from O is aligned along one of the D positive directions.

Unit distance between each couple of adjacent spins

Spins indexing starts from increasing first dimension's coordinate, then second and so forth

n.b. This rules imply that, given a specific spin, each coordinate a_j has values in range $\{0, 1, \dots, N-1\}$. Index i can be expressed as a power series of N with coefficients equal to the coordinates of the i -spin

$$i = \sum_{j=0}^{D-1} a_j N^j$$

Coordinates a_j are computed according to :

$$a_j = [i \% N^{j+1}] / N^j$$

Periodic boundary conditions are applied in order to reduce finite-scale effects.

Energy

Lattice's energy is given by equation (1).

The algorithm implemented for energy computation takes array \mathbf{L} and performs two for loops : one over the system's dimension $d = (0, 1, \dots, D - 1)$ and the other over index $i = (0, 1, \dots, N^D - 1)$.

The key idea is that, given a fixed i -spin, along each dimension d two neighbours $i_{d\pm}$ -spin are found on the increasing and decreasing d-coordinate respectively.

So each single spin has $2D$ interacting neighbours in total, by summing up their energy interaction terms the contribute of the single spin to the total energy is obtained. So energy can be rewritten as :

$$H = \frac{1}{2} \sum_{i=0}^{N^D-1} \sum_{d=0}^{D-1} \sum_{\pm} -J\sigma_i\sigma_{i_{d\pm}}$$

Performing first summation \sum_i , double countings of couples occur and a factor $1/2$ is required.

For each fixed index i , the algorithm takes into account only the interaction term with the i_{d+} -spin so that the number of operation is halved. So the algorithm computes the summation :

$$H = \sum_{i=0}^{N^D-1} \sum_{d=0}^{D-1} -J(L_i \hat{L}_{i_{d+}})$$

$\sigma_i\sigma_{i_{d+}}$ is replaced by $L_i \hat{L}_{i_{d+}}$ since spins are represented by boolean entries L_i . The XOR bitwise operator $\hat{}$ is applied on couple $(L_i, L_{i_{d+}})$ so that it returns the same value of $\sigma_i\sigma_{i_{d+}}$ which can be ± 1 .

From the i index coordinates $\mathbf{a} = (a_0, a_1, \dots, a_{D-1})$ the i_{d+} index coordinates $\mathbf{a}^{d+} = (a_0^{d+}, a_1^{d+}, \dots, a_{D-1}^{d+})$ can be computed.

The vector \mathbf{a}^{d+} differs from \mathbf{a} only on the d -th entry a_d^{d+} which is the only one to be increased, this is computed as $(a_d + 1) \% N$ since we are applying periodic boundary conditions on the Lattice.

From this formulas we can express the i_{d+} index as the sum of two terms:

$$\begin{aligned} i_{d+} &= \left\{ \sum_{j=0}^{d-1} a_j N^j + [(a_d + 1) \% N] N^d \right\} + \left\{ \sum_{j=d+1}^{D-1} a_j N^j \right\} \\ &= \left\{ (i + N^d) \% N^{d+1} \right\} + \left\{ (i / N^{d+1}) N^{d+1} \right\} \end{aligned}$$

n.b. if $d = D - 1$ the second term is 0, so it's not computed by the algorithm.

Metropolis Algorithm

The Metropolis Algorithm proposes a Lattice configuration q' which differs from the initial configuration q only by one spin. The possible N^D configurations are chosen with uniform probability.

Each configuration has probability given by equation (3).

Defining the ratio $a = p(q')/p(q)$, q' is accepted if $a \leq 1$, that is, if q' has a greater probability than q is accepted.

Otherwise if $a \leq 1$ then q' is accepted with probability a . The algorithm is implemented according to the following procedure :

A random integer number i is extracted from $\{0, 1, \dots, N^D - 1\}$ with uniform probability

The energy variation ΔE resulting from flipping the i -spin of Lattice is computed

If $\Delta E \leq 0$ i -spin is flipped;

Else i -spin is flipped with probability $\exp\{-\beta\Delta E\}$; ($k_b = 1$)

Data Collection

Data Storage can be a problem when dealing with a great amount of data. We used root data structures to work out the solution. Storing happens two times during a full simulation: after the “raw” collection and after the analysis.

All the data are ordered, by temperature, in **TTree** and by lattice in **TBranch**. Each measurable quantity is a leaf of the branch. The names of each structures are easy for string comprehension: this way it's easy to read and process previously collected data. The way root saves data let the execution run flawlessly even when processing several Giga Bytes of data.

A Code

This section's aim is to introduce the reader to the C++ implementation of the model. The code is based on TObject class of Root and its scheme is the following:

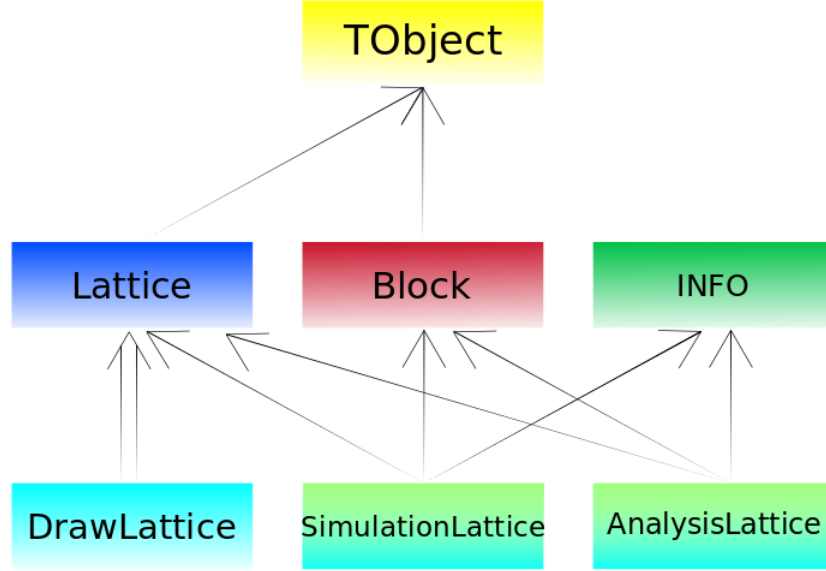


Figure 3: Class scheme

Classes

Lattice

The Lattice class permits to construct a Lattice, compute its thermodynamic quantities and change its state with the Metropolis Algorithm.

Computation details of functions such as **energy()** and **cooling()** are thoroughly explained in Model section.

PRIVATE DATA MEMBERS

const uint	N	number of spins along one edge
const uint	dim	dimension
const uint	num_spin	total number of spins : N^{dim}
bool *	lattice	boolean array of size num_spin
static double	T	temperature

PUBLIC MEMBER FUNCTIONS

CONSTRUCTORS

Lattice()

Default Constructor

Creates Lattice object with N=1 , dim=1

The single entry of **lattice** is set to 0 or 1 with 0.5 probability

Lattice(const uint& _N , const uint& _dim)

Standard Constructor

Creates Lattice object with N = _N, dim = _dim

Sets each **lattice** entry to 0 or 1 with 0.5 probability

Lattice(const Lattice& obj)

Copy Constructor

Creates Lattice object with obj's data members

DESTRUCTOR

~ Lattice

Frees up memory allocated by **lattice**

PHYSICAL AND NUMERICAL FUNCTIONS

bool **flipSpin**(const uint& n)
 If $n < \text{num_spin}$
 Sets **lattice**[n] to **!lattice**[n] and returns true
 Else it doesn't change **lattice** and returns false

int **dE**(const uint& n) const
 Returns energy variation resulting from applying **flipSpin**(n)
 n.b. : it's a const method, it doesn't apply **flipSpin**(n)

int **energy**() const;
 Returns total Energy

float **magnetization**() const
 Returns Magnetization per site

void **cooling**(const uint& iter)
 Applies one step of Metropolis Algorithm

void **cooling**(const uint& iter)
 Applies **iter** steps of Metropolis Algorithm

double * **coolingPar**()
 Applies **cooling**() and returns a four-dimensional array **arr**
 arr are respectively variations of :
 Temperature , Energy , Magnetization , Energy per site

OVERLOADED OPERATORS

Lattice& **operator**=(const Lattice& obj)
 Assignment operator

friend std::ostream& **operator**<<(std::ostream& out, const Lattice& lat)
 Taking **lat** as a reference to a Lattice object
 Prints **lattice** member of **lat** by typing the command `cout << lat ;`

bool **operator**==(const Lattice& obj)
 Taking **lat1** and **lat2** as references to Lattice objects
 lat1 == lat2 returns true if **lat1** and **lat2** have same data members

GETTERS AND SETTERS

uint **getN**() const ; uint **getDim**() const; uint **getNumSpin**() const
returns respectively **N** , **dim** , **num_spin**
bool **getSpin**(const uint & n) const
returns **lattice[n]** entry
double **getT**() ; static void **setT**(const double& _T)
respectively :
Returns **T** ; Sets **T** = _T

OTHERS

void **printLatticeCSV**(const TString& name) const
prints **lattice** in a csv file saved in the working directory
void **printLatticeROOT**(const TString& name , const TString& ln = "lat") const
saves Lattice object in a root file

DrawLattice

DrawLattice class permits to draw a 2D or 3D Lattice inside a TCanvas

The Lattice object to be drawn can be imported in two ways with two Constructors

The first constructor takes a Lattice object as argument

The second constructor takes the name of a root file and the name of a Lattice saved with the **printLatticeROOT** method

The Lattice is displayed in a TMultiGraph which has two TGraphs for up and down spins, with respectively kRed and kBlue color.

The computation of the spin coordinates is explained in the Model Section.

PRIVATE DATA MEMBERS

Lattice	lattice	Lattice object
uint	N, dim, num_spin	N, dim, num_spin of lattice
TString	fname	name of root file
TString	lname	name of Lattice saved in root file fname
TString	cname , ctitle	Tcanvas name and title
TString	gname , gtitle	TMultiGraph name and title

cname, ctitle, gname, gtitle are assigned the same way in each of the three Constructors as : `cname("cv"), ctitle("default canvas"), gname("gr"), gtitle("Ising")`

PUBLIC MEMBER FUNCTIONS

CONSTRUCTORS

DrawLattice()

Default Constructor

Creates lattice with Lattice Default Constructor

DrawLattice(const Lattice& lat)

First Standard Constructor

Sets **lattice** = lat

DrawLattice(const TString& _fname, const TString& _lname)

Second Standard Constructor

Searches a Tfile with name _fname

Sets **lattice** with **readFile()**

void **readFile()**

Gets Lattice object with name _lname from the TFile and sets it to **lattice**

DRAW FUNCTION

void **draw()**

performs a switch statement on **dim**
if **dim** = 2 applies **draw2D()**
if **dim** = 3 applies **draw3D()**
else returns without applying a draw Function

GETTERS

uint **getN()** ; uint **getDim()** ; uint **getNumSpin()**
returns respectively **N**, **dim**, **num_spin**

PRIVATE MEMBER FUNCTIONS

DRAW FUNCTIONS

void **draw2D()**

draws a bidimensional TMultiGraph

void **draw3D()**

draw a three dimensional TMultiGraph

SETTERS

void **setN()** ; void **setDim()** ; void **setNumSpin()**

Sets **N**, **dim**, **num_spin** respectively to **lattice.N**, **lattice.dim**, **lattice.num_spin**
n.b. applied in First and Second Standard Constructor after **lattice** is set

void **setN**(_N) ; void **setDim**(_dim) ; void **setNumSpin**(_num_spin)

Sets **N**, **dim**, **num_spin** respectively to **_N**, **_dim**, **_num_spin**

```

1  /*-----*
2  *                                           *
3  * This macro explains how to construct handle and draw a Lattice *
4  *                                           *
5  *-----*/
6
7  #include "Lattice.h"
8  #include "DrawLattice.h"
9
10 {
11
12     //LATTICE CLASS
13
14     Lattice::setT(0.5); //Set static member Temperature to 0.5
15                         //Default is T = 0.
16
17     int N = 10;
18     int dim = 2;
19     Lattice lat(N,dim); //Construct a bi-dimensional Lattice
20                         //with 10 spins along each edge
21
22     cout << "lat visualization :" << endl;
23     cout << lat << endl; //Print Lattice spins on the console
24                         //The lattice spins will be disposed randomly
25
26     cout << "energy E of lat : " << lat.energy() << endl;
27     cout << "magnetization M of lat : " << lat.magnetization() << endl;
28
29     lat.cooling(); //Perform a Metropolis step
30
31     double * data = new double[4];
32     data = lat.coolingPar(); //perform a Metropolis step collecting data
33
34     cout << "T = " << data[0] << " : temperature" << endl;
35     cout << "dE = " << data[1] << " : energy variation" << endl;
36     cout << "dM = " << data[2] << " : magnetization variation" << endl;
37     cout << "dS = " << data[3] << " : energy per site variation" << endl;
38     delete[] data;
39
40     /*
41     *
42     * According to Metropolis algortihm if dE <0
43     * there's a probability [1 - exp(-dE/T)] (K=1)
44     * that the step will not change lat state with a spinFlip
45     * in that case dE=0 ; dM=0 ; dS=0;
46     *
47     */
48
49
50
51
52
53

```

```

54
55  const unsigned iter = 10000;
56  lat.cooling(iter); // Perform 10000 Metropolis steps
57
58  cout << lat << endl; //Print Lattice spins on the console
59                        //The lattice will now be ordered
60
61  cout << "energy E of lat : " << lat.energy() << endl;
62  // Energy will be around -200
63  cout << "magnetization M of lat : " << lat.magnetization() << endl;
64  // Magnetization per site will be about 1 or -1
65
66  /*
67   *
68   * If T is set to a value greater than the critic temperature
69   * (for 2D Ising Model Tc = 2.27)
70   * and the same Macro is executed,
71   * lat will not thermalize.
72   *
73   */
74
75  //DRAWLATTICE
76
77
78  lat = Lattice(10,2);
79
80  DrawLattice drawLat1(lat); // Create a DrawLattice object
81                            // lat is passed in order to draw it
82
83
84  cout << "lat with dim = " << lat.getDim() << endl;
85  cout << "and edge = " << lat.getN() << "will be drawn" << endl;
86
87  drawLat1.draw(); // Draws the three-dimensional Lattice lat
88
89
90  Lattice lat3D(20,3); // Construct a three-dimensional Lattice
91                      // with 20 spins along each edge
92
93  lat = lat3D; // Use assignment operator to reassign lat
94
95
96  cout << "lat with dim = " << lat.getDim() << endl;
97  cout << "and edge = " << lat.getN() << "will be drawn" << endl;
98
99
100 DrawLattice drawLat2(lat);
101 drawLat2.draw();
102
103 }

```

Listing 1: Caption

SimulationLattice

Simulation Lattice permits to run a simulation and collect data during runtime. The simulation is performed on a set of Lattice objects over a range of temperatures. All Lattices have same edge length and same dimension. For each temperature :

each Lattice is submitted to **IO** cooling iterations in order to reach thermal equilibrium.

In this step data are not collected

each Lattice is submitted to **iter** cooling iterations, during each iteration measures of temperature, energy, magnetization and susceptibility are collected.

PRIVATE DATA MEMBERS

Lattice *	lattice_vector	vector storing a Lattice for each entry
const uint	N	edge length of each Lattice
const uint	dim	dimension of each Lattice
const uint	dim_vector	dimension of lattice_vector
const TString	file	root file name in which data are collected
uint	IO	number of iterations not collecting data
uint	iter	number of iterations collecting data
double	tempmin	minimum range's temperature
double	tempmax	maximum range's temperature
uint	tempstep	number of temperatures in the range

n.b. : **tempstep** should be a multiple of 4 for implementation reasons

PUBLIC MEMBER FUNCTIONS

CONSTRUCTORS

SimulationLattice()

Default Constructor

SimulationLattice(const uint& _N, const uint& _dim, const uint& _dim_vector)

3-Parameters Constructor

The other data members can be assigned with the setter methods

SimulationLattice(const uint& _N, const uint& _dim, const uint& _dim_vector, const TString& _file, const uint& _i0, const uint& _iter, const double& _tempmin, const double& _tempmax, const uint& _tempstep)

Full Parameter Constructor

SimulationLattice(const Lattice& _lat , const uint& _dim_vector, const TString& _file, const uint& _i0, const uint& _iter, const double& _tempmin, const double& _tempmax, const uint& _tempstep)

Constructor based on a Lattice

Sets **N** and **dim** as those of lat

SimulationLattice(const SimulationLattice& obj)

Copy Constructor

SimulationLattice& **operator**=(const SimulationLattice& obj)

Assignment Operator

DESTRUCTOR

~ **SimulationLattice**

Frees up memory allocated by **lattice_vector**

RUN FUNCTION

void **run**() const

Performs the simulation

GETTERS AND SETTERS

Getters methods are defined for all the Private Data Members except for **lattice_vector**, but its entries can be obtained with :

Lattice **getLattice**(const uint& i)

returns **lattice_vector**[i]

Setters methods are defined for all the Private Data Members except for **lattice_vector** **N**, **dim** and **dim_vector**

AnalysisLattice

AnalysisLattice performs an analysis on raw data collected on a simulation input-file
The analysis creates an output-file which stores :

mean and standard deviation of physical quantities for each Lattice and temperature of the simulation.

mean and standard deviation performed over the Lattices for each temperature of the simulation

Once the output file is created, the physical functions can be plotted into a graph
The curves of Magnetization and Susceptibility vs Temperature can be fitted in order to estimate the Critical Temperature and Exponents of the phase transition.

PRIVATE DATA MEMBERS

const TString	file_in	input root file name
const TString	file_out	output root file name
static double	TempCritic	critic temperature

PUBLIC MEMBER FUNCTIONS

CONSTRUCTOR

AnalysisLattice(const TString& file_input, const TString& file_output)

Parametric Constructor

Sets input and output file names

RUN FUNCTION

void **run**()

Performs the analysis of the previous simulation.

Recreates output file

DRAW FUNCTIONS

TGraphErrors * **drawLattice**(cuint& lattice_number, cuint& x_axis, cuint& y_axis)

returns a TGraphErrors of x and y which take value from 0 to 5
0-1-2-3-4-5

TGraphErrors * **drawLatticeMean**(cuint& x_axis, cuint& y_axis)

TGraphErrors * **draw**(cuint& x_axis, cuint& y_axis)

FIT FUNCTIONS

static double **analiticX**(double * x, double * par)

static double **analiticM**(double * x, double * par)

void **findTcritic**()

void **fitLattice**(bool mean, cuInt& x_axis, cuInt& y_axis, double Tc, double fit_temp_min, double fit_temp_max, int lat_number);

GETTERS AND SETTERS

static double **getTempCritic**()

Get critic temperature.

static void **setTempCritic**(const double& _TempCritic);

Set critic temperature.

TString **getFileIn**() const;

Get input file name.

TString **getFileOut**() const

Get output file name.

void **setFileIn**(const TString& file_input)

Set input file name.

void **setFileOut**(const TString& file_out)

Set output file name.

```

1  /*-----*
2  *
3  * This macro explains how to perform a complete simulation
4  * using th libraries.
5  *
6  *-----*/
7  #include "SimulationLattice.h" // Lattice.h included
8  #include "AnalysisLattice.h"  //
9  #include "TString.h"          // Other useful root inclusions
10 #include "TStopwatch.h"       //
11
12 {
13     const unsigned int lattice_size(10);
14     const unsigned int lattice_dimension(2);
15     // this way a 10x10 lattice is created
16     const unsigned int number_of_lattices(5);
17     // simulation performed simultaneously on 5 lattices
18     TString simulation_file("simulation_file.root");
19     TString analysis_file("analysis_file.root");
20     unsigned int iter_pre_simulation(1000000);
21     unsigned int iter_for_simulation(500000);
22     double min_temperature(0.5);
23     double max_temperature(3.5);
24     double steps_of_temperature(30);
25
26     TStopwatch timer;
27
28     SimulationLattice s(lattice_size, lattice_dimension,
29                         number_of_lattices, simulation_file,
30                         iter_pre_simulation, iter_for_simulation,
31                         min_temperature, max_temperature,
32                         steps_of_temperature);
33     /*
34     * Alternative way to call it:
35     *
36     * SimulationLattice s(lattice_size, lattice_dimension,
37     *                       number_of_lattices);
38     * s.setFile(simulation_file);
39     * s.setIO(iter_pre_simulation);
40     * ...
41     * s.run();
42     */
43     timer.Start(); // Simulation started with parameters set
44     s.run();       // simulation_file always recreated
45     timer.Stop();  //
46     timer.Print(); //
47
48     AnalysisLattice a(simulation_file, analysis_file);
49     /*
50     * input and output file must be provided even
51     * if the output file already exists.
52     * The output file is recreated only by run()
53     * but is called in reading mode by the other

```

```

53     * data members
54     */
55     timer.Start();    // Analysis started: parameters got
56     a.run();          // from input file.
57     timer.Stop();     // Output file Recreated.
58     timer.Print();    //
59
60     /*
61     * Once the analysis is performed:
62     * a.draw(TEMPERATURE, MAGNETIZATION);
63     *
64     * defined name      defined name      defined value
65     *
66     * ENERGY           1
67     * TEMPERATURE       TEMP              2
68     * MAGNETIZATION     MAG               3
69     * SITE_ENERGY       SENERGY           4
70     * SUSCEPTIBILITY  SUSC              5
71     */
72
73 }

```

Listing 2: Caption

B Results

This section wants to summarize the simulation results. Under this purpose we underline two main effects:

- Finite size and finite volume of the lattice imply magnetization and energy fluctuations; periodic conditions reduce this phenomena. Moreover finite size leads to no residual magnetization: this effect is out of the temperature's range studied.
- Importance sampling algorithms can produce correlated configurations corresponding to different steps of the simulation. This phenomena is in contrast with theoretical hypothesis of microstates independence and can be correctly treated throw binning technique.

Figure 4: Energy-Temperature graph for 2D Lattices with $I=10,000,000$ and 100 steps of T

Figure 5: Magnetization-Temperature graph for 2D Lattices with $I=10,000,000$ and 100 steps of T

Figure 6: Scusceptibility-Temperature graph for 2D Lattices with $I=10,000,000$ and 100 steps of T

Figure 7: 10,000,000 steps of cooling for the 2D Lattice with $L=100$

Figure 8: Energy-Temperature graph for 3D Lattices with $I=40,000,000$ and 52 steps of T

Figure 9: Magnetization-Temperature graph for 3D Lattices with $I=40,000,000$ and 52 steps of T

Figure 10: Susceptibility-Temperature graph for 3D Lattices with $I=40,000,000$ and 52 steps of T

Figure 11: 1,000,000,000 steps of cooling for the 3D Lattice with $L=40$

Calibrating the model The binning method can take into account the correlation between different configurations. Measures corresponding to different steps of the simulation can have a correct error valuation throw this technique: we divide a set of N ordered configurations in $N/2^n$ groups (each one with n elements), we calculate the

mean for each bin and we iterate this process until the desired level of binning; then we calculate the global mean and its error. In this way we correlate the measure at a particular level of binning (higher level \rightarrow correlation length \ll size of the bins \rightarrow lower correlation \rightarrow higher error). We chose the eighth level of binning for which we found a plateau in the error-level graph.

C Conclusions

This work has analyzed a new solution for the LMP characterized by the delivery process carried out by citizens. As we shown in the first section, the today city complexity brought a proportional increase of the transportation costs in it; indeed the presented solution, based on the sharing economy, can be ecologically and economically sustainable. Citizen becomes active actors in the transportation process delivering packs all around the city. The Agent-Based Model has been realized with a scaled map in order to express the Turin's distances and adequate (from a computational point of view) parameters:

Numb. Packs	Numb. Users	Max Delivery Cost	Storage Box Cost	Users' Pay
1400	700	1.75 €	0.2 €/two days	1 €/km

The code has been written in NetLogo 6.0 and, thanks to the Behavior Search tool, brought the following results for parameters we need in order to minimize the expenses:

- 10 Storages.
- 304 Boxes in each storage.
- Total expenses: 1440 €

Note that the storage's capacity is greater than the minimum required for an uniform distribution of 1400 packs in 10 storages. This shows how the complex system achieves a store optimization for minimizing the expense regarding random place of delivery.

The figure below shows that the curves of expenses and number of packs vs. time have almost an opposite trend; moreover on the right we see that the expenses for each pack decreases with time.

Considering an high and a low number of users we saw that the convergence is faster in the first case and, as expected, less expensive. Note that at the end of the day (1600 ticks) in both cases all packs are delivered.

Increasing the fixed cost parameters we saw that expenses grew, but the model still succeed in delivering all packs in a day (1600 ticks) with a cost for each pack that is lower than 1.75€.

In conclusion this underlines the robustness of the proposed solution both in economical and user's engagement terms, moreover the model held interesting results also in extreme cases.

Performance

Figure 12: Time scaling for different data member initialization