

JOINT CLASSIFICATION AND TRAJECTORY REGRESSION OF ONLINE HANDWRITING USING A MULTI-TASK LEARNING APPROACH

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MOTIVATION

Idea:

- Handwriting is important for the *graphomotoric*, i.e., the learning process of students. State-of-the-art methods to recognize handwriting (a) require to write on a special device (affecting the writing style), (b) require to take images of the text (OCR), or (c) are only prototypical.
- The sensor-enhanced pen by STABILO International GmbH allows to write on normal paper that we use for trajectory reconstruction and text classification.

Problem:

- Reconstructing the pen tip trajectory with distance-based losses does not provide smoothed trajectories.
- Maximizing the similarity is scale invariant.

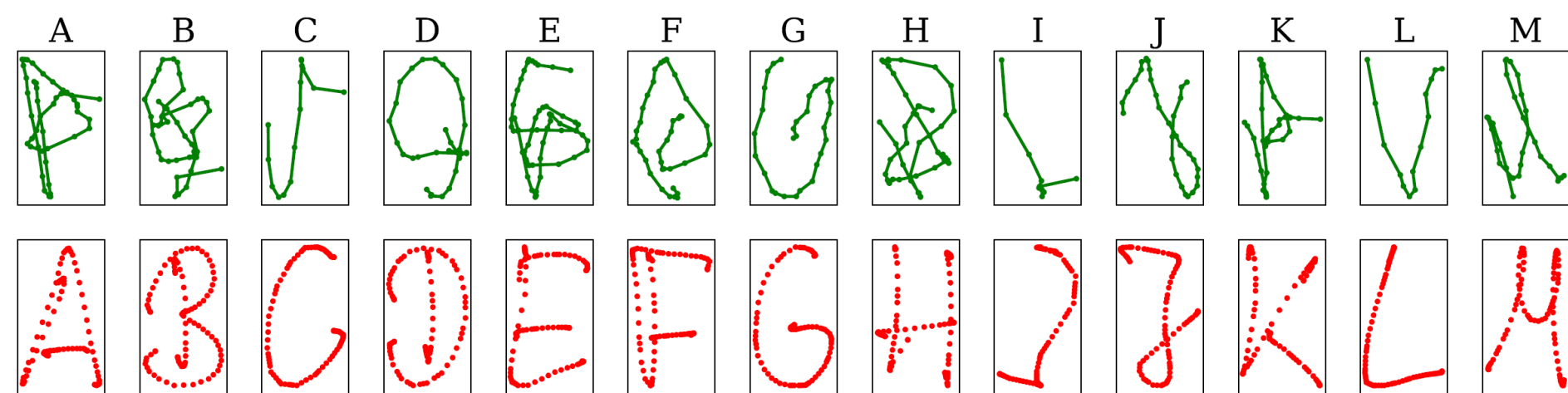
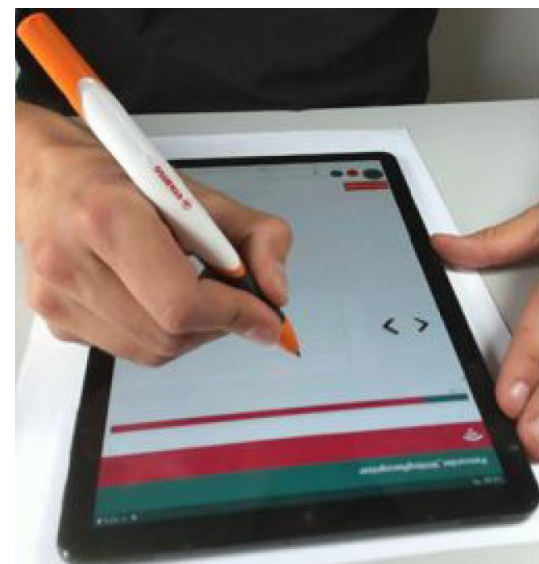
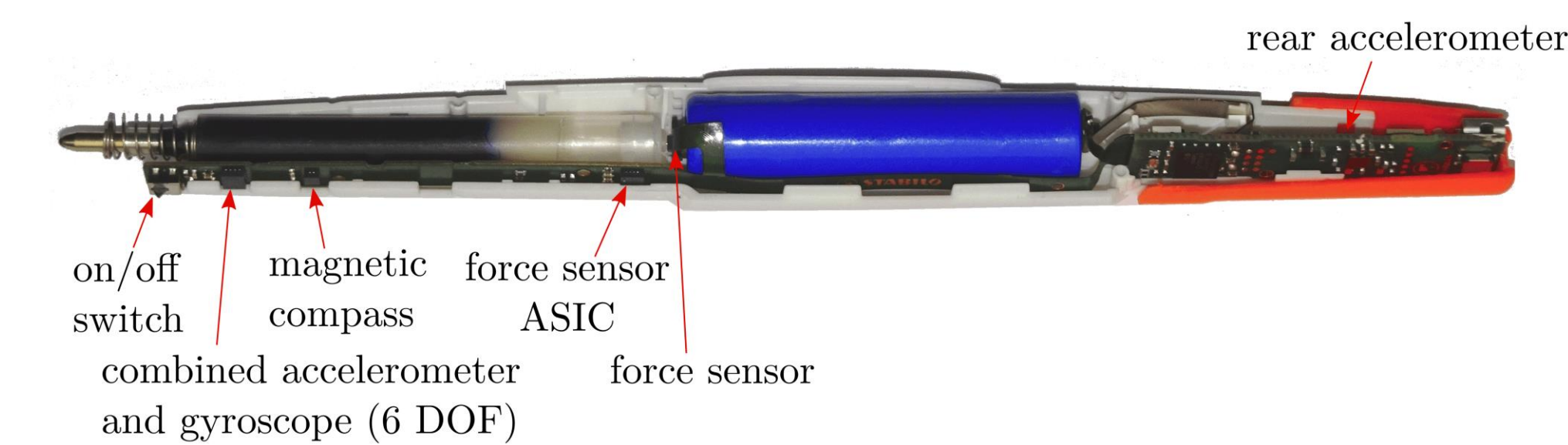
Goal:

- Combine *distance*, *spatio-temporal* and *distribution* losses with Multi-Task Learning techniques.
- Combine classification and trajectory reconstruction task.

Input	Task	Loss	Output
Inertial	Classification	Cross-entropy	Character class
or		Distance	or/and
visual	Regression	Spatio-temporal	trajectory (MTS)
MTS		Distribution	

RECORDING SETUP

- Sensor-enhanced pen with two accelerometers, a gyroscope, a magnetometer and a force sensor (at 100 Hz).
- Writing on a tablet for ground truth trajectory (at 30 Hz).
- Three outside-in cameras for pen tip tracking segmented with U-Net (at 60 Hz).
- Total 2,466 training and 992 validation characters.
- Dataset publicly available:
<https://iis.fraunhofer.de/onhw-dataset/>



METHODOLOGY

Trajectory Reconstruction Loss Functions:

- Distance-based losses: mean squared error \mathcal{L}_{MSE} , Huber loss \mathcal{L}_H , Andrew's Sine loss \mathcal{L}_{AS}
- Spatio-temporal losses: Cosine Similarity \mathcal{L}_{CS} , Pearson Correlation \mathcal{L}_{PC}
- Distribution-based loss: Wasserstein distance \mathcal{L}_{WAS_p}

Architectures With Different Split Points:

- Baselines: A_0 only regression, A_1 only classification
- A_2 classification for regression, A_3 latest split, A_4 late split, A_5 to A_7 intermediate splits, A_8 separate heads

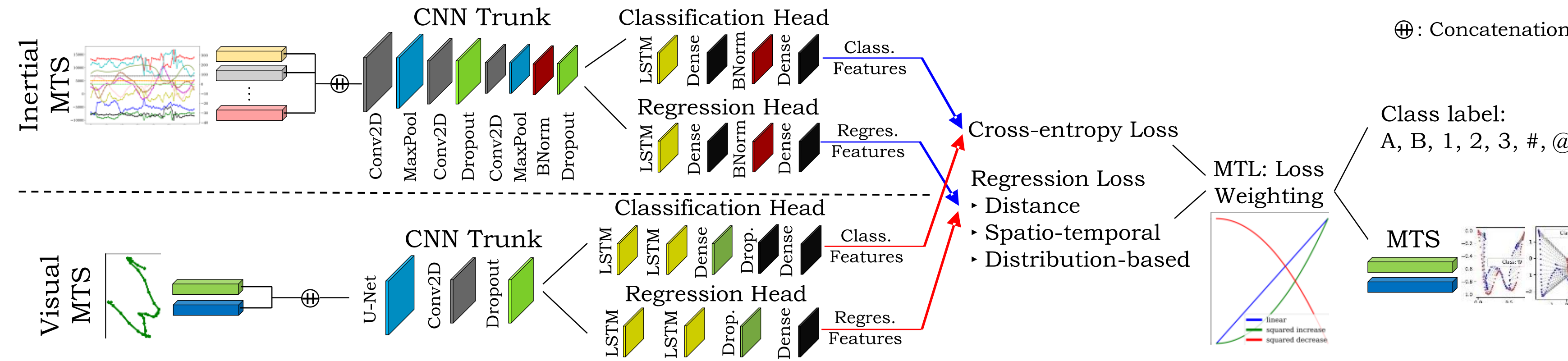
Multi-Task Learning Approaches:

- Naive and epoch-dependent weighting of the second task.

- Dynamic Weight Average (DWA) by averaging task weighting over time: weights for current epoch e are

$$\omega_i(e) = \frac{e^{\lambda_i(e-1)/P}}{\sum_k e^{\lambda_k(e-1)/P}}; \lambda_i(e-1) = \frac{\mathcal{L}_i(e-1)}{\mathcal{L}_i(e-2)}$$

with P as pre-specified softness of task weighting.



Method overview: multivariate time series input (top: inertial data, bottom: visual data). Classification (*cross-entropy*) and regression (*distance*, *spatio-temporal* and *distribution*-based) loss functions are combined with different MTL weighting strategies.

EXPERIMENTAL RESULTS

MTL Architecture Evaluation:

- Baseline: Inertial: 0.1705 rmse / 88.11%
Visual: 0.1360 rmse / 73.19%
- Inertial: improves up to 0.1169 (model A_2) to 0.1623 (model A_6)
- A late split has a positive influence on the trajectory regression by sharing more trainable parameters in the trunk.

Loss Function Evaluation:

- \mathcal{L}_H increases the classification accuracy up to 88.43%.
- Spatio-temporal losses are able to learn the shape of the character, but at a wrong scale. \mathcal{L}_{PC} is smoother compared to \mathcal{L}_{CS} .

Combined Loss Function Evaluation:

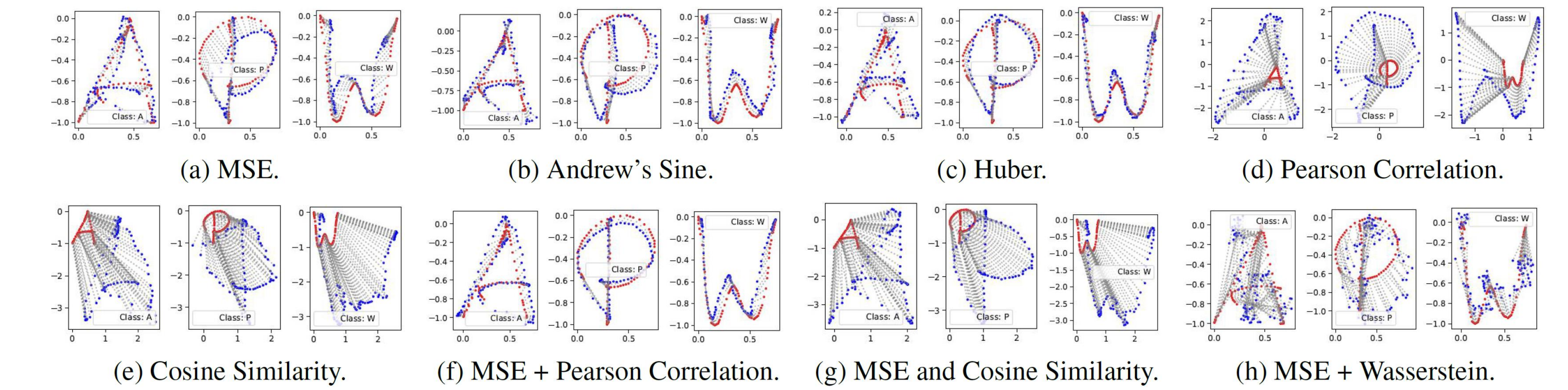
- \mathcal{L}_{MSE} combined with \mathcal{L}_{WAS_p} : the predictions become more evenly distributed for larger p . For $p = 1$ and the naive weighting strategy, the trajectory prediction error is large, but can be significantly improved using alternative MTL strategies.
- \mathcal{L}_{MSE} combined with \mathcal{L}_{PC} provides a suitable shape while still yielding to an improvement in accuracy. DWA is worse than linear or squared weight increase.
- The order of weight increase is important for combining metrics. A slow weight increase is the best approach for jointly learning the classification and trajectory regression tasks.

Network	MSE+CE Traj. Class.	AS+CE Traj. Class.	H+CE Traj. Class.	MSE+PC+CE Traj. Class.	MSE+CS+CE Traj. Class.	MSE+WAS+CE Traj. Class.	PC+CE Class.	CS+CE Class.	WAS+CE Class.
Only regression (A_0)	0.1705	-	0.1501	-	0.1723	-	1.0023	-	0.3107
Only classification (A_1)	-	88.11	-	-	-	-	-	-	-
Class. for regr. (A_2)	0.1169	86.69	0.1779	9.78	0.1290	62.78	0.1127	86.81	0.3554
Latest split (A_3)	0.1381	86.67	0.1856	49.31	0.1569	66.73	0.1381	85.75	6.1464
Late split (A_4)	0.1372	86.46	0.1421	76.28	0.1581	63.64	0.1357	88.64	1.3928
Split after LSTM (A_5)	0.1370	87.34	0.1629	68.64	0.1458	73.74	0.1386	85.53	1.0578
Split after 2. Drop. (A_6)	0.1623	87.68	0.1464	83.96	0.1580	84.76	0.1647	84.94	1.0053
Split after 1. Drop. (A_7)	0.1866	84.27	0.1676	86.93	0.1546	86.89	0.1638	84.55	1.1388
Separate heads (A_8)	0.1936	86.87	0.1660	86.02	0.1533	88.43	0.1490	87.03	1.0986

Evaluation results for the IMU-based dataset trained with different loss combinations. Metrics: RMSE and accuracy (%).

Network	MSE+CE Traj. Class.	AS+CE Traj. Class.	H+CE Traj. Class.	MSE+PC+CE Traj. Class.	MSE+CS+CE Traj. Class.	MSE+WAS+CE Traj. Class.	PC+CE Class.	CS+CE Class.	WAS+CE Class.
Only regression (A_0)	0.1360	-	0.1388	-	0.1271	-	0.1348	-	2.5733
Only classification (A_1)	-	73.19	-	-	-	-	-	-	-
Class. for regr. (A_2)	0.1250	80.15	0.1279	12.47	0.1475	55.81	0.1327	77.27	0.4900
Latest split (A_3)	0.4314	23.21	0.1327	74.3	0.1577	64.15	0.1401	75.54	0.6713
Late split (A_4)	0.1351	78.49	0.1260	78.23	0.1230	79.42	0.1284	80.89	1.1177
Split after LSTM (A_5)	0.1291	80.40	0.1252	81.24	0.1307	78.06	0.1478	73.21	0.1705
LSTM in tr. head (A_6)	0.1334	77.33	0.1383	74.31	0.1605	63.31	0.1243	81.64	0.1747
LSTM in cl. head (A_7)	0.1378	78.58	0.1267	80.52	0.1330	78.86	0.1459	74.25	1.2483
Split after 1. Drop. (A_8)	0.1246	78.56	0.1248	75.69	0.1310	75.18	0.1251	79.27	0.4132

Evaluation results for the visual-based dataset trained with different loss combinations. Metrics: RMSE and accuracy (%).



Trajectory prediction (blue) against the ground truth trajectory (red) of the characters 'A', 'P' and 'W' based on inertial data.