

Homework 4: Geodesic Flow

This set of problems is adapted from [53].

Let (X, g) be a riemannian manifold. The arc-length of a smooth curve $\gamma : [a, b] \rightarrow X$ is

$$\text{arc-length of } \gamma := \int_a^b \left| \frac{d\gamma}{dt} \right| dt, \quad \text{where} \quad \left| \frac{d\gamma}{dt} \right| := \sqrt{g_{\gamma(t)} \left(\frac{d\gamma}{dt}, \frac{d\gamma}{dt} \right)}.$$

1. Show that the arc-length of γ is independent of the parametrization of γ , i.e., show that, if we reparametrize γ by $\tau : [a', b'] \rightarrow [a, b]$, the new curve $\gamma' = \gamma \circ \tau : [a', b'] \rightarrow X$ has the same arc-length. A curve γ is called a curve of *constant velocity* when $\left| \frac{d\gamma}{dt} \right|$ is independent of t . Show that, given any curve $\gamma : [a, b] \rightarrow X$ (with $\frac{d\gamma}{dt}$ never vanishing), there is a reparametrization $\tau : [a, b] \rightarrow [a, b]$ such that $\gamma \circ \tau : [a, b] \rightarrow X$ is of constant velocity.
2. Given a smooth curve $\gamma : [a, b] \rightarrow X$, the *action* of γ is $\mathcal{A}(\gamma) := \int_a^b \left| \frac{d\gamma}{dt} \right|^2 dt$. Show that, among all curves joining x to y , γ minimizes the action if and only if γ is of constant velocity and γ minimizes arc-length.

Hint: Suppose that γ is of constant velocity, and let $\tau : [a, b] \rightarrow [a, b]$ be a reparametrization. Show that $\mathcal{A}(\gamma \circ \tau) \geq \mathcal{A}(\gamma)$, with equality only when $\tau = \text{identity}$.

3. Assume that (X, g) is geodesically convex, that is, any two points $x, y \in X$ are joined by a unique (up to reparametrization) minimizing geodesic; its arc-length $d(x, y)$ is called the riemannian distance between x and y .

Assume also that (X, g) is *geodesically complete*, that is, every geodesic can be extended indefinitely. Given $(x, v) \in TX$, let $\exp(x, v) : \mathbb{R} \rightarrow X$ be the unique minimizing geodesic of constant velocity with initial conditions $\exp(x, v)(0) = x$ and $\frac{d\exp(x, v)}{dt}(0) = v$.

Consider the function $f : X \times X \rightarrow \mathbb{R}$ given by $f(x, y) = -\frac{1}{2} \cdot d(x, y)^2$. Let $d_x f$ and $d_y f$ be the components of $df_{(x, y)}$ with respect to $T_{(x, y)}^*(X \times X) \simeq T_x^* X \times T_y^* X$. Recall that, if

$$\Gamma_f^\sigma = \{(x, y, d_x f, -d_y f) \mid (x, y) \in X \times X\}$$

is the graph of a diffeomorphism $f : T^* X \rightarrow T^* X$, then f is the symplectomorphism generated by f . In this case, $f(x, \xi) = (y, \eta)$ if and only if $\xi = d_x f$ and $\eta = -d_y f$.

Show that, under the identification of TX with $T^* X$ by g , the symplectomorphism generated by f coincides with the map $TX \rightarrow TX$, $(x, v) \mapsto \exp(x, v)(1)$.

Hint: The metric g provides the identifications $T_x X v \simeq \xi(\cdot) = g_x(v, \cdot) \in T_x^* X$. We need to show that, given $(x, v) \in TX$, the unique solution of

$$(\star) \begin{cases} g_x(v, \cdot) = d_x f(\cdot) \\ g_y(w, \cdot) = -d_y f(\cdot) \end{cases} \text{ is } (y, w) = (\exp(x, v)(1), d \frac{\exp(x, v)}{dt}(1)).$$

Look up the Gauss lemma in a book on riemannian geometry. It asserts that geodesics are orthogonal to the level sets of the distance function.

To solve the first line in (\star) for y , evaluate both sides at $v = \frac{d \exp(x, v)}{dt}(0)$. Conclude that $y = \exp(x, v)(1)$. Check that $d_x f(v') = 0$ for vectors $v' \in T_x X$ orthogonal to v (that is, $g_x(v, v') = 0$); this is a consequence of $f(x, y)$ being the arc-length of a *minimizing* geodesic, and it suffices to check locally.

The vector w is obtained from the second line of (\star) . Compute $-d_y f(\frac{d \exp(x, v)}{dt}(1))$. Then evaluate $-d_y f$ at vectors $w' \in T_y X$ orthogonal to $\frac{d \exp(x, v)}{dt}(1)$; this pairing is again 0 because $f(x, y)$ is the arc-length of a minimizing geodesic. Conclude, using the nondegeneracy of g , that $w = \frac{d \exp(x, v)}{dt}(1)$. For both steps, it might be useful to recall that, given a function $\varphi : X \rightarrow \mathbb{R}$ and a tangent vector $v \in T_x X$, we have $d\varphi_x(v) = \frac{d}{du} [\varphi(\exp(x, v)(u))]_{u=0}$.