기계 학습

Part IV. **서포트 벡터 머신(SVM)**

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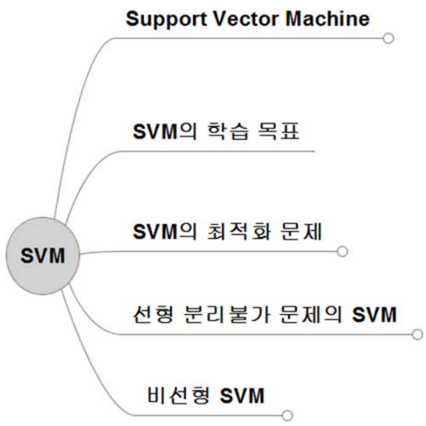
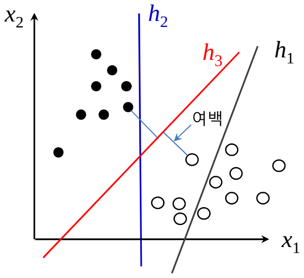


10.1 SVM

❖ **Support Vector Machine** (SVM)

- Vladimir Vapnik이 제안
- 분류 오차를 줄이면서 동시에 **여백**을 **최대**로 하는 **결정 경계(decision boundary)**를 찾는 **이진 분류기**(binary classifier)



h_3가 h_2보다 우수

- **여백**(margin)
  - 결정 경계와 가장 가까이에 있는 학습 데이터까지의 거리
- **서포트 벡터**(support vector)
  - 결정 경계로부터 가장 가까이에 있는 학습 데이터들

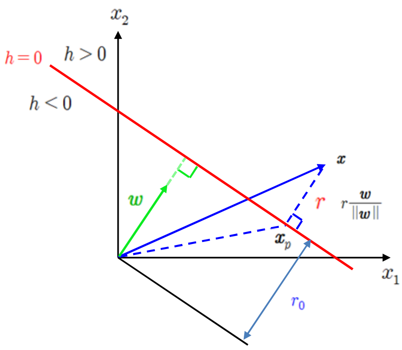
SVM

❖ **초평면 기하학**

- **초평면(hyperplane)**
  - 4차원이상의 공간에서 선형 방정식으로 표현되는 결정 경계

입력 데이터 $\boldsymbol{x} = [x_1 \; x_2 \; \cdots \; x_d]^\top$

$$h(\boldsymbol{x}) = w_1 x_1 + w_2 x_2 + \cdots + w_d x_d + b = \boldsymbol{w}^\top \boldsymbol{x} + b = 0$$



$$\boldsymbol{x} = \boldsymbol{x}_p + r\frac{\boldsymbol{w}}{||\boldsymbol{w}||}$$

$$\boldsymbol{w}^\top \boldsymbol{x} = \boldsymbol{w}^\top \boldsymbol{x}_p + r\frac{\boldsymbol{w}^\top \boldsymbol{w}}{||\boldsymbol{w}||}$$

$$\boldsymbol{w}^\top \boldsymbol{x} = \boldsymbol{w}^\top \boldsymbol{x}_p + r||\boldsymbol{w}||$$

$$\boldsymbol{w}^\top \boldsymbol{x} + b = \boldsymbol{w}^\top \boldsymbol{x}_p + b + r||\boldsymbol{w}||$$

$$h(\boldsymbol{x}) = r||\boldsymbol{w}|| \qquad r = \frac{h(\boldsymbol{x})}{||\boldsymbol{w}||}$$

$$r_0 = \frac{h(\boldsymbol{0})}{||\boldsymbol{w}||} = \frac{b}{||\boldsymbol{w}||}$$

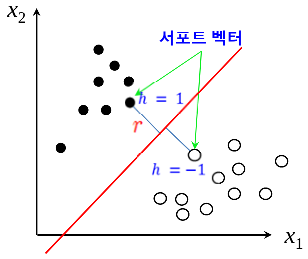
10.2 SVM의 학습

❖ **SVM의 학습 목표**

- 학습데이터 $X = \{(\boldsymbol{x}_1, t_1), (\boldsymbol{x}_2, t_2), \cdots, (\boldsymbol{x}_N, t_N)\}$ $\quad t_i \in \{1, -1\}, \quad i = 1, \cdots, N$
- 분류를 위한 **초평면**의 만족조건

❶ $t_i h(\boldsymbol{x}_i) \geq 1, \quad i = 1, \cdots, N$

❷ 서포트 벡터와의 거리, 즉 여백을 최대로 한다.



조건 ❶ 서포트 벡터 $\boldsymbol{x}'$에서의 $|h(\boldsymbol{x}')| = 1$

$h(\boldsymbol{x}) > 0$인 공간에 $t_i = 1$

$h(\boldsymbol{x}) < 0$인 공간에 $t_i = -1$

조건 ❷ $r = \frac{h(\boldsymbol{x})}{||\boldsymbol{w}||}$ 서포트 벡터에 대해서는 $h(\boldsymbol{x}) = 1$

$r = \frac{1}{||\boldsymbol{w}||}$

Find $\boldsymbol{w}, b$ which minimizes $J(\boldsymbol{w}) = \frac{1}{2}||\boldsymbol{w}||^2$

subject to $t_i h(\boldsymbol{x}_i) \geq 1, \quad i = 1, \cdots, N$

$$h(\boldsymbol{x}) = \boldsymbol{w}^{\top}\boldsymbol{x} + b = 0$$

10.3 SVM의 최적화 문제

❖ **제약조건 최적화**

Find $\boldsymbol{x}$ which minimizes $f(\boldsymbol{x})$

subject to $g(\boldsymbol{x}) = 0$

$h(\boldsymbol{x}) \leq 0$

- **라그랑주 함수**

$$L(\boldsymbol{x}, \alpha, \lambda) = f(\boldsymbol{x}) + \lambda g(\boldsymbol{x}) + \alpha h(\boldsymbol{x})$$

$$(\alpha \geq 0)$$

Find $\boldsymbol{w}, b$ which minimizes $J(\boldsymbol{w}) = \frac{1}{2}||\boldsymbol{w}||^2$

subject to $t_i h(\boldsymbol{x}_i) \geq 1, \quad i = 1, \cdots, N$

⬇

Find $\boldsymbol{w}, b$ which minimizes $J(\boldsymbol{w}) = \frac{1}{2}||\boldsymbol{w}||^2$

subject to $1 - t_i h(\boldsymbol{x}_i) \leq 0, \quad i = 1, \cdots, N$

- **라그랑주 함수**

$$L(\boldsymbol{w}, b, \boldsymbol{\alpha}) = \frac{1}{2}||\boldsymbol{w}||^2 + \sum_{i=1}^{N} \alpha_i (1 - t_i(\boldsymbol{w}^{\top}\boldsymbol{x}_i + b))$$

$$\alpha_i \geq 0$$

SVM의 최적화 문제

❖ SVM의 최적화 문제

$$\boxed{\begin{aligned}&\text{Find } \boldsymbol{w}, b \text{ which minimizes } J(\boldsymbol{w}) = \frac{1}{2}\|\boldsymbol{w}\|^2 \\ &\qquad \text{subject to } 1 - t_i h(\boldsymbol{x}_i) \le 0, \quad i = 1, \cdots, N\end{aligned}}$$

$$L(\boldsymbol{w}, b, \boldsymbol{\alpha}) = \frac{1}{2}\|\boldsymbol{w}\|^2 + \sum_{i=1}^{N} \alpha_i (1 - t_i(\boldsymbol{w}^\top \boldsymbol{x}_i + b)) \quad \alpha_i \ge 0$$

- 해에 대한 **KKT(Karush-Kuhn-Tucker) 조건**
  - ① $\alpha_i \ge 0, \quad i = 1, \cdots, N$
  - ② $1 - t_i h(\boldsymbol{x}_i) = 1 - t_i(\boldsymbol{w}^\top \boldsymbol{x}_i + b) \le 0, \quad i = 1, \cdots, N$
  - ③ $\alpha_i (1 - t_i h(\boldsymbol{x}_i)) = 0, \quad i = 1, \cdots, N$ **상보적 여유성(complementary slackness)**
  - ④ $\frac{\partial L}{\partial \boldsymbol{w}} = 0, \ \frac{\partial L}{\partial b} = 0$
- **쌍대 함수(dual function)**

$$\tilde{L}(\boldsymbol{\alpha}) = \min_{\boldsymbol{w}, b} L(\boldsymbol{w}, b, \boldsymbol{\alpha})$$

$$\frac{\partial L}{\partial \boldsymbol{w}} = 0, \ \frac{\partial L}{\partial b} = 0$$

SVM의 최적화 문제

❖ SVM의 최적화 문제

$$L(\boldsymbol{w}, b, \boldsymbol{\alpha}) = \frac{1}{2}\|\boldsymbol{w}\|^2 + \sum_{i=1}^{N} \alpha_i (1 - t_i(\boldsymbol{w}^\top \boldsymbol{x}_i + b)) \qquad \alpha_i \ge 0$$

- **쌍대함수**(dual function)

$$\tilde{L}(\boldsymbol{\alpha}) = \min_{\boldsymbol{w}, b} L(\boldsymbol{w}, b, \boldsymbol{\alpha})$$

$$\frac{\partial L}{\partial \boldsymbol{w}} = 0, \ \frac{\partial L}{\partial b} = 0$$

- $L(\boldsymbol{w}, b, \boldsymbol{\alpha})$의 미분을 0으로 하면

$$\frac{\partial L}{\partial \boldsymbol{w}} = \boldsymbol{w} - \sum_{i=1}^{N} \alpha_i t_i \boldsymbol{x}_i = 0 \qquad \boxed{\boldsymbol{w} = \sum_{i=1}^{N} \alpha_i t_i \boldsymbol{x}_i}$$

$$\frac{\partial L}{\partial b} = -\sum_{i=1}^{N} \alpha_i t_i = 0 \qquad \boxed{\sum_{i=1}^{N} \alpha_i t_i = 0}$$

SVM의 최적화 문제

❖ **SVM의 최적화 문제**

$$\boldsymbol{w} = \sum_{i=1}^{N} \alpha_i t_i \boldsymbol{x}_i \qquad \sum_{i=1}^{N} \alpha_i t_i = 0$$

- **초평면 함수식**

$$h(\boldsymbol{x}) = \boldsymbol{w}^\top \boldsymbol{x} + b = \boldsymbol{w} \cdot \boldsymbol{x} + b = \sum_{i=0}^{N} \alpha_i t_i \boldsymbol{x_i} \cdot \boldsymbol{x} + b$$

- $L(\boldsymbol{w}, b, \boldsymbol{\alpha})$에 넣어 전개하면

$$L(\boldsymbol{w}, b, \boldsymbol{\alpha}) = \frac{1}{2}||\boldsymbol{w}||^2 + \sum_{i=1}^{N} \alpha_i (-t_i(\boldsymbol{w}^\top \boldsymbol{x_i} + b) + 1)$$

$$\begin{aligned}\tilde{L}(\boldsymbol{\alpha}) &= \frac{1}{2}(\sum_{i=1}^{N} \alpha_i t_i \boldsymbol{x_i})(\sum_{j=1}^{N} \alpha_j t_j \boldsymbol{x_j})^\top - \sum_{i=1}^{N} \alpha_i t_i \sum_{j=1}^{N} \alpha_j t_j \boldsymbol{x_j} \boldsymbol{x_i}^\top - b \sum_{i=1}^{N} \alpha_i t_i + \sum_{i=1}^{N} \alpha_i \\ &= -\frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j t_i t_j \boldsymbol{x}_i \boldsymbol{x}_j^\top + \sum_{i=1}^{N} \alpha_i \\ &= -\frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j t_i t_j \boldsymbol{x}_i \cdot \boldsymbol{x}_j + \sum_{i=1}^{N} \alpha_i\end{aligned}$$

SVM의 최적화 문제

❖ **SVM의 최적화 문제**

$$\boxed{\begin{aligned}&\text{Find } \boldsymbol{w}, b \text{ which minimizes } J(\boldsymbol{w}) = \frac{1}{2}||\boldsymbol{w}||^2 \\ &\qquad \text{subject to } 1 - t_i h(\boldsymbol{x}_i) \le 0, \quad i = 1, \cdots, N\end{aligned}}$$

- **라그랑주 함수**로 표현한 **본 문제(primal problem)**

$$\begin{aligned}&\text{Find } \boldsymbol{w}, b \text{ which minimizes } L(\boldsymbol{w}, b, \boldsymbol{\alpha}) = \frac{1}{2}||\boldsymbol{w}||^2 + \sum_{i=1}^{N} \alpha_i (1 - t_i(\boldsymbol{w}^\top \boldsymbol{x_i} + b)) \\ &\qquad \text{subject to } \alpha_i \ge 0, \quad i = 1, \cdots, N\end{aligned}$$

⬇

- w와 b가 없는 **쌍대 문제(dual problem)**

$$\begin{aligned}&\text{Find } \boldsymbol{\alpha} \text{ which maximizes } \tilde{L}(\boldsymbol{\alpha}) = -\frac{1}{2} \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_i \alpha_j t_i t_j \boldsymbol{x}_i \cdot \boldsymbol{x}_j + \sum_{i=1}^{N} \alpha_i \\ &\qquad \text{subject to } \sum_{i=1}^{N} \alpha_i t_i = 0, \quad i = 1, \cdots, N \\ &\qquad\qquad \alpha_i \ge 0, \quad i = 1, \cdots, N\end{aligned}$$

- **문제 복잡도**
  - 데이터 개수 N에 관계
  - 데이터 차원과 무관

SVM의 최적화 문제

❖ SVM의 최적화 문제 해결

- **쌍대 문제**(dual problem)의 **최소화 문제 변환**

Find $\boldsymbol{\alpha}$ which maximizes $\widetilde{L}(\boldsymbol{\alpha}) = -\frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boldsymbol{x}_i \cdot \boldsymbol{x}_j + \sum_{i=1}^{N}\alpha_i$

subject to $\sum_{i=1}^{N}\alpha_i t_i = 0, \quad i = 1, \cdots, N$

$\alpha_i \geq 0, \quad i = 1, \cdots, N$

⬇

Find $\boldsymbol{\alpha}$ which minimizes $\widetilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boldsymbol{x}_i \cdot \boldsymbol{x}_j - \sum_{i=1}^{N}\alpha_i$

subject to $\sum_{i=1}^{N}\alpha_i t_i = 0, \quad i = 1, \cdots, N$

$\alpha_i \geq 0, \quad i = 1, \cdots, N$

이차식 계획법(quadratic programming) 문제

SVM의 최적화 문제

❖ 이차식 계획법(quadratic programming)

Find $\boldsymbol{\alpha}$ which minimizes $\widetilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boldsymbol{x}_i \cdot \boldsymbol{x}_j - \sum_{i=1}^{N}\alpha_i$

subject to $\sum_{i=1}^{N}\alpha_i t_i = 0, \quad i = 1, \cdots, N$

$\alpha_i \geq 0, \quad i = 1, \cdots, N$

$$\widetilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\begin{bmatrix}\alpha_1 & \alpha_2 & \cdots & \alpha_N\end{bmatrix}\begin{bmatrix} t_1 t_1 \boldsymbol{x}_1 \cdot \boldsymbol{x}_1 & t_1 t_2 \boldsymbol{x}_1 \cdot \boldsymbol{x}_2 & \cdots & t_1 t_N \boldsymbol{x}_1 \cdot \boldsymbol{x}_N \\ t_2 t_1 \boldsymbol{x}_2 \cdot \boldsymbol{x}_1 & t_2 t_2 \boldsymbol{x}_2 \cdot \boldsymbol{x}_2 & \cdots & t_2 t_N \boldsymbol{x}_2 \cdot \boldsymbol{x}_N \\ \vdots & \vdots & \ddots & \vdots \\ t_N t_1 \boldsymbol{x}_N \cdot \boldsymbol{x}_1 & t_N t_2 \boldsymbol{x}_N \cdot \boldsymbol{x}_2 & \cdots & t_N t_N \boldsymbol{x}_N \cdot \boldsymbol{x}_N \end{bmatrix}\begin{bmatrix}\alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N\end{bmatrix} - \sum_{i=1}^{N}\alpha_i$$

$$= \frac{1}{2}\boldsymbol{x}^\top H \boldsymbol{x} - \sum_{i=1}^{N}\alpha_i$$

- 선형대수학의 **quadratic problem solver** 라이브러리 이용
  - MatLab/Octave의 **quadprog( )**
  - Python의 **solvers.qp( )**

SVM의 최적화 문제

❖ **이차식 계획법(quadratic programming) – cont.**

- MatLab/Octave의 **quadprog( )**
  - **이차식 계획법의 표준식(canonical form)**

$$\text{Find } \boldsymbol{\alpha} \text{ which minimizes } L_D(\boldsymbol{\alpha}) = \frac{1}{2}\boldsymbol{\alpha}^\top H\boldsymbol{\alpha} + \boldsymbol{f}^\top\boldsymbol{\alpha}$$

$$\text{subject to } A\boldsymbol{\alpha} \le \boldsymbol{a} \text{ and } B\boldsymbol{\alpha} = \boldsymbol{b}$$

▪ `α = quadprog(H, f, A, a, B, b)`

  - **SVM의 쌍대문제**

$$\tilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\begin{bmatrix}\alpha_1 & \alpha_2 & \cdots & \alpha_N\end{bmatrix}\begin{bmatrix} t_1t_1\boldsymbol{x_1}\cdot\boldsymbol{x_1} & t_1t_2\boldsymbol{x_1}\cdot\boldsymbol{x_2} & \cdots & t_1t_N\boldsymbol{x_1}\cdot\boldsymbol{x_N} \\ t_2t_1\boldsymbol{x_2}\cdot\boldsymbol{x_1} & t_2t_2\boldsymbol{x_2}\cdot\boldsymbol{x_2} & \cdots & t_2t_N\boldsymbol{x_2}\cdot\boldsymbol{x_N} \\ \vdots & \vdots & \ddots & \vdots \\ t_Nt_1\boldsymbol{x_N}\cdot\boldsymbol{x_1} & t_Nt_2\boldsymbol{x_N}\cdot\boldsymbol{x_2} & \cdots & t_Nt_N\boldsymbol{x_N}\cdot\boldsymbol{x_N}\end{bmatrix}\begin{bmatrix}\alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N\end{bmatrix} - \sum_{i=1}^{N}\alpha_i$$

$$= \frac{1}{2}\boldsymbol{\alpha}^\top H\boldsymbol{\alpha} - \sum_{i=1}^{N}\alpha_i$$

$$\text{subject to } \sum_{i=1}^{N}\alpha_i t_i = 0, \quad i = 1, \cdots, N$$

$$\alpha_i \ge 0, \quad i = 1, \cdots, N \quad \Rightarrow \quad -\alpha_i \le 0, \quad i = 1, \cdots, N$$

SVM의 최적화 문제

❖ **이차식 계획법(quadratic programming) – cont.**

- MatLab/Octave의 **quadprog( )**

$$\text{Find } \boldsymbol{\alpha} \text{ which minimizes } L_D(\boldsymbol{\alpha}) = \frac{1}{2}\boldsymbol{\alpha}^\top H\boldsymbol{\alpha} - \sum_{i=1}^{N}\alpha_i$$

$$\text{subject to } -\alpha_i \le 0 \text{ and } \sum_{i=1}^{N}\alpha_i t_i = 0, \; i = 1, \cdots, N$$

$$\text{Find } \boldsymbol{\alpha} \text{ which minimizes } L_D(\boldsymbol{\alpha}) = \frac{1}{2}\boldsymbol{\alpha}^\top H\boldsymbol{\alpha} + \boldsymbol{f}^\top\boldsymbol{\alpha}$$

$$\text{subject to } A\boldsymbol{\alpha} \le \boldsymbol{a} \text{ and } B\boldsymbol{\alpha} = \boldsymbol{b}$$

▪ `α = quadprog(H, f, A, a, B, b)`

  - **SVM의 쌍대문제**

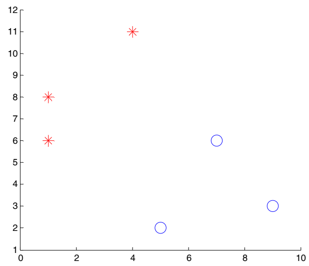
$$H = \begin{bmatrix} t_1t_1\boldsymbol{x_1}\cdot\boldsymbol{x_1} & t_1t_2\boldsymbol{x_1}\cdot\boldsymbol{x_2} & \cdots & t_1t_N\boldsymbol{x_1}\cdot\boldsymbol{x_N} \\ t_2t_1\boldsymbol{x_2}\cdot\boldsymbol{x_1} & t_2t_2\boldsymbol{x_2}\cdot\boldsymbol{x_2} & \cdots & t_2t_N\boldsymbol{x_2}\cdot\boldsymbol{x_N} \\ \vdots & \vdots & \ddots & \vdots \\ t_Nt_1\boldsymbol{x_N}\cdot\boldsymbol{x_1} & t_Nt_2\boldsymbol{x_N}\cdot\boldsymbol{x_2} & \cdots & t_Nt_N\boldsymbol{x_N}\cdot\boldsymbol{x_N}\end{bmatrix} = \begin{bmatrix}t_1 \\ t_2 \\ \vdots \\ t_N\end{bmatrix}\begin{bmatrix}t_1 \\ t_2 \\ \vdots \\ t_N\end{bmatrix}^\top .* \begin{bmatrix}\boldsymbol{x_1} \\ \boldsymbol{x_2} \\ \vdots \\ \boldsymbol{x_N}\end{bmatrix}\begin{bmatrix}\boldsymbol{x_1} \\ \boldsymbol{x_2} \\ \vdots \\ \boldsymbol{x_N}\end{bmatrix}^\top$$

$$\boldsymbol{f} = \begin{bmatrix}-1 \\ -1 \\ \vdots \\ -1\end{bmatrix} \quad A = \begin{bmatrix}-1 & 0 & \cdots & 0 \\ 0 & -1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & -1\end{bmatrix} \quad \boldsymbol{a} = \begin{bmatrix}0 \\ 0 \\ \vdots \\ 0\end{bmatrix} \quad B = \begin{bmatrix}t_1 & t_2 & \cdots & t_N\end{bmatrix} \quad \boldsymbol{b} = \begin{bmatrix}0\end{bmatrix}$$

SVM의 학습 예

❖ **MatLab/Octave의 사용한 예**

- 부류 1 (+1) : (1,6), (1,8), (4,11)
- 부류 2 (−1) : (5,2), (7,6), (9,3)



- 입력데이터 **X**
  - `X = [1 6; 1 8; 4 11; 5 2; 7 6; 9 3]`

$$X = \begin{bmatrix} 1 & 6 \\ 1 & 8 \\ 4 & 11 \\ 5 & 2 \\ 7 & 6 \\ 9 & 3 \end{bmatrix}$$

- 출력 데이터 t
  - `t = [1; 1; 1; -1; -1; -1]`

$$t = \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \\ -1 \\ -1 \end{bmatrix}$$

- 행렬 H
  - `H = (X*X').*(t*t')`

$$H = \begin{bmatrix} 37 & 49 & 70 & -17 & -43 & -27 \\ 49 & 65 & 92 & -21 & -55 & -33 \\ 70 & 92 & 137 & -42 & -94 & -69 \\ -17 & -21 & -42 & 29 & 47 & 51 \\ -43 & -55 & -94 & 47 & 85 & 81 \\ -27 & -33 & -69 & 51 & 81 & 90 \end{bmatrix}$$

SVM의 학습 예

❖ **MatLab/Octave의 사용한 예 – cont.**

- `f = -ones(6,1)`
- `A = -eye(6)`
- `a = zeros(6,1)`
- `B = t'`
- `b = [0]`

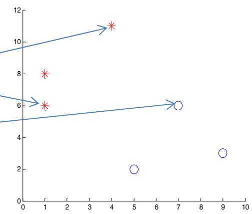
$$f = \begin{bmatrix} -1 \\ -1 \\ -1 \\ -1 \\ -1 \\ -1 \end{bmatrix} \quad A = \begin{bmatrix} -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{bmatrix} \quad a = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 1 & 1 & -1 & -1 & -1 \end{bmatrix}$$

- **이차식 계획법 사용**
  - `α = quadprog(H+eye(6)*0.001, f, A, a, B, b)`

$$X = \begin{bmatrix} 1 & 6 \\ 1 & 8 \\ 4 & 11 \\ 5 & 2 \\ 7 & 6 \\ 9 & 3 \end{bmatrix} \qquad \alpha = \begin{bmatrix} 0.0356 \\ 0.0000 \\ 0.0400 \\ 0.0000 \\ 0.0756 \\ 0.0000 \end{bmatrix}$$

서포트 벡터



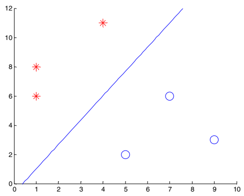
SVM의 학습 예

❖ **SVM의 최적화 문제 해결**

- 선형대수학의 **quadratic problem solver** 라이브러리를 이용
  - 최적화 문제의 해인 $\alpha_1, \alpha_2, \ldots, \alpha_N$ 계산
- KKT 조건의 $\alpha_i(1-h(\boldsymbol{x}_i))=0$ 때문에, $\alpha_i \neq 0$이라면 $h(\boldsymbol{x}_i)=1$
- $\alpha_i \neq 0$인 $\boldsymbol{x}_i$가 서포트 벡터
- $\boldsymbol{w}$의 계산

$$\boldsymbol{w} = \sum_{i=1}^{N} \alpha_i t_i \boldsymbol{x}_i = \begin{bmatrix} -0.333 \\ 0.200 \end{bmatrix}$$

$$X = \begin{bmatrix} 1 & 6 \\ 1 & 8 \\ 4 & 11 \\ 5 & 2 \\ 7 & 6 \\ 9 & 3 \end{bmatrix} \qquad \boldsymbol{\alpha} = \begin{bmatrix} 0.0356 \\ 0.0000 \\ 0.0400 \\ 0.0000 \\ 0.0756 \\ 0.0000 \end{bmatrix}$$



$$\boxed{\begin{aligned} h(\boldsymbol{x}) &= \boldsymbol{w} \cdot \boldsymbol{x} + b \\ &= \sum_{i=1}^{N} a_i t_i \boldsymbol{x}_i \cdot \boldsymbol{x} + b \end{aligned}}$$

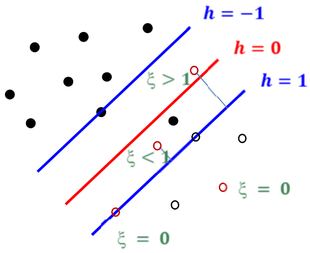
$$h(x_1, x_2) = -0.333x_1 + 0.2x_2 + 0.13$$

- b의 계산
  - 서포트 벡터 하나를 $t_i(\boldsymbol{w}^\top \boldsymbol{x}_i - b) = 1$ 에 넣어 계산

$$\begin{bmatrix} -0.333 \\ 0.200 \end{bmatrix}^\top \begin{bmatrix} 1 \\ 6 \end{bmatrix} - b = 1 \qquad b = 0.13$$

10.4 선형 분리불가 문제의 SVM

❖ **선형 분리불가 문제의 SVM**



- **슬랙변수**(slack variable) ξ_i
  - 학습 데이터별로 하나씩 생성
  - SVM의 분할 초평면에서 서포트벡터보다 멀리 위치하면, $\xi_i = 0$
  - 이외의 경우, $\xi_i = |t_i - h(\boldsymbol{x}_i)|$

$$\boxed{t_i h(\boldsymbol{x}_i) \geq 1 - \xi_i, \quad i = 1, \cdots, N}$$

선형 분리불가 문제의 SVM

❖ **선형분리가 되지 않는 데이터에 대한 SVM**

- **최적화 문제**
  - 슬랙 변수를 허용하는 **제약조건**

$$t_i h(\boldsymbol{x}_i) \geq 1 - \xi_i, \quad i = 1, \cdots, N$$

  - **슬랙 변수 값**의 **합**을 **최소화**

$$\text{Find } \boldsymbol{w}, b \text{ which minimizes } J(\boldsymbol{w}) = \frac{1}{2}\|\boldsymbol{w}\|^2 + C\sum_{i=1}^{N}\xi_i$$

$$\text{subject to } t_i h(\boldsymbol{x}_i) \geq 1 - \xi_i, \quad i = 1, \cdots, N$$

$$\xi_i \geq 0, \quad i = 1, \cdots, N$$

$$C > 0$$

  - **라그랑주 함수**

$$L(\boldsymbol{w}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{2}\|\boldsymbol{w}\|^2 + C\sum_{i=1}^{N}\xi_i + \sum_{i=1}^{N}\alpha_i(1 - t_i h(\boldsymbol{x}_i) - \xi_i) - \sum_{i=1}^{N}\beta_i\xi_i$$

선형 분리불가 문제의 SVM

❖ **선형분리가 되지 않는 데이터에 대한 SVM**

- **최적화 문제 - cont.**
  - **라그랑주 함수**

$$L(\boldsymbol{w}, b, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta}) = \frac{1}{2}\|\boldsymbol{w}\|^2 + C\sum_{i=1}^{N}\xi_i + \sum_{i=1}^{N}\alpha_i(1 - t_i h(\boldsymbol{x}_i) - \xi_i) - \sum_{i=1}^{N}\beta_i\xi_i$$

  - **쌍대 문제(dual problem)**

$$\tilde{L}(\boldsymbol{\alpha}) = \sum_{i=1}^{N}\alpha_i - \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boldsymbol{x}_i \cdot \boldsymbol{x}_j$$

$$\sum_{i=1}^{N}\alpha_i t_i = 0$$

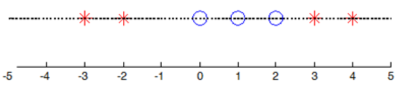
$$0 \leq \alpha_i \leq C$$ ← 상한(upper bound)에 대한 제약조건 추가

10.5 비선형 SVM

❖ **선형 SVM** (linear SVM)
- **선형**인 **초평면**으로 **공간 분할**
- **슬랙변수**를 도입하더라도 **한계**

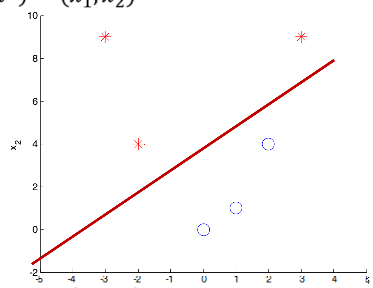
❖ **데이터의 고차원 사상**(high-dimensional mapping)
- 데이터를 고차원의 사상하면 선형 분리 가능

$\Phi(x) = (x, x^2) = (x_1, x_2)$



$h(x_1, x_2) = w_1 x + w_2 x^2 + b$

비선형 함수

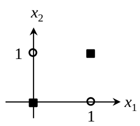


$h(x_1, x_2) = w_1 x_1 + w_2 x_2 + b$

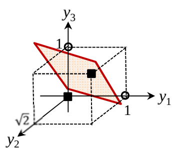
선형 함수

비선형 SVM

❖ **데이터의 고차원 사상 – cont.**
- **XOR 문제**



$\Phi(\boldsymbol{x}) = (x_1^2, \sqrt{2}x_1x_2, x_2^2) = (y_1, y_2, y_3)$



❖ **고차원 변환의 문제점**
- **차원의 저주**(curse of dimensionality) 문제 발생
- 테스트 데이터에 대한 **일반화**(generalization) **능력 저하** 가능
  - **여백(margin) 최대화**를 통해 일반화 능력 유지
- **계산 비용** 증가
  - **커널 트릭(kernel trick)** 사용으로 해결

비선형 SVM

❖ SVM의 최적화 문제

- 선형 SVM

$$\text{Find } \boldsymbol{\alpha} \text{ which minimizes } \widetilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boxed{\boldsymbol{x}_i \cdot \boldsymbol{x}_j} - \sum_{i=1}^{N}\alpha_i$$

$$\text{subject to } \sum_{i=1}^{N}\alpha_i t_i = 0, \quad i = 1, \cdots, N$$

$$\alpha_i \geq 0, \quad i = 1, \cdots, N$$

$$h(\boldsymbol{x}) = \sum_{i=0}^{N}\alpha_i t_i \boxed{\boldsymbol{x}_i \cdot \boldsymbol{x}} + b$$

- 데이터의 고차원 변환

$$\boldsymbol{x}_i \rightarrow \Phi(\boldsymbol{x}_i)$$

- 비선형 SVM

$$\widetilde{L}(\boldsymbol{\alpha}) = -\frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boxed{\Phi(\boldsymbol{x}_i) \cdot \Phi(\boldsymbol{x}_j)} + \sum_{i=1}^{N}\alpha_i$$

$$h(\boldsymbol{x}) = \sum_{i=1}^{N}\alpha_i t_i \boxed{\Phi(\boldsymbol{x}_i) \cdot \Phi(\boldsymbol{x})} + b$$

비선형 SVM

❖ **커널 트릭**(kernel trick)

- $\boldsymbol{\Phi}(\boldsymbol{x}_i) \cdot \boldsymbol{\Phi}(\boldsymbol{x}_j)$를 고차원으로 **변환하여 계산하지 않고**, 원래 데이터에서 계산
- 고차원 변환없이 계산할 수 있는 **커널 함수**(kernel function) $\boldsymbol{K}$ 사용
  - $K(\boldsymbol{x}_i, \boldsymbol{x}_j) = \boldsymbol{\Phi}(\boldsymbol{x}_i) \cdot \boldsymbol{\Phi}(\boldsymbol{x}_j)$

❖ 커널 함수의 예

- $K(\boldsymbol{x}, \boldsymbol{y}) = (\boldsymbol{x}^T \boldsymbol{y})^2$
  - $\boldsymbol{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \boldsymbol{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$
  - $(\boldsymbol{x}^T \boldsymbol{y})^2 = (x_1 y_1 + x_2 y_2)^2 = (x_1 y_1)^2 + 2(x_1 y_1)(x_2 y_2) + (x_2 y_2)^2$
    $= [(x_1)^2 \quad \sqrt{2}x_1 x_2 \quad (x_2)^2][(y_1)^2 \quad \sqrt{2}y_1 y_2 \quad (y_2)^2]^T$
    $= \boldsymbol{\Phi}(\boldsymbol{x}) \cdot \boldsymbol{\Phi}(\boldsymbol{y})$
  - $\boldsymbol{\Phi}(\boldsymbol{x}) = \begin{bmatrix} (x_1)^2 \\ \sqrt{2}x_1 x_2 \\ (x_2)^2 \end{bmatrix} \quad \boldsymbol{\Phi}(\boldsymbol{y}) = \begin{bmatrix} (y_1)^2 \\ \sqrt{2}y_1 y_2 \\ (y_2)^2 \end{bmatrix}$

비선형 SVM

❖ **대표적인 커널 함수**(kernel function)

- **다항식 커널**(polynomial kernel)

  $K(\boldsymbol{x}_i, \boldsymbol{x}_j) = (\boldsymbol{x}_i \cdot \boldsymbol{x}_j + 1)^p$, p는 양의정수

- **RBF**(radial basis function) **커널**

  $K(\boldsymbol{x}_i, \boldsymbol{x}_j) = e^{-\|\boldsymbol{x}_i - \boldsymbol{x}_j\|^2/(2\sigma^2)}$

- **하이퍼볼릭 탄젠트**(hyperbolic tangent) **커널**

  $K(\boldsymbol{x}_i, \boldsymbol{x}_j) = \tanh(\alpha \boldsymbol{x}_i \cdot \boldsymbol{x}_j + \beta)$

비선형 SVM

❖ **커널 트릭을 사용할 때의 최적화 문제**

$$\widetilde{L}(\boldsymbol{\alpha}) = -\frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boxed{\Phi(\boldsymbol{x}_i) \cdot \Phi(\boldsymbol{x}_j)} + \sum_{i=1}^{N}\alpha_i$$

$$h(\boldsymbol{x}) = \sum_{i=1}^{N} a_i t_i \boxed{\Phi(\boldsymbol{x}_i) \cdot \Phi(\boldsymbol{x})} + b$$

- **커널 함수 적용**

$$\widetilde{L}(\boldsymbol{\alpha}) = -\frac{1}{2}\sum_{i=1}^{N}\sum_{j=1}^{N}\alpha_i\alpha_j t_i t_j \boxed{K(\boldsymbol{x}_i, \boldsymbol{x}_j)} + \sum_{i=1}^{N}\alpha_i$$

$$h(\boldsymbol{x}) = \sum_{i=1}^{N} a_i t_i \boxed{K(\boldsymbol{x}_i, \boldsymbol{x})} + b$$

비선형 SVM

❖ 초평면 결정

- 선형 SVM

$$\widetilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\begin{bmatrix}\alpha_1 & \alpha_2 & \cdots & \alpha_N\end{bmatrix}\begin{bmatrix} t_1t_1\boldsymbol{x_1}\cdot\boldsymbol{x_1} & t_1t_2\boldsymbol{x_1}\cdot\boldsymbol{x_2} & \cdots & t_1t_N\boldsymbol{x_1}\cdot\boldsymbol{x_N} \\ t_2t_1\boldsymbol{x_2}\cdot\boldsymbol{x_1} & t_2t_2\boldsymbol{x_2}\cdot\boldsymbol{x_2} & \cdots & t_2t_N\boldsymbol{x_2}\cdot\boldsymbol{x_N} \\ \vdots & \vdots & \ddots & \vdots \\ t_Nt_1\boldsymbol{x_N}\cdot\boldsymbol{x_1} & t_Nt_2\boldsymbol{x_N}\cdot\boldsymbol{x_2} & \cdots & t_Nt_N\boldsymbol{x_N}\cdot\boldsymbol{x_N}\end{bmatrix}\begin{bmatrix}\alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N\end{bmatrix} - \sum_{i=1}^{N}\alpha_i$$

- 비선형 SVM

$$\widetilde{L}(\boldsymbol{\alpha}) = \frac{1}{2}\begin{bmatrix}\alpha_1 & \alpha_2 & \cdots & \alpha_N\end{bmatrix}\begin{bmatrix} t_1t_1K(\boldsymbol{x_1},\boldsymbol{x_1}) & t_1t_2K(\boldsymbol{x_1},\boldsymbol{x_2}) & \cdots & t_1t_NK(\boldsymbol{x_1},\boldsymbol{x_N}) \\ t_2t_1K(\boldsymbol{x_2},\boldsymbol{x_1}) & t_2t_2K(\boldsymbol{x_2},\boldsymbol{x_2}) & \cdots & t_2t_NK(\boldsymbol{x_2},\boldsymbol{x_N}) \\ \vdots & \vdots & \ddots & \vdots \\ t_Nt_1K(\boldsymbol{x_N},\boldsymbol{x_1}) & t_Nt_2K(\boldsymbol{x_N},\boldsymbol{x_2}) & \cdots & t_Nt_NK(\boldsymbol{x_N},\boldsymbol{x_N})\end{bmatrix}\begin{bmatrix}\alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N\end{bmatrix} - \sum_{i=1}^{N}\alpha_i$$

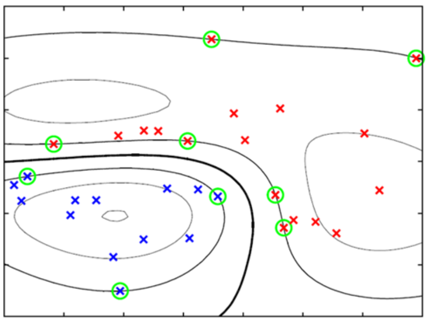
- 이차식 계획법 라이브러리 사용
  - quadprog( ), solver.qp()
  - $\alpha_1, \alpha_2, \ldots, \alpha_N$ 계산
  - 고차원의 초평면 함수 결정

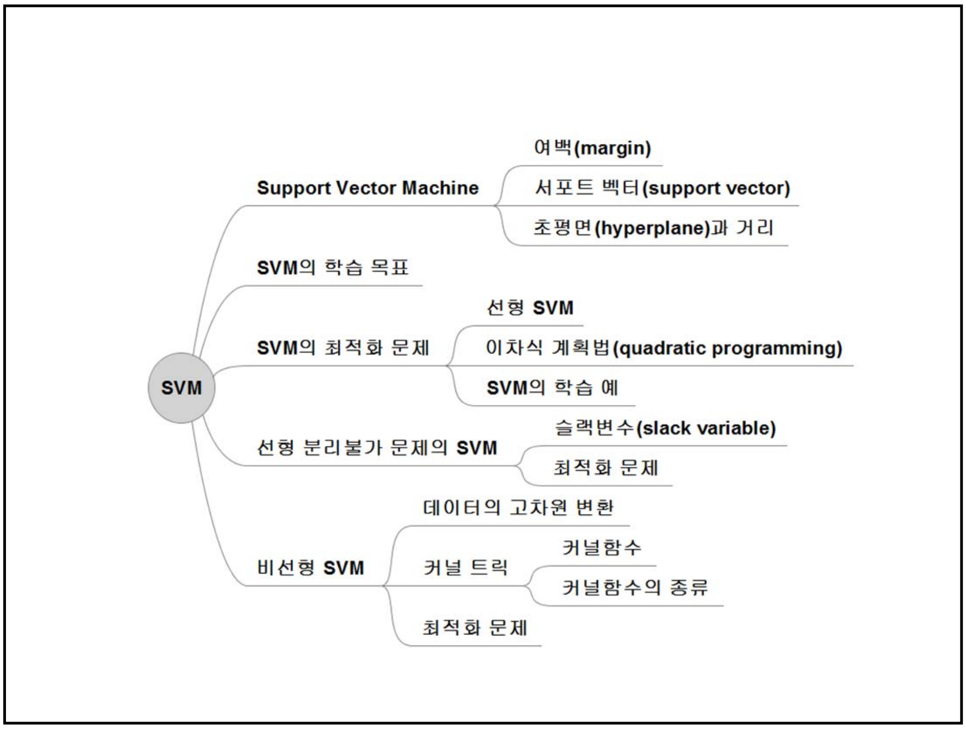
$$h(x) = \sum_{i=1}^{N} a_i t_i \Phi(x_i)\cdot\Phi(x) + b$$

$$h(\boldsymbol{x}) = \sum_{i=1}^{N} a_i t_i K(\boldsymbol{x}_i, \boldsymbol{x}) + b$$

SVM

❖ 비선형 SVM에 의한 결정 경계 및 서포트 벡터




SVM
Support Vector Machine
여백(margin)
서포트 벡터(support vector)
초평면(hyperplane)과 거리
SVM의 학습 목표
SVM의 최적화 문제
선형 SVM
이차식 계획법(quadratic programming)
SVM의 학습 예
선형 분리불가 문제의 SVM
슬랙변수(slack variable)
최적화 문제
비선형 SVM
데이터의 고차원 변환
커널 트릭
커널함수
커널함수의 종류
최적화 문제