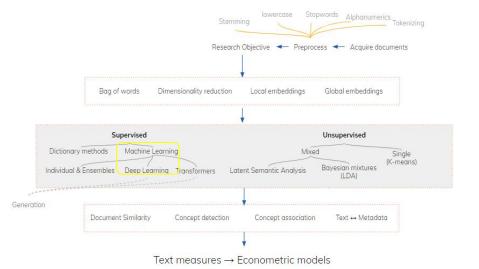


# Natural Language Processing in Economics

Advanced Supervised Learning





# **Neural Networks**



- Recall the logistic regression model presented in the previous lecture

$$\hat{\mathbf{w}}_{ML} = \underset{\mathbf{w}}{\operatorname{argmin}} \ \sum_{i=1}^{N} \underbrace{-y_i \log \hat{y}_i - (1-y_i) \log (1-\hat{y}_i)}_{\text{Binary Cross Entropy Loss } \mathcal{L}(\hat{y}_i, y_i)}$$

with 
$$\hat{y} = f_{\mathbf{w}}(\mathbf{x}) = \sigma(\mathbf{w}^{\top}\mathbf{x})$$
 and  $\sigma(x) = \frac{1}{1 + e^{-x}}$ 

- Minimisation of a **non-linear objective** requires the calculation of gradients  $\nabla_{\mathbf{w}} \mathcal{L}(\hat{y}_i, y_i) = (\hat{y}_i y_i)\mathbf{x}_i$
- This is often a difficult problem to visualise and compute → **computation graphs**



#### Idea

- Decompose complex computations into a sequence of atomic assignments, called a computation graph
- The forward pass takes a training point (x, y) as input and computes a loss, ie.

$$\mathcal{L} = -\log p_{model}(y|\mathbf{x}, \mathbf{w})$$

- The relevant gradients can be computed using a **backward pass**, which are efficient due to the use of dynamic programming, ie. storing and reusing intermediate results
- This decomposition and reuse of computation is key to the success of the backpropagation algorithm, the primary workhorse of deep learning

#### Three kind of nodes

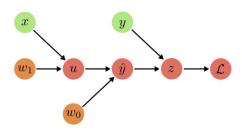
- Green: Input nodes
- Orange: Parameter nodes
- Red: Compute nodes

(1) 
$$u = w_1 x$$

(2) 
$$\hat{y} = w_0 + u$$

$$(3) \quad z = \hat{y} - y$$

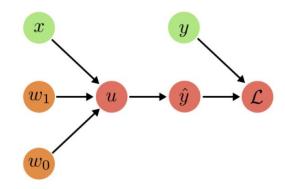
(4) 
$$\mathcal{L} = z^2$$





#### **Example - Logistic Regression**

- (1)  $u = w_0 + w_1 x$
- $(2) \quad \hat{y} = \sigma(u)$
- (3)  $\mathcal{L} = -y \log \hat{y} (1 y) \log(1 \hat{y})$



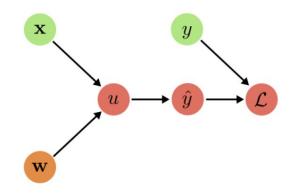


#### **Example - Logistic Regression**

$$(1) \quad u = \mathbf{w}^{\top} \mathbf{x}$$

$$(2) \quad \hat{y} = \sigma(u)$$

(3) 
$$\mathcal{L} = -y \log \hat{y} - (1 - y) \log(1 - \hat{y})$$



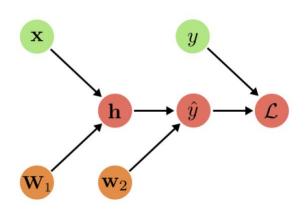


#### Example - Multilayer perceptron

(1) 
$$\mathbf{h} = \sigma(\mathbf{W}_1^{\top} \mathbf{x})$$

(2) 
$$\hat{y} = \sigma(\mathbf{w}_2^{\top} \mathbf{h})$$

(3) 
$$\mathcal{L} = -y \log \hat{y} - (1 - y) \log(1 - \hat{y})$$





$$\frac{\mathrm{d}}{\mathrm{d}x}f(g(x)) = \frac{\mathrm{d}f}{\mathrm{d}g}\frac{\mathrm{d}g}{\mathrm{d}x}$$

$$\frac{\mathrm{d}}{\mathrm{d}x}f(g(x)) = \frac{\mathrm{d}f}{\mathrm{d}g}\frac{\mathrm{d}g}{\mathrm{d}x} \qquad \frac{\mathrm{d}}{\mathrm{d}x}f(g_1(x),\dots,g_M(x)) = \sum_{i=1}^M \frac{\partial f}{\partial g_i}\frac{\mathrm{d}g_i}{\mathrm{d}x}$$

#### Backpropagation

We optimise model parameters w by using gradient descent with respect to the loss function

$$\nabla_{\mathbf{w}} \mathcal{L}(\mathbf{y}, \mathbf{X}, \mathbf{w}) = \nabla_{\mathbf{w}} \sum_{i=1}^{N} \mathcal{L}(y_i, \mathbf{x}_i, \mathbf{w}) = \sum_{i=1}^{N} \nabla_{\mathbf{w}} \mathcal{L}(y_i, \mathbf{x}_i, \mathbf{w})$$

#### Forward Pass:

(1) 
$$y = x^2$$

(2) 
$$\mathcal{L} = 2y$$

Loss:  $\mathcal{L} = 2x^2$ 

A simple example of **forward pass** followed by the **backward pass** 

#### **Backward Pass:**

(2) 
$$\frac{\partial \mathcal{L}}{\partial y} = \frac{\partial \mathcal{L}}{\partial \mathcal{L}} \frac{\partial \mathcal{L}}{\partial y} = 2$$

(1) 
$$\frac{\partial \mathcal{L}}{\partial x} = \frac{\partial \mathcal{L}}{\partial y} \frac{\partial y}{\partial x} = \frac{\partial \mathcal{L}}{\partial y} 2x$$

► **Red:** back-propagated gradients

▶ Blue: local gradients



$$\frac{\mathrm{d}}{\mathrm{d}x}f(g(x)) = \frac{\mathrm{d}f}{\mathrm{d}g}\frac{\mathrm{d}g}{\mathrm{d}x}$$

$$\frac{\mathrm{d}}{\mathrm{d}x}f(g(x)) = \frac{\mathrm{d}f}{\mathrm{d}g}\frac{\mathrm{d}g}{\mathrm{d}x} \qquad \qquad \frac{\mathrm{d}}{\mathrm{d}x}f(g_1(x),\dots,g_M(x)) = \sum_{i=1}^M \frac{\partial f}{\partial g_i}\frac{\mathrm{d}g_i}{\mathrm{d}x}$$

#### **Backpropagation**

#### Forward Pass:

$$(1) \quad y = y(x)$$

$$(2) \quad u = u(y)$$

$$(2) \quad v = v(y)$$

(3) 
$$\mathcal{L} = \mathcal{L}(u, v)$$

#### **Backward Pass:**

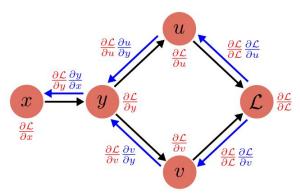
(3) 
$$\frac{\partial \mathcal{L}}{\partial u} = \frac{\partial \mathcal{L}}{\partial \mathcal{L}} \frac{\partial \mathcal{L}}{\partial u} = \frac{\partial \mathcal{L}}{\partial u}$$

(3) 
$$\frac{\partial \mathcal{L}}{\partial v} = \frac{\partial \mathcal{L}}{\partial \mathcal{L}} \frac{\partial \mathcal{L}}{\partial v} = \frac{\partial \mathcal{L}}{\partial v}$$

(2) 
$$\frac{\partial \mathcal{L}}{\partial y} = \frac{\partial \mathcal{L}}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial \mathcal{L}}{\partial v} \frac{\partial v}{\partial y}$$

$$(1) \quad \frac{\partial \mathcal{L}}{\partial x} = \frac{\partial \mathcal{L}}{\partial y} \frac{\partial y}{\partial x}$$

**Loss:**  $\mathcal{L}(u(y(x)), v(y(x)))$ 



$$\frac{\mathrm{d}}{\mathrm{d}y}\mathcal{L}(u(y),v(y)) = \frac{\partial \mathcal{L}}{\partial u}\frac{\mathrm{d}u}{\mathrm{d}y} + \frac{\partial \mathcal{L}}{\partial v}\frac{\mathrm{d}v}{\mathrm{d}y}$$

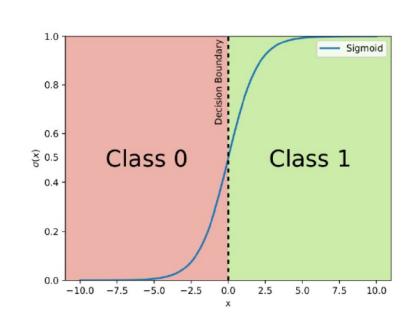
All incoming gradients must be **summed** up!



# A Logistic Regression is a Neural Network

$$\hat{y} = \sigma(\mathbf{w}^T \mathbf{x} + w_0)$$
 with  $\sigma(x) = \frac{1}{1 + \exp(-x)}$ 

- Let  $\mathbf{x} \in \mathbf{R}^2$
- Decision boundary:  $\mathbf{w}^T \mathbf{x} + w_0 = 0$
- Decide for Class  $0 \leftrightarrow \mathbf{w}^T \mathbf{x} < -w_0$
- Decide for Class  $1 \leftrightarrow \mathbf{w}^T \mathbf{x} > -w_0$

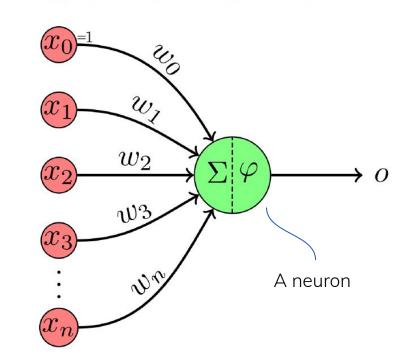




### The Perceptron

$$o = \sigma(w_0x_0 + w_1x_1 + w_2x_2...) = \sigma(\sum w_ix_i) = \sigma(\mathbf{w}^T\mathbf{x})$$

- Let  $x \in \mathbb{R}^n$
- Decision boundary:  $\sigma(\mathbf{w}^T\mathbf{x}) = 0.5$
- Binary Cross Entropy Loss
- Backpropagation
- Stochastic Gradient Descent

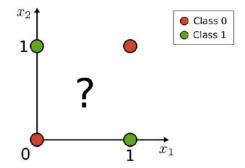




# The XOR problem

#### Linear Classifier:

Class 
$$1 \Leftrightarrow \mathbf{w}^{\top} \mathbf{x} > -w_0$$



- Minsky & Papert's 1969 book on the limitations of perceptrons
- The first Al winter

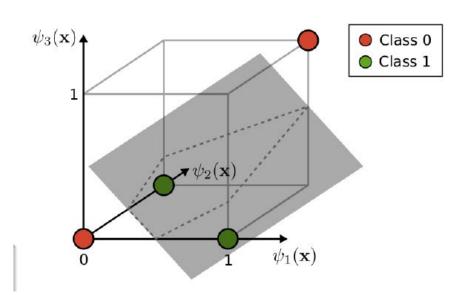


### The XOR solution

# Linear classifier with non-linear features $\psi$ :

$$\mathbf{w}^{\top} \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_1 x_2 \end{pmatrix}} > -w_0$$

$$\underbrace{\psi(\mathbf{x})}$$



- Non-linear features allow linear classifier to solve non-linear classification problems
- Analogous to using kernel tricks in regressions or SVMs







## **Universal Approximation Theorem**

#### Theorem (Cybenko, 1989; Hornik, 1991)

A feedforward neural network with a single hidden layer containing a finite number of neurons can approximate any continuous function on a compact subset of **R**n

- This result is agnostic about the choice of activation function
- The result does not imply the approximation (weights) can be learned



# **Multilayer Perceptrons**

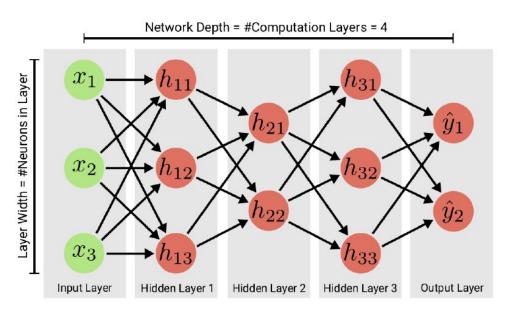
- MLPs are **feedforward** neural networks (no feedback connections)
- They compose several nonlinear functions  ${f f}({f x})=\hat{{f y}}({f h}_3({f h}_2({f h}_1({f x}))))$  where  ${f h}$  are hidden layers and  ${f y}$  is the output layer
- The data specifies only the behavior of the output layer (thus the name **hidden**)
- Each layer **i** comprises multiple neurons **j** which are implemented as **affine transformations**  $(\mathbf{a}^{\top}\mathbf{x} + \mathbf{b})$  followed by nonlinear activation functions **g**

$$h_{ij} = g(\mathbf{a}_{ij}^{\top} \mathbf{h}_{i-1} + \mathbf{b}_{ij})$$

- Each neuron in each layer is fully connected to all neurons of the previous layer
- The overall length of the chain is the **depth** of the model → Deep Learning



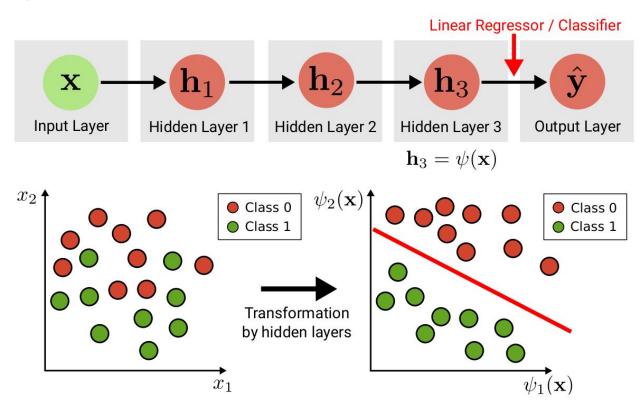
## **Multilayer Perceptrons**



- Neurons are grouped into layers, each neuron is **fully connected** to all previous ones
- **Hidden layer h** has an activation function **g** and weights **A**, **b**

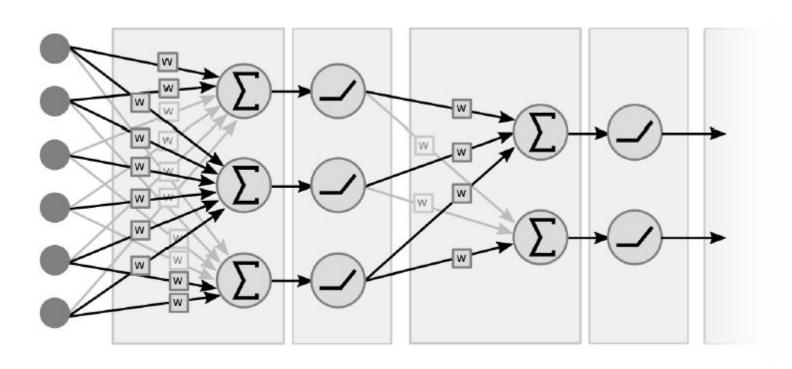


### Multilayer Perceptrons - Feature learning





# **Multilayer Perceptrons**

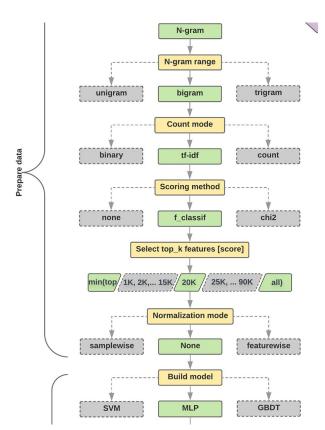




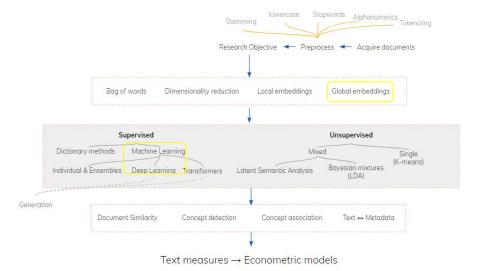
### Google Developers **Guide** for Text Classification

- With relative few, longer documents, use an MLP
- The inputs **x** are **tf-idf weighted bigrams** 
  - Select 20,000 features using SML
- Employ an MLP with two hidden layers

A MLP is one of the models tried by the Peterson and Spirling (2018) paper we saw on predicting polarisation in the UK parliament







# **Sequential Models**



### Classical IMDb classification problem



- Bag of words models can't capture the importance of "don't love" or "nothing don't love", even with many hidden layers
- N-grams have a large feature space and don't share information across similar words and n-grams



### Sequence data

The deep learning breakthrough on NLP  $\rightarrow$  move from bag-of-many representations to sequences

- Rather than inputting counts over n-grams, these models take as input a sequence of tokens

Note as well that feedforward MLP handle fix-length data, but many applications have variable lengths

$$\begin{aligned} \mathbf{x}_1 &= (\mathbf{x}_{1,1}, \mathbf{x}_{1,2}, \mathbf{x}_{1,3}, \mathbf{x}_{1,4}, \mathbf{x}_{1,5}) & \mathbf{x}_1 &= (\mathbf{x}_{1,1}, \mathbf{x}_{1,2}, \mathbf{x}_{1,3}, \mathbf{x}_{1,4}, \mathbf{x}_{1,5}) \\ \mathbf{x}_2 &= (\mathbf{x}_{2,1}, \mathbf{x}_{2,2}, \mathbf{x}_{2,3}, \mathbf{x}_{2,4}, \mathbf{x}_{2,5}) & \mathbf{x}_2 &= (\mathbf{x}_{2,1}, \mathbf{x}_{2,2}, \mathbf{x}_{2,3}) \\ \mathbf{x}_3 &= (\mathbf{x}_{3,1}, \mathbf{x}_{3,2}, \mathbf{x}_{3,3}, \mathbf{x}_{3,4}, \mathbf{x}_{3,5}) & \mathbf{x}_3 &= (\mathbf{x}_{3,1}, \mathbf{x}_{3,2}, \mathbf{x}_{3,3}, \mathbf{x}_{3,4}) \end{aligned}$$

Sentence sentiment classification Sound phenomene Recognition Filmed activities

#### **Sub-par solutions**

- Zero-pad up to length of longest sequence

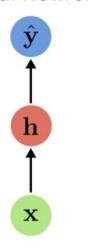
- Iterate a single layer over each value

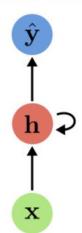


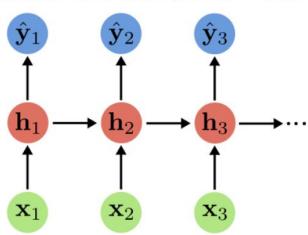
#### **Recurrent Neural Network**

Feedforward Neural Network Recurrent Neural Network (RNN) with feedback connection

Recurrent Neural Network (RNN) unrolled over time (index = time t)







#### Core idea

- Update hidden state **h** based on a new input and the previous hidden state using the same parameters at each time step → **encodes** sequences into vectors, & **decodes** vectors into sequences
- Allows for processing **sequences of variable length**, and stores long-term dependencies

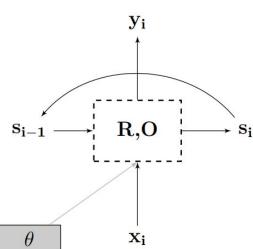


#### **Recurrent Neural Network Architecture**

- At each step **t**:
  - A recursion function  $R(s_{t-1}, x_t; \theta_R)$  computes the state vector  $\mathbf{s}_t$  given current word  $\mathbf{x}_t$  and previous state  $\mathbf{s}_{t-1}$
  - An output function  $O(s_t; \theta_O)$  computes the state vector **y** (to be compared to the outcome variable in the dataset.

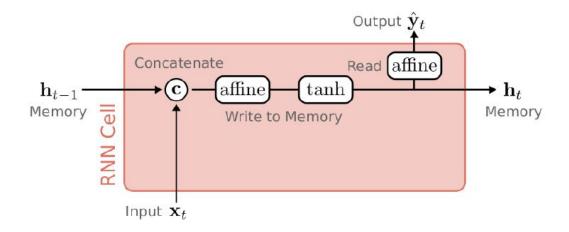
$$\hat{\boldsymbol{y}}_t = O(\boldsymbol{s}_t, \theta_O)$$
  
 $\boldsymbol{s}_t = R(\boldsymbol{s}_{t-1}, \boldsymbol{x}_t, \theta_R)$ 

The parameters of those functions  $\theta = (\theta_R, \theta_O)$  are learned during training





#### **Recurrent Neural Network Architecture**



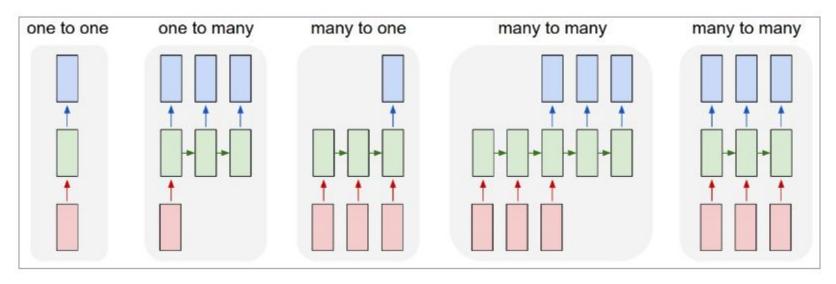
$$\mathbf{h}_t = f_h(\mathbf{h}_{t-1}, x_t) = anh\left(\mathbf{A}^{(h)}\mathbf{h}_{t-1} + \mathbf{A}^{(x)}x_t + b\right)$$

$$\hat{\mathbf{y}}_t = f_y(\mathbf{h}_t) = \mathbf{A}^{(y)}\mathbf{h}_t$$

Parameters  $\mathbf{A}^{(h)}$ ,  $\mathbf{A}^{(x)}$ ,  $\mathbf{A}^{(y)}$  and b are constant over time.



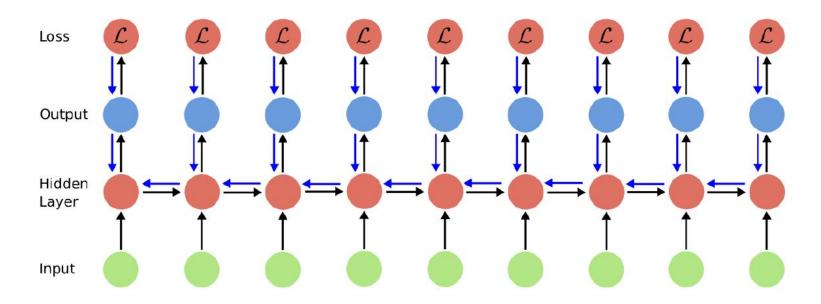
### **Recurrent Neural Network Architecture**



- One to one: image to label
- **One to many**: image to sentence
- Many to one: sentence to label
- **Many to many**: sentence to sentence

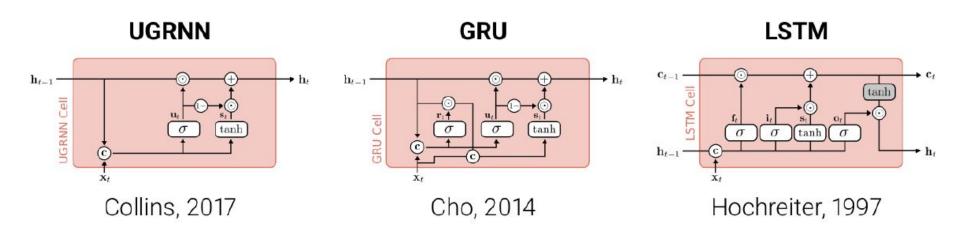


### **Training a Recurrent Neural Network**





#### **Gated Recurrent Neural Network**



Shared attribute: **gates** for filtering information

- UGRNN: A sigmoid gate controls how much new information is sued
- GRU: A reset gate controls the relevance of the previous state on f
- LSTM: An additional cell **c** carries long term information

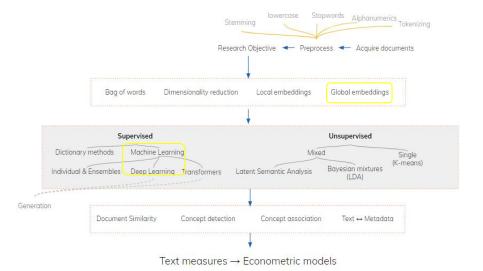


#### **Gated Recurrent Neural Network**

#### **Caveats**

- **Sequence-to-sequence mapping**: Traditional RNNs are designed for synchronized input-output mapping. In many applications, such as machine translation or text summarising, often we deal with variable-length outputs
- **Information bottleneck**: in traditional RNNs, the hidden state must encode all the relevant information from the input sequence into the fixed-length vector, leading to memory leakage and forgetting long-term dependencies
- **Bidirectional context**: RNNs process sequences in a forward-only manner, which means they have limited access to future context when making predictions. This can be problematic for tasks where future context matters



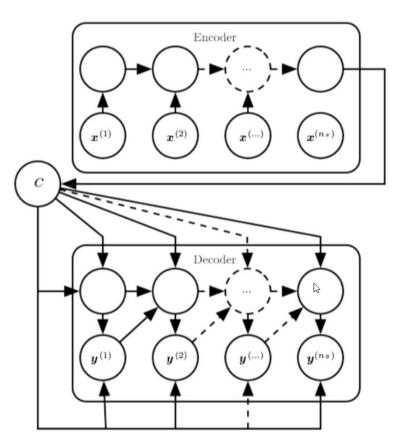


# **Encoder-Decoder models**



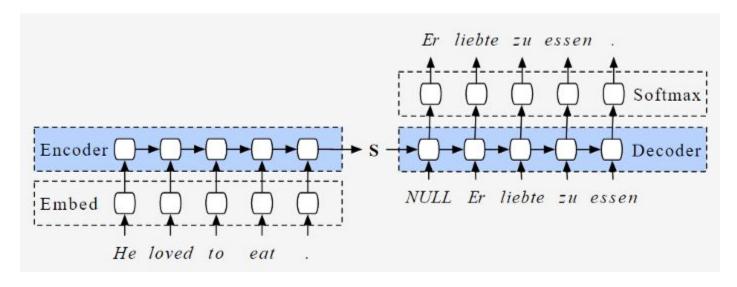
### **Encoder-Decoders: Machine Translation**

- The **seq2seq** model:
  - $-x^{(i)}$ ;  $i^{th}$  word input
  - $-y^{(i)}$ ;  $i^{th}$  word output
  - c; context vector
- Applications
  - Question Answering
  - Machine translation
  - Machine conversation





### **Encoder-Decoders: Machine Translation**



**Problem**: The **s** vector aggregates all contextual relations within a paragraph, and does not discriminate among within-string relations

**Solution**: The **Attention** mechanism



### **Attention mechanism**

- Probabilistic retrieval of a **value v**i for a **query q**□ based on a **key k**i

similarity
$$(q_m, k_i) = q_m^{\top} k_i$$

- Similarities are transformed into probabilities through a softmax

$$a_{m,i} = \frac{\exp\left(q_m^\top k_i\right)}{\sum_{j} \exp\left(q_m^\top k_j\right)}$$

- The output is a linear combination of values or vectors  $v_i$ 

$$\operatorname{attention}(q_m, \mathbf{k}, \mathbf{v}) = \sum_i a_{m,i} \cdot v_i$$

- The embeddings  $\mathbf{q}$ ,  $\mathbf{k}$ ,  $\mathbf{v}$  are learned from the data



### **Attention mechanism in Machine Translation**

- values v: The encoder hidden states  $h_i$  for  $i \in \{1, 2, \dots, H\}$
- queries q: The decoder hidden states  $s_i$  for  $i \in \{1, 2, \dots, S\}$
- **keys** k: The **encoder** hidden states  $h_i$  for  $i \in \{1, 2, ..., H\}$
- The similarity measure for decoding step  ${f i}$  and encoding step  ${f j}$  is

similarity
$$(s_i, h_j) = s_i^{\top} h_j$$

- The attention weight is the softmax probability

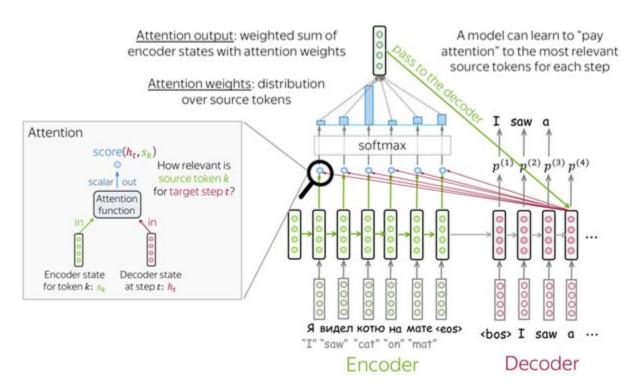
$$a_{i,j} = \frac{\exp\left(s_i^{\top} h_j\right)}{\sum_{i} \exp\left(s_i^{\top} h_j\right)}$$

- The new context vector for decoding step **i** is the **attention** 

$$c_i = \sum_i a_{i,j} \cdot h_j$$



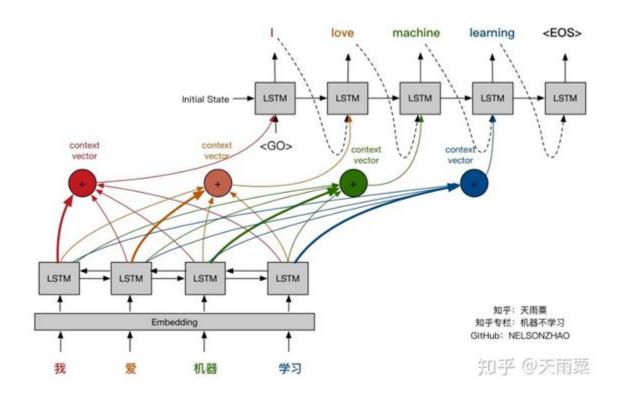
### **Attention mechanism in Machine Translation**



A layer, like a dense layer, an embedding layer

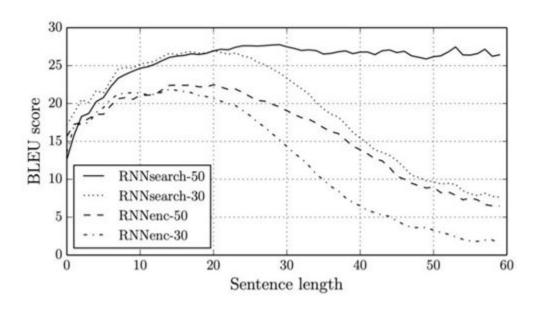


### **Attention mechanism in Machine Translation**





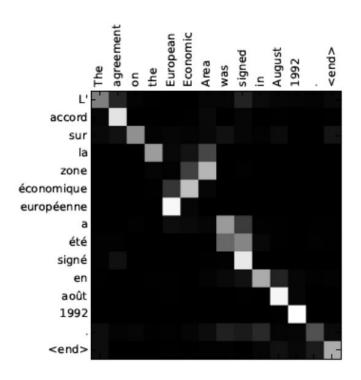
# Attention mechanism in Machine Translation

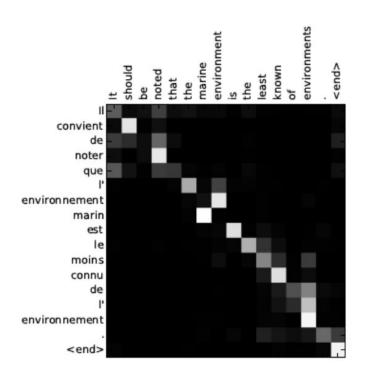


The Bilingual Evaluation Understudy score is a metric used to evaluate the quality of machine-generated translations by comparing them to one or more human reference translations.

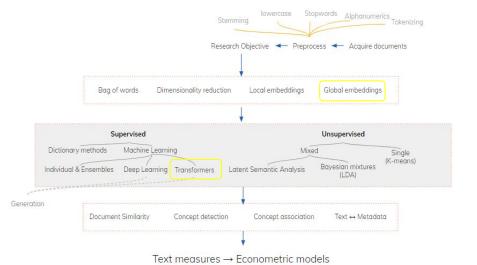


# Attention mechanism in Machine Translation \_\_









# **Transformers**



### **Transformers**

- Most NLP deep learning use transformer-based architectures since Vaswani et al. (2017)
- Recurrent neural nets can process whole documents word-by-word, but they have to sweep through the whole document at each training epoch. This greatly reduces their scalability, as it creates I/O bottlenecks and prevents parallelization.

#### **Transformers** overcome this limitation:

- These methods process inputs in parallel, making them highly scalable and efficient for large-scale NLP tasks. They don't process the entire input sequentially (no recurrence).
- They use self-attention mechanisms, enabling them to capture long-range dependencies in text effectively. This allows to retain relationships between words or tokens that are distant from each other.

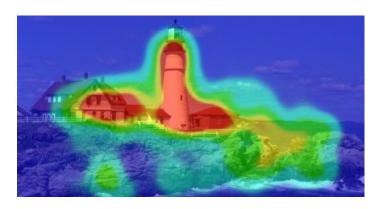


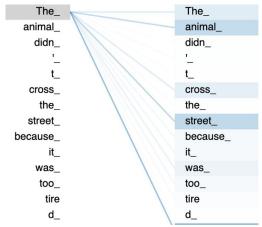
### **Attention in AI Research**

- Attention in Computer Vision (2014)
  - Used to highlight important parts of an image that assist downstream tasks



- 2015: Aligned Machine Translation
- 2017: Transformer Networks & Language Modeling







### **Transformers in NLP**

- Transformer models consist of (many) stacked blocks of parallel **attention heads** 
  - These are machine-reading filters, which allow each word to scan over every other word in the document and pick up the most predictive key-value interactions

#### Encoder models

- **BERT** Trained to predict left-out words in the middle of a sequence
- **AlphaFold** Protein folding encoder
- **CLIP** Image & Object classification

#### - Decoder models

- **GPT** Train a transformer to predict the next word at the end of a sequence
- **LLaMA** Commonsense reasoning, reading comprehension
- **Alpaca** Text generation and classification task

Bottom line: many pre-trained models, can be quickly fine-tuned for downstream tasks (Transfer Learning)



# huggingface 🤗

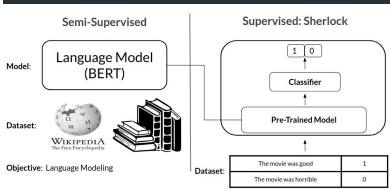
- A popular open-source library and platform for NLP tasks. It offers a comprehensive set of tools and deep learning resources, including Python's most popular **transformer** library.
- It contains hundreds of pre-trained models based on most popular transformer architectures, trained on massive amounts of text data and easily fine-tunable.
- Easy to use API interface, and a large repository of community-contributed pre-trained models, datasets, and evaluation metrics.
- A Hub where people upload and share their models, and explore others'.

```
from transformers import pipeline
sentiment_analysis = pipeline("sentiment-analysis")

pos_text = "I enjoy studying computational algorithms."
neg_text = "I dislike sleeping late everyday."

pos_sent = sentiment_analysis(pos_text)[0]
print(pos_sent['label'],0 pos_sent['score'])

neg_sent = sentiment_analysis(neg_text)[0]
print(neg_sent['label'], neg_sent['score'])
```





### **Self-attention mechanism**

- A self-referencing attention mechanism
  - **values** v: Word embedding vectors **x** (either input or output)
  - **keys** k: Word embedding vectors **x** (either input or output)
  - queries q: Word embedding  $x_i$  of the previously generated output
- The similarity measure for **queried embedding**  $x_i$  and other embeddings is

$$h_i = \sum_{j=1}^{n_L} a(x_i, x_j) x_j$$

- The attention weight is the softmax probability (sum of weights = 1)

$$a(x_i, x_j) = \operatorname{softmax}(\frac{x_i \cdot x_j}{\sqrt{n_E}}) = \frac{\exp(\frac{x_i \cdot x_j}{\sqrt{n_E}})}{\sum_{k=1}^{n_L} \exp(\frac{x_i \cdot x_j}{\sqrt{n_E}})}$$
 Scaled by embedding length

- Note
  - Basic self-attention has no learnable parameters & ignores word order



# Self-attention mechanism - example

Consider a sentence

the, cat, walks, on, the, street

with embeddings

- Feeding this sentence into **self-attention layer** produces

$$h_{\text{the}}, h_{\text{cat}}, h_{\text{walks}}, h_{\text{on}}, h_{\text{the}}, h_{\text{street}}$$

where

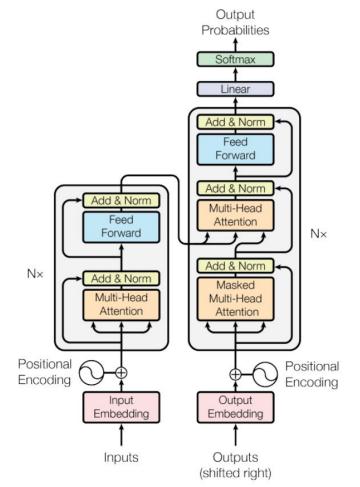
$$\boldsymbol{h}_i = a(x_i \cdot \boldsymbol{x}_{\text{the}}) \boldsymbol{x}_{\text{the}} + a(x_i \cdot \boldsymbol{x}_{\text{cat}}) \boldsymbol{x}_{\text{cat}} + ... + a(x_i \cdot \boldsymbol{x}_{\text{street}}) \boldsymbol{x}_{\text{street}}$$



### Vaswani et al. (2017) - Attention Is All You Need

- An **encoder-decoder** based on attention
- No recurrence
  - Input: entire sequence to translate
  - **Output**: entire translated sentence
  - Positional encoding necessary to distinguish embeddings from some BoW representation
- Core idea: use attention to learn abstract embeddings
  - **n=1**: pairs of embeddings
  - n=2: pairs of pairs of embeddings

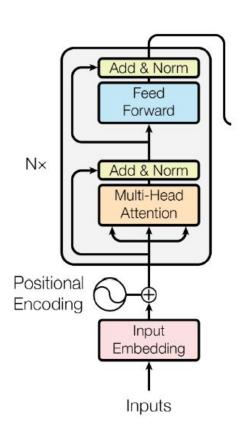
...





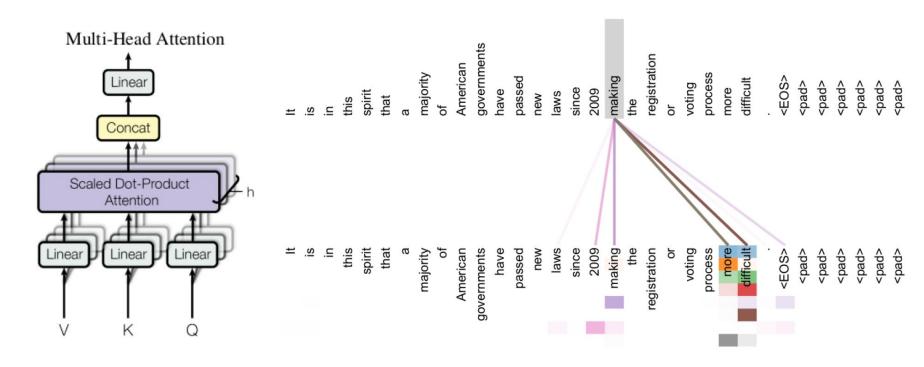
### Vaswani et al. (2017) - Attention Is All You Need

- Input embedding: vocabulary-sized embedding
- Positional encodings: joins chunk index position
- Repeat N times
  - Multi-headed attention layer
  - Bypass & add input embedding, normalise
  - Two linear transformations & ReLU activation
  - Bypass & add embeddings, normalise
- Feed forward to encoder
- Note: Model is bidirectional because next word predictions are done forwards and backwards





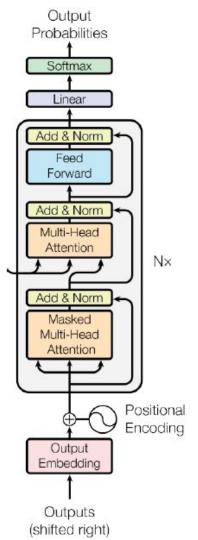
Vaswani et al. (2017) - Attention Is All You Need



As nice as this is, this is also the models' main drawback: token limits

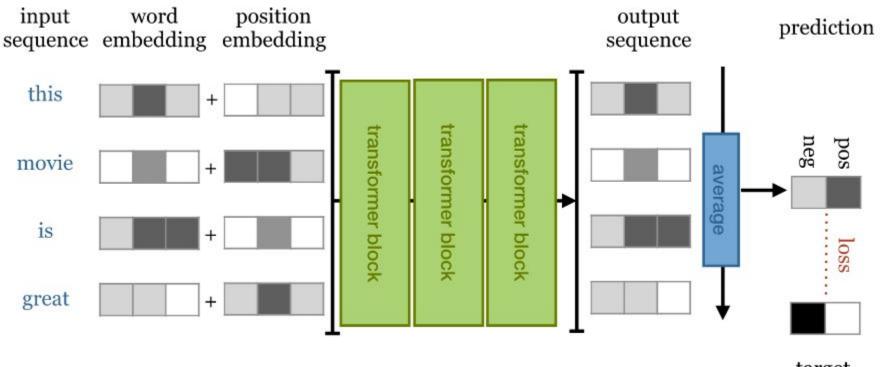
### Vaswani et al. (2017) - Attention Is All You Need

- Output embedding: vocabulary-sized embedding
- **Positional encodings**: joins chunk index position
- Repeat N times
  - Multi-headed attention layer
  - Bypass & add input embedding, normalise
  - Multi-head attention for retrieving output embeddings using the encoder query
  - Bypass & add embeddings, normalise
  - Two linear transformations & ReLU activation
  - Bypass & add embeddings, normalise
- Linear transformation, softmax for probabilities
- Prediction





## Transformers for practitioners: sentiment



target



### 

BIngler et al. (2023) - Cheap talk and cherry picking: ClimateBERT

#### Goal

Fine tune a BERT architecture to identify firms' voluntary disclosures related to climate (TCFD) & compare actions

#### Methodology

- Create sample: collect firms' annual reports and identify manually sentences related to climate disclosures align in one of several TCFD categories
- **Fine-tune model**: use a BERT decoder, and add Linear Layers on top to predict sentences categories (if apply)
- Predict & Compare: Compare talk with actual actions

#### Results

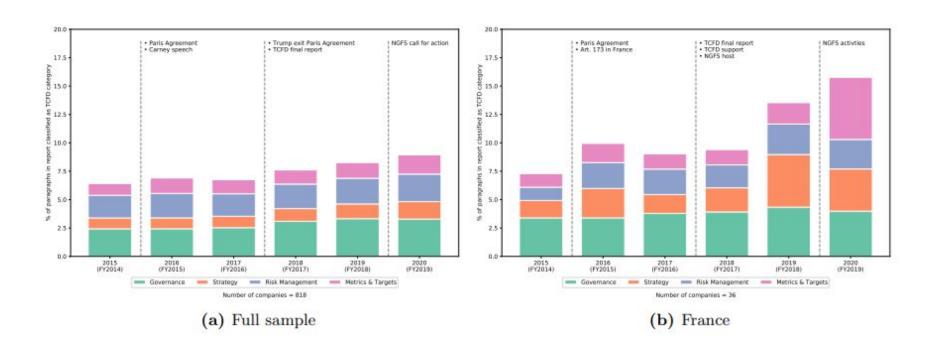
- Voluntary disclosures suffer from cheap talk
- Announced TCFD support does not lead to an increase in disclosures, and cherry pick disclosures to overwhelmingly reflect non-material categories

Governance	Strategy	Risk Management	Metrics and Targets
Disclose the organization's governance around climate- related risks and opportuni- ties.	Disclose the actual and po- tential impacts of climate- related risks and opportu- nities on the organization's businesses, strategy, and fi- nancial planning where such information is material.	Disclose how the organization identifies, assesses, and manages climate-related risks.	Disclose the metrics and targets used to assess and manage relevant climate- related risks and opportuni- ties where such information is material.
	Recommende	ed Disclosures	
Describe the board's over- sight of climate-related risks and opportunities	Describe the climate-related risks and opportunities the organization has identified over the short, medium, and long term.	Describe the organization's processes for identifying and assessing climate-related risks	Disclose the metrics used by the organization to assess climate-related risks and op- portunities in line with its strategy and risk manage- ment process.
Describe management's role in assessing and managing climate-related risks and op- portunities.	Describe the impact of climate-related risks and opportunities on the organi- zation's businesses, strategy, and financial planning.	Describe the organization's processes for managing climate-related risks.	Disclose Scope 1, Scope 2, and, if appropriate, Scope 3 greenhouse gas (GHG) emis- sions, and the related risks.
	Describe the resilience of the organization's strategy, tak- ing into consideration differ- ent climate-related scenar- ios, including a 2°C or lower scenario.	Describe how processes for identifying, assessing, and managing climate-related risks are integrated into the organization's overall risk management.	Describe the targets used by the organization to manage climate-related risks and op- portunities and performance against targets.



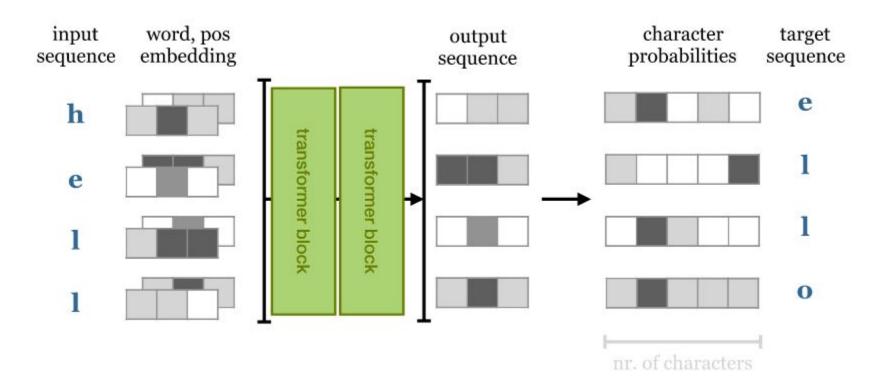
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BIngler et al. (2023) - Cheap talk and cherry picking: ClimateBERT





# Transformers for practitioners: autoregression





### **Evolution of Generative Pre-Trained Transformers**

#### **GPT-1 (2018) - 117M params**

- Trained on the Books corpus
- Trained on a language modeling task, as well as a multi-task that adds a supervised learning task

#### GPT-2 (2019) - 1.5B params

- All articles linked from Reddit with at least 3 upvotes (8 million documents, 40GB of text)
- Dispense with supervised learning task, make adjustments, enlarge the model by many orders of magnitud

#### GPT-3 (2020) - 175B params

- Use an even larger corpus (Common Crawl, WebText2, Books1, Books2, Wikipedia)
- Model becomes much larger

#### InstructGPT ↔ GPT-3.5 ↔ GPT-4

- Add reinforcement learning with human feedback to improve responsiveness & user satisfaction
- Closed-source, controversial for OpenAI an organisation built on the backs of the open-source crowd