

# Daisuke Inoue

RESEARCHER, TOYOTA CENTRAL R&D LABS., INC.

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## About me

Daisuke Inoue is a researcher at Toyota Central R&D Labs., Inc. He has been a Sponsored Researcher at Imperial College London since September 2025. He received a B.E. degree in engineering from Osaka University in 2014 and an M.S. degree in informatics from Kyoto University in 2017. He received a Ph.D. degree in mathematical science from the University of Tokyo in 2024. His current research interests include control engineering, multi-agent systems, and swarm intelligence.

## Experience

### Imperial College London

SPONSORED RESEARCHER

London, UK

Sep. 2025 - Aug. 2027

- Research on control and identification methods for large-scale systems

### Toyota Central R&D Labs., Inc.

RESEARCH ENGINEER

Aichi, Japan

Aug. 2017 - Present

- Controller design for very large-scale systems
- Exploring applications of quantum annealing machines for control engineering

### Kyoto University

TEACHING ASSISTANT

Kyoto, Japan

July. 2016 - Mar. 2017

- Teaching Assistant for Complex Analysis Class

### Siemens Industry Software N.V.

RESEARCH INTERNSHIP

Leuven, Belgium

July. 2015 - Mar. 2016

- Motion Controller Design for Airbus A330 based on 1-D & 3-D Co-simulation

### Mitsubishi Heavy Industries, Ltd.

INTERNSHIP

Kobe, Japan

July. 2014

- Development of Nuclear Power Plant Simulator

## Education

### The University of Tokyo

PH.D. IN MATHEMATICAL SCIENCES

Tokyo, Japan

Mar. 2024

- Thesis: Numerical Methods for Nonlinear Partial Differential Equations Arising from Large-Scale Multi-Agent Control Problems

### Kyoto University

M.S. IN INFORMATICS

Kyoto, Japan

Mar. 2017

- Thesis: Stability Analysis of Networked Monotone Systems

### Osaka University

B.S. IN ENGINEERING

Osaka, Japan

Mar. 2014

- Thesis: Stationary performance evaluation of control systems with random dither quantization

## Selected Publication

### JOURNAL (REFEREED)

#### An Uncertainty-Aware, Mesh-Free Numerical Method for Kolmogorov PDEs

Journal of Scientific Computing

D. INOUE, Y. ITO, T. KASHIWABARA, N. SAITO, AND H. YOSHIDA

2025

#### Traffic signal optimization in large-scale urban road networks: an adaptive-predictive controller using Ising models

IEEE Access

D. INOUE, H. YAMASHITA, K. AIHARA, AND H. YOSHIDA

2024

#### Partially Centralized Model-Predictive Mean Field Games for Controlling Multi-Agent Systems

IFAC Journal of Systems and Control

D. INOUE, Y. ITO, T. KASHIWABARA, N. SAITO, AND H. YOSHIDA

2023

<b>A fictitious-play finite-difference method for linearly solvable mean field games</b>	ESAIM: M2AN
D. INOUE, Y. ITO, T. KASHIWABARA, N. SAITO, AND H. YOSHIDA	2023
<b>Traffic Signal Optimization on a Square Lattice with Quantum Annealing</b>	Scientific Reports
D. INOUE, A. OKADA, T. MATSUMORI, K. AIHARA AND H. YOSHIDA	2021
<b>Optimal Transport-based Coverage Control for Swarm Robot Systems: Generalization of the Voronoi Tessellation-based Method</b>	IEEE Control Systems Letters
D. INOUE, Y. ITO AND H. YOSHIDA	2020
<b>Model Predictive Control for Finite Input Systems using the D-Wave Quantum Annealer</b>	Scientific Reports
D. INOUE, H. YOSHIDA	2020
CONFERENCE (REFEREED)	
<b>Stability Analysis of Logit Dynamics with Committed Minority and Internal/External Conformity Biases</b>	Proc. 22nd IFAC World Congress
T. MIYANO, Y. ITO, D. INOUE, S. KOIDE, AND T. HATANAKA	Yokohama, Japan, 2023
<b>Model Predictive Mean Field Games for Controlling Multi-Agent Systems</b>	2021 IEEE International Conference on Systems, Man, and Cybernetics
D. INOUE, Y. ITO, T. KASHIWABARA, N. SAITO, AND H. YOSHIDA	Melbourne, Australia, 2021
<b>Optimal Transport-based Coverage Control for Swarm Robot Systems: Generalization of the Voronoi Tessellation-based Method</b>	American Control Conference 2021
D. INOUE, Y. ITO AND H. YOSHIDA	New Orleans, USA, 2021
<b>Replay attack detection in control systems with quantized signals</b>	European Control Conference 2015
K. KASHIMA AND D. INOUE	Linz, Austria, 2015
<b>Stationary performance evaluation of control systems with random dither quantization</b>	European Control Conference 2014
K. KASHIMA AND D. INOUE	Strasbourg, France, 2014

## Awards

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2024	<b>Dean's Award, Graduate School of Mathematical Sciences</b> , The University of Tokyo
2017	<b>Repayment Exemption for Students with Excellent Grades</b> , Japan Student Services Organization
2016	<b>Best presentation award at The 59th Japan Automatic Control Conference</b> , The Society of Instrument and Control Engineer
2015	<b>Research Encouragement Award at The 58th Annual Conference of the Institute of Systems, Control and Information Engineers</b> , The Institute of Systems, Control and Information Engineers
2014	<b>Research Encouragement Award at The 1st Multi-symposium on Control Systems</b> , The Society of Instrument and Control Engineers

## Grants

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2015	<b>Vulcanus in Europe (15,540 dollars)</b> , Program enabling selected students to study local languages and gain work experience in Europe through the EU-Japan Centre for Industrial Cooperation.
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