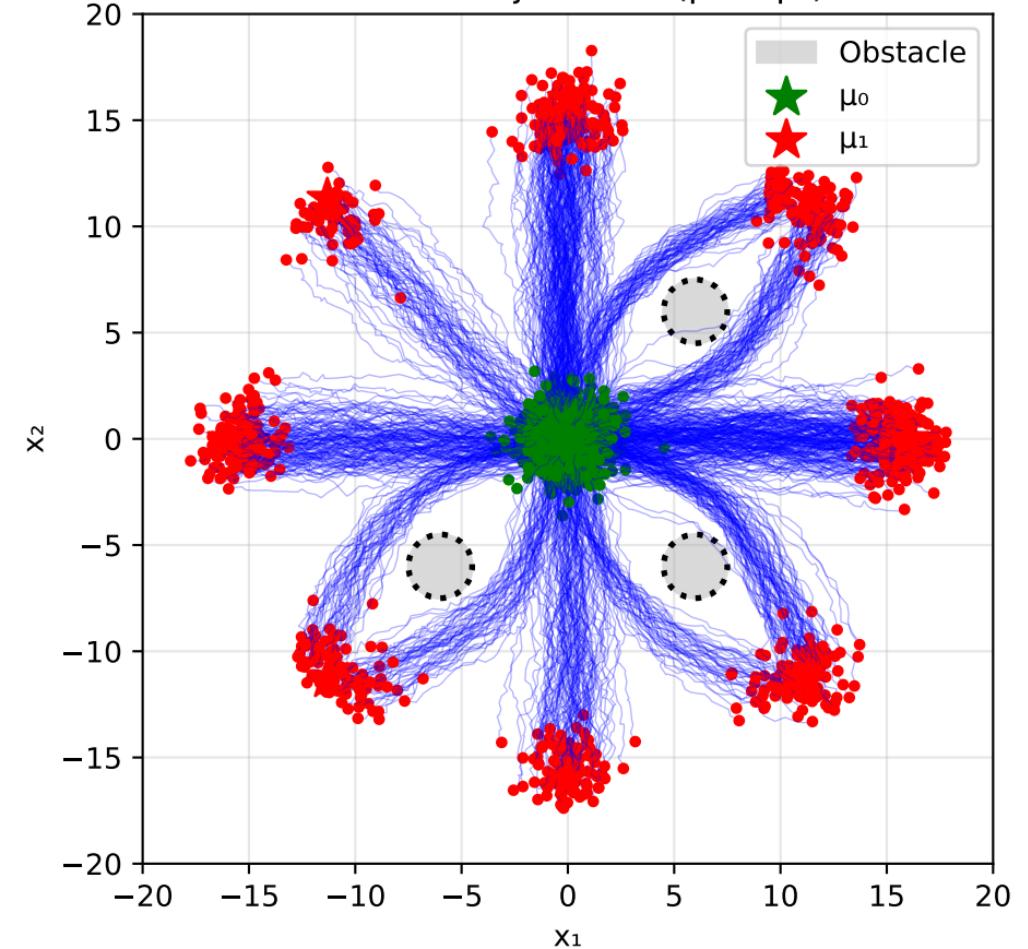


Forward Trajectories ($\rho_0 \rightarrow \rho_1$)



Backward Trajectories ($\rho_1 \rightarrow \rho_0$)

