Forward Trajectories ($\rho_0 \to \rho_1$)
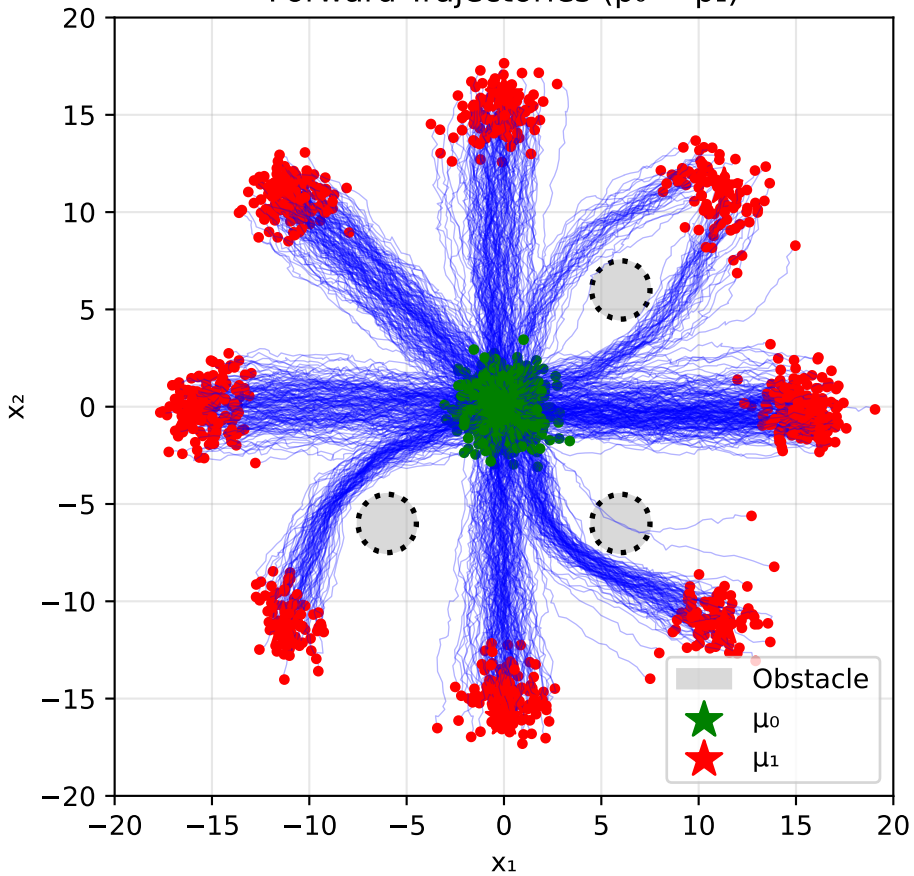
Backward Trajectories ($\rho_1 \to \rho_0$)

Obstacle

μ_0

μ_1

x_1

x_2