

Preferences in AI Project Report

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October 7, 2025

1 Introduction

This report presents experiments on free-riding in sequential decision-making under different *statistical cultures*, following the framework of [1]. Our goal is to replicate the structure of Section 5 of that work while extending it with additional statistical cultures and updated parameter settings.

2 Background

2.1 Multi-Issue Model

We study sequential decision-making in *multi-issue elections*, where a set of voters must decide on several issues, each with multiple candidates. Each voter submits approval preferences for all candidates on each issue. A voting rule is then applied issue by issue to determine the collective outcome.

2.2 Voting Rules

We focus on two major families of rules, following [1]:

- **Sequential Utilitarian Rule:** selects in each issue the candidate with the highest total number of approvals. This rule is equivalent to the mean OWA and is known to be immune to manipulation.
- **Thiele-Based Rules:** a general class where voter satisfaction decreases marginally as more of their approved candidates are selected. We evaluate sequential Thiele rules with parameters $x \in \{1, 5, 7\}$, where $x = 0$ corresponds to utilitarian aggregation.
- **OWA-Based Rules:** aggregate voter satisfaction using Ordered Weighted Averages (OWAs). Following [1], we use normalized positive weights (no zeros) interpolating between utilitarian and leximin behavior. We evaluate parametric OWA rules with $x \in \{1, 5, 10, 15\}$ and include an explicit *leximin* OWA limit.

2.3 Statistical Cultures

The way preferences are generated strongly influences manipulation risks. We consider four cultures:

- **p-IC:** per-issue impartial culture, sampling approvals independently with probability $p = 0.5$.
- **Disjoint Groups:** voters are divided into $g = 2$ groups with internally aligned preferences.
- **Resampling Model:** preferences are generated by resampling with parameters $(p, \phi) = (0.5, 0.5)$ controlling randomness and correlation.
- **Hamming Noise:** preferences are first generated from another culture and then perturbed by flipping approvals with small probability $\epsilon = 0.1$ per issue. This noise model captures robustness under small random perturbations.

2.4 Free-Riding Notion Used in the Experiments

We adopt the paper’s definition and apply the following operationalization: (i) a voter can attempt to free-ride on issue i only if she *originally approved the winning candidate* on i ; (ii) to test manipulation, we replace the ballot on issue i by a *restricted* deviation that drops that single approval (all other approvals are kept fixed), and we require that the winner on issue i *remains unchanged* (the voter is non-pivotal on i); (iii) the election outcome is recomputed using the manipulated profile, but the voter’s gain/loss is assessed with her *truthful* utilities. This deviation class is a subset of all free-riding deviations discussed in [1] but is sufficient for our experiments.

2.5 Risk Metrics

We evaluate manipulation opportunities using the following metrics:

- **Trials:** total number of voter–issue pairs considered ($n \times k$).
- **Eligible:** # pairs where the voter originally approved the winner.
- **Possible:** # eligible pairs where dropping that single approval leaves the winner unchanged.
- **Successes:** # possible pairs where the voter’s truthful utility increases.
- **Harms:** # possible pairs where the voter’s truthful utility decreases.
- **Success rate:** successes/trials.

- **Harm rate:** harms/trials.
- **Risk:** harms/possible (conditional probability of harmful manipulation).

3 Methodology

We replicate the experiments from Section 5 of [1], using four statistical cultures: impartial culture (p-IC), disjoint groups, the (p, ϕ) -resampling model, and the Hamming-noise model. For each culture, we run multiple random seeds and compare risk metrics under sequential utilitarian, sequential Thiele rules ($x = 1, 5, 7$), and OWA rules ($x = 1, 5, 10, 15$, plus leximin).

3.1 Parameters

The main parameters used in our experiments are:

- Number of voters: $n = 20$
- Number of issues: $k = 5$
- Candidates per issue: $c = 4$
- Random seeds: 200
- Cultures and hyperparameters: as defined above.

All configurations were executed using a unified experimental pipeline, which produces both tabular summaries and risk plots.

4 Results

The combined results table is automatically generated by the experiment pipeline. The table below is included directly from the output file:

4.1 Per-Culture Comparisons

To visualize the trends, we show manipulation risks by rule family (Thiele and OWA) for each statistical culture.

p-IC. Under p-IC, the utilitarian rule is immune (zero across all metrics). Within Thiele and OWA families, success rates are small but increase with the family parameter x ; harms remain tiny, and risk (harms/possible) is near zero. In our runs, the leximin extreme shows the largest success within OWA, consistent with the trend that moving away from utilitarian slightly increases exploitable opportunities.

culture	rule	seeds	trials	eligible	possible	successes	harms	success_rate	harm_rate	risk
p.ic	utilitarian	200	100.000	61.785	39.480	0.000	0.000	0.000	0.000	0.000
p.ic	thiele_x1	200	100.000	61.355	40.085	3.185	0.010	0.032	0.000	0.001
p.ic	thiele_x5	200	100.000	58.950	41.125	6.745	0.030	0.067	0.000	0.001
p.ic	thiele_x7	200	100.000	58.930	41.220	6.850	0.030	0.068	0.000	0.001
p.ic	owa_x1	200	100.000	61.785	39.485	0.085	0.000	0.001	0.000	0.000
p.ic	owa_x5	200	100.000	61.505	40.050	1.905	0.010	0.019	0.000	0.000
p.ic	owa_x10	200	100.000	60.315	39.860	5.310	0.075	0.053	0.001	0.002
p.ic	owa_x15	200	100.000	59.040	41.195	7.145	0.130	0.071	0.001	0.003
p.ic	owa_leximin	200	100.000	57.845	41.960	7.460	0.095	0.075	0.001	0.002
disjoint	utilitarian	200	100.000	34.530	28.045	0.000	0.000	0.000	0.000	0.000
disjoint	thiele_x1	200	100.000	33.835	28.275	1.495	0.000	0.015	0.000	0.000
disjoint	thiele_x5	200	100.000	33.085	29.210	1.910	0.010	0.019	0.000	0.000
disjoint	thiele_x7	200	100.000	33.085	29.210	1.920	0.010	0.019	0.000	0.000
disjoint	owa_x1	200	100.000	34.530	28.190	0.140	0.000	0.001	0.000	0.000
disjoint	owa_x5	200	100.000	33.550	28.625	1.675	0.000	0.017	0.000	0.000
disjoint	owa_x10	200	100.000	33.110	28.875	2.070	0.000	0.021	0.000	0.000
disjoint	owa_x15	200	100.000	32.880	29.245	1.995	0.010	0.020	0.000	0.000
disjoint	owa_leximin	200	100.000	32.600	29.005	2.030	0.025	0.020	0.000	0.001
resampling	utilitarian	200	100.000	77.450	57.490	0.000	0.000	0.000	0.000	0.000
resampling	thiele_x1	200	100.000	77.335	57.000	2.180	0.000	0.022	0.000	0.000
resampling	thiele_x5	200	100.000	75.610	58.280	6.030	0.000	0.060	0.000	0.000
resampling	thiele_x7	200	100.000	75.325	58.380	6.430	0.005	0.064	0.000	0.000
resampling	owa_x1	200	100.000	77.450	57.390	0.035	0.000	0.000	0.000	0.000
resampling	owa_x5	200	100.000	77.400	57.010	0.610	0.000	0.006	0.000	0.000
resampling	owa_x10	200	100.000	77.075	57.840	3.290	0.040	0.033	0.000	0.001
resampling	owa_x15	200	100.000	76.005	58.125	6.025	0.005	0.060	0.000	0.000
resampling	owa_leximin	200	100.000	74.705	58.850	7.395	0.010	0.074	0.000	0.000
hamming	utilitarian	200	100.000	61.405	38.255	0.000	0.000	0.000	0.000	0.000
hamming	thiele_x1	200	100.000	60.905	39.890	3.235	0.035	0.032	0.000	0.001
hamming	thiele_x5	200	100.000	58.590	41.935	6.165	0.030	0.062	0.000	0.001
hamming	thiele_x7	200	100.000	58.520	41.885	6.245	0.035	0.062	0.000	0.001
hamming	owa_x1	200	100.000	61.405	38.335	0.115	0.005	0.001	0.000	0.000
hamming	owa_x5	200	100.000	61.160	38.625	1.950	0.015	0.019	0.000	0.000
hamming	owa_x10	200	100.000	59.825	40.235	5.180	0.020	0.052	0.000	0.000
hamming	owa_x15	200	100.000	58.580	42.070	6.805	0.055	0.068	0.001	0.001
hamming	owa_leximin	200	100.000	57.875	42.790	6.690	0.045	0.067	0.000	0.001

Table 1: Combined results across cultures and rules. Risk metrics include trials, eligible, possible, successes, harms, success/harm rates, and risk (defined as harms/possible).

Disjoint Groups. Correlated group structure reduces overall opportunities compared to p-IC. Success rates remain low across both families; harms are close to zero and risk is negligible.

Resampling Model. Resampling yields patterns similar to p-IC: utilitarian is immune; success rates increase modestly with x in both families; harms and risk remain very small.

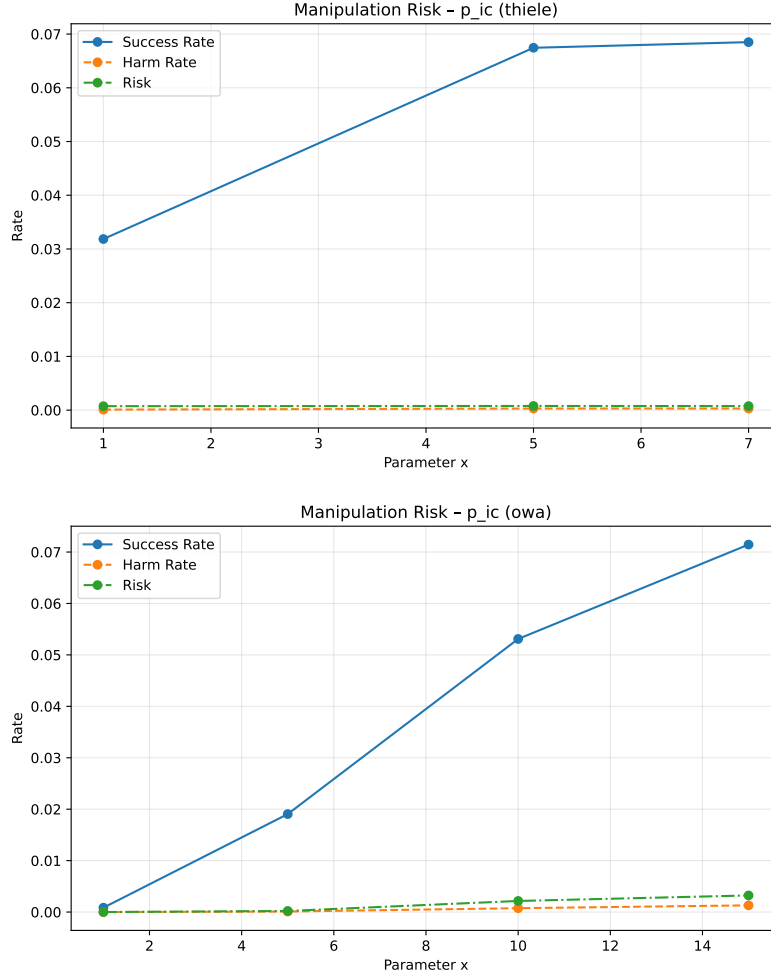


Figure 1: Manipulation risk under p-IC culture. Top: Thiele rules. Bottom: OWA rules.

Hamming Noise. Noise adds mild random perturbations but preserves the qualitative trends: utilitarian stays immune; success rises slightly with x ; harms and risk remain near zero.

5 Discussion

Our experiments highlight the dependence of manipulation risk on both the voting rule and the statistical culture.

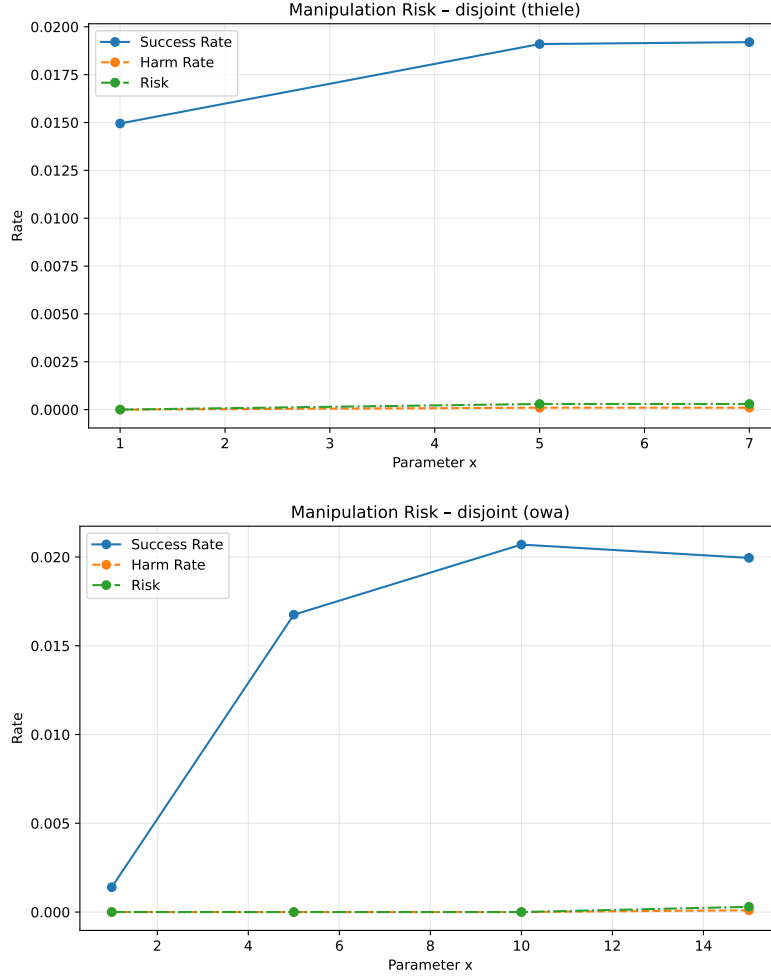


Figure 2: Manipulation risk under disjoint-group culture. Top: Thiele rules. Bottom: OWA rules.

Effect of Statistical Cultures. The *p-IC* and *resampling* cultures show modest manipulation opportunities. The *disjoint* model has fewer opportunities overall. *Hamming noise* perturbs preferences slightly but does not qualitatively change the picture.

Effect of Voting Rules. The *utilitarian rule* (equivalently mean OWA) is immune to manipulation. For both Thiele and OWA families, moving away from the utilitarian endpoint (larger x in our parameterization) increases the fraction of successful free-rides, while harm remains rare; consequently, risk (harms/possible) stays very small.

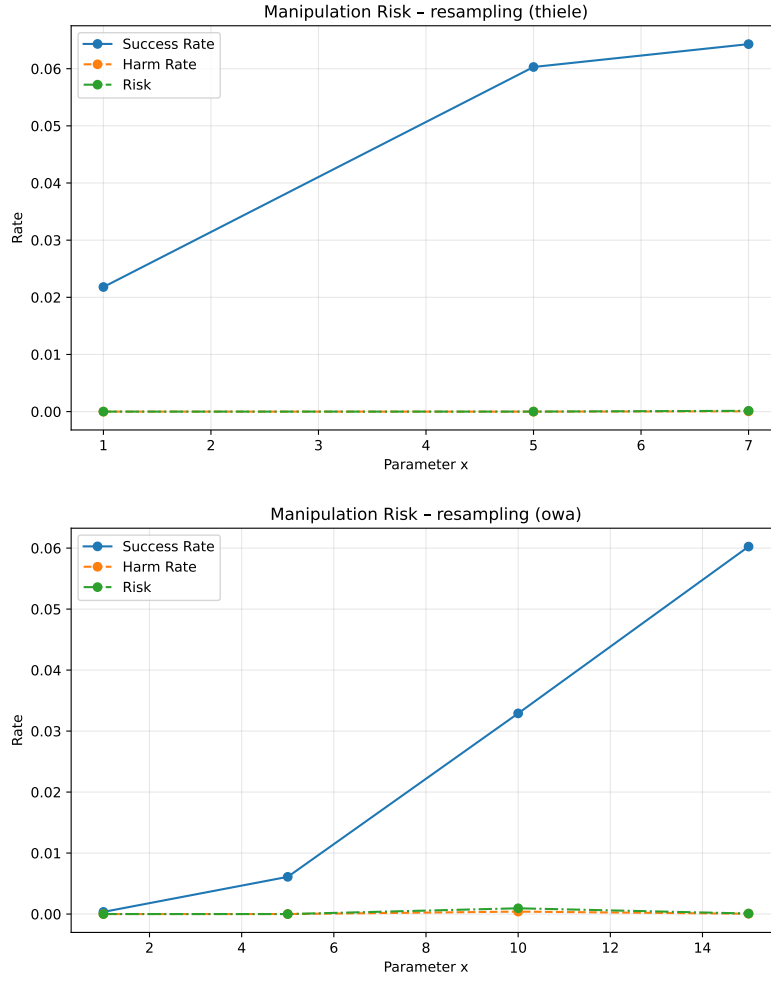


Figure 3: Manipulation risk under resampling culture. Top: Thiele rules. Bottom: OWA rules.

Risk Metrics. Across all settings, harms are rare relative to both trials and possible cases, and the risk measure (harms/possible) is consistently close to zero. Taken together, manipulators succeed more often than they harm themselves under the restricted deviation class we test.

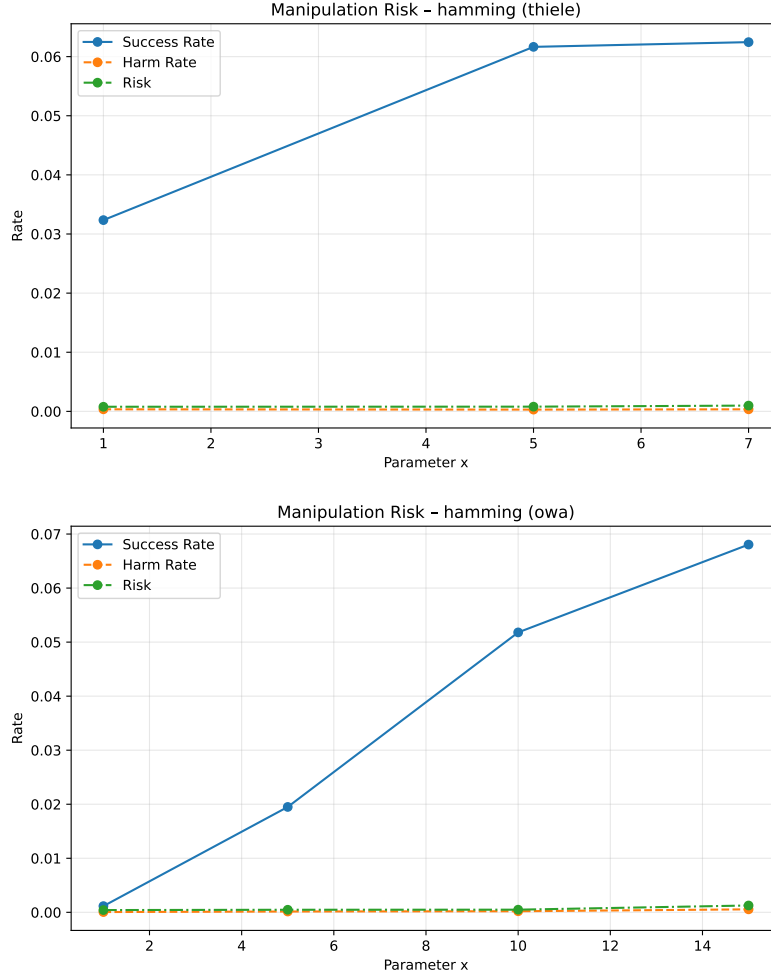


Figure 4: Manipulation risk under Hamming-noise culture. Top: Thiele rules. Bottom: OWA rules.

6 Conclusion

The choice of statistical culture influences the frequency of free-riding opportunities, but the qualitative ranking across voting rules is stable in our experiments. Utilitarian is immune; within Thiele/OWA families, higher x values show somewhat more manipulability, yet harms remain rare and risk is small. These findings are compatible with the trends discussed by [1] under our (restricted) deviation model.

Future work could extend these experiments by exploring richer parameter grids for (p, ϕ) and ϵ , by scaling to larger electorates, and by testing the full family of admissible

free-riding deviations described in [1] (beyond single-approval drops).

Repository

The full project code and report sources are available at:
github.com/inquisitour/preferences-in-ai

References

- [1] Martin Lackner, Jan Maly, and Oliviero Nardi. Free-riding in multi-issue decisions. In *Proceedings of the 22nd International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, pages 2040–2048. International Foundation for Autonomous Agents and Multiagent Systems, 2023. Also available as arXiv preprint: [arXiv:2310.08194](https://arxiv.org/abs/2310.08194).