# Synchronous semantics of multi-mode multi-periodic systems

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1 Introduction

2 State of the Art

3 Contribution

4 Conclusion

#### **Problem statement**

#### Goal : Program real-time multi-mode systems

- 1 Extending the semantics of a synchronous language
- 2 Static analysis (clock calculus) to guarantee soundness
- 3 Allow different mode change protocols

1 Introduction

2 State of the Art

3 Contribution

4 Conclusion

#### Multi-mode real-time systems

- Change func. requirements during execution
- Mode = task set
- Mode change protocol
  - lacksquare Switch from task set  $\mathcal{T}$  to task set  $\mathcal{T}'$
- How to transition between  $\mathcal{T}$  and  $\mathcal{T}'$ ?
- Metrics observed by the scheduling community :
  - Promptness
  - Schedulability

Real, and Crespo. Mode change protocols for real-time systems: A survey and a new proposal. 2004.

#### Multi-mode real-time systems

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- Mode = task set
- Mode change protocol
  - lacksquare Switch from task set  $\mathcal{T}$  to task set  $\mathcal{T}'$
- How to transition between  $\mathcal{T}$  and  $\mathcal{T}'$ ?
- Metrics observed by the scheduling community :
  - Promptness
  - Schedulability
- Semantics?

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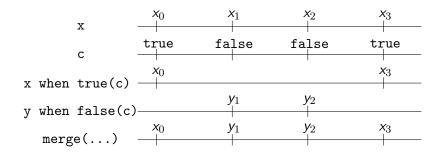
#### Synchronous state machines

- Formally defined language for multi-mode systems
- Based on Lustre and Lucid Synchrone
- Transpiles state machines into when and merge

Colaço, Pagano, and Pouzet. A conservative extension of synchronous data-flow with state machines. 2005.

#### **Synchronous state machines**

Reminder: when and merge



#### Synchronous state machines

#### **Transpilation process**

```
automaton
                             ps = S1 fby s;
| S1 ->
                             s = merge(ps,
                               S1->if c when S1(ps)
 unless c then S2;
  o = i;
                                 then S2 else S1,
I S2 ->
                               S2->if c when S2(ps)
                                 then S1 else S2);
 unless c then S1;
  o = j;
                             o = merge(s,
end
                               S1->i when S1(s).
                               S2->j when S2(s));
```

## **Synchronous state machines Limitations**

#### Problem

- No explicit time constraints
- All flows within the automaton must share the same clock

#### Solution



## **Synchronous state machines Limitations**

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- No explicit time constraints
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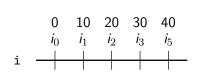
#### Solution

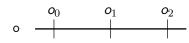




- LUSTRE-like synchronous dataflow language
- Explicit real-time constraints

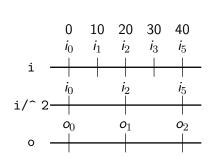
```
node main(i: int rate (10,0))
returns (o: int rate (20,0))
let
    o = f(i ???);
tel
```





- LUSTRE-like synchronous dataflow language
- Explicit real-time constraints
- Built-in *rate-transition operators*

```
node main(i: int rate (10,0))
returns (o: int rate (20,0))
let
   o = f(i/^2);
tel
```



- LUSTRE-like synchronous dataflow language
- Explicit real-time constraints
- Built-in *rate-transition operators*
- when and merge inherit the same definition as LUSTRE

## **State Machines in PRELUDE**Naive approach

```
i: rate(5,0) j: rate(7,0)
                                  ps = S1 fby s;
c: rate(11,0)
                                  s = merge(ps, ...);
automaton
                                  o = merge(s,
| S1 ->
                                     S1->f1(i when S1(s)),
  unless c then S2;
                                     S2\rightarrow f2(i \text{ when } S2(s)));
  o = f1(i);
                                  p = merge(s,
  p = g1(j);
                                     S1->g1(j \text{ when } S1(s)),
L S2 ->
                                     S2->g2(j when S2(s));
  unless c then S1;
  o = f2(i):
  p = g2(j);
end
```

## State Machines in PRELUDE Naive approach

```
i: rate(5,0) j: rate(7,0)
                                    ps = S1 fby s;
c: rate(11,0)
                                    s = merge(ps, ...);
automaton
                                    o = merge(s,
| S1 ->
                                       S1->f1(i when S1(s)),
  unless c then S2;
                                       S2 \rightarrow f2(i \text{ when } S2(s)):
  o = f1(i);
                                    p = merge(s,
  p = g1(j);
                                       S1->g1(j \text{ when } S1(s)),
L S2 ->
                                       S2 \rightarrow g2(i \text{ when } S2(s)));
  unless c then S1;
  o = f2(i):
                                    s must be synchronous with
  p = g2(j);
                                    both i and j
end
```

## **State Machines in Prelude**Further issues with rate-transition operators

i: rate 
$$(3,0) \Rightarrow (3,0)$$
 c: rate  $(3,0) \Rightarrow (3,0)$  i \*^3 \Rightarrow (1,0) i /^2 \Rightarrow (6,0) i /^2 \Rightarrow (2,0) i \*^3/^2 \Rightarrow (2,0) i when true(c) \Rightarrow (3,0) on true(c)

i /^2 \*^3 and i \*^3 /^2 don't produce the same values, but are synchronous (produce the values at the same instants)

## **State Machines in Prelude**Further issues with rate-transition operators

i: rate 
$$(3,0) \Rightarrow (3,0)$$
 c: rate  $(3,0) \Rightarrow (3,0)$   
i \*^3 \Rightarrow (1,0) i /^2 \Rightarrow (6,0)  
i /^2\*^3 \Rightarrow (2,0) i \*^3/^2 \Rightarrow (2,0)  
i when true(c) \Rightarrow (3,0) on true(c)  
i when true(c) \*^3 /^2 \Rightarrow (2,0) on true(c)  
i when true(c) /^2 \*^3 \Rightarrow (2,0) on true(c)  
But the expressions i when true(c) \*^3 /^2 and  
i when true(c) /^2 \*^3 aren't synchronous!

#### **State Machines in Prelude**

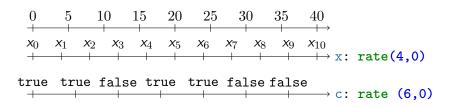
#### Further issues with rate-transition operators

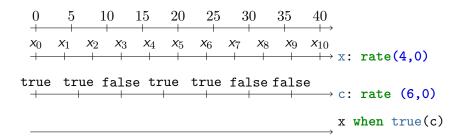
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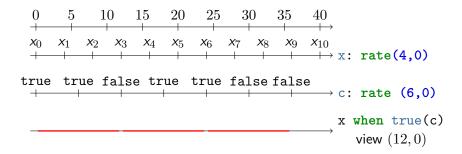
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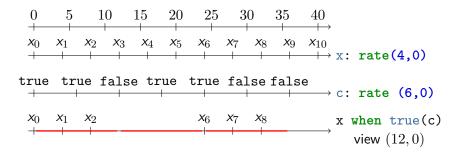
3 Contribution

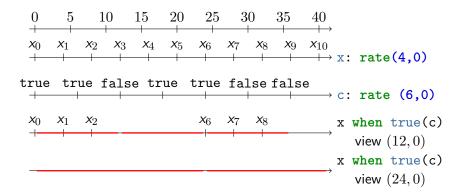
4 Conclusion

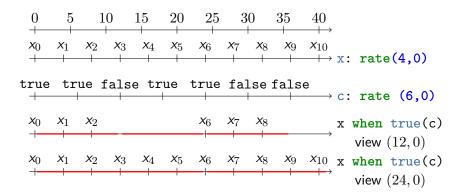












## Formal clock semantics Notation

- Tagged-signal model
  - Clocks define a set of tags (instants)
  - Dataflows define a set of tag-value pairs
- $t \in ck \Leftrightarrow ck$  is present at instant t
- $\blacksquare \pi(ck)$  : period  $\varphi(ck)$  : offset
- Strictly periodic clock  $(n, p) = \{p + i * n \mid i \in \mathbb{N}\}$

• Conditionally sub-sampled clock ck on C(c, w)

ck : Sub-sampled clockC : Condition value

c : Condition dataflow

V.

■ w : View

■ Conditionally sub-sampled clock ck on C(c, w)

$$w=(n,p)$$

ck : Sub-sampled clock

C : Condition value

c: Condition dataflow

■ w : View

• Conditionally sub-sampled clock ck on C(c, w)

```
w = (n, p)\{t \mid t \in ck,
```

- ck : Sub-sampled clock
- C : Condition value
- c: Condition dataflow
- w : View

• Conditionally sub-sampled clock ck on C(c, w)

```
w = (n, p)
\{t \mid t \in ck, \exists (C, t'') \in c,
```

- ck : Sub-sampled clock
- C : Condition value
- c: Condition dataflow
- w : View

■ Conditionally sub-sampled clock ck on C(c, w)

```
w = (n, p)
\{t \mid t \in ck, \exists (C, t'') \in c, \exists t' \in w,
\}
```

- ck : Sub-sampled clock
- C : Condition value
- c: Condition dataflow
- w : View

• Conditionally sub-sampled clock ck on C(c, w)

```
w = (n, p)

\{t \mid t \in ck, \exists (C, t'') \in c, \exists t' \in w, t' \le t < t' + n, \}
```

- ck : Sub-sampled clock
- C : Condition value
- c: Condition dataflow
- w : View

• Conditionally sub-sampled clock ck on C(c, w)

$$w = (n, p)$$
  
{t | t \in ck, \exists (C, t'') \in c, \exists t' \in w,  
t' \le t < t' + n, t'' = t' + \varphi(c) - p}

- ck : Sub-sampled clock
- C : Condition value
- c : Condition dataflow
- w : View

#### Clock calculus

- Need to verify the clock consistency
- Compute clock views
- $\Rightarrow$  Clock calculus : Dedicated type system

- Extends an existing type system
- Refine types with predicates (in a decidable logic)
- SMT solvers are used to verify those predicates

## $\{\nu:b\mid r\}$

The base type b (e.g. int, int list) refined by the boolean predicate r (e.g.  $\nu \geq 0 \land \nu < x$ ) such that r is true for all values inhabiting  $\{\nu:b\mid r\}$ . The variable  $\nu$  represents the value of the typed expression.

- Extends an existing type system
- Refine types with predicates (in a decidable logic)
- SMT solvers are used to verify those predicates

4: int

 $\mathtt{mod} \colon \mathtt{int} \to \mathtt{int} \to \mathtt{int}$ 

 $\mathtt{static\_assert} \colon \mathtt{bool} \to \mathtt{unit}$ 

- Extends an existing type system
- Refine types with predicates (in a decidable logic)
- SMT solvers are used to verify those predicates

$$4 \colon \{\nu : \mathtt{int} | \nu = 4\}$$
 
$$\mathtt{mod} \colon \mathtt{int} \to \mathtt{int} \to \mathtt{int}$$
 
$$\mathtt{static\_assert} \colon \mathtt{bool} \to \mathtt{unit}$$

- Extends an existing type system
- Refine types with predicates (in a decidable logic)
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$$4 \colon \{\nu : \mathtt{int} | \nu = 4\}$$
 
$$\mathtt{mod} \colon \mathtt{x} \colon \mathtt{int} \to \mathtt{y} \colon \{\nu : \mathtt{int} \, | \, \nu > 0\} \to \{\nu : \mathtt{int} \, | \, \nu = \mathtt{x}\%\mathtt{y}\}$$
 
$$\mathtt{static\_assert} \colon \mathtt{bool} \to \mathtt{unit}$$

- Extends an existing type system
- Refine types with predicates (in a decidable logic)
- SMT solvers are used to verify those predicates

$$\begin{aligned} 4 \colon \{\nu : \mathtt{int} | \nu = 4\} \\ \mathtt{mod} \colon \mathtt{x} \colon \mathtt{int} \to \mathtt{y} \colon \{\nu : \mathtt{int} \, | \, \nu > 0\} \to \{\nu : \mathtt{int} \, | \, \nu = \mathtt{x} \% \mathtt{y}\} \\ \mathtt{static\_assert} \colon \mathtt{b} \colon \! \{\nu : \mathtt{bool} \, | \, \nu\} \to \mathtt{unit} \end{aligned}$$

- Clocks  $\neq$  clock types
- Clock type : Reconstruction of the clock by the type system
- Base clocks *ck<sub>b</sub>* 
  - **pck**: A strictly periodic clock ((n, p) with n and p unknown)
  - $ck_b$  on C(c, w): Application of on C(c, w) to  $ck_b$
- Refinements relate to the period and offset of the clock

i: rate (10,5) 
$$\Rightarrow \{\nu : \mathrm{pck} \mid \pi(\nu) = 10 \land \varphi(\nu) = 5\}$$

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i: rate (10,5) 
$$\Rightarrow$$
 { $\nu$ :pck |  $\pi(\nu) = 10 \land \varphi(\nu) = 5$ } 
$$*^2 \Rightarrow x : \{ \nu : \text{pck } | \ 2 \text{ div } \pi(\nu) \} \rightarrow \{ \nu : \text{pck } | \ \pi(\nu) = \pi(x)/2 \land \varphi(\nu) = \varphi(x) \}$$

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For brevity :  $\{\nu : \operatorname{ck} \mid \pi(\nu) = r_n \land \varphi(\nu) = r_o\} = \{\nu : \operatorname{ck} \mid \langle r_n, r_o \rangle\}$ 

- Clocks ≠ clock types
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i: rate (10,5) 
$$\Rightarrow$$
 { $\nu$ :pck |  $\langle 10,5 \rangle$ } 
$$*^2 \Rightarrow x : \{ \nu : \text{pck} \mid 2 \text{ div } \pi(\nu) \} \rightarrow \{ \nu : \text{pck} \mid \langle x/2, x \rangle \}$$

For brevity : 
$$\{\nu: ck \mid \pi(\nu) = r_n \land \varphi(\nu) = r_o\} = \{\nu: ck \mid \langle r_n, r_o \rangle\}$$

# Refinement clock calculus View computation

```
i when true(c) \Rightarrow \{\nu: pck \text{ on } true(c, \{\nu: pck \mid \langle 20, 5 \rangle\}) \mid \langle 10, 5 \rangle\}
```

- Users don't annotate views
- Collect constraints on the view
- ⇒ Refinement typer (SMT solver) finds solution with lowest period

## Automata semantics

#### Classification

```
i: rate(10,0) j: rate(20,0)
c: rate(15,0)
o,p = h(k,1);
automaton
| S1 ->
 unless c then S2;
 k = f1(i);
 1 = g1(j);
I S2 ->
 unless c then S1;
 k = f2(i);
  1 = g2(j);
end
```

Transitioning from mode S1 to S2 ...

Dataflow compliant

Breaks dataflow (not supported)

# Automata semantics Classification

```
i: rate(10,0) j: rate(20,0)
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  1 = g2(j);
end
```

```
Transitioning from mode S1 to
S2 ...
Unchanged task (h(k,1))
  Periodic : Unaffected
  Aperiodic : Execution
    suppressed
    Dataflow compliant
    Breaks dataflow (not
```

supported)

# Automata semantics Classification

```
i: rate(10,0) j: rate(20,0)
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  1 = g1(j);
I S2 ->
 unless c then S1;
 k = f2(i);
  1 = g2(j);
end
```

```
Transitioning from mode S1 to
S2 ...
Old-mode task (f1(i), g1(j))
  ■ Late retirement : Executes
     until specific point
  ■ Early retirement : Abort
     immediately
     Dataflow compliant
     Breaks dataflow (not
```

supported)

# Automata semantics

#### Classification

```
i: rate(10,0) j: rate(20,0)
c: rate(15,0)
o,p = h(k,1);
automaton
| S1 ->
 unless c then S2;
 k = f1(i);
  1 = g1(j);
I S2 ->
 unless c then S1;
 k = f2(i);
  1 = g2(j);
end
```

Transitioning from mode S1 to S2 ...

New-mode task (f2(i), g2(j))

- Non-overlapping : Distinct before-after
- Overlapping : Potential co-overlapp between modes

Dataflow compliant

Breaks dataflow (not supported)

# Automata semantics Flexibility

```
i: rate(10,0) j: rate(20,0)
c: rate(15.0)
o,p = h(k,1);
automaton
I S1 ->
 unless c then S2;
 k = f1(i):
  1 = g1(j);
I S2 ->
  unless c then S1;
 k = f2(i);
  1 = g2(j);
end
```

- k observes the automaton state with view (30,0)
- $\blacksquare$  1 observes the automaton state with view (60,0)
- Implements an overlapping mode change protocol, i.e. during a transition, f2(i) and g1(j) might co-exist
- Switching to a non-overlapping requires to give all dataflows the same view

# Automata semantics Flexibility

```
i: rate(10,0) j: rate(20,0)
c: rate(15.0)
o,p = h(k,1);
c slow = c/^2;
automaton
I S1 ->
 unless c slow then S2;
 k = f1(i);
  1 = g1(j);
I S2 ->
  unless c_slow then S1;
 k = f2(i):
  1 = g2(j);
end
```

- k observes the automaton state with view (30,0)
- 1 observes the automaton state with view (60,0)
- Implements an overlapping mode change protocol, i.e. during a transition, f2(i) and g1(j) might co-exist
- Switching to a non-overlapping requires to give all dataflows the same view

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#### Conclusion

- Extended a multi-periodic sync. language to support mode-change automata
- Flexible enough for different mode change protocols
- Clock calculus guarantees that programs remain sound

#### **Future work**

- Lift requirement to annotate node inputs
- View computation  $\sim$  program synthesis?
  - "Completely" remove rate-transition operators

Thank you for your attention Questions? Postdoc offers?