MECHANIZED SEMANTICS AND VERIFIED COMPILATION FOR A DATAFLOW SYNCHRONOUS LANGUAGE WITH RESET

Timothy Bourke^{1,2} Lélio Brun^{1,2} Marc Pouzet ^{3,2,1}

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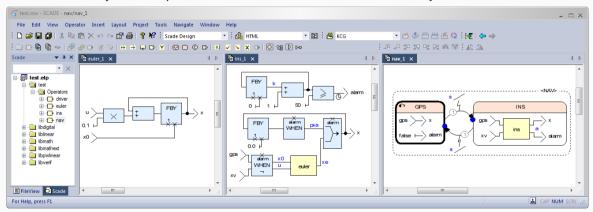
¹Inria Paris

²École normale supérieure – PSL University

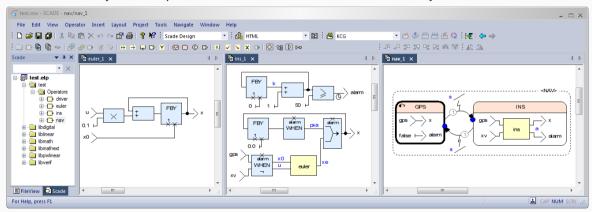
³Sorbonne University

velus.inria.fr
github.com/INRIA/velus

www.ansys.com/products/embedded-software/ansys-scade-suite

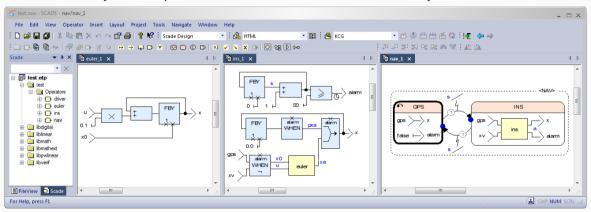


www.ansys.com/products/embedded-software/ansys-scade-suite



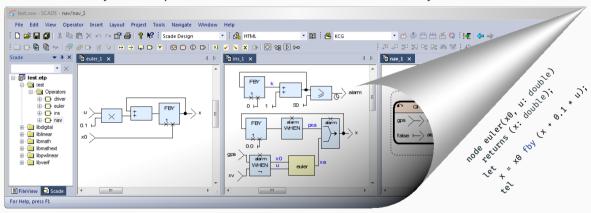
block / node = system line = signal

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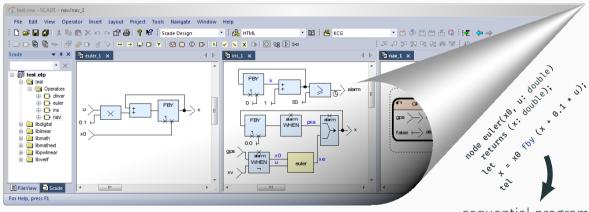
```
block / node = system = stream function
line = signal = stream of values
```

www.ansys.com/products/embedded-software/ansys-scade-suite



block / node = system = stream function line = signal = stream of values

www.ansys.com/products/embedded-software/ansys-scade-suite



block / node = system = stream function
line = signal = stream of values

sequential program (C, Ada, assembly)

THE VÉLUS PROJECT

Model-Based Design Languages



SCADE, Lustre, Simulink

Challenges

- 1. Mechanize the semantics
- 2. Prove the compilation algorithms correct

Interactive Theorem Provers

Coq

THE VÉLUS PROJECT

Model-Based Design Languages



SCADE, Lustre, Simulink

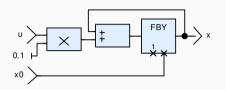
Interactive Theorem Provers

Coq

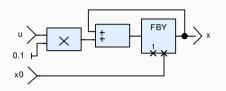
Challenges

- 1. Mechanize the semantics
- 2. Prove the compilation algorithms correct

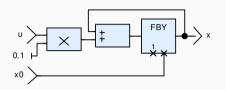
Focus: modular reset



<i>X</i> ₀	0.00	1.55	3.62	5.46	
И	15.00	20.00	17.00	12.00	• • •
$x + 0.1 \times u$	1.50	3.50	5.20	6.70	
X	0.00	1.50	3.50	5.20	



<i>X</i> ₀	0.00	1.55	3.62	5.46	
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$x + 0.1 \times u$	1.50	3.50	5.20	6.70	
X	0.00	1.50	3.50	5.20	



```
node euler(x0, u: double)
  returns (x: double);
let
  x = x0 fby (x + 0.1 * u);
tel
```

<i>X</i> ₀	0.00	1.55	3.62	5.46	• • •
и	15.00	20.00	17.00	12.00	
$x + 0.1 \times u$	1.50	3.50	5.20	6.70	
Χ	0.00	1.50	3.50	5.20	

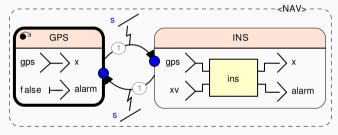
```
node ins(gps, xv: double)
 FBY
                                             returns (x: double, alarm: bool)
                                             var pxa. xe: double: k: int:
                                          let
           alarm
                      alarm
                                             k = 0 fby (k + 1);
 FBY
                 pxa
           WHEN
                                             alarm = (k > 50):
                                             xe = euler((gps, xv) when not alarm);
0.0 ⊦
                                             pxa = (0. fby x) when alarm;
                    хe
                                               = merge alarm pxa xe;
  WHEN
              euler
                                          tel
            0.00
                      1.55
                              3.62
                                        5.46
                                                     86.52
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                                                                       90.91
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```

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 FBY
                                            returns (x: double, alarm: bool)
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```

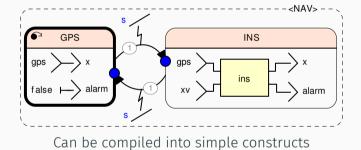
```
node ins(gps, xv: double)
 FBY
                                             returns (x: double, alarm: bool)
                                             var pxa. xe: double: k: int:
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           alarm
                      alarm
                                             k = 0 fby (k + 1);
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                                          tel
            0.00
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            15.00
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  ΧV
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  k
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            0.00
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```

```
node ins(gps, xv: double)
 FBY
                                             returns (x: double, alarm: bool)
                                             var pxa. xe: double: k: int:
                                          let
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                      alarm
                                             k = 0 fby (k + 1);
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           WHEN
                                             alarm = (k > 50):
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0.0 ⊦
                                             pxa = (0. fby x) when alarm;
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  WHEN
              euler
                                          tel
            0.00
                      1.55
                              3.62
                                        5.46
                                                     86.52
                                                              88.40
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  gps
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                                       12.00
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  ΧV
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```

```
node ins(gps, xv: double)
 FBY
                                             returns (x: double, alarm: bool)
                                             var pxa. xe: double: k: int:
                                           let
           alarm
                       alarm
                                             x = merge alarm pxa xe;
 FBY
                 pxa
           WHEN
                                             k = 0 \text{ fbv } (k + 1):
                                             pxa = (0. fby x) when alarm;
0.0 ⊦
                                             xe = euler((gps, xv) when not alarm);
                     хe
                                             alarm = (k > 50);
  WHEN
              euler
                                           tel
            0.00
                      1.55
                               3.62
                                        5.46
                                                      86.52
                                                               88.40
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  ΧV
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  X
                                                . . .
                                                                                  . . .
```



Can be compiled into simple constructs



We need a way to reset the state of a node

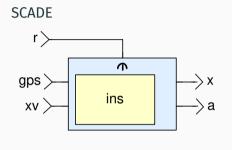
WITHOUT MODULAR RESET

```
node euler(x0, u: double, r: bool)
 returns (x: double);
let
 x = if r then x0 else x0 fby (x + 0.1 * u);
tel
node ins(gps, xv: double, r: bool)
  returns (x: double, alarm: bool)
 var k: int:
let
 x = merge alarm
        ((0. fbv x) when alarm)
        (euler((gps, xv, r) whenot alarm));
 alarm = (k > 50):
  k = if r then 0 else 0 fby (k + 1);
tel
. . .
(x, a) = ins(gps, xv, r);
```

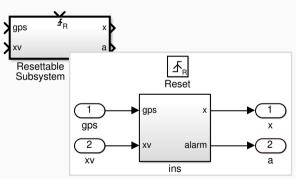
WITH MODULAR RESET

```
node euler(x0, u: double, r: bool)
                                                   node euler(x0, u: double)
  returns (x: double);
                                                    returns (x: double);
let
                                                   1et
  x = if r then x0 else x0 fbv (x + 0.1 * u);
                                                   x = x0 \text{ fby } (x + 0.1 * u);
tel
                                                   tel
node ins(gps, xv: double, r: bool)
                                                   node ins(gps, xv: double)
  returns (x: double. alarm: bool)
                                                     returns (x: double. alarm: bool)
  var k: int;
                                                     var pxa, xe: double; k: int;
let
                                                   let
  x = merge alarm
                                                     k = 0 \text{ fby } (k + 1);
                                                     alarm = (k \ge 50);
        ((0. fby x) when alarm)
        (euler((gps, xv, r) whenot alarm));
                                                     xe = euler((gps, xv) when not alarm);
  alarm = (k > 50):
                                                     pxa = (0. fby x) when alarm;
  k = if r then 0 else 0 fby (k + 1);
                                                     x = merge alarm pxa xe;
tel
                                                   tel
. . .
                                                   . . .
                                                   (x, a) = (restart ins every r) (gps. xv):
(x. a) = ins(gps. xv. r):
                                                                                           4/15
```

GRAPHICAL MODULAR RESET CONSTRUCT







```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F
i	0
nat(i)	0
<pre>(restart nat every r)(i)</pre>	0

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F
i	0	5
nat(i)	0	1
<pre>(restart nat every r)(i)</pre>	0	1

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F	Т	
i	0	5	10	
nat(i)	0	1	2	
<pre>(restart nat every r)(i)</pre>	0	1	10	

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F	Τ	F	
i	0	5	10	15	
nat(i)	0	1	2	3	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F	Τ	F	F	
i	0	5	10	15	20	
nat(i)	0	1	2	3	4	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F	Τ	F	F	Τ	
i	0	5	10	15	20	25	
nat(i)	0	1	2	3	4	5	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F	Τ	F	F	Τ	F	
i	0	5	10	15	20	25	30	
nat(i)	0	1	2	3	4	5	6	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

```
node nat(i: int)
  returns (n: int)
let
  n = i fby (n + 1);
tel
```

r	F	F	Τ	F	F	Τ	F	
i	0	5	10	15	20	25	30	• • •
nat(i)	0	1	2	3	4	5	6	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

```
node nat(i: int)
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let
  n = i fby (n + 1);
tel
```

r	F	F	Τ	F	F	Τ	F	
i	0	5	10	15	20	25	30	• • •
nat(i)	0	1	2	3	4	5	6	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

Could be implemented in a higher-order recursive language

```
node nat(i: int)
returns (n: int)
let
n = i fby (n + 1);
tel
```

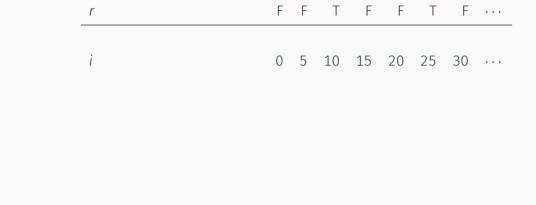
r	F	F	Т	F	F	Τ	F	
i	0	5	10	15	20	25	30	• • •
nat(i)	0	1	2	3	4	5	6	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

Could be implemented in a higher-order recursive language

```
node nat(i: int)
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tel
```

r	F	F	Τ	F	F	Т	F	
i	0	5	10	15	20	25	30	
nat(i)	0	1	2	3	4	5	6	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

Could be implemented in a higher-order recursive language



(restart nat every r)(i) 0 1 10 11 12 25 26 ···

r	F	F	Т	F	F	Т	F	• • •	
count r	0	0	1	1	1	2	2		
i	0	5	10	15	20	25	30		

 $(restart \ nat \ every \ r)(i)$ 0 1 10 11 12 25 26 ...

r	F	F	Т	F	F	Т	F	• • • •
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^{0}_r$ i	0	5						

 $(restart \ nat \ every \ r)(i)$ 0 1 10 11 12 25 26 ...

r	F	F	Т	F	F	Т	F	• • • •
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^0_r$ i	0	5						
nat(mask ⁰ i)	0	1						

 $(restart \ nat \ every \ r)(i) \ 0 \ 1 \ 10 \ 11 \ 12 \ 25 \ 26 \ \cdots$

r	F	F	Т	F	F	Τ	F	• • •
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^0_r$ i	0	5						
$nat(mask_r^0 i)$	0	1						
$mask_r^1 i$			10	15	20			

```
(restart \ nat \ every \ r)(i) 0 1 10 11 12 25 26 ...
```

r	F	F	Т	F	F	Т	F	• • • •
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^0_r$ i	0	5						
$nat(mask_r^0 i)$	0	1						
$mask_r^1 i$			10	15	20			
$nat(mask_r^1 i)$			10	11	12			

```
(restart \ nat \ every \ r)(i) 0 1 10 11 12 25 26 ...
```

r	F	F	Т	F	F	Т	F	
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^0_r$ i	0	5						
$nat(mask_r^0 i)$	0	1						
$mask^1_ri$			10	15	20			
nat(mask ¹ i)			10	11	12			
mask <mark>?</mark> i						25	30	

 $(restart \ nat \ every \ r)(i)$ 0 1 10 11 12 25 26 ...

r	F	F	Т	F	F	Τ	F	• • •
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^0_r$ i	0	5						
$nat(mask_r^0 i)$	0	1						
$mask^1_ri$			10	15	20			
$nat(mask_r^1 i)$			10	11	12			
$mask^2_ri$						25	30	
$nat(mask_r^2 i)$						25	26	
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

r	F	F	Τ	F	F	Τ	F	• • •
count r	0	0	1	1	1	2	2	
i	0	5	10	15	20	25	30	
$mask^0_r$ i	0	5						
$nat(mask_r^0 i)$	0	1						
$mask^1_r i$			10	15	20			
$nat(mask_r^1 i)$			10	11	12			
$mask^2_ri$						25	30	
$nat(mask_r^2 i)$						25	26	
:								
<pre>(restart nat every r)(i)</pre>	0	1	10	11	12	25	26	

$$H \vdash_{eqn} \mathbf{x} = f(\mathbf{e})$$

$$H \vdash_{exp} e \Downarrow es$$

$$H \vdash_{eqn} \mathbf{x} = f(\mathbf{e})$$

$$\frac{H \vdash_{\mathsf{exp}} \mathbf{e} \Downarrow \mathbf{es} \quad \vdash_{\mathsf{node}} f(\mathbf{es}) \Downarrow \mathbf{xs}}{H \vdash_{\mathsf{eqn}} \mathbf{x} = f(\mathbf{e})}$$

$$\frac{H \vdash_{\text{exp}} e \Downarrow es \quad \vdash_{\text{node}} f(es) \Downarrow xs \quad H(x) = xs}{H \vdash_{\text{eqn}} x = f(e)}$$

Node instantiation

$$\frac{H \vdash_{\mathsf{exp}} e \Downarrow es \quad \vdash_{\mathsf{node}} f(es) \Downarrow xs \quad H(x) = xs}{H \vdash_{\mathsf{eqn}} x = f(e)}$$

Modular reset

$$H \vdash_{eqn} \mathbf{x} = (\mathbf{restart} f \mathbf{every} y)(\mathbf{e})$$

Node instantiation

$$\frac{H \vdash_{\mathsf{exp}} \mathbf{e} \Downarrow \mathbf{es} \quad \vdash_{\mathsf{node}} f(\mathbf{es}) \Downarrow xs \quad H(x) = xs}{H \vdash_{\mathsf{eqn}} x = f(\mathbf{e})}$$

Modular reset

$$\frac{H \vdash_{\text{exp}} e \Downarrow es}{H \vdash_{\text{eqn}} x = (\text{restart} f \text{ every } y)(e)}$$

Node instantiation

$$\frac{H \vdash_{\mathsf{exp}} \mathbf{e} \Downarrow \mathbf{es} \quad \vdash_{\mathsf{node}} f(\mathbf{es}) \Downarrow xs \quad H(x) = xs}{H \vdash_{\mathsf{eqn}} x = f(\mathbf{e})}$$

Modular reset

$$\frac{H(y) = rs \quad r = \text{bools-of } rs}{H \vdash_{\text{exp}} e \Downarrow es \quad \forall k, \, \vdash_{\text{node}} f(\text{mask}_r^k es) \Downarrow \text{mask}_r^k xs \quad H(x) = xs}{H \vdash_{\text{eqn}} x = (\text{restart } f \text{ every } y)(e)}$$

Node instantiation

$$\frac{H \vdash_{\mathsf{exp}} \mathbf{e} \Downarrow \mathbf{es} \quad \vdash_{\mathsf{node}} f(\mathbf{es}) \Downarrow xs \quad H(x) = xs}{H \vdash_{\mathsf{eqn}} x = f(\mathbf{e})}$$

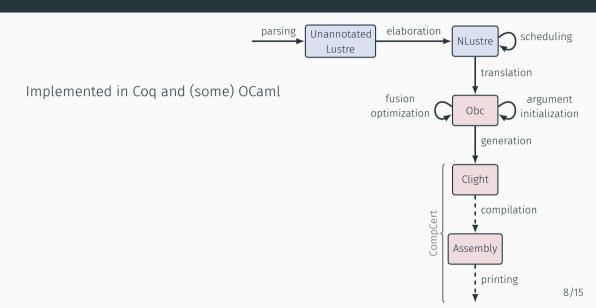
Modular reset

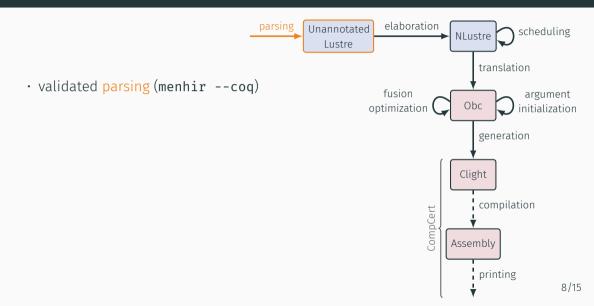
$$H(y) = rs \quad r = \text{bools-of } rs$$

$$H \vdash_{\text{exp}} e \Downarrow es \quad \forall k, \vdash_{\text{node}} f(\text{mask}_r^k es) \Downarrow \text{mask}_r^k xs \quad H(x) = xs$$

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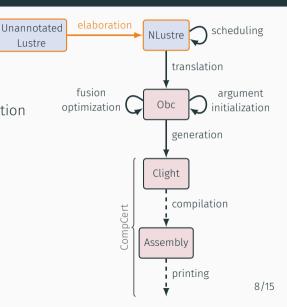
Universally quantified relation: unbounded number of constraints







elaboration to get clock and type information

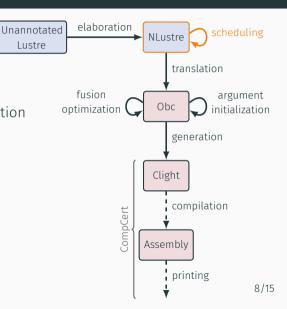




 \cdot elaboration to get clock and type information

parsing

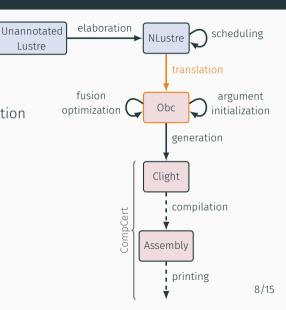
scheduling of NLustre code





 \cdot elaboration to get clock and type information

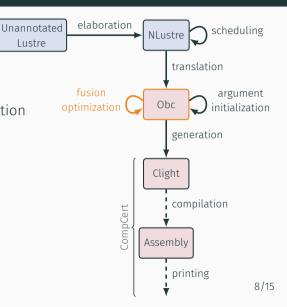
- · scheduling of NLustre code
- translation to Obc code





 \cdot elaboration to get clock and type information

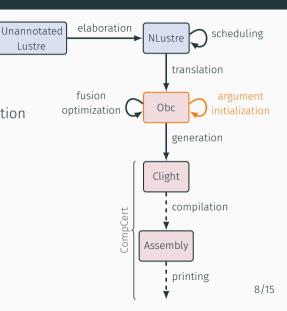
- · scheduling of NLustre code
- translation to Obc code
- fusion optimization of conditionals





 \cdot elaboration to get clock and type information

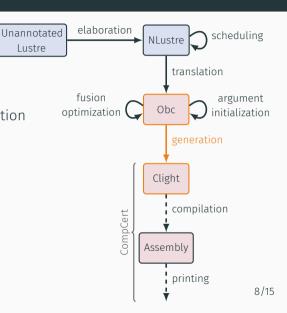
- · scheduling of NLustre code
- translation to Obc code
- fusion optimization of conditionals
- initialization of variable arguments





• elaboration to get clock and type information

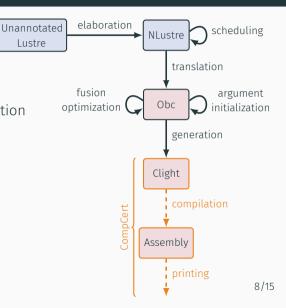
- · scheduling of NLustre code
- translation to Obc code
- fusion optimization of conditionals
- initialization of variable arguments
- Generation of Clight code





· elaboration to get clock and type information

- · scheduling of NLustre code
- · translation to Obc code
- fusion optimization of conditionals
- initialization of variable arguments
- Generation of Clight code
- Rely on CompCert for compilation



```
class driver {
                                               instance x: ins, y: ins;
                                                reset() { ins(x).reset();
                                                          ins(y).reset() }
node driver(x0, y0, u, v: double, r: bool)
  returns (x, y: double)
                                                step(x0, y0, u, v: double, r: bool)
 var ax, ay: bool;
                                                  returns (x, y: double)
let
                                                  var ax, ay: bool
  x, ax = (restart ins every r)(x0. u):
 v, av = (restart ins every <math>r)(v0, v);
                                                  if r { ins(x).reset() }:
tel
                                                  x, ax := ins(x).step(x0. u):
                                                  if r { ins(y).reset() };
                                                  y, ay := ins(y).step(y0, v)
                                                                                9/15
```

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class driver {
                                               instance x: ins, y: ins;
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                                                                               9/15
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                                                 if r { ins(x).reset() }:
tel
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9/15

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                                                 if r { ins(x).reset() };
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                                                 x, ax := ins(x).step(x0. u):
                                                 if r { ins(y).reset() };
                                                 v, av := ins(v).step(v0, v)
                                                                               9/15
```

STC: SYNCHRONOUS TRANSITION CODE

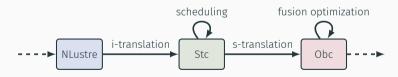
Propose a new intermediate language

- Invariant semantics under permutation
- Separate reset construct
- Explicit state: state variables and instances

STC: SYNCHRONOUS TRANSITION CODE

Propose a new intermediate language

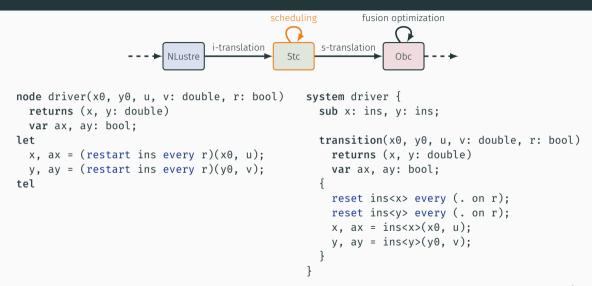
- Invariant semantics under permutation
- Separate reset construct
- Explicit state: state variables and instances



```
scheduling
                                                           fusion optimization
                                                    s-translation
                        NLustre
                                                                 Obc
                                              Stc
node driver(x0, y0, u, v: double, r: bool)
                                                 system driver {
  returns (x, y: double)
                                                    sub x: ins, y: ins;
  var ax. av: bool:
let
                                                    transition(x0, y0, u, v: double, r: bool)
  x. ax = (restart ins every r)(x0. u):
                                                      returns (x. v: double)
  v, av = (restart ins every <math>r)(v0, v);
                                                      var ax. av: bool:
tel
                                                      x, ax = ins < x > (x0, u);
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scheduling
                                                           fusion optimization
                                                    s-translation
                        NLustre
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                                                 system driver {
  returns (x, y: double)
                                                    sub x: ins, y: ins;
  var ax. av: bool:
let
                                                    transition(x0, y0, u, v: double, r: bool)
  x, ax = (restart ins every r)(x0, u);
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  v, av = (restart ins every <math>r)(v0, v);
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                                                      v, av = ins < v > (v0, v);
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scheduling
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                                                   transition(x0, y0, u, v: double, r: bool)
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                                                     var ax, ay: bool;
tel
                                                     x, ax = ins < x > (x0, u);
                                                     reset ins<x> every (. on r):
                                                     v, av = ins < v > (v0, v);
                                                     reset ins<y> every (. on r);
```



```
scheduling
                                                         fusion optimization
                                i-translation
                       NLustre
                                             Stc
                                                               Ohc
system driver {
                                                class driver {
  sub x: ins, y: ins;
                                                  instance x: ins, y: ins;
  transition(x0, y0, u, v: double, r: bool)
                                                 reset() { ins(x).reset();
    returns (x. v: double)
                                                             ins(v).reset() }
    var ax, ay: bool;
                                                  step(x0. v0. u. v: double. r: bool)
                                                    returns (x, y: double)
    reset ins<x> every (. on r);
    reset ins<v> every (. on r);
                                                    var ax, ay: bool
    x. ax = ins < x > (x0. u):
    v, av = ins < v > (v0, v);
                                                    if r { ins(x).reset() }:
                                                    if r { ins(v).reset() }:
                                                    x, ax := ins(x).step(x0, u);
                                                    v. av := ins(v).step(v0. v)
```

```
scheduling
                                i-translation
                                                  s-translation
                       NLustre
                                             Stc
                                                               Ohc
                                                class driver {
system driver {
  sub x: ins, y: ins;
                                                  instance x: ins, y: ins;
  transition(x0, y0, u, v: double, r: bool)
                                                 reset() { ins(x).reset();
    returns (x. v: double)
                                                            ins(v).reset() }
    var ax, ay: bool;
                                                  step(x0. v0. u. v: double. r: bool)
                                                    returns (x, y: double)
    reset ins<x> every (. on r);
    reset ins<v> every (. on r);
                                                    var ax, ay: bool
    x. ax = ins < x > (x0. u):
    v, av = ins < v > (v0, v);
                                                    if r { ins(x).reset();
                                                           ins(v).reset() }:
                                                    x, ax := ins(x).step(x0, u);
                                                    v. av := ins(v).step(v0. v)
```

STC INTUITIVE SEMANTICS

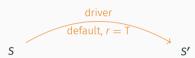
Transition system

- Start state S, end state S'
 Transition constraints

Transient state I

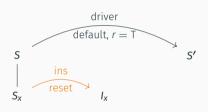
- Start state S. end state S' Transition constraints Transient state I

```
system driver {
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    v, av = ins < v > (v0, v);
    reset ins<v> every (. on r);
```



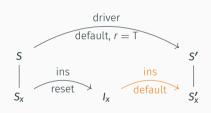
- Start state *S*, end state *S'*
- Transition constraints
 Transient state I

```
system driver {
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  transition(x0, y0, u, v: double, r: bool)
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```



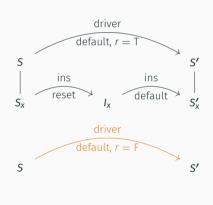
- Start state *S*, end state *S'*
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system driver {
  sub x: ins, y: ins;
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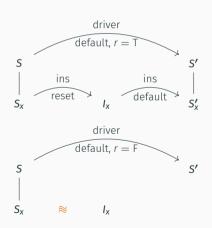
- Start state S, end state S'
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```
system driver {
  sub x: ins, y: ins;
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```



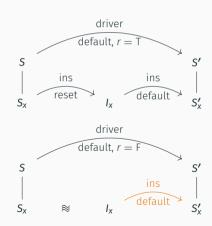
- Start state *S*, end state *S'*
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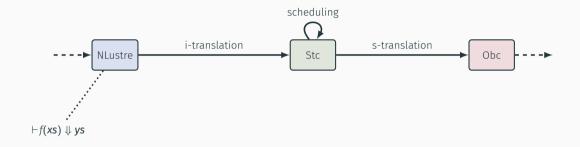
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```

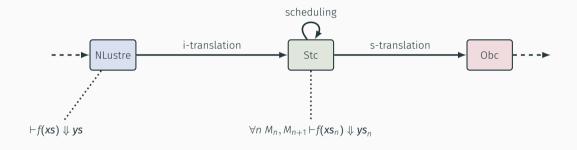


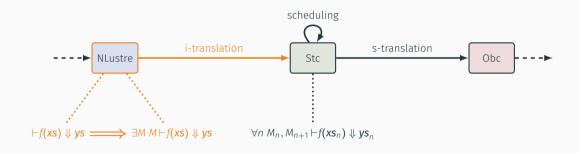
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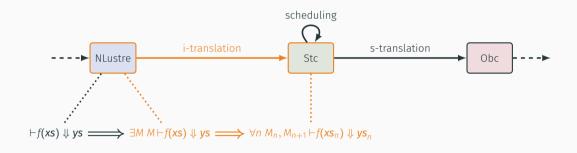
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```

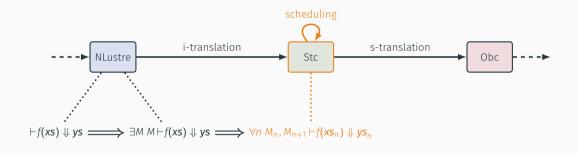


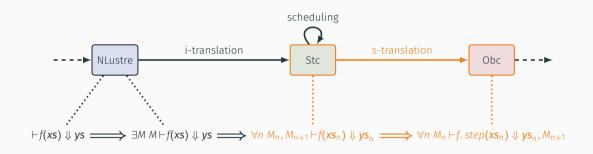












Theorem (Vélus correctness)

Given a list of declarations D, a name f, lists of streams of values xs and ys, an NLustre program G and an assembly program P such that compile D f = OK (G, P) and $G \vdash f(xs) \Downarrow ys$, then there exists an infinite trace of events T such that

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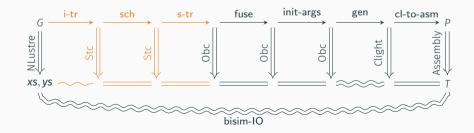
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CONCLUSION

Contributions:

- · A verified compiler for Lustre with reset
- · A single additional semantic rule for the reset
- · An intermediate transition system language: Stc

Next goal: State machines

velus.inria.fr
github.com/INRIA/velus

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