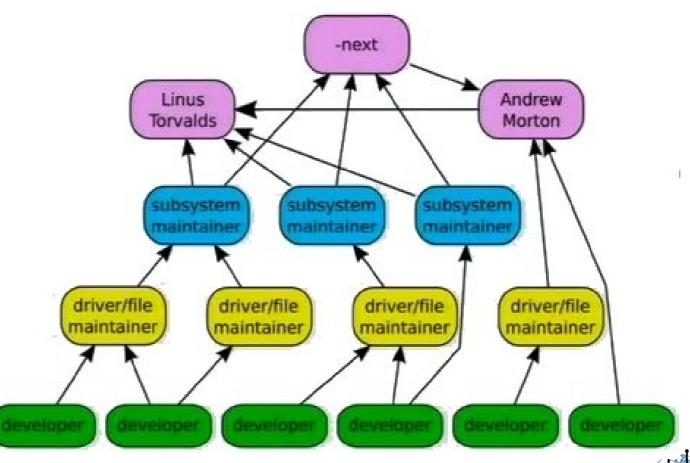


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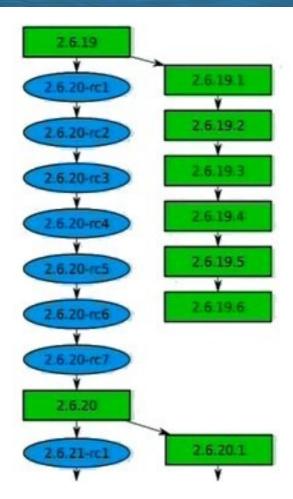
Who is doing and how it is being done?

- Fastest moving project known to everybody (during 2007-2008, per day)
 - 4,300 lines added
 - 1,800 lines removed
 - 1,500 lines modified
- By 2008
 - 9.2 million lines of code
 - 2399 developers



Releases

- New enhancements and bug fixes in rc-s
- Support of the previous version
- Important is to not break kernel for existing arcl
- The main testing is done by the users
- The patches done on old release should be done also on the upstream tree
- New release every 2 ¾ months



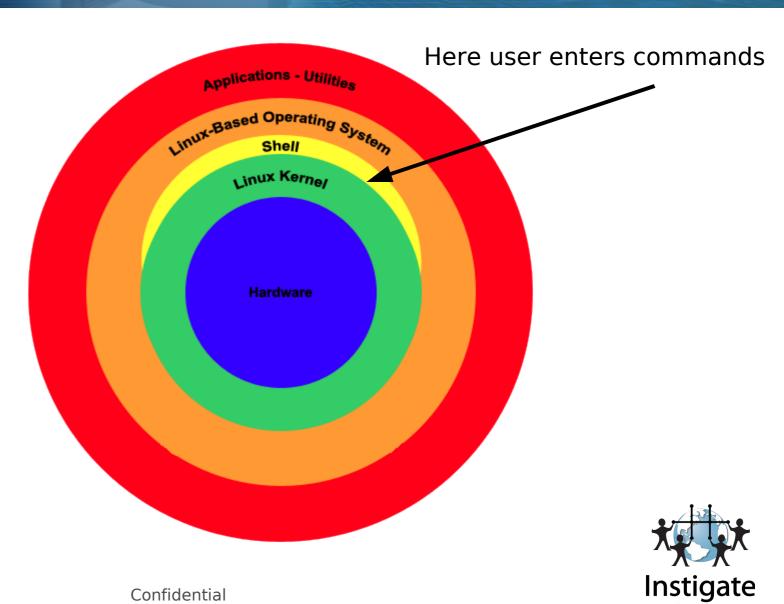


Confidential

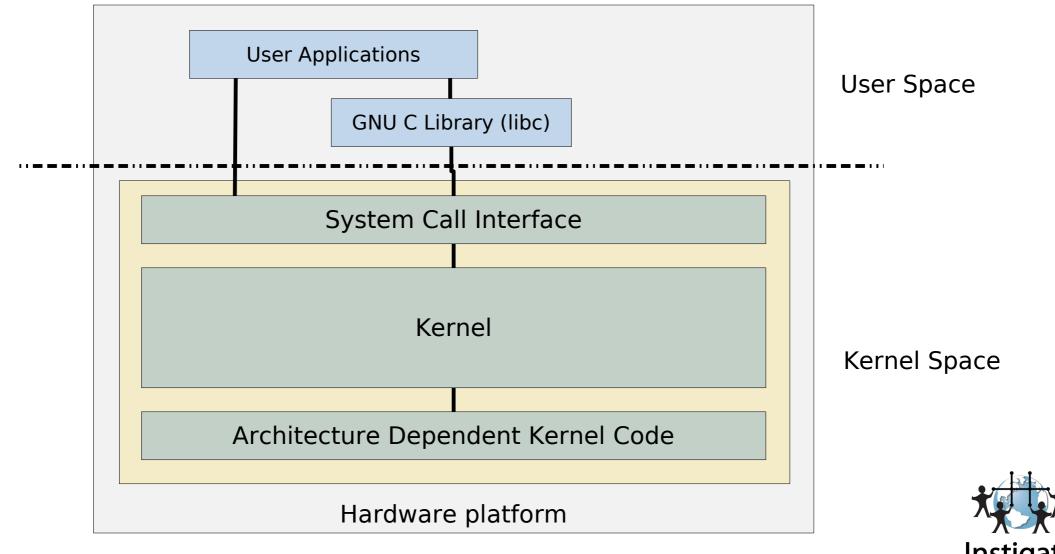
Architecture

Important parts

- Kernel
- Shell
- Graphical subsystem X
- Network subsystem

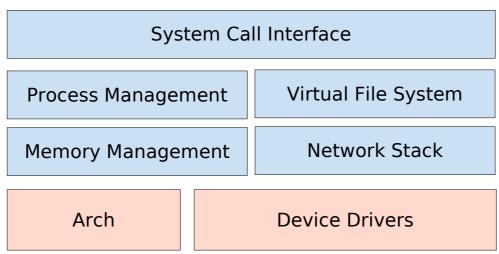


Kernel Architecture



User and Kernel Space Components

- User applications
- Glibc provides the system call interface that connects to the kernel
- System call interface provides the basic functions (read and write)
- Kernel
 - Architecture-independent kernel code common to all processor architectures
 - Architecture-Dependent Code processor and platform specific code
- Kernel Subsystems





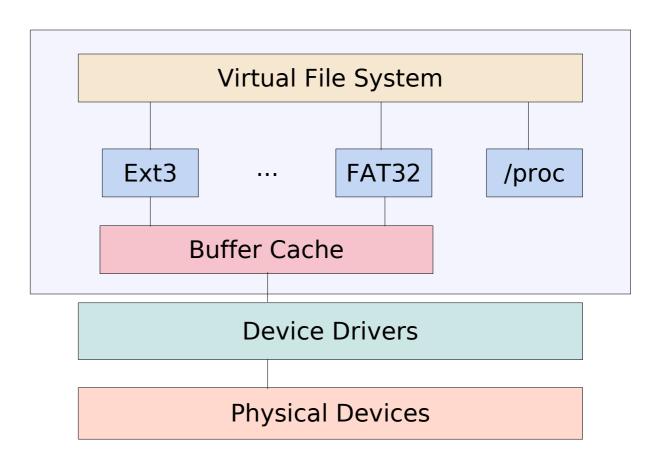
Kernel Subsystems

- System Call Interface
 - Provides the means to perform function calls from user space into the kernel
- Process Management
 - Focused on the execution of the processes
 - Each has an individual virtualization of the processor (data, stack, registers)
 - Kernel provides API to start start, stop and communicate with processes
 - Kernel implements constant time scheduling algorithm regardless the # of threads
- Memory Management
 - Memory is managed in pages (typically 4KB per page)
 - Keeps tracks of which pages are full, partially used, empty,
 - Swaps to disk if physical memory runs out



Virtual File System

- Virtual File system
 - Presents a common API (open, close, read, write)
 - Support over 50 different file systems
- Buffer Cache Optimizes access to the physical devices by caching
- Network Stack
 - Managing connections
 - Moving data between endpoints
- Device Drivers most of the kernel source code





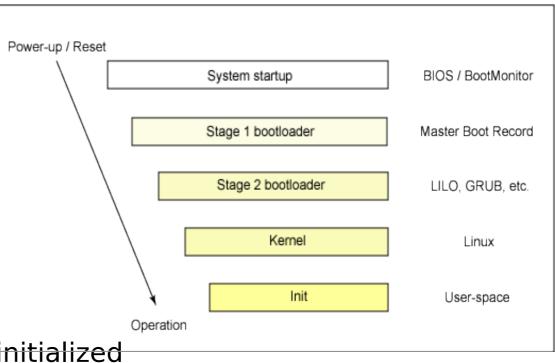
Modularity

- Many components of the Linux kernel may be compiled as modules which the kernel can dynamically load and remove as required.
- The best components to modularize are ones not required at boot time, for example peripheral devices and supplementary file systems.
 - Ismod list currently loaded modules
 - rmmod remove a single module
 - insmod insert a single module
 - depmod create the database of module dependencies modules.dep
 - modprobe insert a module and dependencies listed in modules.dep
 - modinfo list information about the author, license type and module parameters



Booting

- Processor executes code at a well-known location – BIOS, located in the flash memory of MB
 - BIOS determines devices to boot
- First-stage boot loader is loaded into RAM and executed (< 512 bytes)
 - Loads the second-stage boot loader
- Second-stage boot loader is loaded into RAM and executed
 - Passes control to the kernel image and the kernel is decompressed and initialized
- Kernel checks the system hardware, enumerates the attached hardware devices, mounts the root device, loads the necessary kernel modules and starts init.



Building Linux Kernel

- Why upgrade or build your own kernel?
 - You want to optimize a kernel (for speed, size, etc.)
 - Optimize for security with extra enhancements (e.g. remove modules support, remove networking support, limit drivers)
 - You want to patch your kernel to use non-standard features.
 - You are adding a new hardware to machine not supported under current kernel



References

- Architecture of the Linux Kernel
- Greg Kroah Hartman on the Linux Kernel
- Booting process

